

OMRON

SYSMAC CS/CJ-Series

Position Control Units

CJ1W-NCF71 CS1W-NCF71 NEW

Transforming Devices with Motion Field Network MECHATROLINK-II-compatible Position Control Unit

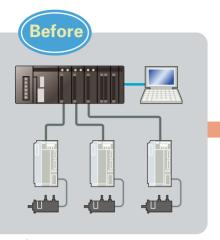




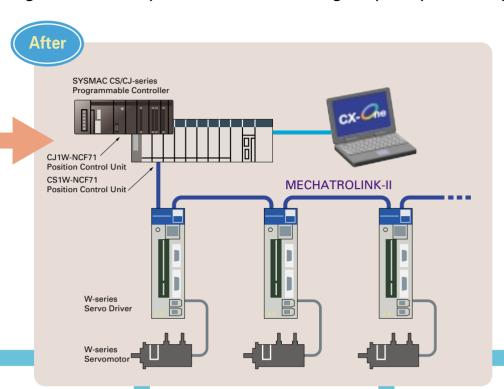
realizing

Quick and Simple Multi-axis System

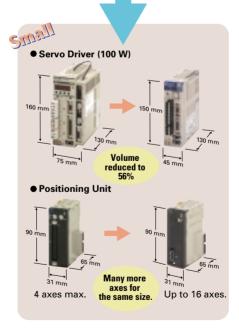
Introducing a Position Control Unit that can control up to 16 axes across a MECHATROLINK-II* high-speed field network. With it, every aspect of multi-axis systems from machine design to future expansions can be changed quickly and simply.



- Routing wires was difficult because of the number of wires involved.
- Expanding or modifying equipment was complicated because the number of axes dictated the number of Units.
- Settings took time because Controllers and Servo Drivres had to be set separately.



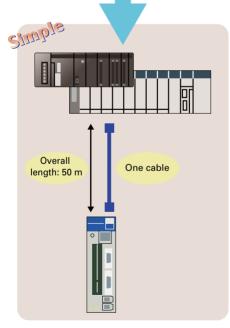
More Compact



Even smaller

Previously, W-series Units had to be connected to a MECHATROLINK-II Module. Now, OMNUC W-series AC Servo Drivers with built-in MECHATROLINK-II communications are available. This reduces the volume to 2/3 or more of previous models.

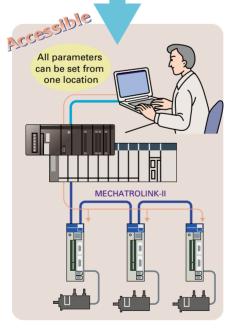
Less Wiring



Single-cable connection offers wiring flexibility

Servo Driver connection was greatly simplified: just one shielded twisted-pair cable is needed with a MECHATROLINK-II network. The overall cable length is 50 m (30 m max. with 16 axes connected) and there is less wiring and more flexibility in device arrangement.

Centralized Data Control



Less Time Spent on Startup and Maintenance

Servo Driver parameters can be set from the PLC. This means that settings and adjustments can be performed from one location rather than having to connect a Programming Device to each Servo Drive individually. Servo Drive alarm status and other information, such as speed and torque, can also be monitored from the PLC

mplementation

Multi-axis Control MECHATROLINK-II 16 axes max.

Simple Expansion

An easily expandable system can be constructed that is just as efficient now with a few axes or later with up to 16 axes.

*MECHATROLINK and MECHATROLINK are registered trademarks of Yaskawa Electric Corporation.

A Whole New World of Machine Control from OMRON

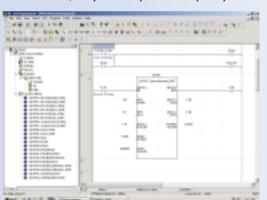
OMRON has developed a whole new environment that seamlessly integrates different control devices and networks over the entire life cycle of equipment and machines, ranging from design and startup to operation and maintenance. The system will still be viable as new systems are developed and new control devices and controllers become available. It all begins with OMRON Standard Libraries.

OMRON Standard Libraries

OMRON Standard Libraries are software applications that customers can load into their system and use without modification. The OMRON FB Library and Smart Active Parts (SAPs) Library are available now. These libraries simplify the software developed for interface components between Programmable Controllers (PLCs) or Programmable Terminals and various other control devices. They also improve the quality of the software by using standardized software components.

OMRON FB Library

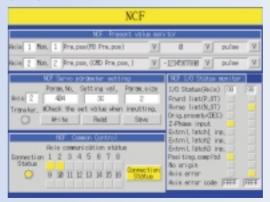
The OMRON FB Library contains functional components for Programmable Controllers (PLCs). These components can be used by customers to produce finished programs that interface with various control devices in much less time. Since the components are standardized, they also improve the quality of the finished programs.



Frequently used ladder programming is provided in each function block. Several function blocks form a library that facilitates program and program asset development.

Smart Active Parts (SAPs) Library

The Smart Active Parts (SAPs) Library, formerly known as the Device Library, consists of screens with functions for Programmable Terminals. SAPs can be used on screens developed by customers to produce finished screens that interface with various control devices in much less time. Since the components are standardized, they also improve screen quality.



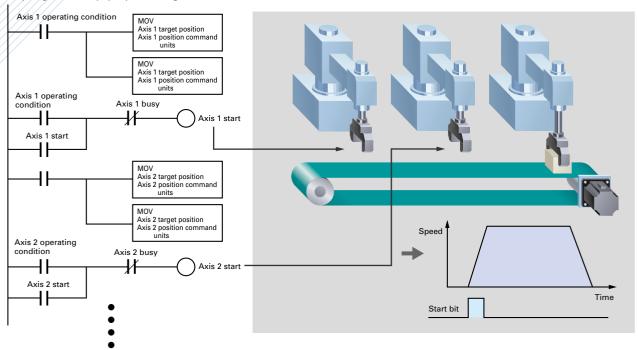
The SAPs include various operating screens for Position Control Units. Simply paste SAPs to simplify design work and eliminate unnecessary user programming.

The OMRON FB Library and Smart Active Parts Library can be used with CS/CJ-series Programmable Controller CPU Units version 3.0 or later and NS-series Programmable Terminals version 6 or later, respectively.

Simplifying the Task of Designing Various T

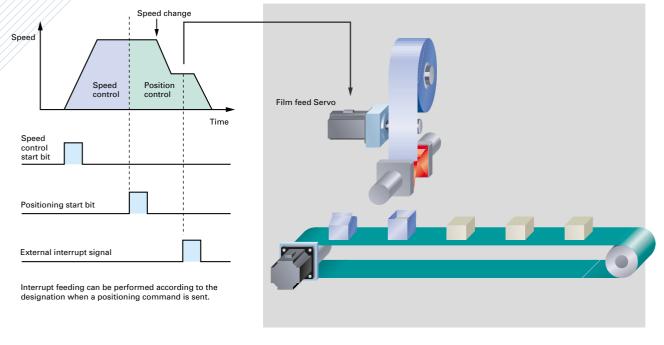
Assembly Equipment

Absolute and relative positioning of multiple axes can be performed by manipulating bits directly from the PLC. The target position and target speed can be changed instantly even while the positioning operation is in progress simply by sending another command.



Feeders

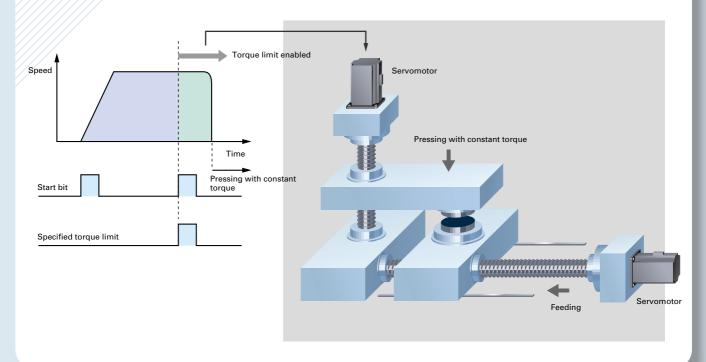
Just as with position control, speed and torque can also be controlled by operating bits directly from the PLC. The position, speed, and torque can be changed while the axis is operating simply by turning ON individual control bits.



ypes of Control

Processing Equipment

Position, speed, and torque can be controlled using a torque limit. The torque limit can be enabled or disabled and a new torque limit can be written while the axis is operating.



Conveyors

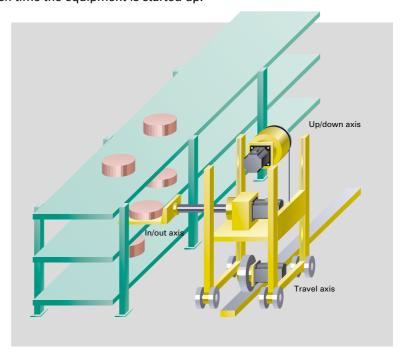
This example uses a W-series Servomotor with an Absolute Encoder.

This eliminates establishing the origin each time the equipment is started up.

Establish the origin and set the offset the first time only.

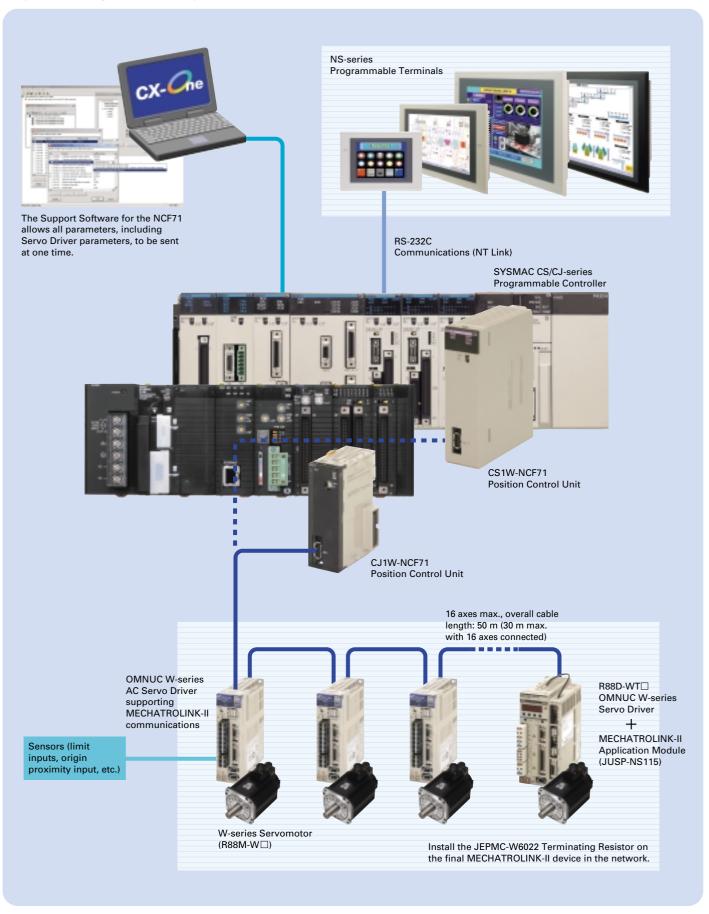
After that, just turn ON the power to start operation.

This simplifies standby and recovery processing when faults such as a power interruptions occur.



Full advantage can be taken of more advanced Servo Drivers and Servomotors to meet customer needs thanks to motion field network capabilities that include monitoring functions for various Servo Driver status conditions and a wide speed command range.

■System Configuration Examples



■Ordering Information

Name	Model	Standards			
Position Control Unit	CJ1W-NCF71	CE, UL			
Position Control Onit	CS1W-NCF71	CE, UL			

■Related Products

Name	Yaskawa model number	OMRON model number	Remarks
MECHATROLINK-II Application Module	JUSP- NS115	FNY-NS115	
	JEPMC-W6003-A5	FNY-W6003-A5	0.5 m
	JEPMC-W6003-01	FNY-W6003-01	1.0 m
	JEPMC-W6003-03	FNY-W6003-03	3.0 m
MECHATROLINK-II Cable	JEPMC-W6003-05	FNY-W6003-05	5.0 m
	JEPMC-W6003-10	FNY-W6003-10	10 m
	JEPMC-W6003-20	FNY-W6003-20	20 m
	JEPMC-W6003-30	FNY-W6003-30	30 m
MECHATROLINK-II Terminating Resistor	JEPMC-W6022	FNY-W6022	

The MECHATROLINK-II Application Module, Cables, and Terminating Resistor (all made by Yaskawa Electric Corporation) can be ordered from OMRON using our model numbers in the table above.

■Support Software

	Name	Specification	Model	Standards	
	C-One FA Integrated ol Package version 1.1	The CX-One is an integrated tool package that provides programming and monitoring	One license	CXONE-AL01C-E	
		software for OMRON PLCs and components.	Three licenses	CXONE-AL03C-E	
		The CX-One runs on any of the following operating systems: Windows 98 SE, Me, NT 4.0 (Service Pack 6a), 2000 (Service Pack 3 or higher), or XP	Ten licenses	CXONE-AL10C-E	<u> </u>
loo		The CX-One includes CX-Motion-NCF Ver 1	Thirty licenses CXONE-AL30C-E		
		neier to the CA-One Catalog (N134) for details.	Fifty licenses	CXONE-AL50C-E	
		The CX-Motion-NCF can also be ordered individually using the following model number.			
	CX-Motion-NCF Ver. 1.□	-NCF Support Software for Position Control Units with MECHATROLINK-II communications. Operating system: Windows 98 SE, Me, NT 4.0 (Service Pack 6a), 2000 (Service Pack 3 or higher), or XP		WS02-MNTC1	_

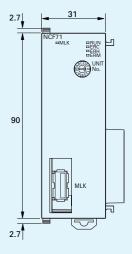
■Specifications

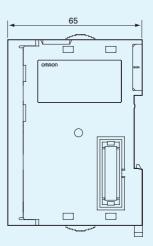
Site-licensed products are available for users who will run CX-One onmultiple computers. Ask your OMRON sales representative for details.

	Item	Specification						
Model		CJ1W-NCF71 CS1W-NCF71						
Unit classifica	tion	CPU Bus Unit						
Applicable PL	Cs	CJ Series CS Series						
Unit number s	settings	0 to F						
I/O	Common Operating Memory Area	Words allocated in CPU Bus Unit Area: 25 words (15 output words, 10 input words)						
allocations	Axis Operating Memory Area	Allocated in one of the following areas (user-specified): CIO, Work, Auxiliary, Holding, DM, or EM Area Number of words allocated: 50 words (25 output words, 25 input words) x Highest axis number used						
Compatible de	evices	OMRON W-series Servo Drivers equipped with MECHATROLINK-II Ap	plication Module					
Control metho	od	Control commands executed using MECHATROLINK-II synchronous co	ommunications					
Maximum nur	mber of controlled axes	16 axes						
Control	Position commands	-2,147,483,648 to 2,147,483,647 (command units) (The command unit	depends on the Electronic Gear Settings in the Servo Parameter					
commands	Speed commands for position control	0 to 2,147,483,647 (command units/s)						
	Acceleration/deceleration for position control	1 to 65,535 (10,000 command units/s²)						
	Speed commands for control	-199.999 to 199.999% (0.001% units) The upper limit of the speed command range is a percentage (%) of the maximum speed and depends on the specifications of the Servo Driver.						
	Torque commands for torque control	-199.999 to 199.999% (0.001% units) The upper limit of the torque command range is a percentage (%) of the maximum torque and depends on the specifications of the Servo Driver.						
Control	Servo lock/unlock	Locks and unlocks the Servo Driver.						
functions	Position control	Performs absolute or relative positioning according to the target position and target speed specified by the ladder program. (Linear interpolation for up to 4 axes is possible with appropriate settings.)						
	Establishing the origin	Origin search: Establishes the origin using the specified search method. Present position preset: Changes the present position to a specified position to establish the origin. Origin return: Returns the axis from any position to the established origin. Absolute encoder origin: Establishes the origin using a Servomotor that has an absolute encoder, without having to use an origin search.						
	Jogging	Outputs pulses at a fixed speed in the CW or CCW direction.						
	Interrupt feeding	Performs positioning by moving the axis a fixed amount when an external interrupt input is received while the axis is moving.						
	Speed control	Performs speed control by sending a command to the Servo Driver speed loop.						
	Torque control	Performs torque control by sending a command to the Servo Driver current loop.						
	Stop functions	Deceleration stop: Decelerates the moving axis to a stop. Emergency stop: Positions the moving axis for the number of pulses remaining in the error counter and then stops the axis.						
	Acceleration/deceleration curves	Any of the following can be set: a trapezoidal (linear) curve, an exponential curve, or an S-curve (moving average).						
	Torque limit	Restricts the output torque during axis operation.						
	Override	Multiplies the axis command speed by a specified ratio. Override: 0.01% to 327.67%						
	Servo parameter transfer	Reads and writes the Servo Driver parameters from the ladder program in the CPU Unit.						
	Monitoring function	Monitors the control status of the Servo Driver, such as the command coordinate positions, feedback position, current speed, and torque.						
	Software limits	Sets limits on the software level applied to the positioning range of axis operations.						
	Backlash compensation	Compensates for the amount of play in the mechanical system according to a set value.						
External I/O	Position Control Unit	One MECHATROLINK-II interface port						
	Servo Driver I/O	CW/CCW limit inputs, origin proximity inputs, external interrupt inputs 1 to 3 (can be used as external origin inputs)						
Self-diagnostic functions Error detection functions Internal current consumption Dimensions		Watchdog, flash memory check, memory corruption check						
		Overtravel, Servo Driver alarm detection, CPU error, MECHATROLINK communications error, Unit setting error						
		360 mA max. at 5 V DC 360 mA max. at 5 V DC						
		31 x 90 x 65 mm (W x H x D) 35 x 130 x 101 mm (W x H x D)						
Weight		95 g max. 188 g max.						
	ating temperature	0 to 55°C	0 to 55°C					

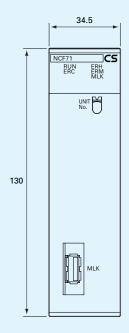
•When a MECHATROLINK-II Application Module must be mounted to a W-series Servo Driver, use the following device versions.									
Device	Compatible versions	The versions of both the W-series Servo Driver and MECHATROLINK-II Application Module can be found on the nameplate on the side of each device. If an earlier							
R88D-WT□ W-series Servo Driver	Version 39 or later	version of the device is used, it will not function properly. Always use products with							
JUSP-NS115 MECHATROLINK-II Application Module	Version□□□03 or later	versions listed in the table (or later versions).							

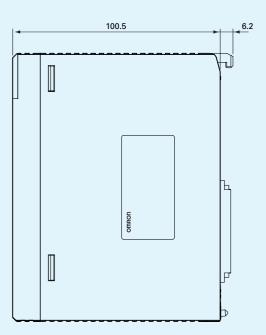
CJ1W-NCF71





CS1W-NCF71





■ AC Servo Driver and Servomotor Selection

•The following combinations of Servo Drivers and Servomotors can be connected to Position Control Units.

	Combination	Servo Driver	AC Servomotor			
Ī	1	R88D-WN□□□-ML2 OMNUC W-series AC Servo Driver supporting MECHATROLINK-II communications	OMNUC W-series AC Servomotor Use a 200-V AC Servomotor for both 100-V and 200-V Servo Drivers.			
	2	R88D-WT□□□ OMNUC W-series AC Servo Driver with MECHATROLINK-II Interface Unit	OMNUC W-series AC Servomotor			

Servo Driver and Servomotor Combinations

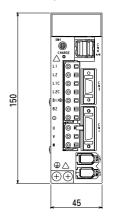
			1		2								
	Servomotors R88M-			R88D-□-ML2 Servo Drivers with MECHATROLINK-II Communications		Servo Drivers R88D-			Application				
Туре	Rated speed (maximum number of rotations)	Capacity	International standards CE, UL/cUL	Shaft end (not using decelerator)	Enclosure rating	100 V	200 V single phase	200 V three phase	100 V	200 V single phase	200 V three phase		
		30 W							WTA3HL	WTA3H		• Low-inertia machines	
		50 W	-	Straight With key With key and tap Straight with tap	IP55 (excluding shaft opening)	WNA5L	WNA5H		WTA5HL	WTA5H			
		100 W				WN01L	WN01H		WT01HL	WT01H			
		200 W				WN02L	WN02H		WT02HL	WT02H			
		400 W				WN04L	WN04H			WT04H		 Machines with fast tact time 	
	3000 r/min	750 W	Approved				WN08H			WT08H*	WT08H	Robots	
	(5000 r/min)	1 KW	Approved					WN10H			WT10H	Assembly machines	
		1.5 KW	-		IP67			WN15H			WT15H		
		2 KW	_	With key and tap	(excluding			WN20H			WT20H	Conveyors	
		3 KW		Straight	shaft opening)			WN30H			WT30H		
		4 KW									WT50H		
		5 KW									WT50H		
Cylinder	1500 r/min (3000 r/min)	450 W	_	With key and tap Straight	IP67 (excluding shaft opening)			WN05H			WT05H		
Š		850 W	Approved					WN10H			WT10H		
		1.3 KW						WN15H			WT15H	Machines	
		1.8 KW						WN20H			WT20H	requiring high torque Simple processing machines Assembly machines Transfer machines • Machines requiring high	
		2.9 KW									WT30H		
		4.4 KW									WT50H		
		5.5 KW	-								WT60H		
		7.5 KW	-								WT75H		
		11 KW	_								WT150H		
		15 KW									WT150H		
		300 W						WN05H			WT05H		
		600 W						WN10H			WT08H		
		900 W			IP67			WN10H			WT10H	torque	
	1000 r/min (2000 r/min)	1.2 KW	Approved	With key and tap Straight	(excluding shaft			WN15H WN20H			WT15H	Simple processing machines	
	,2000 1/111111/	2 KW			opening)			VVINZUIT			WT20H WT30H	Assembly machines	
		3 KW 4 KW	-								WT50H	Transfer machines	
		5.5 KW	-								WT60H		
											VV 1 00 F1	Machines with	
	3000 r/min (5000 r/min)	100 W				WN01L	WN01H		WT01HL	WT01H		limited motor depth	
ofile		200 W	-	Straight With key With key and tap Straight with tap	IP55 (excluding shaft opening) IP67	WN02L	WN02H		WT02HL	WT02H		 Machines requiring water-resistant 	
Slim profile		400 W	Approved			WN04L	WN04H			WT04H		Semiconductor manufacturing machines	
		750 W					WN08H			WT08H*	WT08H	Food-processing machines	
		1.5 KW					_	WN15H	_	_	WT15H	AGVs	

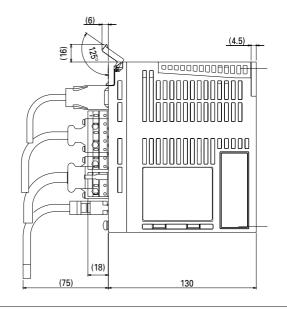
^{*}Power supply wiring must be partly changed when using 200-V single-phase Servo Drivers. The power supply input specifications are 220 to 230 VAC (+10% to -15%).

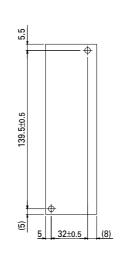
■Dimensions of AC Servo Driver with MECHATROLINK-II Communications

AC Servo Drivers

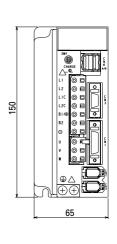
- 200 VAC: 50 W, 100 W or 200 W R88D-WNA5H-ML2/WN01H-ML2/WN02H-ML2
- 100 VAC: 50 W, 100 W or 200 W R88D-WNA5L-ML2/WN01L-ML2/WN02L-ML2

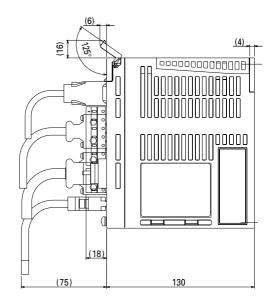


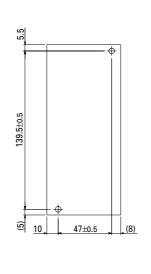




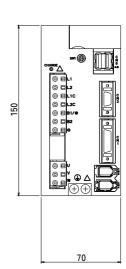
• 200 VAC: 400 W R88D-WN04H-ML2

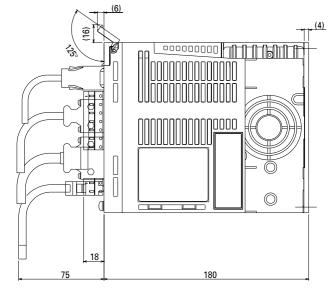


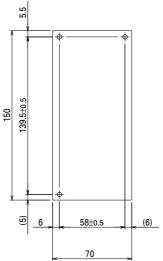


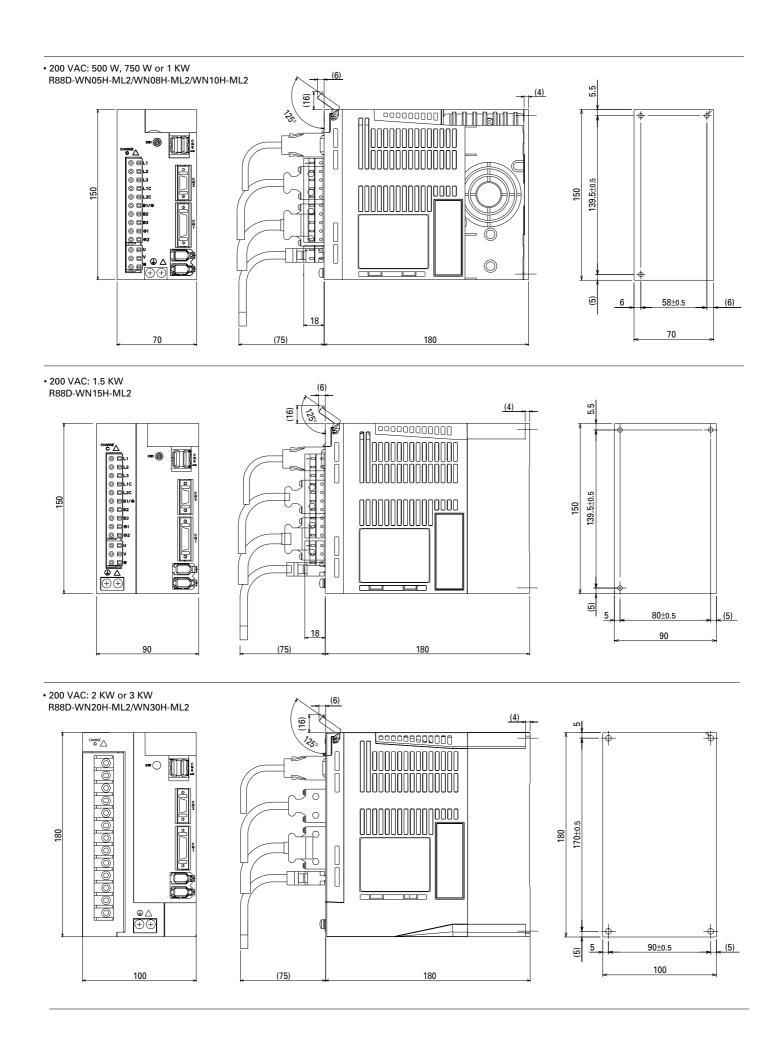


• 100 VAC: 400 W R88D-WN04L-ML2









Warranty and Limitations of Liability

WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

OMMON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS, OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY

In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

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Note: Do not use this document to operate the Unit.

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Note: Specifications subject to change without notice.

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