

Confocal Fiber Displacement Sensor ZW Series

The 24×24×64-mm Sensor Head redefines the meaning of ultra-compact



New
Right-angle type

EtherCAT  Standard Feature

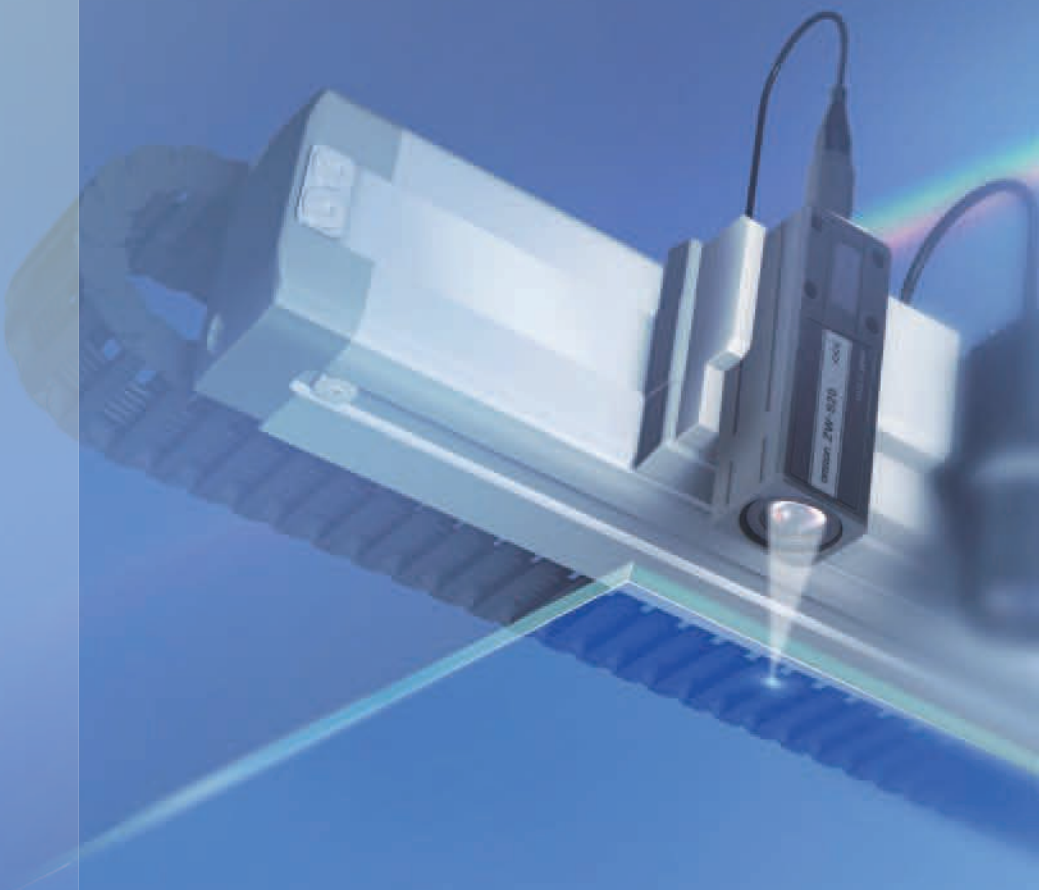
» Robust Sensor Head Structure

» Ultra-compact and Ultra-lightweight

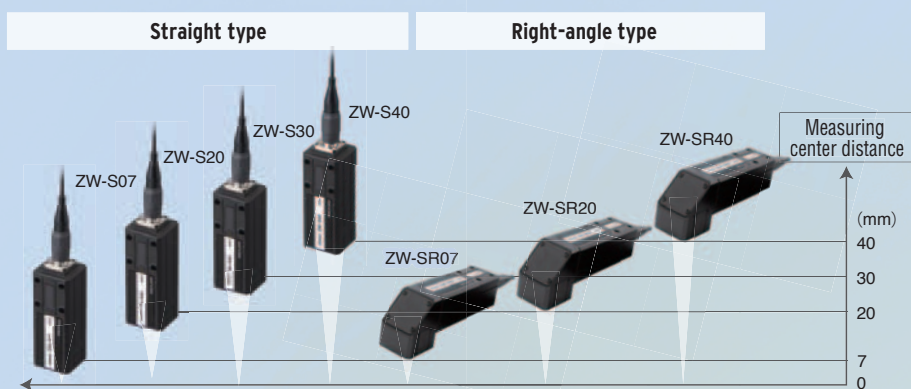
» Stable Measurements for Any Material

Goes beyond traditional displacement sensor concepts with a new confocal principle.

Displacement Sensors are indispensable in non-contact measurement of heights, thicknesses, and other dimensions in machine operation control. However, building them into the system has always presented problems. The Confocal Fiber Displacement ZW Series Sensor solves these problems in ways that were not possible with traditional triangulation. The ZW-series Sensors provide the compact size, light weight, immunity to electrical/magnetic noise, and other features to make them ideal for solving installation space problems. And OMRON's new confocal principle provides the measurement resolution that is needed for operation control. The ZW Series solves the problems that came with laser triangulation, such as deviations between different materials and inclination tolerance.



Two Types of Sensor Heads



Expanded Communications

Standard-feature
EtherCAT

> p.10

Standard-feature EtherNet/IP™



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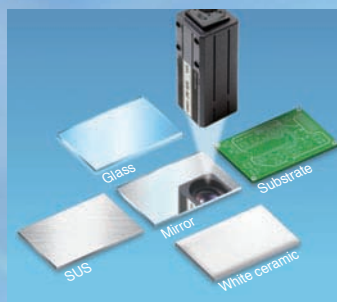
The Three Benefits of OMRON's White Light Confocal Principle



Ultra-compact and Ultra-lightweight

The slim design measures only 24 × 24 mm. It weighs only 105 g. This incredibly compact size could not be achieved with traditional triangulation. Any objects can be measured with the Sensor mounted perpendicular to them to save even more space.

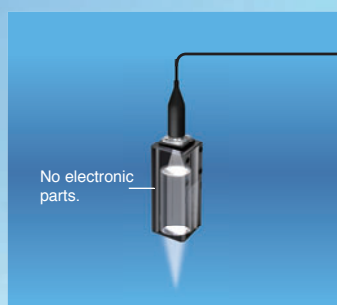
> P.4



Stable Measurements for Any Material

You can measure objects of any material or color at the same position. A wide angle characteristic of $\pm 8^\circ$ enables high-resolution measurement of the position even for large objects with mirror-like surfaces without being affected by warping.

> P.6



Robust Sensor Head Structure

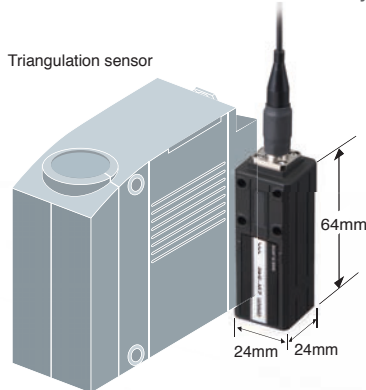
The sensor head design maintains reliable operation in installations with electronic and magnetic noise. Devices in close proximity will not be affected by noise or heat from the sensor head or fiber cables due to their advanced design.

> P.8

Ultra-compact and Ultra-lightweight

Utilize Narrow Spaces in Machines

The 24 × 24-mm Sensor Head fits easily into essentially any machine.



Volume
ratio
1/8*

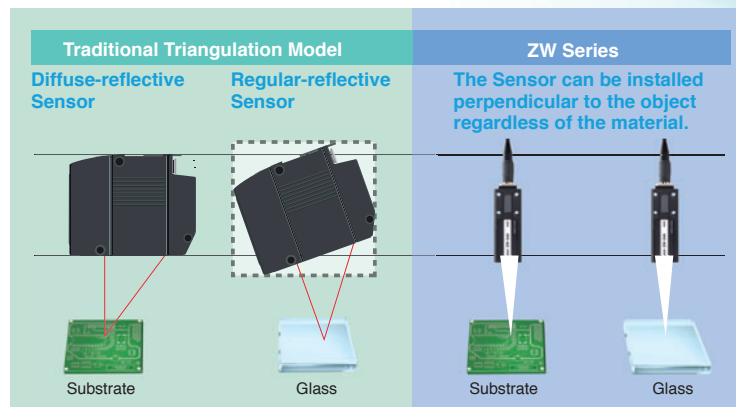
Weight
ratio
1/8*

*In-house comparisons.

Mounting area Reduced to 1/7*

*In-house comparison.

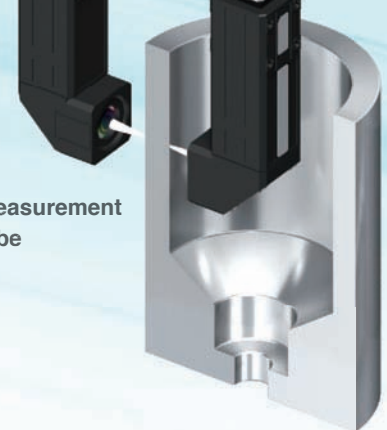
With traditional triangulation, it was necessary to use either diffuse reflection or regular reflection depending on the material. However, the confocal principle used for the ZW Series eliminates the need to change the Sensor installation even if the material changes.



Height Control of a Dispenser Nozzle



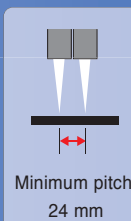
Thickness Measurement of a Metal Tube



Installation in Tight Spaces

Space restrictions, heat generation, and mutual interference often prevent side-by-side installation of many traditional triangulation sensors. The compact, non-heat generating ZW-series Sensor Head eliminates these problems. Furthermore, the right-angle type Sensor Head can be installed in a limited space over workpieces without a turning mirror.

The traditional sensors generally measure the thickness of a workpiece by calculating the difference between the heights of the stage and the top surface of the workpiece. The ZW-series Sensor Head can be installed in the small space under the stage to directly measure the height from the top and bottom surfaces of the workpiece, which enables more accurate thickness inspection.

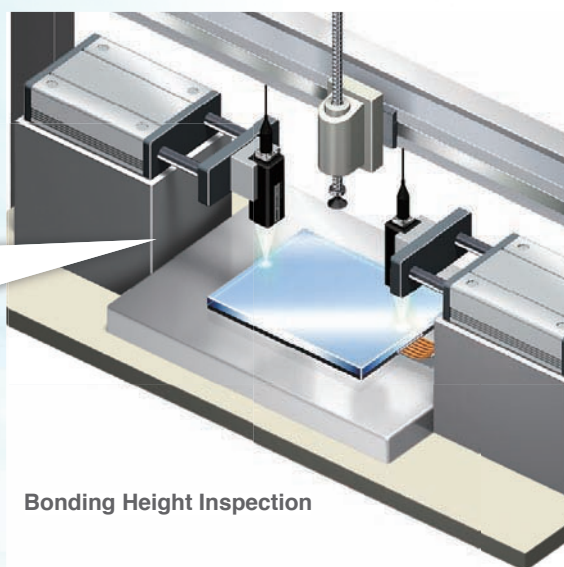
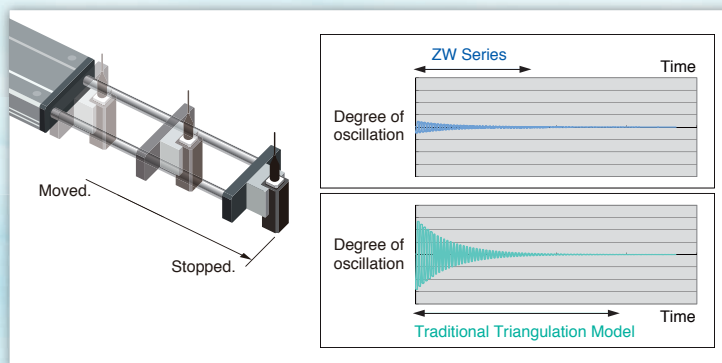


Thickness Inspection of Small Electronic Parts



Smooth Movement and Stopping

Using power cylinders to move sensors to measurement positions only when necessary so that the sensors do not interfere with machine motion resulting in delays in measurements while waiting for settling time if the sensors are heavy. A ZW-series Sensor Head, however, weighs only 105 g so that measurements can be made as soon as the cylinder operation stops.



Bonding Height Inspection

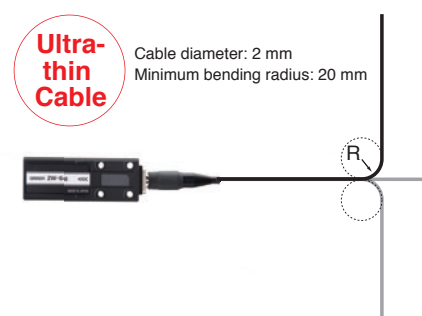
Flexible Fiber Cable for Easy Installation

The Controller connects to the Sensor Head with a 2-mm-diameter Flexible Fiber Cable. The Cable has cleared a bending test consisting of 2,000,000* repetitions for reliable application on moving parts.

*Cable was tested with OMRON's bending test consisting of 2,000,000 bends to a 70-mm bending radius and 1,000,000 bends to a 20-mm bending radius.

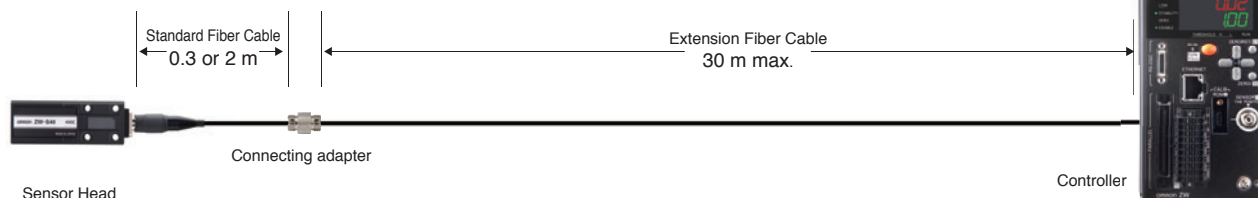


Installation in a Cable Carrier



Cable Extendable to 32 m

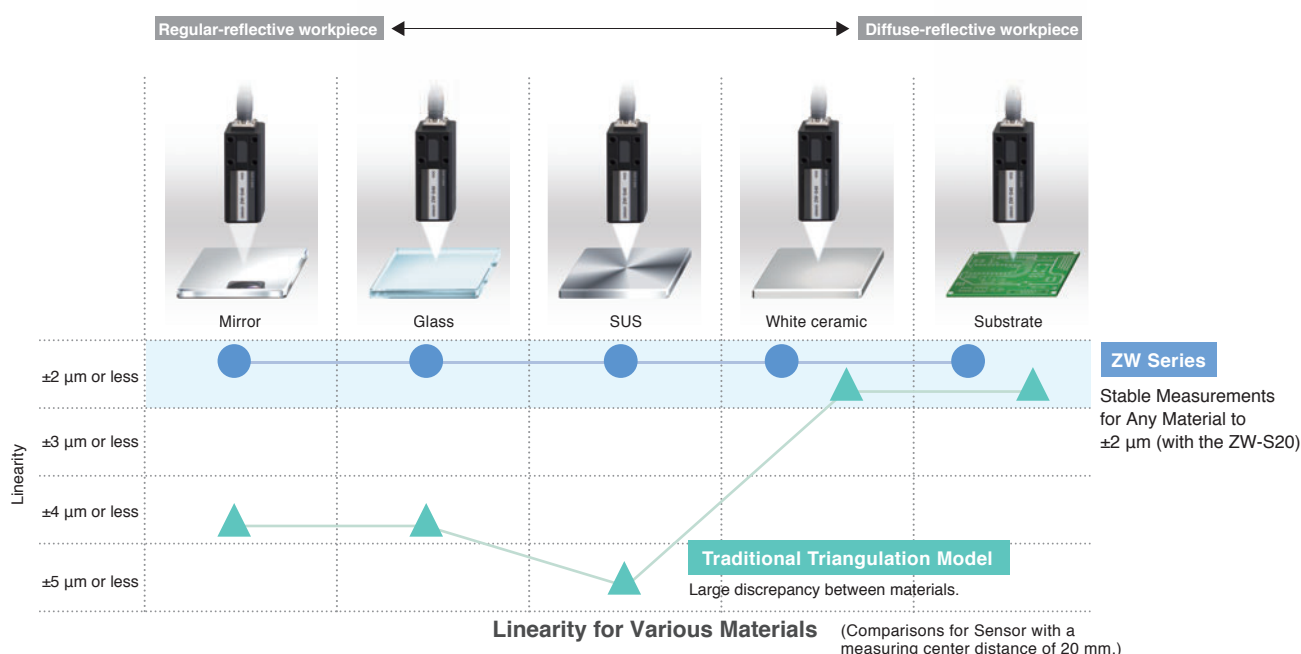
An Extension Fiber Cable can be used between the Sensor Head and Controller to extend the distance to up to 32 m. Attach the Sensor Head to a moving part and place the Controller in the control panel or other convenient location to achieve a flexible system design.



Stable Measurements for Any Material with Superior Angle Characteristic

Stable Measurements from the Same Mounting Position Even for Different Materials

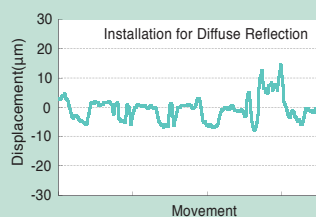
There is no need to change or tune the Sensor for each material. Even if the material changes, you can continue to achieve stable measurements with the same Sensor from the same mounting position.



Stable Measurements across Boundaries between Materials

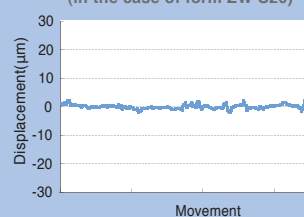


Traditional Triangulation Model



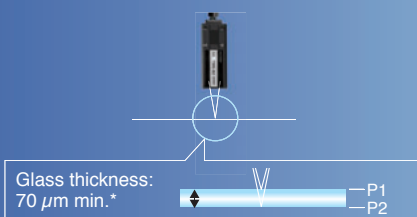
ZW Series

(in the case of form ZW-S20)



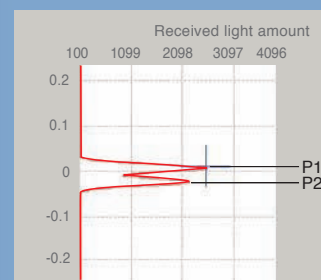
Compact Sensor Heads Provide Stable Measurements of Thin Transparent Glass

To stably measure transparent glass, the received light waveforms from the front and back surfaces of the glass must be separated. With thin transparent glass, the influence of lens aberration makes it difficult to achieve separation with compact sensor heads. Even with its compact size that saves space, the ZW-S07 stably measures transparent surface displacement on glass as thin as $70 \mu\text{m}$ min., a feat not easily achieved by previous compact sensor heads.



* Reference values considering refractive index of glass

Model	ZW-S07 ZW-SR07	ZW-S20 ZW-SR20	ZW-S30	ZW-S40 ZW-SR40
Glass thickness (μm) min.	70	150	600	900
max.	900	3,000	9,000	18,000



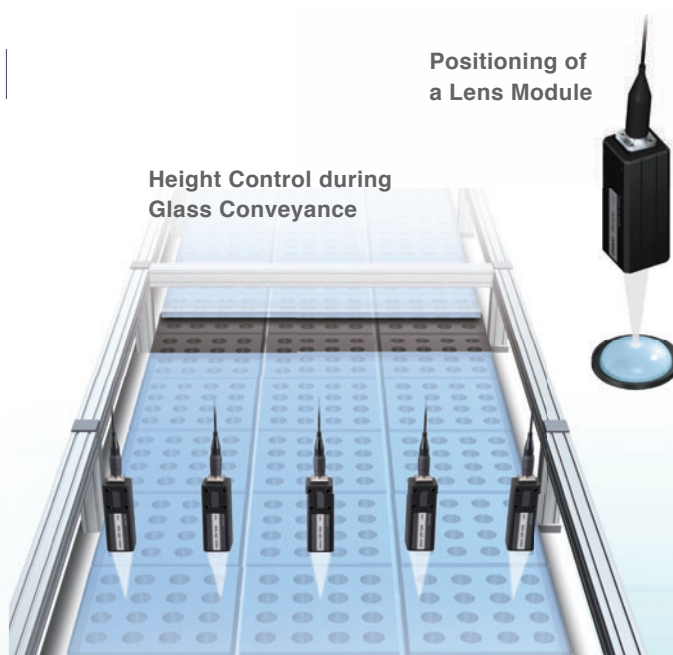
Received Waveform for ZW-series Sensor

Superior Angle Characteristic

When measuring an object that has a mirror-like surface with traditional triangulation, performance is greatly reduced depending on the angle of the Sensor. When many Sensors are used for height control during glass conveyance, the angles of the Sensors must be adjusted with high precision during setup. The confocal Sensor ZW series enables high-resolution measurements without strict angle adjustment. This results in reduction of cost and space for the adjusting jig and time for adjustment.

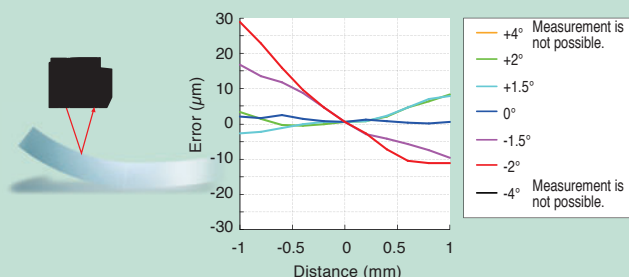
* This is not a guaranteed value.
Refer to Characteristic Data (P23)
for typical examples.

**Angle
characteristic
 $\pm 8^\circ$ ***



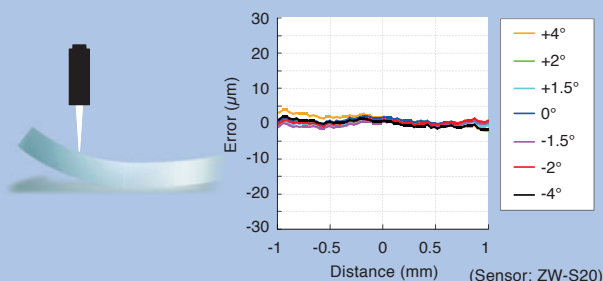
Traditional Triangulation Model

With triangulation, even if the angle is adjusted with high precision during the setup of the Sensor, stable measurement results are difficult to obtain when the measurement object is warped or inclined.



ZW Series

ZW-series Sensors operate on the confocal principle, so high-resolution measurements are possible regardless of inclination and warping of the measurement object.



Further Benefits of Confocal Principle

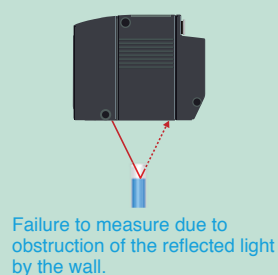
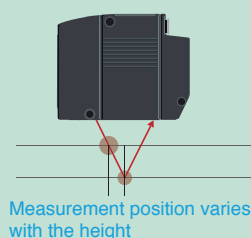
No Discrepancy in the Measurement Point

With triangulation, the measurement position and spot size vary with the height. This means there are times when the position cannot be measured with high resolution due to warping and inclination. With the confocal principle used for the ZW Series, the measurement point remains the same at any position in the measuring range so that precise measurements can always be made.

Measurement in Confined Spaces

When the triangulation sensor measures the inside of a narrow tube or the height of a small depression, the wall often obstructs the reflected light, and the orientation of the sensor and workpiece must be adjusted many times. The ZW Series using the confocal principle can measure the points in narrow spaces or small objects, without changing its installation orientation, because the emitted light and reflected light are positioned along the same axis.

Traditional Triangulation Model



ZW Series



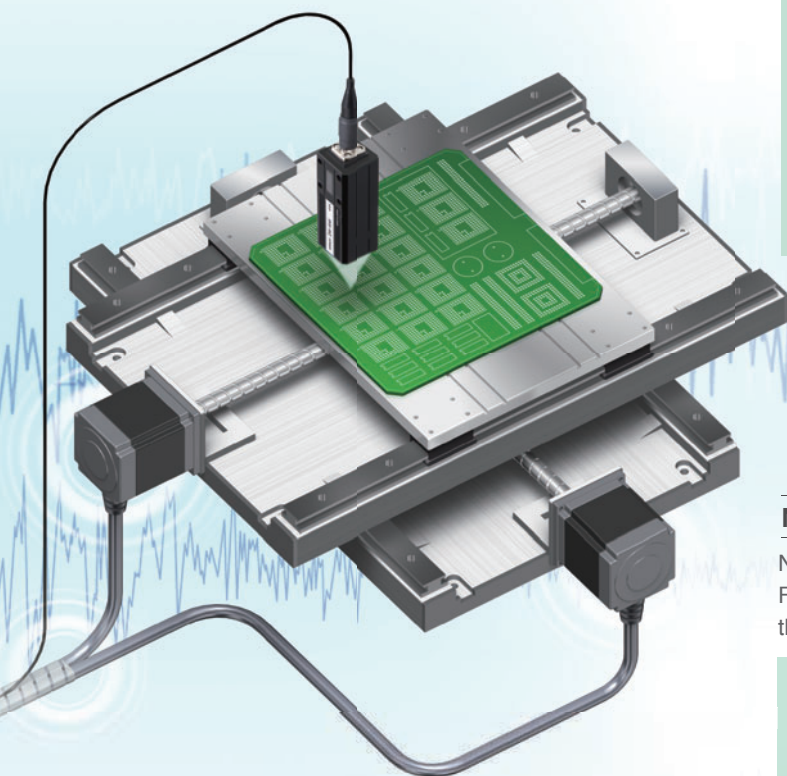
Robust Sensor Head Structure

No Noise

Reduced Work for
EMC Countermeasures

Not Affected by Noise

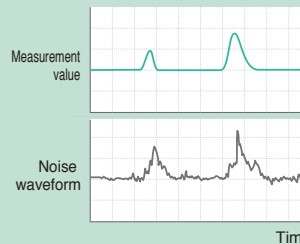
To ensure high-resolution measurements with normal sensors, countermeasures must be implemented to protect the sensor from the electromagnetic noise that is emitted by any nearby devices. The ZW-series Sensor Heads, however, contain no electronic parts to enable stable measurements even near power sections. Also, the Fiber Cable that connects the Sensor Head to the Controller can be placed near power lines and other cables that emit noise without affecting operation.



Substrate Height Inspection

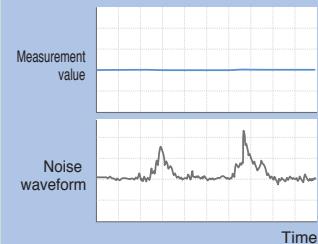
Traditional Triangulation Model

Changes in Measurement
Values Caused by Noise



ZW Series

Measurements are not affected by
noise and remain stable.

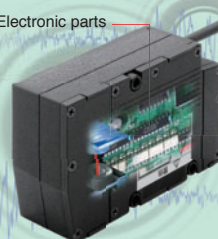


No Noise Emission

No electronic parts are used in the ZW-series Sensor Heads or Fiber Cables, so they give off no electromagnetic noise. You can therefore use them reliably together with other devices.

Traditional Triangulation Model

Electronic parts



Electromagnetic noise is emitted from
the sensor and from cables.

ZW Series

Fiber Cable



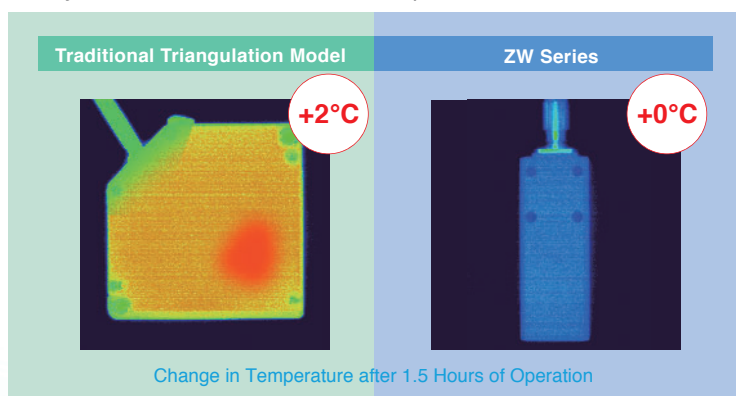
No electronic parts.

No Noise Emitted.

No Heat Generation

Reduced Work in Thermal Design

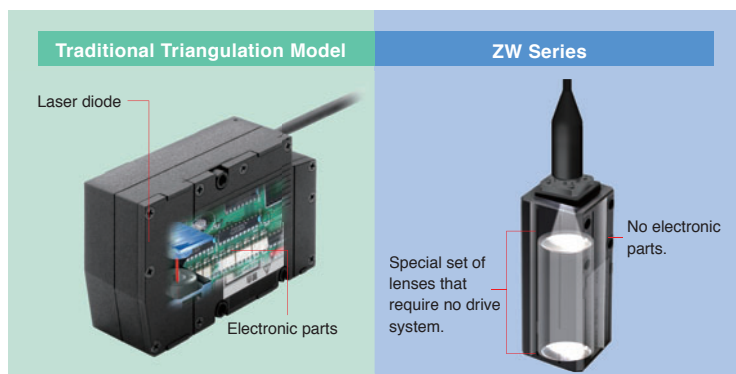
In high-resolution machine control, the heat generated by a sensor head can adversely affect nearby equipment and cause the error to increase. The ZW-series Sensor Heads, however, generate no heat and therefore do not affect nearby equipment. You can also install many Sensor Heads side by side and still be sure of reliable operation.



No Electronic Parts

Reduced Maintenance Costs

Displacement sensors are often installed in moving applications and other installations that are subject to vibration. It is important that they can withstand this type of requirement. The ZW series Sensor Heads are designed for this type of environment, they have no electronic parts or PCB's that a standard triangulation sensor contains. The reduction of parts to lenses and fiber cables reduces the maintenance requirements, and the LED light source also eliminates the standard safety measures required for lasers.



An LED is used in place of a laser for the light source to eliminate the need for safety measures.

Electric circuits and the light source are contained in the Controller.



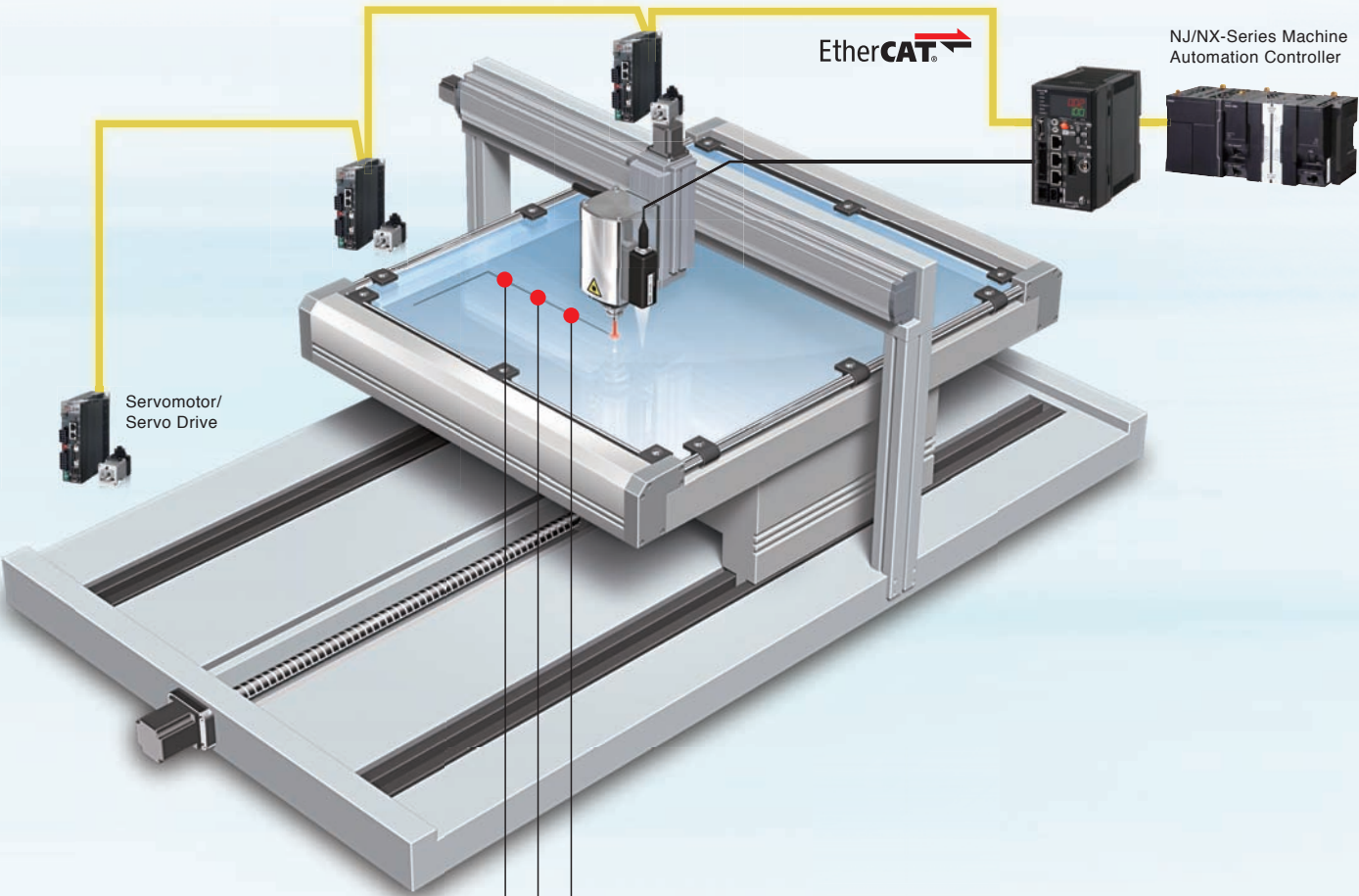
EtherCAT

Machine Control Network

The EtherCAT high-speed open network was optimized for machine control. The ZW-series Sensors are the first OMRON Displacement Sensors with EtherCAT to provide a highly efficient design for high-precision machine control applications that use measurement results to control machine operation.

Combining Height Information and Position Coordinates

EtherCAT can be used to connect to servo drives or encoder input slaves to quickly get the position coordinates and ZW displacement. The height information and XY position coordinates can be easily linked so that the machine control applications can increase processing precision in respect to the height and the inspection applications benefit from maintenance, such as helping to isolate errors or perform trend analysis.



Measurement point	Measurement result Z	Servo/encoder X	Servo/encoder Y
Point 1	Z1	X1	Y1
Point 2	Z2	X2	Y2
Point 3	Z3	X3	Y3
⋮	⋮	⋮	⋮

Results of Linking with the Position Coordinates

Machine Controls

Increased processing precision

No need for constant-speed control

Inspection Applications

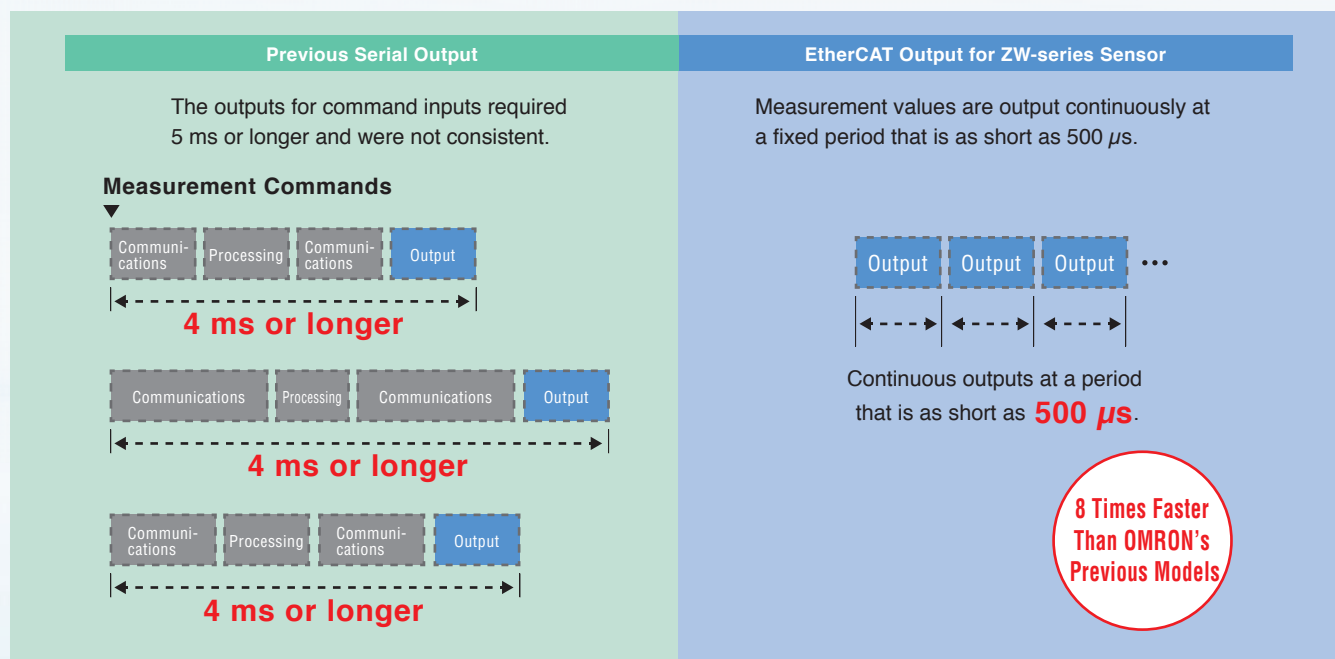
Isolation of errors

Trend management for specific positions

High-speed Digital Output

Shorter Machine Takt Times

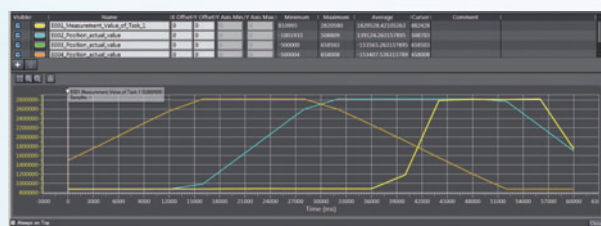
With previous digital (serial) outputs through Ethernet or RS-232C, the response period for measurement commands was both inconsistent and slow, making them unsuitable for realtime control. With EtherCAT, a constant period as short as 500 μ s enables continuous digital (serial) outputs so that the overall workpiece height information can be mapped at high speed.



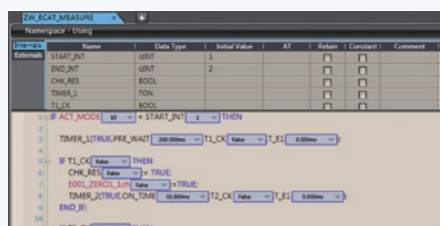
Tracing Machine Movement

Fewer Steps in System Commissioning

You can develop, test, and adjust devices that are connected via EtherCAT with just one Support Software package. The Automation Software Sysmac Studio allows you to creatively design your controls. You can see the entire range from sensing to motion control to reduce the number of steps required to commission the system or to aid in troubleshooting. There are also plenty of offline features to debug signal control programming. You can also simulate machine operation before actual application onsite.



Data Trace



Debugging Control Programming

Note: Sysmac Studio version 1.05 or higher is required for these software interface features described.

Long-distance Wiring: 100 m

Flexible Wiring for Machines

You can use EtherCAT to connect slaves that are up to 100 m apart. With digital communications, error does not occur due to the influences of ambient noise. This solves the previous problems with analog output methods, such as the inability to support long-distance transmissions and noise countermeasures, and enables reliable installation in previously difficult large-scale machines.

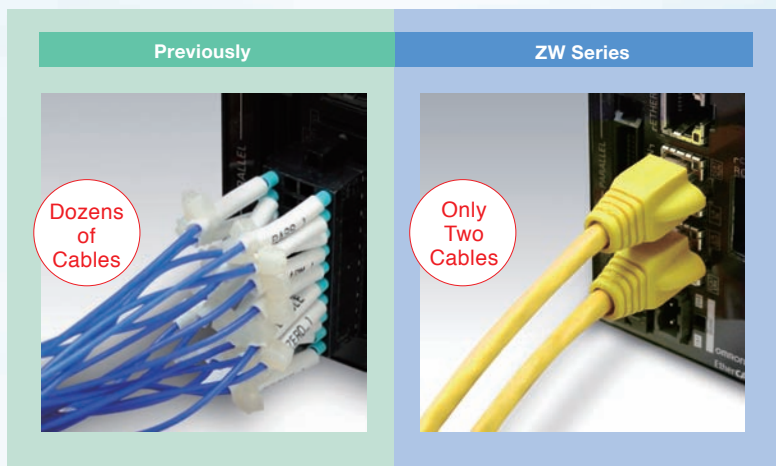
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Multipoint Measurement with EtherCAT Concurrency

EtherCAT communications provide both high speed and time-consistent performance so that integrated controls for Sensors and other slaves can be achieved in realtime. Even for multipoint measurements for Displacement Sensor applications, the following advantages are provided.

Reduced Wiring: Only Two Cables Less Wiring for Many Sensors

With previous parallel I/O, manual wiring was required for dozens of points, and it was necessary to take sufficient caution to avoid sources of noise. This required extensive time to use many Displacement Sensors in a row. With EtherCAT, all you have to do is connect two lines for each Controller.



NJ/NX-Series Machine Automation Controller



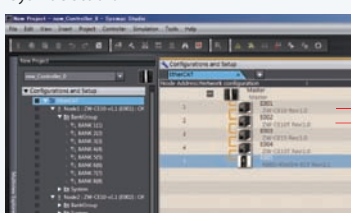
EtherCAT®



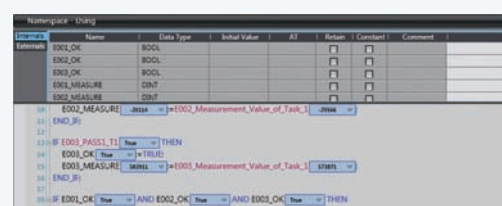
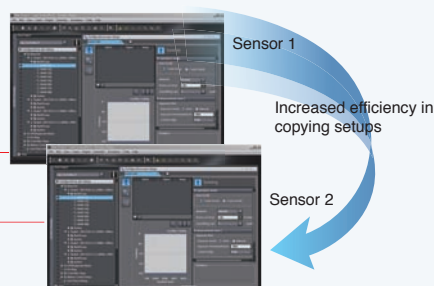
One Software Fewer Steps in System Design

You can set up all of the slaves that are connected via EtherCAT with just the Automation Software Sysmac Studio. Even when you combine many Sensors, you can copy setup data to effectively integrate setup work or you can easily program calculations between the Sensors.

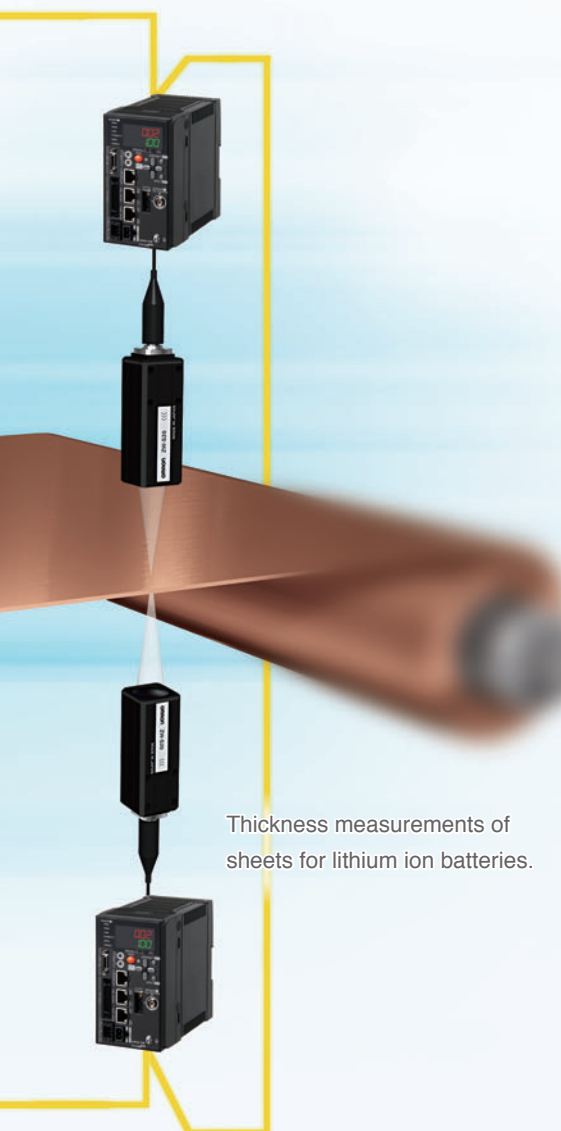
Sysmac Studio



Efficient Setup of Measurement Conditions for Many Sensors



Easy Programming of Thickness Calculations



Synchronous Measurements

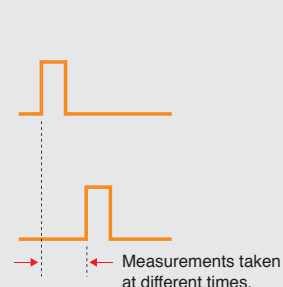
Fewer Thickness Errors due to Vibration

The highly precise synchronization performance of EtherCAT reduces the time error in measurements between different Sensors to $1\ \mu\text{s}$ or less. Synchronous measurement is useful when measurements must be made with more than one Sensor at the same time, such as measurements from both sides of a sheet or inclination control of a substrate.

Previously Not Synchronized

The thickness includes error.

Vibration that occurs during measurements taken at different time causes the output thickness to be larger than normal.

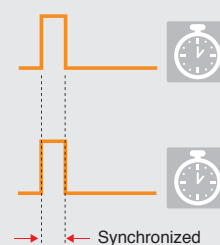


Z W

Synchronized with EtherCAT

Thickness

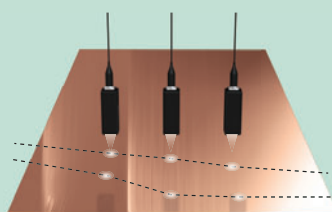
The correct thickness is measured without being influenced by vibration.



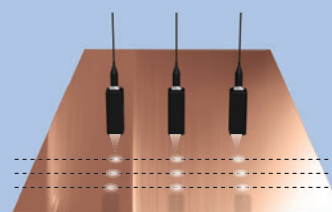
Continuous Measurements of Sheets without Position Offset

When Sensors are installed in a row to continuously log sheet height, nonsynchronous measurements can cause offsets in the lateral measurement positions. With synchronous measurements using EtherCAT, you can continuously log sheet height with all of the Sensors at the same lateral position.

Previously: Not Synchronized



ZW: Synchronized with EtherCAT



Robust Sensor Head Structure

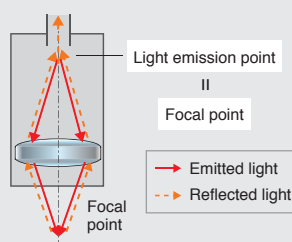
To achieve a compact Sensor Head and high-resolution measurements, the ZW Series uses a white light confocal principle to detect objects. This principle is described below.

Confocal principle Confocal Light Emission and Reception

Based on the confocal principle, the emitted light and received light are positioned along the same axis. Light is received only when it is focused on the measurement object, allowing the height to be calculated. Unlike triangulation, the received light waveform is not disrupted by the material or inclination of the measurement object. The received light waveform is always stable, which enables high-resolution measurements.

Object Located at Focal Point

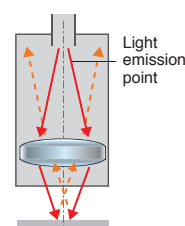
The reflected light is focused at the same point as the emitted light. The reflected light becomes the received light signal.



The height is calculated from the position at which the reflected light was received.

Object Not Located at Focal Point

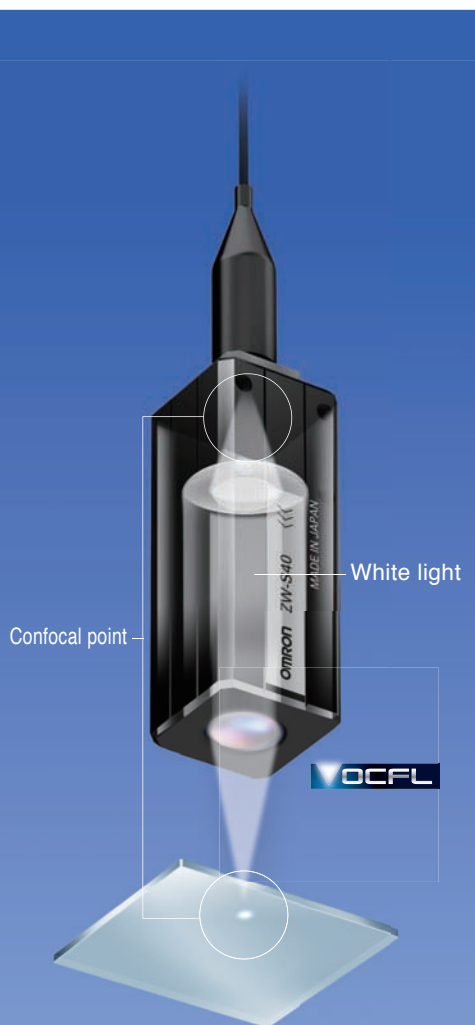
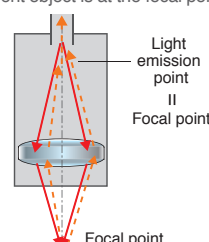
Reflected light is not received because the reflected light is not focused at the light emission point.



Light is not received.

Inclination and Differences in Materials

Even if the measurement object is inclined or contains different materials, the reflected light will be focused at the light emission point as long as the measurement object is at the focal point.



OCFL Module

The OCFL module contains a special lens set developed by OMRON that changes the focal point for each color (i.e., wavelength) of white light. The spot diameter is the same at any position within the measuring range. It does not change the way it does for a triangulation. High-precision lens manufacturing technology has allowed us to achieve a lens structure that is extremely small and that also does not require a drive mechanism.

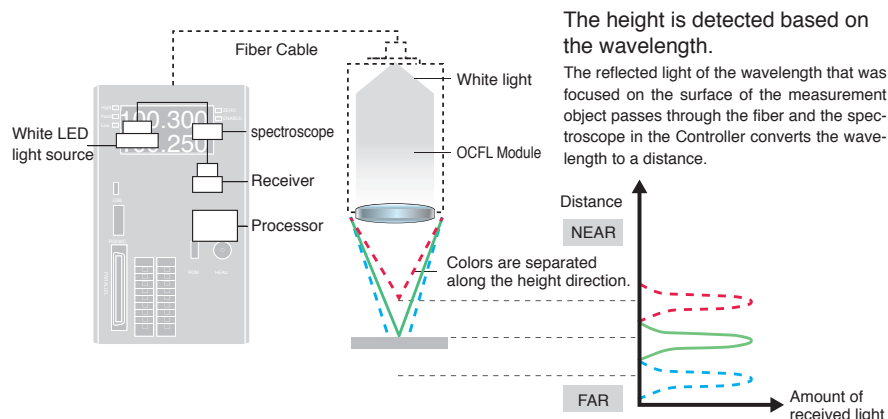


*OCFL : Omron Chromatic Focus Lens

White Light Separation into Colors with Different Wavelengths at Emission

Patent Pending

The white light from the LED is focused at different points for each color (i.e., wavelength) due to a special set of lenses in the OCFL module in the Sensor Head. As a result, only the color of light that is focused on the measurement object is returned, allowing the distance from the Sensor Head to the measurement object to be calculated based on the color of the reflected light. The Sensor Head contains the special set of lenses that separates white light into different colors and the Controller contains the white LED light source, and the spectroscopy and processor that convert the color of the reflected light to a distance. There is no need for a lens drive mechanism or electronic parts in the Sensor Head, even though they were considered to be standard in previous confocal models. This achieves a much more compact design and much greater immunity to noise than triangulation models and or previous confocal models.

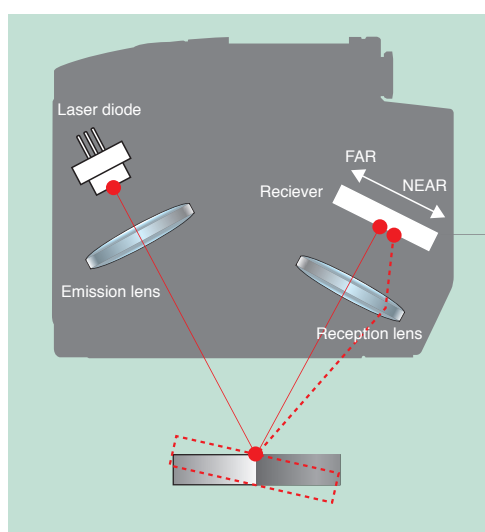


The height is detected based on the wavelength.

The reflected light of the wavelength that was focused on the surface of the measurement object passes through the fiber and the spectroscopy in the Controller converts the wavelength to a distance.

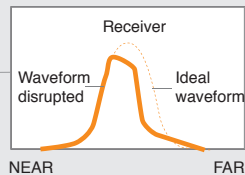
Problems with Previous Models

Triangulation



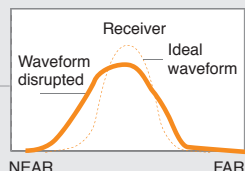
Triangulation measures the height of an object based on the position of the spot on a receiver (CCD or CMOS). The peak, center of gravity, and other features are calculated from the received light waveform to reduce error, but in principle, the received waveform is offset or disrupted due to differences in materials or inclination. This results in measurement error.

Light Reception for Different Materials



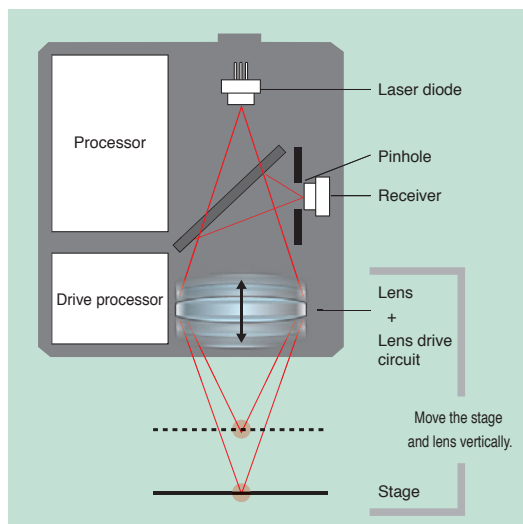
Different materials have different reflection factors. This disrupts the waveform that is received on the receiver. The peak in the waveform or the center of gravity are used to calculate the height, but error will remain in the measurement results.

Light Reception for Inclination



If the measurement object is inclined, the received waveform is offset or disrupted due to the effects of aberration. This results in measurement error.

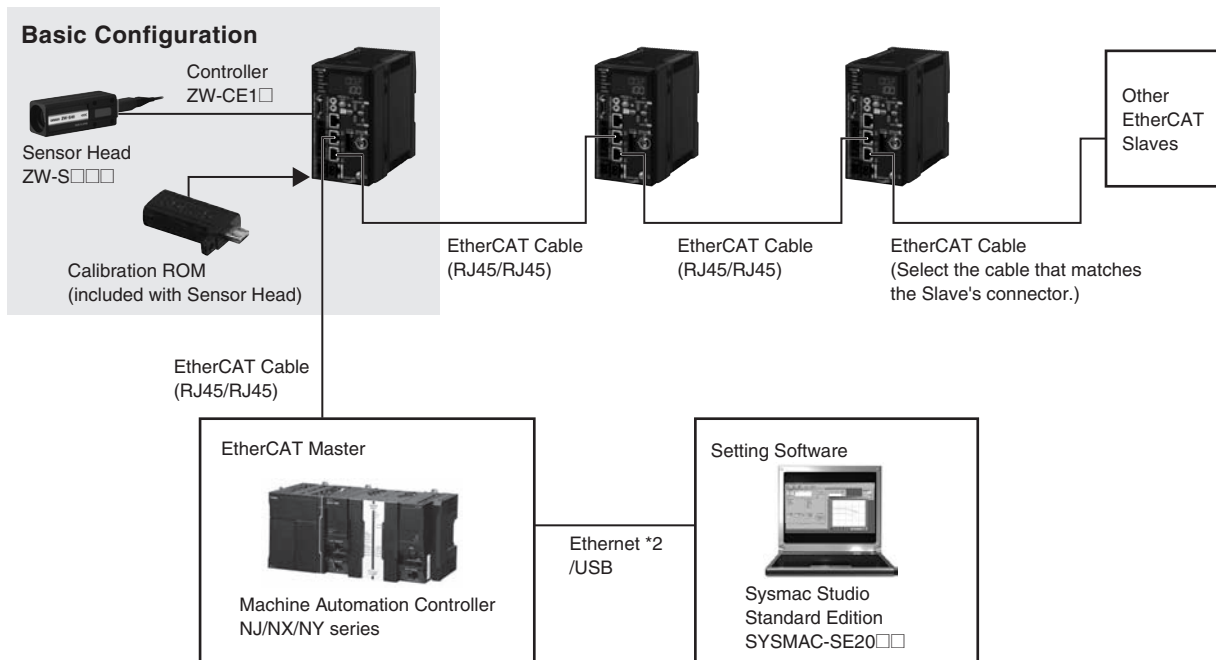
Normal Confocal Principle



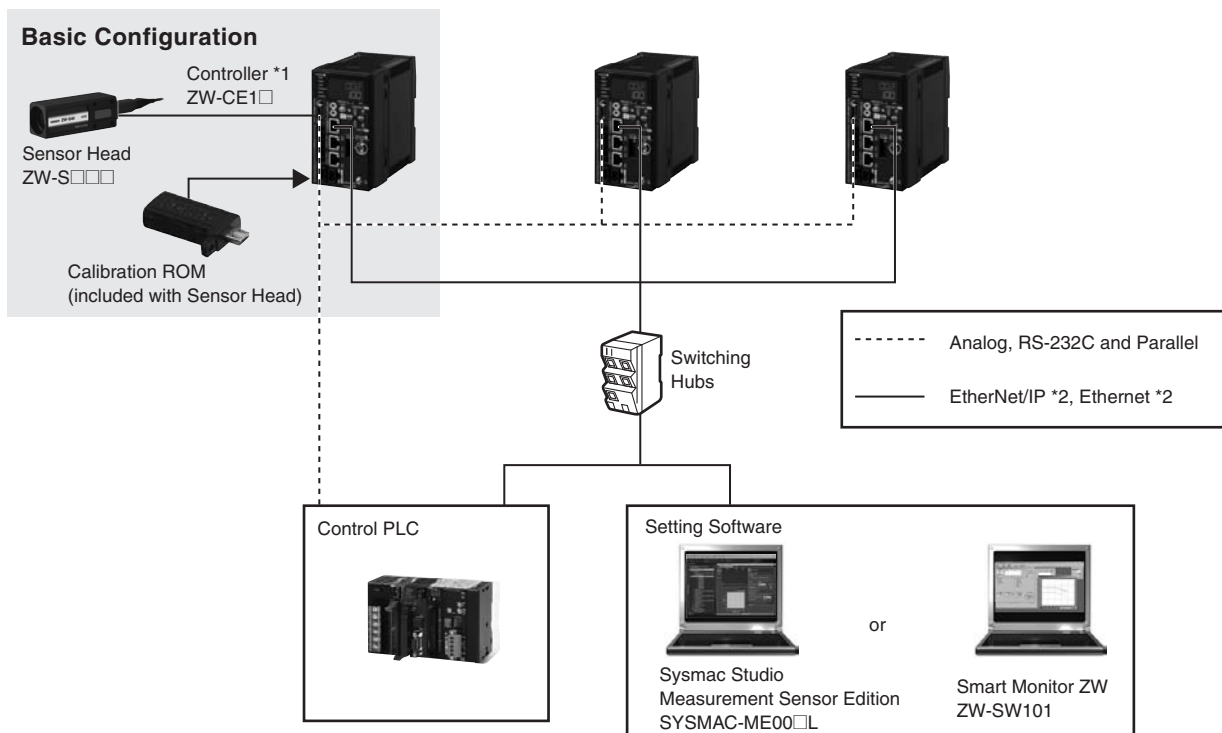
In a normal confocal model, a stage and lens are driven vertically to change the focal point. This requires a more complex structure, and the large number of parts interferes with downsizing. The use of a laser beam increases the chances of interference, and the received light waveform can be disrupted by the surface conditions within the small spot on the measurement object.

System Configuration

EtherCAT connections



Analog, EtherNet/IP, Ethernet, RS-232C and Parallel connections



*1 Controllers with binary outputs are also available (ZW-C10T/-C15T).

Please contact your OMRON sales representative for details.

*2 Prepare commercially available Ethernet cable satisfying the following requirements:

- Category 5e or more, 30 m or less
- RJ45 connector (8-pin modular jack)
- For direct connection: Select cross cable.
- For connection through an industrial switching hub: Select straight cable.

Order Information

● Sensor Head

Straight type

Right-angle type

Measuring range:	7±0.3mm	20±1mm	30±3mm	40±6mm	7±0.3mm	20±1mm	40±6mm
Spot diameter	18μm dia.	40μm dia.	60μm dia.	80μm dia.	18μm dia.	40μm dia.	80μm dia.
Static resolution	0.25μm	0.25μm	0.25μm	0.25μm	0.25μm	0.25μm	0.25μm
Model	ZW-S07 2M ZW-S07 0.3M	ZW-S20 2M ZW-S20 0.3M	ZW-S30 2M ZW-S30 0.3M	ZW-S40 2M ZW-S40 0.3M	ZW-SR07 2M ZW-SR07 0.3M	ZW-SR20 2M ZW-SR20 0.3M	ZW-SR40 2M ZW-SR40 0.3M

● Controller with EtherCAT

Appearance	Power supply	Output type	Model
	DC24V	NPN	ZW-CE10T
		PNP	ZW-CE15T

Note: Controllers with binary outputs are also available (ZW-C10T/-C15T). Please contact your OMRON sales representative for details.

● Cable

Appearance	Item	Cable length	Model
	Sensor Head - Controller Extension Fiber Cable (flexible cable) (Fiber Adapter ZW-XFC provided)	2m	ZW-XF02R
		5m	ZW-XF05R
		10m	ZW-XF10R
		20m	ZW-XF20R
		30m	ZW-XF30R
	Fiber Adapter (between Sensor Head pre-wired cable and Extension Fiber Cable)	—	ZW-XFC
	Parallel cable for ZW-CE1□T 32-pole* (included with Controller ZW-CE1□T)	2m	ZW-XCP2E
	RS-232C Cable for personal computer	2m	ZW-XRS2
	RS-232C Cable for PLC/programmable terminal	2m	ZW-XPT2

* A parallel cable for Controllers with binary outputs is also available (ZW-XCP2). Please contact your OMRON sales representative for details.

● Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually.

Each model of licenses does not include any DVD.

Product name	Specifications			Model	Standards
		Number of licenses	Media		
Sysmac Studio Standard Edition Ver.1.□□ *2	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCat Slave, and the HMI.	— (Media only)	DVD	SYSMAC-SE200D	—
	Sysmac Studio runs on the following OS. Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/ Windows 8.1 (32-bit/64-bit version)/Windows 10 (32-bit/64-bit version)	1 license*1	—	SYSMAC-SE201L	—
	This software provides functions of the Measurement Sensor Edition. Refer to Sysmac Catalog (P072) for details such as supported models and functions.				
Sysmac Studio Measurement Sensor Edition Ver.1.□□ *3	Sysmac Studio Measurement Sensor Edition is a limited license that provides selected functions required for ZW-series Displacement Sensor settings.	1 license	—	SYSMAC-ME001L	—
	Because this product is a license only, you need the Sysmac Standard Edition DVD media to install it.	3 license	—	SYSMAC-ME003L	—

*1. Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

*2. ZW-series is supported by Sysmac Studio version 1.05 or higher.

*3. The Setting Software Smart Monitor ZW is also available (ZW-SW101). Please contact your OMRON sales representative for details.

● Accessories

Item	Model
Fiber Connector Cleaner	ZW-XCL

Note: Place orders in units of boxes (contacting 10 units).

●Recommended EtherCAT Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

●Cabel with Connectors

Item	Appearance	Recommended manufacturer	Cable length(m) *1	Model
Standard type Cable with Connectors on Both Ends (RJ45/RJ45) Wire Gauge and Number of Pairs: AWG26, 4-pair Cable Cable Sheath material: LSZH *2 Cable color: Yellow *3		OMRON	0.3	XS6W-6LSZH8SS30CM-Y
			0.5	XS6W-6LSZH8SS50CM-Y
			1	XS6W-6LSZH8SS100CM-Y
			2	XS6W-6LSZH8SS200CM-Y
			3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
Rugged type Cable with Connectors on Both Ends (RJ45/RJ45) Wire Gauge and Number of Pairs: AWG22, 2-pair Cable		OMRON	0.3	XS5W-T421-AMD-K
			0.5	XS5W-T421-BMD-K
			1	XS5W-T421-CMD-K
			2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
Rugged type Cable with Connectors on Both Ends (M12 Straight/RJ45) Wire Gauge and Number of Pairs: AWG22, 2-pair Cable		OMRON	0.3	XS5W-T421-AMC-K
			0.5	XS5W-T421-BMC-K
			1	XS5W-T421-CMC-K
			2	XS5W-T421-DMC-K
			5	XS5W-T421-GMC-K
			10	XS5W-T421-JMC-K
Rugged type Cable with Connectors on Both Ends (M12 Right-angle/RJ45) Wire Gauge and Number of Pairs: AWG22, 2-pair Cable		OMRON	0.3	XS5W-T422-AMC-K
			0.5	XS5W-T422-BMC-K
			1	XS5W-T422-CMC-K
			2	XS5W-T422-DMC-K
			5	XS5W-T422-GMC-K
			10	XS5W-T422-JMC-K

Note: For details, refer to Cat.No.G019.

*1. Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20 m are available.

Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15 m are available.

*2. The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use.

*3. Cables colors are available in blue, yellow, or Green.

●Cables / Connectors

Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	—	Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 × 4P *
	—	Kuramo Electric Co.	KETH-SB *
	—	SWCC Showa Cable Systems Co.	FAE-5004 *
RJ45 Connectors	—	Panduit Corporation	MPS588-C *

* We recommend you to use above cable and connector together.

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	—	Kuramo Electric Co.	KETH-PSB-OMR *
	—	JMACS Japan Co.,Ltd.	PNET/B *
RJ45 Assembly Connector		OMRON	XS6G-T421-1 *

Note: Connect both ends of cable shielded wires to the connector hoods.

* We recommend you to use above cable and connector together.

●Industrial switching hubs for Ethernet

Appearance	Number of ports	Failure detection	Current consumption	Model
	3	None	0.22A	W4S1-03B
	5	None	0.22A	W4S1-05B
		Supported		W4S1-05C

Note: Industrial switching hubs are cannot be used for EtherCAT.

●EtherCAT junction slaves

Appearance	Number of ports	Power supply voltage	Current consumption	Model
	3	20.4 to 28.8 VDC (24 VDC -15 to 20%)	0.08A	GX-JC03
	6		0.17A	GX-JC06

Note: 1. Please do not connect EtherCAT junction slave with OMRON position control unit, Model CJ1W-NC□81/□82.

2. EtherCAT junction slaves cannot be used for EtherNet/IP™ and Ethernet.

Specifications

● Sensor Head

Item		ZW-S07	ZW-S20	ZW-S30	ZW-S40	ZW-SR07	ZW-SR20	ZW-SR40
Measuring center distance		7 mm	20 mm	30 mm	40 mm	7 mm	20 mm	40 mm
Measuring range		±0.3 mm	±1 mm	±3 mm	±6 mm	±0.3 mm	±1 mm	±6 mm
Static resolution *1		0.25 μm	0.25 μm	0.25 μm	0.25 μm	0.25 μm	0.25 μm	0.25 μm
Linearity *2		±0.8 μm	±1.2 μm	±4.5 μm	±7.0 μm	±1.1 μm	±1.6 μm	±9.3 μm
Spot diameter *3	Near	20 μm dia.	45 μm dia.	70 μm dia.	90 μm dia.	20 μm dia.	45 μm dia.	90 μm dia.
	Center	18 μm dia.	40 μm dia.	60 μm dia.	80 μm dia.	18 μm dia.	40 μm dia.	80 μm dia.
	Far	20 μm dia.	45 μm dia.	70 μm dia.	90 μm dia.	20 μm dia.	45 μm dia.	90 μm dia.
Measuring cycle		500 μs to 10 ms						
Applicable sensor controller		ZW-C1□□□/-CE1□□						
Operating ambient illumination		Illumination on object surface 10,000 lx or less: incandescent light						
Ambient temperature range		Operating: 0 to 50°C, Storage: -15 to 60°C (with no icing or condensation)						
Ambient humidity range		Operating and storage: 35% to 85% (with no condensation)						
Degree of protection		IP40 (IEC60529)						
Vibration resistance (destructive)		10 to 150 Hz, 0.35 mm single amplitude, 80 min each in X, Y, and Z directions						
Shock resistance (destructive)		150 m/s ² 3 times each in six directions (up/down, left/right, forward/backward)						
Temperature characteristic *4		0.6 μm/°C	1.5 μm/°C	2.8 μm/°C	4.8 μm/°C	0.6 μm/°C	1.5 μm/°C	4.8 μm/°C
Materials		Case: aluminum die-cast Fiber cable sheath: PVC Calibration ROM: PC						
Fiber cable length		0.3 m, 2 m (Flex-resistant cable)						
Fiber cable minimum bending radius		20 mm						
Insulation resistance (Calibration ROM)		Between case and all terminals: 20 MΩ (by 250 V megger)						
Dielectric strength (Calibration ROM)		Between case and all terminals: 1,000 VAC, 50/60 Hz, 1 min						
Weight		Approx. 105 g (Chassis, fiber cable total)						
Accessories included with sensor head		Instruction sheet, Fixing screw (M2) for Calibration ROM, Precautions for correct use						

*1. Capacity value when Omron standard mirror surface target is measured at the measurement center distance as the average of 4,096 times.

*2. Material setting for the Omron standard mirror surface target: Error from an ideal straight line when measuring on mirror surface.

The reference values for linearity when targets to measure other than the above are as in the table below.

Item	ZW-S07	ZW-S20	ZW-S30	ZW-S40	ZW-SR07	ZW-SR20	ZW-SR40
Glass	±1.0 μm	±1.2 μm	±4.5 μm	±7.0 μm	±1.1 μm	±1.6 μm	±9.3 μm
SUS BA	±1.2 μm	±1.4 μm	±5.5 μm	±8.5 μm	±1.2 μm	±1.8 μm	±9.3 μm
White ceramic	±1.6 μm	±1.7 μm	±6.4 μm	±9.5 μm	±1.6 μm	±1.9 μm	±11.0 μm

*3. Capacity value defined by $1/e^2$ (13.5%) of the center optical intensity in the measured area.

*4. Temperature characteristic at the measurement center distance when the Sensor Head and the target are fastened with an aluminum jig and the Sensor Head and the Controller are set in the same temperature environment.

● Automation Software Sysmac Studio

System Requirements

Item	Requirement
Operating system (OS) *1 *2	Windows XP (Service Pack 3 or higher, 32-bit version)/Windows Vista (32-bit version)/ Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit version)/Windows 8.1 (32-bit/64-bit version)/ Windows 10 (32-bit/64-bit version)
CPU	Windows computers with Celeron 540 (1.8 GHz) or faster CPU. Core i5 M520 (2.4 GHz) or equivalent or faster recommended
Main memory	2 GB min.
Recommended videomemory / video card for using 3D motion trace	Video memory: 512 MB min. Video card: Either of the following video cards: • NVIDIA GeForce 200 Series or higher • ATI Radeon HD 5000 Series or higher
Hard disk	At least 1.6 GB of available space
Display	XGA 1024 × 768, 16 million colors. WXGA 1280 × 800 min. recommended
Disk drive	DVD-ROM drive
Communications ports	USB port corresponded to USB 2.0, or Ethernet port *3
Supported languages	Japanese, English, German, French, Italian, Spanish, simplified Chinese, traditional Chinese, Korean

*1. Sysmac Studio Operating System Precaution: System requirements and hard disk space may vary with the system environment.

*2. The following restrictions apply when Sysmac Studio is used with Microsoft Windows Vista or Windows 7.

Some Help files cannot be accessed.

The Help files can be accessed if the Help program distributed by Microsoft for Windows (WinHlp32.exe) is installed. Refer to the Microsoft homepage listed below or contact Microsoft for details on installing the file. (The download page is automatically displayed if the Help files are opened while the user is connected to the Internet.)
<http://support.microsoft.com/kb/917607/en-us>

*3. Refer to the hardware manual for your Controller for hardware connection methods and cables to connect the computer and Controller.

● Setting Software Smart Monitor ZW ZW-SW101

System Requirements

Item	Condition
Operating System(OS)	Windows 7 (32 or 64-bit version) Windows XP (Service Pack3 or more, 32-bit version)
CPU	Intel Pentium III, 850 MHz or more (2 GHz or more is recommended.)
Main memory	1 GB or more
Hard disk	50 MB or more
Display	1024 × 768 dots or more, 16 million colors or more
Supported languages	Japanese/English
Communication port	Ethernet port

●Controller

Item		ZW-CE10T	ZW-CE15T
Input/Output type		NPN	PNP
Number of connected Sensor Heads		1 per Controller	
Applicable sensor head		ZW-S□□/SR□□	
Light source for measurement		White LED	
Segment display	Main display	11-segment red display, 6 digits	
	Sub-display	11-segment green display, 6 digits	
LED display	Status indicators	HIGH (orange), PASS (green), LOW (orange), STABILITY (green), ZERO (green), ENABLE (green), THRESHOLD-H (orange), THRESHOLD-L (orange), RUN (green)	
	EtherCAT indicators	L/A IN(Link Activity IN)(green), L/O OUT(Link Activity OUT)(green), ECAT RUN(green), ECAT ERR(red)	
External interface	Ethernet		100BASE-TX, 10BASE-T, No-protocol Communications (TCP/UDP), EtherNet/IP™
	EtherCAT		EtherCAT-specific protocol 100BASE-TX
	RS-232C		115,200 bps max.
	Analog output terminal block	Analog voltage output (OUT1V)	-10 V to +10 V, output impedance: 100 Ω
		Analog current output (OUT1A)	4 mA to 20 mA, maximum load resistance: 300Ω
	32-pole extension connector	Judgment output (HIGH1/PASS1/LOW1)	Transistor output system Output voltage: 21.6 to 30 VDC Load current: 50 mA or less Residual voltage when turning ON: 1.2 V or less Leakage voltage when turning OFF: 0.1 mA or less
		BUSY output (BUSY1)	
		ALARM output (ALARM1)	
		ENABLE output (ENABLE)	
		LED OFF input (LED OFF1)	DC input system
		ZERO RESET input (ZERO)	Input voltage: 24 VDC ·10% (21.6 to 26.4 VDC) Input current: 7 mA Typ. (24 VDC)
		TIMING output (TIMING1)	Voltage/Current when turning ON: 19 V/3 mA or more Voltage/Current when turning OFF: 5 V/1 mA or less
		RESET output (RESET1)	
	Bank	Selected bank output (BANK_OUT 1 to 3)	Transistor output system Output voltage: 21.6 to 30 VDC Load current: 50 mA or less Residual voltage when turning ON: 1.2 V or less Leakage voltage when turning OFF: 0.1 mA or less
		Selected bank input (BANK_SEL 1 to 3)	DC input system Input voltage: 21.6 to 26 VDC Input current: 7 mA Typ. (24 VDC) Voltage/Current when turning ON: 19 V/3 mA or more Voltage/Current when turning OFF: 5 V/1 mA or less
Main functions	Exposure time		Auto/Manual
	Measuring cycle		500 μs to 10 ms
	Material setting		Standard/Mirror/Diffusion surfaces
	Measurement item		Height/Thickness/Calculation
	Filtering		Median/Average/Differentiation/High pass/Low pass/Band pass
	Outputs		Scaling/Different holds/Zero reset/Logging for a measured value
	Display		Measured value/Threshold value/Analog output voltage or current value/Judgment result/Resolution/Exposure time
	Number of configurable banks		Max. 8 banks
	Task process		Multi-task (up to 4 tasks per bank)
Ratings	System		Save/Initialization/Display measurement information/Communication settings/Sensor Head calibration/Key-lock/Trigger-key input
	Power supply voltage		21.6 to 26.4 VDC (including ripple)
	Current consumption		600 mA max.
	Insulation resistance		Across all lead wires and controller case: 20 MΩ(by 250 V megger)
Environmental	Dialectic strength		Across all lead wires and controller case: 1,000 VAC, 50/60 Hz, 1 min.
	Degree of protection		IP20(IEC60529)
	Vibration resistance (destructive)		10 to 55 Hz, 0.35-mm single amplitude, 50 min each in X, Y, and Z directions
	Shock resistance (destructive)		150 m/s ² , 3 times each in six directions (up/down, left/right, forward/backward)
	Ambient temperature		Operating: 0 to 40°C Storage: -15 to 60°C (with no icing or condensation)
	Ambient humidity		Operating and storage: 35% to 85% (with no condensation)
Grounding		D-type grounding (Grounding resistance of 100 Ω or less) Note: For conventional Class D grounding	
Materials		Case: PC	
Weight		Approx. 750 g (main unit only), Approx. 150 g (Parallel Cable)	
Accessories included with controller		Instruction sheet, Member registration sheet, Parallel cable ZW-XCP2E	

Note: Controllers with binary outputs are also available (ZW-C10T/-C15T). Please contact your OMRON sales representative for details.

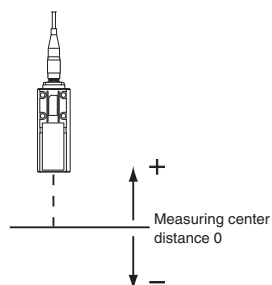
●ZW Series EtherCAT Communications Specifications

Item	Specification
Communications standard	IEC61158 Type12
Physical layer	100BASE-TX(IEEE802.3)
Connectors	RJ45 × 2 ECAT IN: EtherCAT input ECAT OUT: EtherCAT output
Communications media	Category 5 or higher (cable with double, aluminum tape and braided shielding) is recommended.
Communications distance	Distance between nodes: 100 m max.
Process data	Variable PDO mapping
Mailbox (CoE)	Emergency messages, SDO requests, SDO responses, and SDO information
Distributed clock	Synchronization in DC mode.
LED display	L/A IN (Link/Activity IN) × 1, AL/A OUT (Link/Activity OUT) × 1, AECAT RUN × 1, AECAT ERR × 1

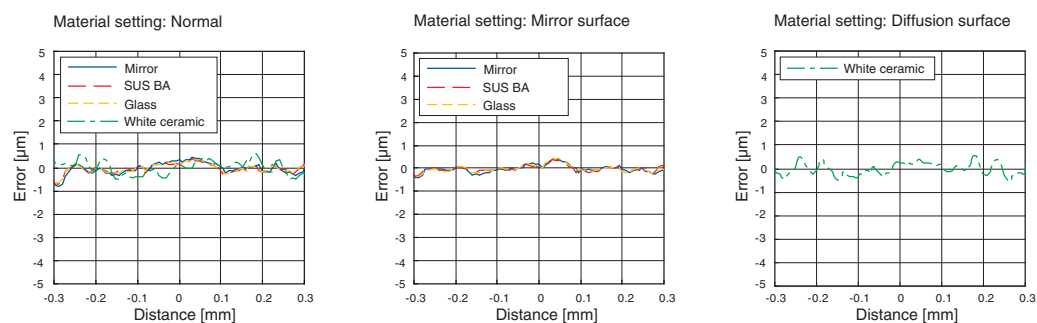
Characteristic data (typical examples)

Linearity Characteristic by Materials

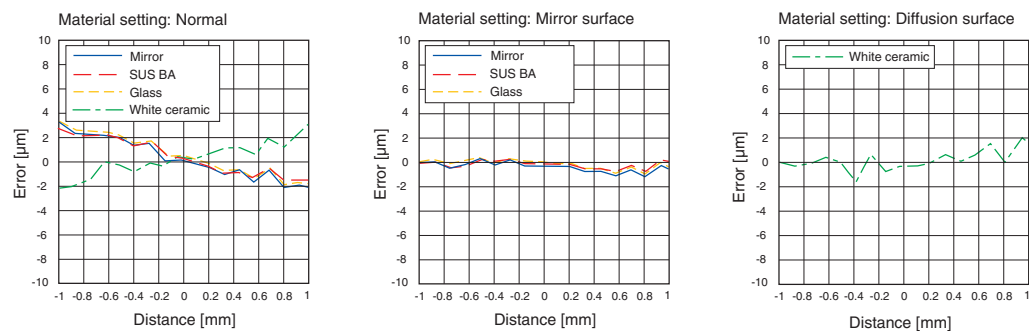
Straight type



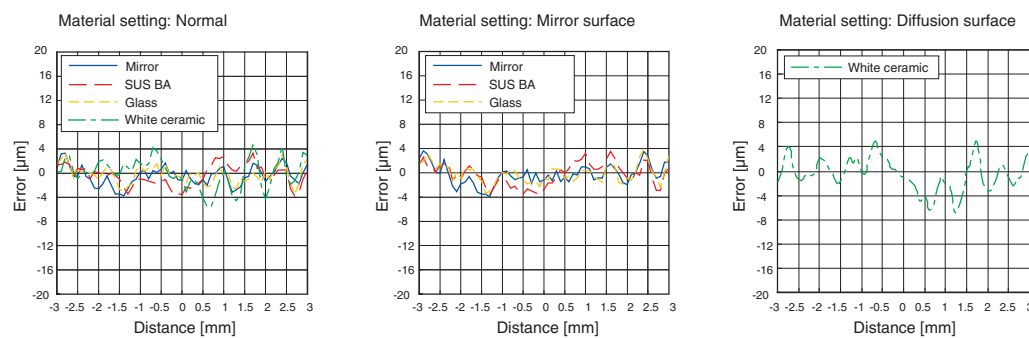
ZW-S07



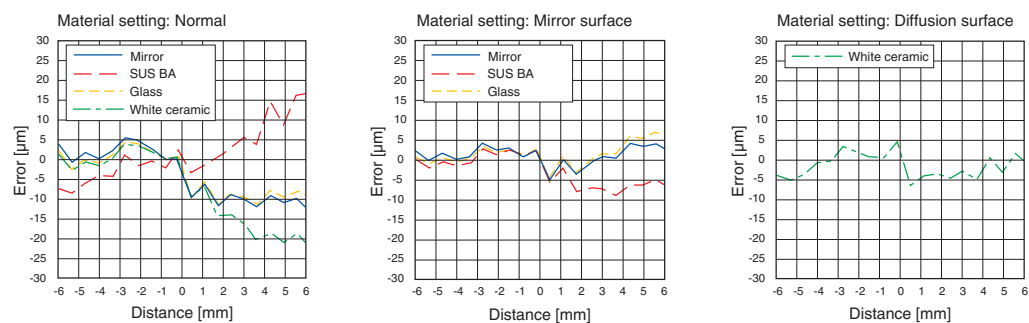
ZW-S20



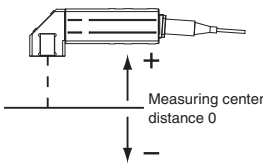
ZW-S30



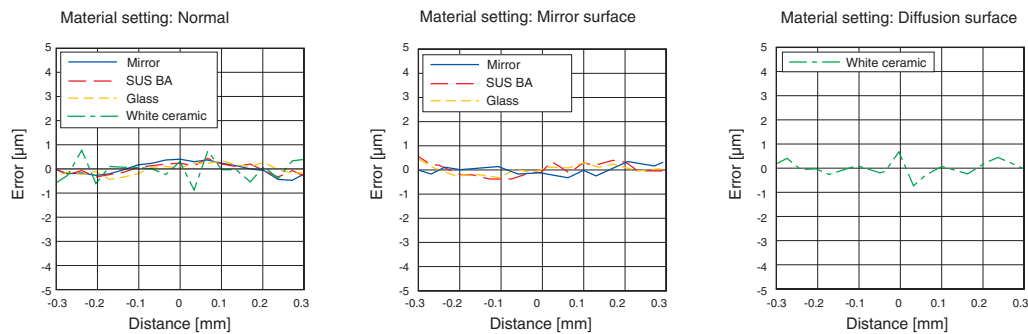
ZW-S40



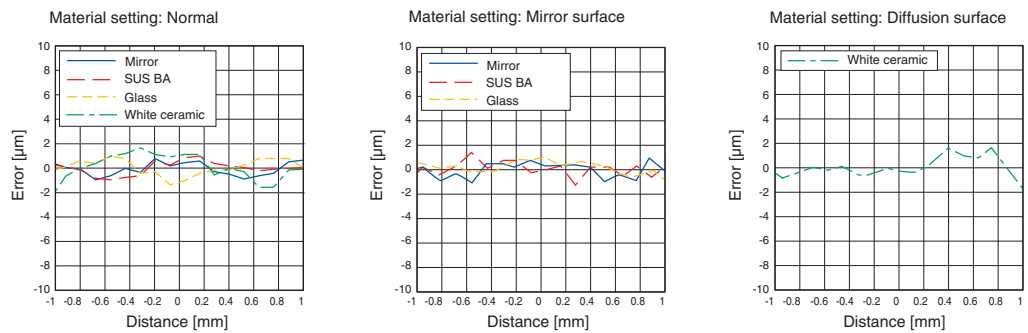
Right-angle type



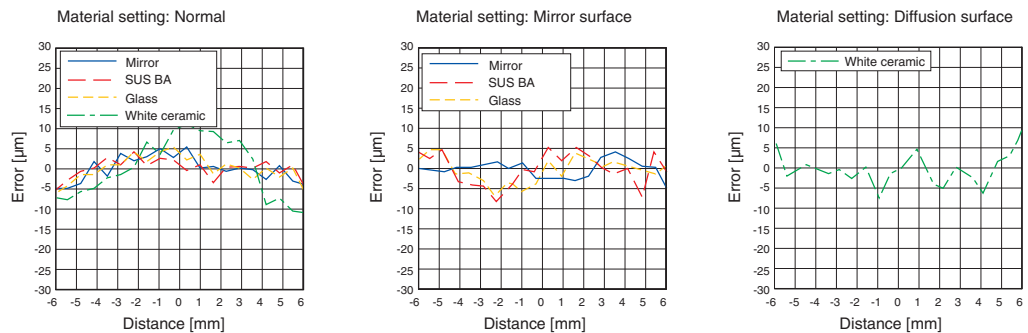
ZW-SR07



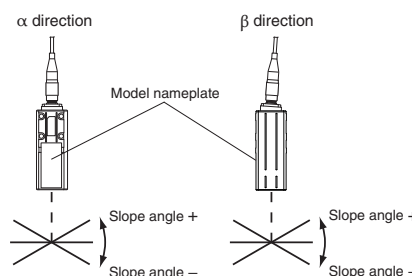
ZW-SR20



ZW-SR40

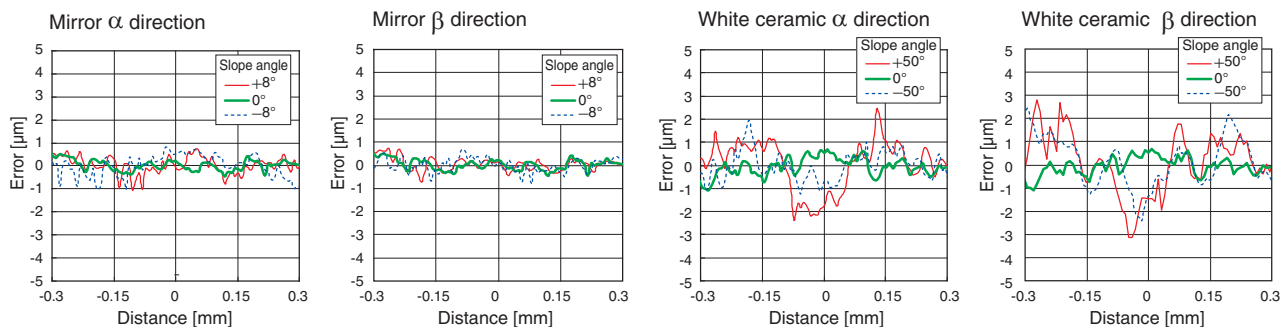


●Angle Characteristic * Straight type

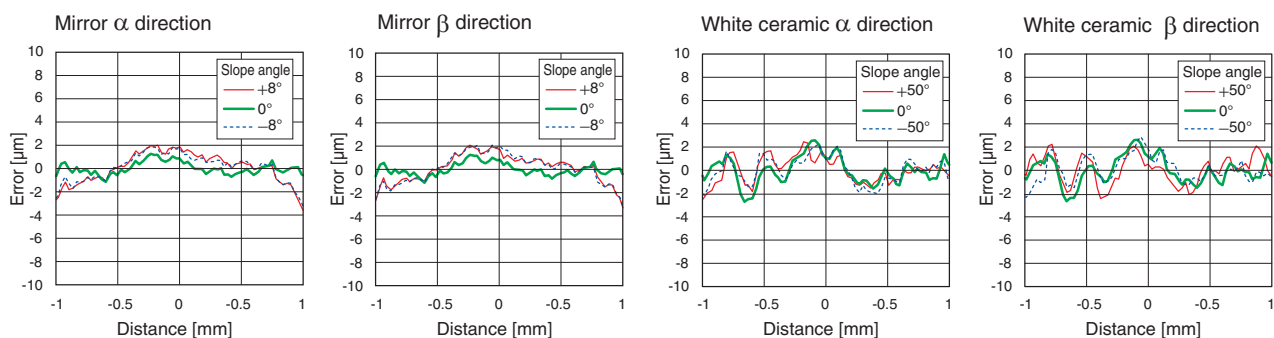


* The above show the results after executing scaling.

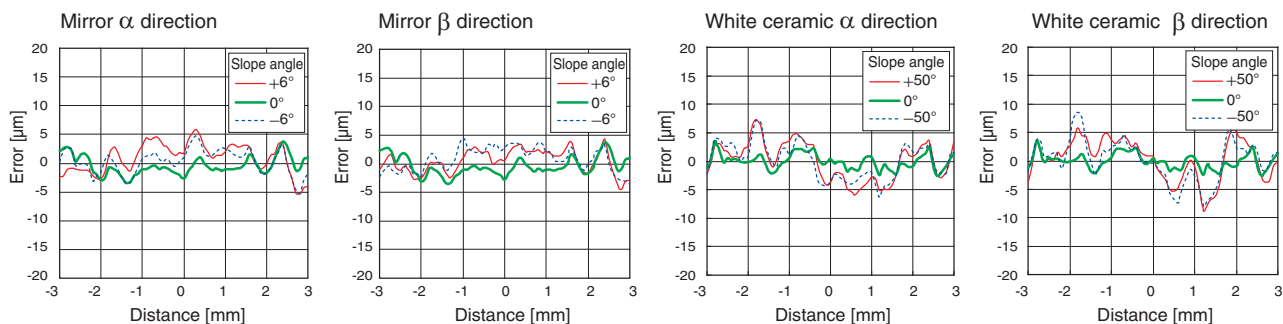
ZW-S07



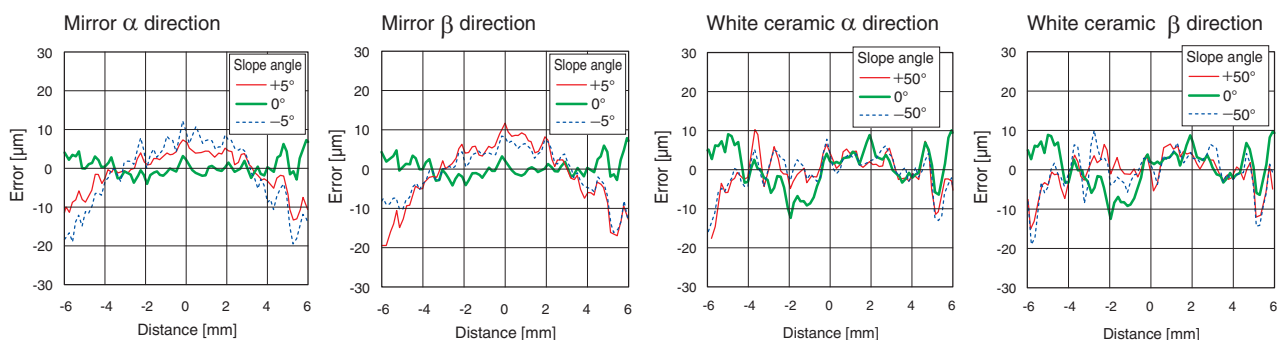
ZW-S20



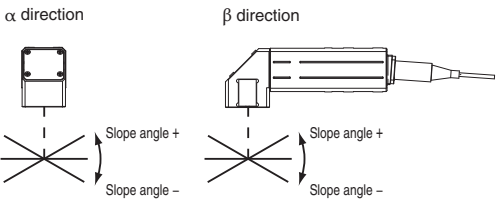
ZW-S30



ZW-S40

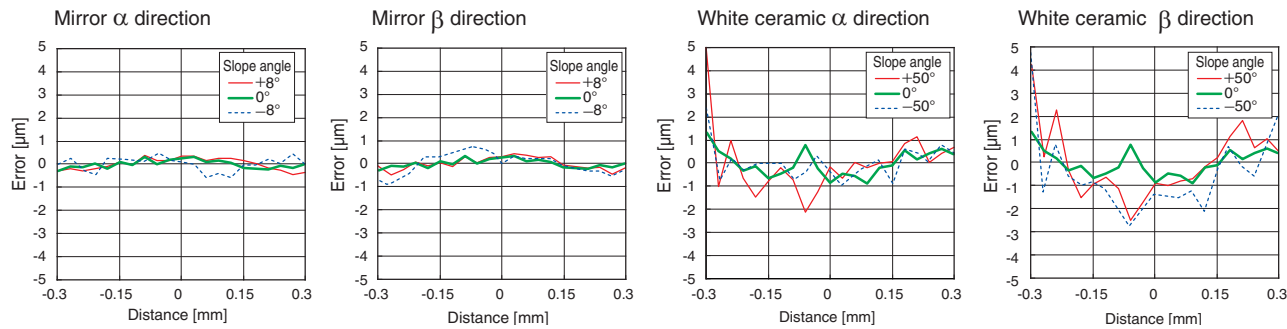


Right-angle type

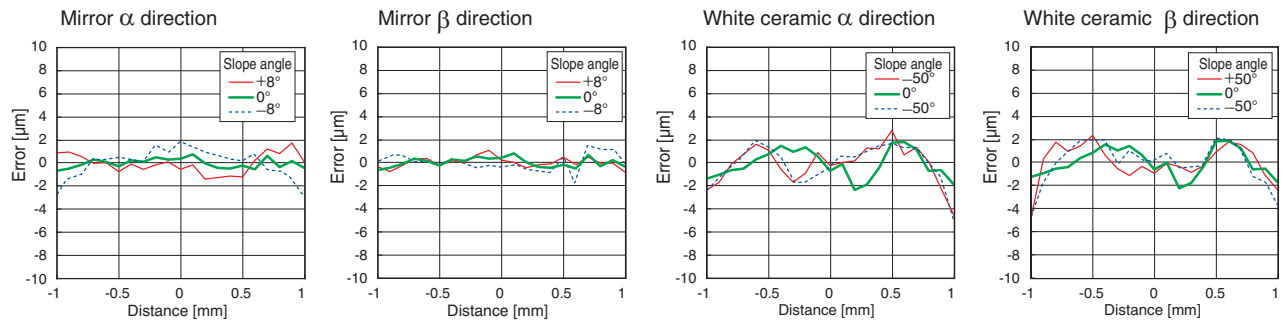


* The above show the results after executing scaling.

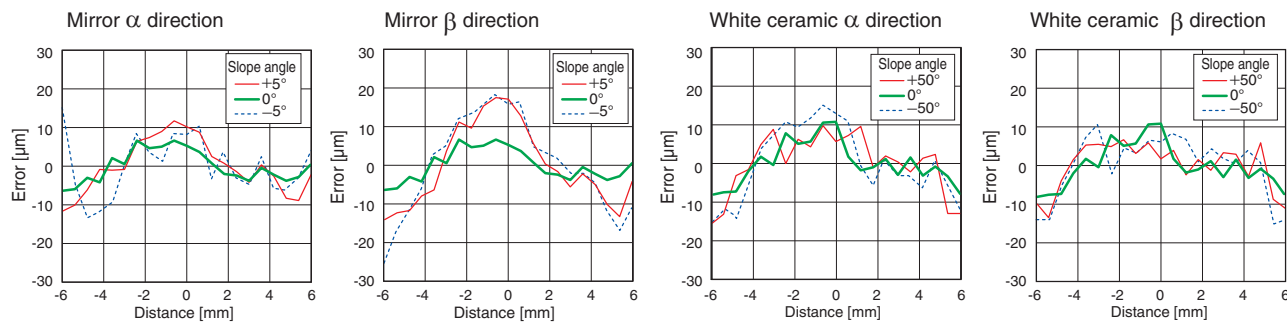
ZW-SR07



ZW-SR20



ZW-SR40



External Dimensions

Sensor Head Straight type

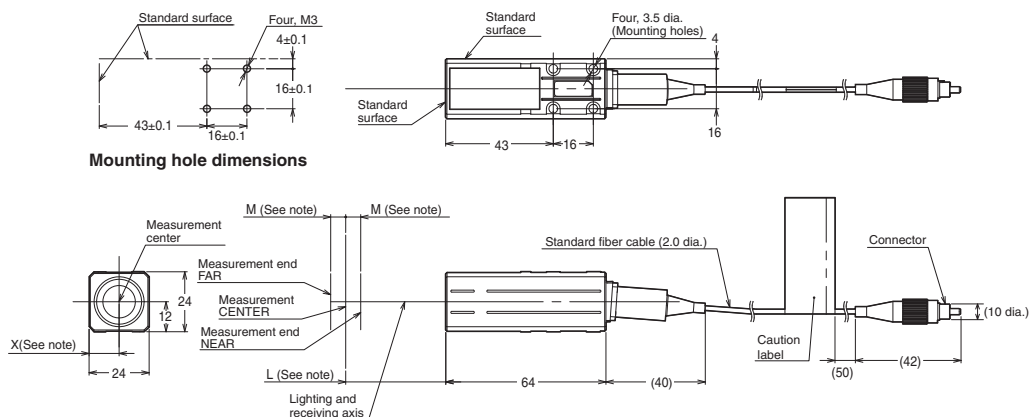
ZW-S07/-S20/-S30/-S40

(Unit: mm)



Note:

Model	L	M	X
ZW-S07	7	0.3	12
ZW-S20	20	1	11.8
ZW-S30	30	3	11.7
ZW-S40	40	6	11.7



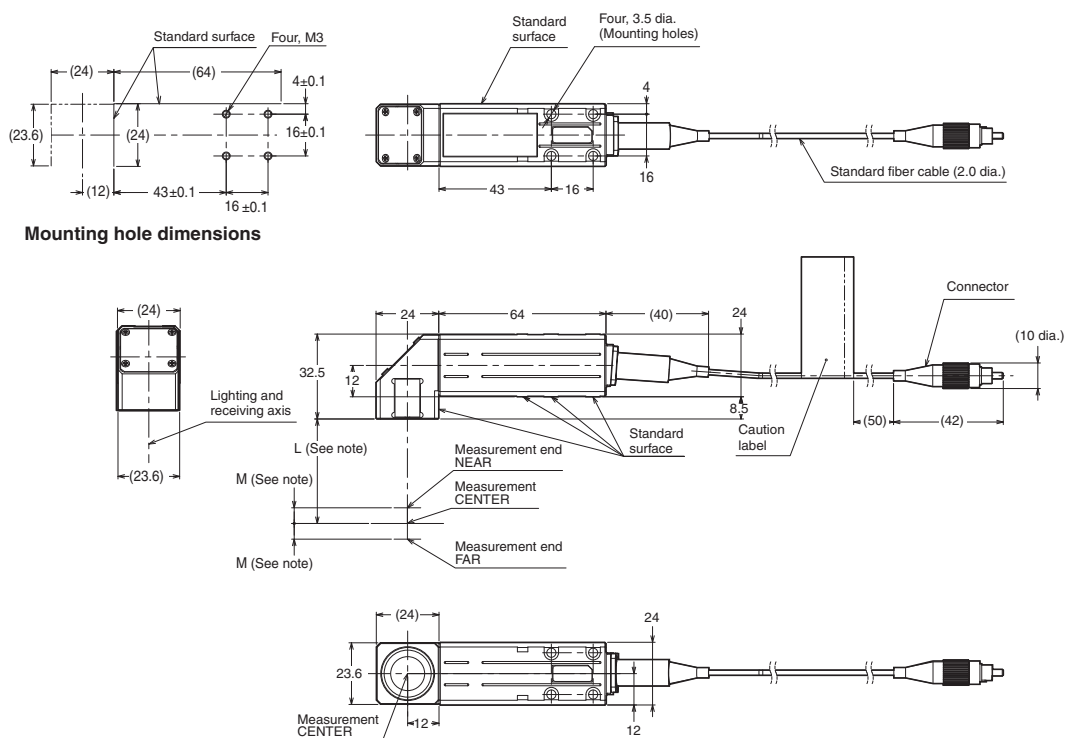
Right-angle type

ZW-SR07/-SR20/-SR40

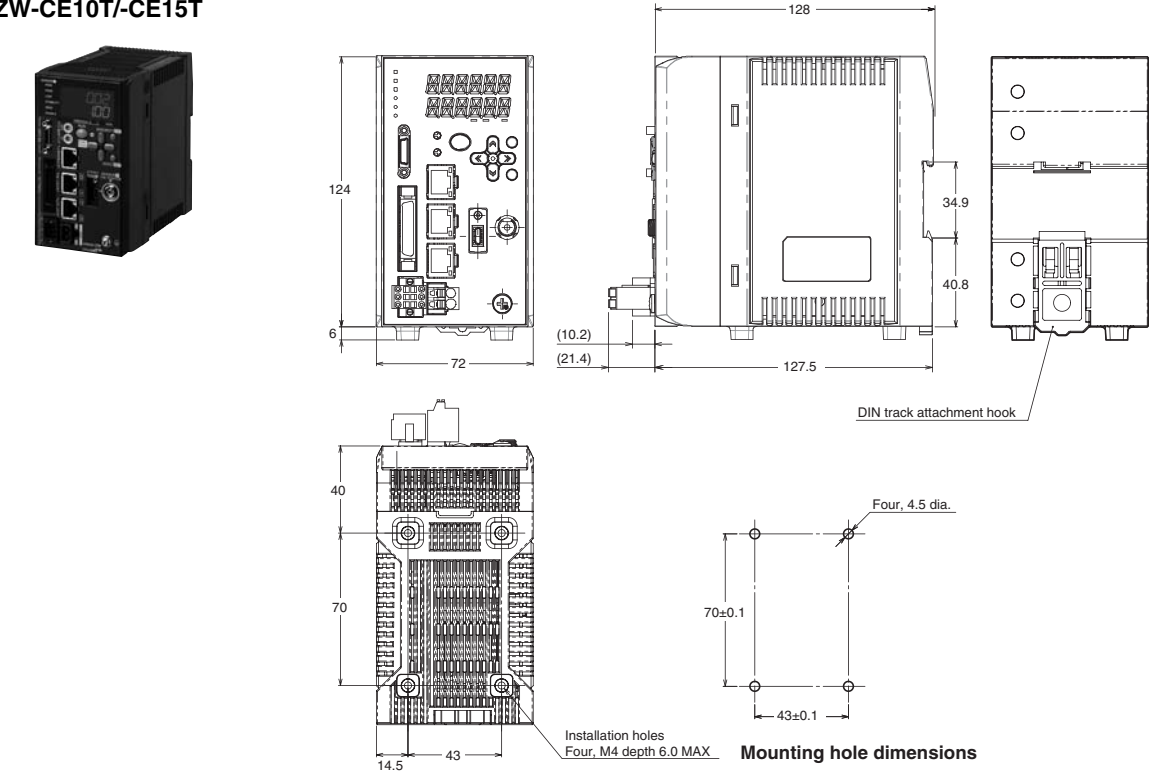


Note:

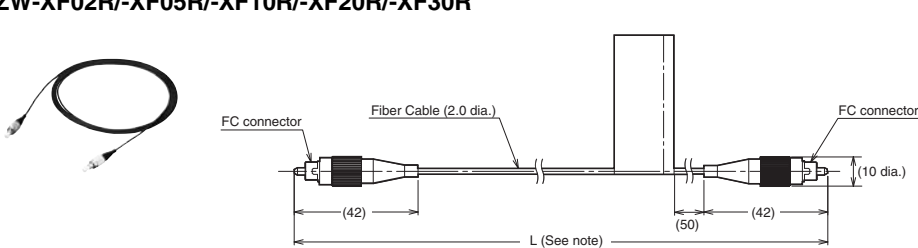
Model	L	M
ZW-SR07	7	0.3
ZW-SR20	20	1
ZW-SR40	40	6



Controller
ZW-CE10T/-CE15T



Extension Fiber Cable
ZW-XF02R/-XF05R/-XF10R/-XF20R/-XF30R



Note: The following table lists cable lengths per models.

Model	Cable length	L
ZW-XF02R	2 m	2,000±20
ZW-XF05R	5 m	5,000±50
ZW-XF10R	10 m	10,000±100
ZW-XF20R	20 m	20,000±200
ZW-XF30R	30 m	30,000±300

Related Manuals

Man.No.	Model number	Manual
Z332	ZW-CE1□T	Displacement Measurement Sensor ZW-CE1□T Series User's Manual

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OMRON Corporation Industrial Automation Company
Tokyo, JAPAN

Contact: www.ia.omron.com

Regional Headquarters

OMRON EUROPE B.V.

Wegalaan 67-69, 2132 JD Hoofddorp
The Netherlands
Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ELECTRONICS LLC

2895 Greenspoint Parkway, Suite 200
Hoffman Estates, IL 60169 U.S.A
Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON ASIA PACIFIC PTE. LTD.

No. 438A Alexandra Road # 05-05/08 (Lobby 2),
Alexandra Technopark,
Singapore 119967
Tel: (65) 6835-3011/Fax: (65) 6835-2711

OMRON (CHINA) CO., LTD.

Room 2211, Bank of China Tower,
200 Yin Cheng Zhong Road,
PuDong New Area, Shanghai, 200120, China
Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

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