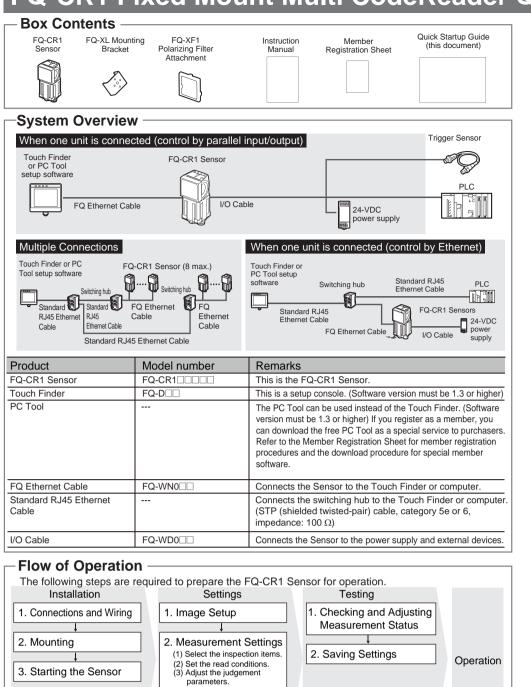
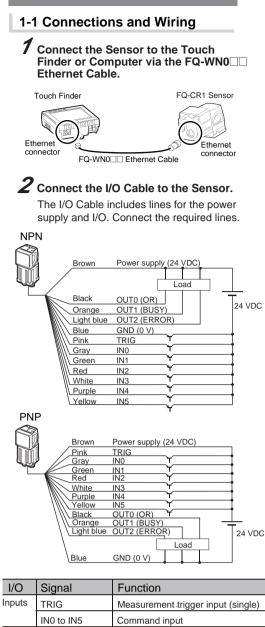
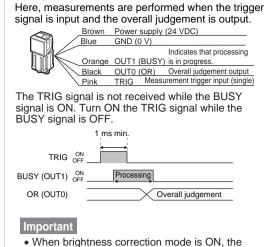
# FQ-CR1 Fixed Mount Multi CodeReader Quick Startup Guide



# 1. Installation



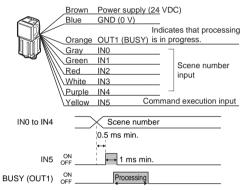


- When brightness correction mode is ON, the brightness is stable but a delay of 25 ms occurs.
- Refer to the User's Manual for details. • Use a no-contact output device (e.g., SSR or PLC transistor output) for the TRIG signal. If a contact (e.g., relay) is used, contact hound ma
- contact (e.g., relay) is used, contact bound may cause the trigger to be input again during execution of a measurement.

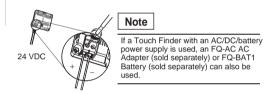
#### Example 2

Example 1

Here, a process switching signal is input from an external device to switch the scene.



## **3** Connect a power supply to the Touch Finder.

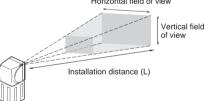


### 1-2 Mounting

**7** Check the mounting position.

Use the optical charts in the enclosed Instruction Manual and check the installation distance to be sure it is suitable for the field of view to be measured. Horizontal field of view

3. I/O Settings



The horizontal field of view is given in the optical chart. The vertical field of view is approx. 60% of the horizontal field of view.

Example: FQ-CR10050F

For a 30-mm field of view, the Sensor must be installed at an installation distance of 115 mm.





# 1-3 Starting the Sensor

**1** Power ON the Sensor.

## $oldsymbol{2}$ Power ON the Touch Finder.

Turn ON the power switch on the side of the Touch Finder, too.



To use the PC Tool, click [Program] -[OMRON] - [FQ] - [PC tool for FQ] from the Windows Start Menu.

Confirm that the software version for the Touch Finder and also the PC Tool is version 1.3 or higher.

Select the language to display on the Touch Finder.



# 2. Settings

Outputs

1

OUT0 (OR)

OUT1 (BUSY)

OUT2 (ERROR)

## 2-1 Image Setup

Make sure the image is stable and adjust the brightness and image input timing.

Overall judgement output

Indicates that processing is in progress.

Indicates an error has occurred

## **7** Focus the image.

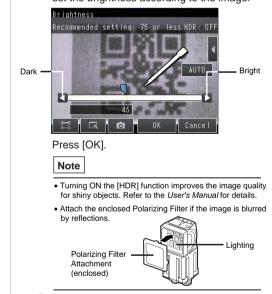
Press [Camera setup]

| lmage   | In Camera setun            |
|---------|----------------------------|
| Inspect | 🖿 Camera setup 🗸           |
| mspect  | Warment Dalling and Water, |
| In/Out  | 🖶 Trigger setup            |
|         | and the second second      |
| Test    | Position compensation      |
| Run     | POSITION COMpensation      |

The camera image will be displayed.

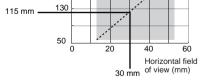


Adjust the brightness with the slider at the bottom of the display. You can also press [AUTO] to automatically set the brightness according to the image.



**3** Adjust the image input timing.

2



**2** Attach the Mounting Bracket to the Sensor and mount the Sensor at the correct position.



## Installing the PC Tool

To use the PC Tool, register as a member, download the PC Tool, and install the PC Tool on your computer.

Use the following network settings on your computer if you connect the computer directly to the Sensor. If you connect the computer and Sensor through a hub using a DHCP server, the following IP address does not need to be set.

- IP address: 10.5.5.101
- Subnet mask: 255.255.255.0

If more than one Sensor is connected, a display will appear to select the Sensor to be set. Select the Sensor.

The following initial display will appear when the Sensor is selected.



The higher the value, the better the focus.

Use the focus adjustment screw on the top of the Sensor to focus the image.



## $\mathbf{2}$ Adjust the brightness.

The FQ-CR1 Sensor will automatically adjust the brightness according to the measurement object. If the resulting brightness is not suitable, it can be adjusted manually.

#### Press [] and then [Brightness].

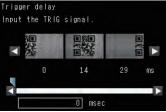


Adjust the delay from when the trigger is input until the image is input. Press [Trigger setup].





After the TRIG signal is input, images will be continuously input.

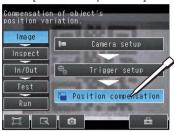


Select the image that was taken with the best timing. Press [OK].

## **4** Set up the Position Compensation.

To enable measurement even if the location of the measurement object is not consistent, register a mark that exists on all measurement objects. This function is called position compensation.

Press [Position compensation].



Press [Mode on/off] and then [ON]. Then press [Settings].



Press [Teach]



Place the object that is to be used as the measurement reference in front of the camera. Move the rectangle so that the characteristic part for position compensation is inside it.

| Hodel region ( | Position co<br>100, 78)-( | mpensation<br>204, 178) | Drag a corner to  |
|----------------|---------------------------|-------------------------|---|
|                |                           |                         | size the<br>rectangle.<br>Drag the<br>rect-<br>angle to |
|                | ОК                        | Cancel                  | move it.  |

Check the area, press the [OK] Button, and then press the [TEACH] Button. The characteristic part and reference position for position compensation will be registered. Press [OK].

**1** Perform tests. Press [Test]. Then press [Continous test]. 0.Scen Continuous test H

#### Press [Graphics+Details]

| Continuous test    | FO       |
|--------------------|----------|
|                    | 0.Scene0 |
| Graphics           |          |
| Graphics+Details   |          |
| All results/region |          |
| Trond monitor      |          |

Continuous measurements will be performed. Input images of some samples to see if the judgements are correct.



#### 2-2 Measurement Settings

Select an item that is appropriate for the purpose of measurement, and set the measurement settings. The procedure for automatically setting the 2D-code measurement settings is shown here.

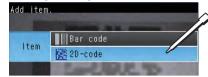
#### **7** Select the inspection items.

Ex.: Reading 2D-codes

Press [Inspect]. Next, touch [Inspection]. Press an unused inspection item number and then press [Add item.] on the menu.



## Touch [2D-code]



 $m{2}$  Set the 2D-code read conditions.

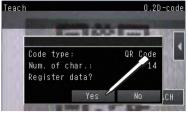
Press [Teach] odify Settings Teach

Confirm that the 2D-code is inside the green frame



Press [Teach].

If reading is successful, the 2D-code type and num. of characters will display.



#### Touch [Yes] Press [Back] to end teaching.

The text string read in as master data will display

| states and states in |   |
|----------------------|---|
| a0 <@omron.co.jp>    | ~ |
| a1                   |   |
| a2                   |   |
| ĉ                    | 1 |

#### Press [Back].

To register additional master data, follow the procedure shown below.

- Touch the master data to be registered.
- Touch [Automatic Registration].
- Touch [TEACH].

3

To manually register master data, follow the procedure shown below.

- Touch the master data to be registered.
- Touch [Manual Registration].
- Input the text string to be registered.

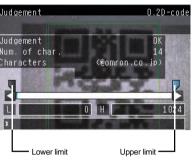
If reading is unsuccessful, check the condition of the workpiece and the lighting, and then perform the teaching process again.



**3** Adjust the judgement parameters. Press [Judgement].



Adjust the judgement parameters for the num. of characters and the text string while inputting images of a number of sample items.



Press [OK].

## 2-3 I/O Settings

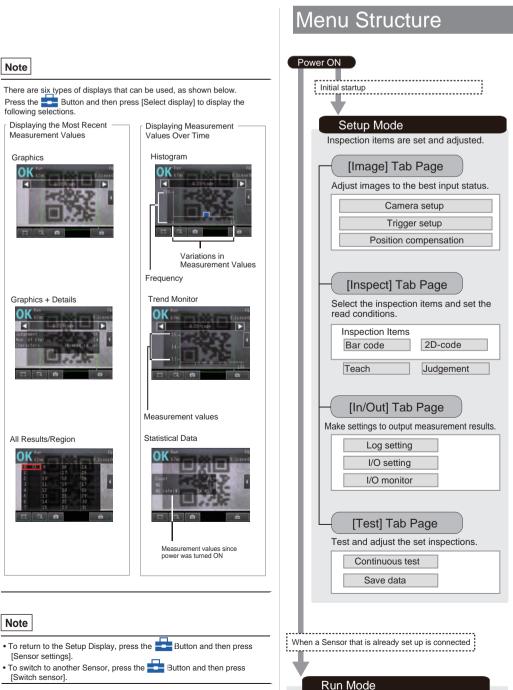
The data that is output to external devices and the input signal assignments can be changed. (Changes are not normally required.) For example, the following can be input or output. Judgements for individual inspection items can

- be output.
- If you want to output characters
  If you want to output data externally

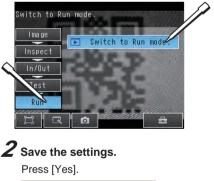
## Refer to the User's Manual for details.

# 3. Testing

Tests are made with some samples to see if correct measurements are possible. When Test Mode is entered, images are measured continuously. A trigger input is not required. Measurement results are only displayed. They are not output to an external device.



**7** Switch to the Run Mode display.



Save data ave sensor data and touch inder data.

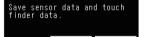
Yes

**3** Execute measurements.

4. Operation

Press [Run]. Then press [Switch to Run mode].







**2** If correct judgements are not made, adjust the judgement parameters. Press []. Press [Adjust judgement]



Measurements will be executed according to the trigger signal input. And the result of measurement will be output to an external device.



The inspections that were set on the Setup

Mode are used to perform measurements.

4