## **FQM1 Series**

**FQM1-CM002** 

FQM1-MMP22

FQM1-MMA22

# Flexible Motion Controller

# INSTRUCTIONS REFERENCE MANUAL

OMRON

#### Notice:

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.

The following conventions are used to indicate and classify precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to property.

**!** DANGER

Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury. Additionally, there may be severe property damage.

/ WARNING

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. Additionally, there may be severe property damage.

Caution

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

#### **OMRON Product References**

All OMRON products are capitalized in this manual. The word "Unit" is also capitalized when it refers to an OMRON product, regardless of whether or not it appears in the proper name of the product.

The abbreviation "Ch," which appears in some displays and on some OMRON products, often means "word" and is abbreviated "Wd" in documentation in this sense.

The abbreviation "CM" means Coordinator Module and the abbreviation "MM" means Motion Control Module.

## Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

**Note** Indicates information of particular interest for efficient and convenient operation of the product.

1. Indicates lists of one sort or another, such as procedures, checklists, etc.

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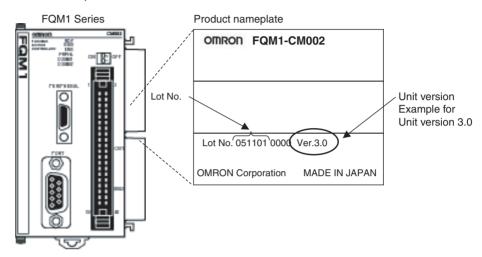
## Unit Versions of FQM1 Series Flexible Motion Controller

## **Unit Versions**

The FQM1 Series Controllers have "unit versions", which are used to manage the differences in functionality associated with upgrades to the Coordinator Modules and Motion Control Modules.

Notation of Unit Versions on Products

The unit version is listed just to the right of the lot number on the nameplate of the Module, as shown below.



#### **Unit Versions and Model Numbers**

Name	Unit Ver. 2.0	Unit Ver. 3.0
Coordinator Module	FQM1-CM001	FQM1-CM002
Motion Control Module		FQM1-MMA22 FQM1-MMP22

Note The Ver. 2.0 Modules (FQM1-CM001, FQM1-MMA21, and FQM1-MMP21) can be used together with the Ver. 3.0 Modules (FQM1-CM002, FQM1-MMA22, and FQM1-MMP22).

# Version Upgrade Guide

#### ■ Functional Improvements from Version 3.0 to Version 3.1

Previous version (unit version 3.0)	Unit version 3.1 or later
Not UL listed	UL listed
	Note: For an FQM1-series Controller to conform to the UL listing, the system must be configured with an XW2B-80J7-1A Relay Unit and XW2Z-\Bullet \Bullet \Bull

#### ■ Functional Improvements from Version 3.1 to Version 3.2

Previous version (unit version 3.1)	Unit version 3.2 or later
Not in previous version	When PULS(886) is used in electronic cam mode (ring), the pulse output can be set to pass through 0 in the CW direction or CCW direction.
When PULS(886) is used in electronic cam mode (linear or ring), the user set the present operation's reference position and pulse output frequency in the instruction's operands.	When PULS(886) is used in electronic cam mode (linear or ring), a new option can be selected to automatically calculate the pulse output frequency based on the previous reference value and the present operation's reference value.
Not in previous version	Two cyclic refreshing areas (up to 25 words each for output and input) can be added. These areas are primarily used as interface areas between the Coordinator Module and the base FB in the Motion Control Module. When the base FB is not being used, these areas can be used as work words.
Mounting CJ-series Units  Basic I/O Units (except the CJ1W-INT01 and CJ1W-IDP01)  CPU Bus Units: CJ1W-SPU01 and CJ1W-NCF71  Special I/O Units: CJ1W-SRM21  Communications Units: CJ1W-DRM21	The following Units can be mounted, in addition to the Units listed on the left.  CPU Bus Units: CJ1W-ADG41  Special I/O Units: CJ1W-NC113/213/413/133/ 233/ 433, CJ1W-V600C11/V600C12  Note: The FQM1 Controllers do not support the IORD(222) and IOWR(223) instructions.
Not in previous version	When the counter reset method is set to Phase-Z signal + software reset in the system settings, an interrupt task can be started when the counter is reset.
When the 20-MHz clock is specified in the system settings for the pulse output function, the output frequency range is 400 Hz to 1 MHz.	When the 20-MHz clock is specified in the system settings, a new option can be selected to set an output frequency range of 1 Hz to 1 MHz.
When the high-speed analog sampling function is used with counter 1 as the sampling timing counter, the multiplier is always 1x, regardless of the counter 1 multiplier setting (1x, 2x, or 4x).	The sampling timing counter uses the same 1x, 2x, or 4x multiplier setting that is set for counter 1.
The VIRTUAL AXIS (AXIS (981)) instruction's calculation cycle can be set to 0.5 ms, 1 ms, or 2 ms.	The calculation cycle settings have been expanded. The cycle can be set to 0.5 ms, 1 ms, 2 ms, 3 ms, or 4 ms.
	The following conditions were removed from the conditions detected as errors when the instruction is executed.
	<ul> <li>Target position (travel amount in relative mode) = 0</li> <li>Target position (target position in absolute mode) = Present position</li> <li>Target frequency &lt; Deceleration rate</li> </ul>

#### ■ Functional Improvements from Version 3.2 to Version 3.3

Previous version (unit version 3.2)	Unit version 3.3 or later	
OMNUC W-series Absolute Encoders can be used.	Absolute Encoders of OMNUC G-series Servomotors can be now be used (in addition to the Absolute Encoders of W-series Servomotors).	
CJ-series Units can be mounted.	In addition to the Units that could previously be mounted, the following Special I/O Units can now be mounted.  • Analog Output Units: CJ1W-DA08V, CJ1W-DA08C, CJ1W-DA041, and CJ1W-DA021  • Analog Input Units: CJ1W-AD081-V1 and CJ1W-041-V1  • Analog I/O Unit: CJ1W-MAD42	
The offset and gain of an analog output can be adjusted separately.	In addition to the previous functions, the default adjustment data can now be registered as the offset value for the analog output offset/gain adjustment function when adjusting the gain. This feature is useful for connecting to a Servo Driver, adjusting the offset using the Servo Driver, and then adjusting only the gain.	

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### About this Manual:

This manual describes the ladder diagram programming instructions of the Coordinator Module and Motion Control Modules of the FQM1-series Flexible Motion Controllers.

Please read this manual and all related manuals listed in the table on the next page and be sure you understand information provided before attempting to program or use FQM1-series Flexible Motion Controllers in a control system.

Name	Cat. No.	Contents
FQM1 Series	O012	This manual provides an overview of and describes
FQM1-CM002, FQM1-MMP22, FQM1-MMA22		the following information for the FQM1-series Flexible
Flexible Motion Controllers Operation Manual		Motion Controllers: features, system configuration,
		system design, installation, wiring, maintenance, I/O
		memory allocation, troubleshooting, etc.
FQM1 Series	O013	Describes the ladder diagram programming instruc-
FQM1-CM002, FQM1-MMP22, FQM1-MMA22		tions supported by FQM1-series Flexible Motion Con-
Flexible Motion Controllers		trollers. Use this manual together with the Operation
Instructions Reference Manual (this manual)		Manual (Cat. No. O012).
SYSMAC WS02-CXPC1-E-V7	W446	Provides information on how to use the CX-Program-
CX-Programmer Operation Manual Version 7.x		mer (except for function block functionality).
SYSMAC WS02-CXPC1-E-V7	W447	Provides specifications and operating procedures for
CX-Programmer Operation Manual Version 7.x		function blocks.
Function Blocks		
SYSMAC CXONE-AL□□C-E	W445	Provides an overview of the CX-One FA Integrated
CX-One FA Integrated Tool Package Setup		Tool and installation procedures.
Manual		

**Section 1** provides information on general instruction characteristics as well as the errors that can occur during instruction execution.

Section 2 provides summaries of instructions used with the FQM1.

Section 3 describes each of the instructions that can be used in programming the FQM1.

Section 4 provides instruction execution times and the number of steps for each FQM1 instruction.

#### Read and Understand this Manual

Please read and understand this manual before using the product. Please consult your OMRON representative if you have any questions or comments.

## Warranty and Limitations of Liability

#### WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

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In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

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## **Application Considerations**

#### SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

At the customer's request, OMRON will provide applicable third party certification documents identifying ratings and limitations of use that apply to the products. This information by itself is not sufficient for a complete determination of the suitability of the products in combination with the end product, machine, system, or other application or use.

The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this manual.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical
  equipment, amusement machines, vehicles, safety equipment, and installations subject to separate
  industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

#### PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

### **Disclaimers**

#### CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

#### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

#### PERFORMANCE DATA

Performance data given in this manual is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

#### **ERRORS AND OMISSIONS**

The information in this manual has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

## **PRECAUTIONS**

This section provides general precautions for using the FQM1-series Flexible Motion Controllers and related devices.

The information contained in this section is important for the safe and reliable application of the FQM1-series Flexible Motion Controller. You must read this section and understand the information contained before attempting to set up or operate a control system using the FQM1-series Flexible Motion Controller.

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Intended Audience 1

#### **Intended Audience** 1

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- · Personnel in charge of installing FA systems.
- Personnel in charge of designing FA systems.
- Personnel in charge of managing FA systems and facilities.

#### **General Precautions** 2

The user must operate the product according to the performance specifications described in the operation manuals.

Before using the product under conditions which are not described in the manual or applying the product to nuclear control systems, railroad systems, aviation systems, vehicles, combustion systems, medical equipment, amusement machines, safety equipment, petrochemical plants, and other systems, machines, and equipment that may have a serious influence on lives and property if used improperly, consult your OMRON representative.

Make sure that the ratings and performance characteristics of the product are sufficient for the systems, machines, and equipment, and be sure to provide the systems, machines, and equipment with double safety mechanisms.

/!\ WARNING It is extremely important that the FQM1 be used for the specified purpose and under the specified conditions, especially in applications that can directly or indirectly affect human life. You must consult with your OMRON representative before applying an FQM1 System to the above-mentioned applications.

#### 3 **Safety Precautions**

/!\ WARNING Do not attempt to take any Modules apart while the power is being supplied. Doing so may result in electric shock.

/!\ WARNING Do not touch any of the terminals or terminal blocks while the power is being supplied. Doing so may result in electric shock.

/!\ WARNING Do not attempt to disassemble, repair, or modify any Modules. Any attempt to do so may result in malfunction, fire, or electric shock.

/!\ WARNING Provide safety measures in external circuits, i.e., not in the Flexible Motion Controller (referred to as the "FQM1"), to ensure safety in the system if an abnormality occurs due to malfunction of the FQM1 or another external factor affecting the FQM1 operation. Not doing so may result in serious accidents.

- Emergency stop circuits, interlock circuits, limit circuits, and similar safety measures must be provided in external control circuits.
- The FQM1 will turn OFF all outputs when its self-diagnosis function detects any error or when a severe failure alarm (FALS) instruction is executed. As a countermeasure for such errors, external safety measures must be provided to ensure safety in the system.
- The FQM1 outputs may remain ON or OFF due to destruction of the output transistors. As a countermeasure for such problems, external safety measures must be provided to ensure safety in the system.

> • When the 24-VDC output (service power supply to the FQM1) is overloaded or short-circuited, the voltage may drop and result in the outputs being turned OFF. As a countermeasure for such problems, external safety measures must be provided to ensure safety in the system.

/!\ WARNING Fail-safe measures must be taken by the customer to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes. Not doing so may result in serious accidents.

/!\ Caution Execute online edit only after confirming that no adverse effects will be caused by extending the cycle time. Otherwise, the input signals may not be readable.

/!\ Caution User programs and parameters written to the Coordinator Module or Motion Control Module will be automatically backed up in the FQM1 flash memory (flash memory function). The contents of I/O memory (including the DM Area). however, are not written to flash memory. Part of the DM Area used as a holding area when recovering from a power interruption is backed up using a super capacitor, but correct values will not be maintained if an error occurs that prevents memory backup. As a countermeasure for such problems, take appropriate measures in the program using the Memory Not Held Flag (A316.14) when externally outputting the contents of the DM Area.

(Caution Confirm safety at the destination Module before transferring a program to another Module or editing the I/O area. Doing either of these without confirming safety may result in injury.

/!\ Caution Tighten the screws on the terminal block of the AC Power Supply Unit to the torque specified in the operation manual. The loose screws may result in burning or malfunction.

/!\ Caution Do not touch the Power Supply Unit while the power is ON, and immediately after turning OFF the power. Touching hot surfaces may result in burning.

/!\ Caution Pay careful attention to the polarities (+/-) when wiring the DC power supply. A wrong connection may cause malfunction of the system.

#### 3-1 **Operating Environment Precautions**

/!\ Caution Do not operate the control system in the following places:

- · Locations subject to direct sunlight
- Locations subject to temperatures or humidity outside the range specified in the specifications
- Locations subject to condensation as the result of severe changes in temperature
- Locations subject to corrosive or flammable gases
- Locations subject to dust (especially iron dust) or salts
- Locations subject to exposure to water, oil, or chemicals
- Locations subject to shock or vibration

/!\ Caution Take appropriate and sufficient countermeasures when installing systems in the following locations:

- Locations subject to static electricity or other forms of noise
- Locations subject to strong electromagnetic fields
- Locations subject to possible exposure to radioactivity
- · Locations close to power supplies

/!\ Caution The operating environment of the FQM1 System can have a large effect on the longevity and reliability of the system. Improper operating environments can lead to malfunction, failure, and other unforeseeable problems with the FQM1 System. Make sure that the operating environment is within the specified conditions at installation and remains within the specified conditions during the life of the system.

#### 3-2 **Application Precautions**

/!\ WARNING Always heed these precautions. Failure to abide by the following precautions could lead to serious or possibly fatal injury.

- Always connect to a ground of 100 Ω or less when installing the FQM1. Not doing so may result in electric shock.
- Always connect to a ground of 100  $\Omega$  or less when short-circuiting the functional ground and line ground terminals of the Power Supply Unit, in particular.
- Always turn OFF the power supply to the FQM1 before attempting any of the following. Not turning OFF the power supply may result in malfunction or electric shock.
  - Mounting or dismounting Power Supply Unit, Coordinator Module, Motion Control Module, I/O Control Module, CJ-series Units, and End Module
  - Assembling the Modules
  - · Setting DIP switches
  - Connecting or wiring the cables
  - Connecting or disconnecting the connectors

/!\ Caution Failure to abide by the following precautions could lead to faulty operation of the FQM1 or the system, or could damage the FQM1. Always heed these precautions.

- Always use the CX-Programmer (Programming Device for Windows) to create new cyclic tasks and interrupt tasks.
- The user program, parameter area data, and part of the DM Area in the Coordinator Module and Motion Control Modules is backed up in the builtin flash memory. Do not turn OFF the power supply to the FQM1 while the user program or parameter area data is being transferred. The data will not be backed up if the power is turned OFF.
- The FQM1 will start operating in RUN mode when the power is turned ON with the default settings (i.e., if the operating mode at power ON (startup mode) setting in the System Setup is disabled).
- Configure the external circuits so that the control power supply turns ON after the power supply to the FQM1 turns ON. If the power is turned ON in the opposite order, the built-in outputs and other outputs may momentarily malfunction and the control outputs may temporarily not operate correctly.

Outputs may remain ON due to a malfunction in the built-in transistor outputs or other internal circuits. As a countermeasure for such problems, external safety measures must be provided to ensure the safety of the system.

- Part of the DM Area (data memory) in the Motion Control Module is held using the super capacitor. Corrupted memory may prevent the correct values from being saved, however. Take appropriate measures in the ladder program whenever the Memory Not Held Flag (A316.14) turns ON, such as resetting the data in the DM Area.
- Part of the DM Area in the Coordinator Module is backed up in the built-in flash memory when transferring data from the CX-Programmer. Do not turn OFF the power to the FQM1 while data is being transferred. The data will not be backed up if the power is turned OFF.
- Confirm that no adverse effect will occur in the system before attempting any of the following. Not doing so may result in an unexpected operation.
  - Changing the operating mode of the FQM1 (including setting the operating mode at startup)
  - Force-setting/force-resetting any bit in memory
  - Changing the present value of any word or any set value in memory
- Install external breakers and take other safety measures against short-circuiting in external wiring. Insufficient safety measures against short-circuiting may result in burning.
- Be sure that all the terminal screws and cable connector screws are tightened to the torque specified in the relevant manuals. Incorrect tightening torque may result in malfunction.
- Mount the Modules only after checking the connectors and terminal blocks completely.
- Before touching the Module, be sure to first touch a grounded metallic object in order to discharge any static built-up. Not doing so may result in malfunction or damage.
- Be sure that the terminal blocks, connectors, and other items with locking devices are properly locked into place. Improper locking may result in malfunction.
- Wire correctly according to the specified procedures.
- Always use the power supply voltage specified in the operation manuals.
   An incorrect voltage may result in malfunction or burning.
- Take appropriate measures to ensure that the specified power with the rated voltage and frequency is supplied. Be particularly careful in places where the power supply is unstable. An incorrect power supply may result in malfunction.
- Leave the dust protective label attached to the Module when wiring. Removing the label may result in malfunction.
- Remove the dust protective label after the completion of wiring to ensure proper heat dissipation. Leaving the label attached may result in malfunction
- Use crimp terminals for wiring. Do not connect bare stranded wires directly to terminals. Connection of bare stranded wires may result in burning.
- Do not apply voltages to the built-in inputs in excess of the rated input voltage. Excess voltages may result in burning.

 Do not apply voltages or connect loads to the built-in outputs in excess of the maximum switching capacity. Excess voltage or loads may result in burning.

- Disconnect the functional ground terminal when performing withstand voltage tests. Not disconnecting the functional ground terminal may result in burning.
- Wire correctly and double-check all the wiring or the setting switches before turning ON the power supply. Incorrect wiring may result in burning.
- Check that the DIP switches and data memory (DM) are properly set before starting operation.
- Check the user program for proper execution before actually running it on the Module. Not checking the program may result in an unexpected operation.
- Resume operation only after transferring to the new Module the contents
  of the DM Areas, programs, parameters, and data required for resuming
  operation. Not doing so may result in an unexpected operation.
- Do not pull on the cables or bend the cables beyond their natural limit. Doing either of these may break the cables.
- Do not place objects on top of the cables. Doing so may break the cables.
- Use the dedicated connecting cables specified in operation manuals to connect the Modules. Using commercially available RS-232C computer cables may cause failures in external devices or the Coordinator Module.
- Do not connect pin 6 (+5V) on the RS-232C port on the Coordinator Module to any external device other than the NT-AL001 or CJ1W-CIF11 Conversion Adapter. Doing so may result in damage to the external device and the Coordinator Module.
- When replacing parts, be sure to confirm that the rating of a new part is correct. Not doing so may result in malfunction or burning.
- When transporting or storing the product, cover the PCBs with electrically conductive materials to prevent LSIs and ICs from being damaged by static electricity, and also keep the product within the specified storage temperature range.
- Do not touch the mounted parts or the rear surface of PCBs because PCBs have sharp edges such as electrical leads.
- When connecting the Power Supply Unit, Coordinator Module, Motion Control Module, I/O Control Module, CJ-series Units, and End Module, slide the upper and lower sliders until a click sound is heard to lock them securely. Desired functionality may not be achieved unless Modules are securely locked in place.
- Be sure to mount the End Module supplied with the Coordinator Module to the rightmost Module. Unless the End Module is properly mounted, the FQM1 will not function properly.
- Make sure that parameters are set correctly. Incorrect parameter settings
  may result in unexpected operations. Make sure that equipment will not
  be adversely affected by the parameter settings before starting or stopping the FQM1.

#### 4 Conformance to EC Directives

#### 4-1 Applicable Directives

- EMC Directives
- · Low Voltage Directive

#### 4-2 Concepts

#### **EMC Directives**

OMRON devices that comply with EC Directives also conform to the related EMC standards so that they can be more easily built into other devices or the overall machine. The actual products have been checked for conformity to EMC standards (see the following note). Whether the products conform to the standards in the system used by the customer, however, must be checked by the customer.

EMC-related performance of the OMRON devices that comply with EC Directives will vary depending on the configuration, wiring, and other conditions of the equipment or control panel on which the OMRON devices are installed. The customer must, therefore, perform the final check to confirm that devices and the overall machine conform to EMC standards.

Note Applicable EMC (Electromagnetic Compatibility) standards are as follows:

EMS (Electromagnetic Susceptibility): EN61000-6-2 EMI (Electromagnetic Interference): EN61000-6-4

(Radiated emission: 10-m regulations)

#### **Low Voltage Directive**

Always ensure that devices operating at voltages of 50 to 1,000 V AC and 75 to 1,500 V DC meet the required safety standards for the Motion Controller (EN61131-2).

#### 4-3 Conformance to EC Directives

The FQM1-series Flexible Motion Controllers comply with EC Directives. To ensure that the machine or device in which the Motion Controller is used complies with EC Directives, the Motion Controller must be installed as follows:

- 1,2,3... 1. The Motion Controller must be installed within a control panel.
  - You must use reinforced insulation or double insulation for the DC power supplies used for the communications power supply and I/O power supplies.
  - 3. Motion Controllers complying with EC Directives also conform to the Common Emission Standard (EN61000-6-4). Radiated emission characteristics (10-m regulations) may vary depending on the configuration of the control panel used, other devices connected to the control panel, wiring, and other conditions. You must therefore confirm that the overall machine or equipment complies with EC Directives.

#### 4-4 EMC Directive Conformance Conditions

The immunity testing condition of the Motion Controller Modules is as follows: Overall accuracy of FQM1-MMA22 analog I/O: +4%/-2%

### 4-5 Relay Output Noise Reduction Methods

The FQM1-series Flexible Motion Controller conforms to the Common Emission Standards (EN61000-6-4) of the EMC Directives. However, noise generated by relay output switching may not satisfy these Standards. In such a case, a noise filter must be connected to the load side or other appropriate countermeasures must be provided external to the Motion Controller.

Countermeasures taken to satisfy the standards vary depending on the devices on the load side, wiring, configuration of machines, etc. Following are examples of countermeasures for reducing the generated noise.

#### **Countermeasures**

(Refer to EN61000-6-4 for more details.)

Countermeasures are not required if the frequency of load switching for the whole system with the Motion Controller included is less than 5 times per minute.

Countermeasures are required if the frequency of load switching for the whole system with the Motion Controller included is more than 5 times per minute.

#### **Countermeasure Examples**

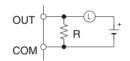
When switching an inductive load, connect a surge protector, diodes, etc., in parallel with the load or contact as shown below.

Circuit	Current		Characteristic	Required element	
	AC	DC			
CR method  C   exitonpul  Power R   peol	Yes	Yes	If the load is a relay or solenoid, there is a time lag between the moment the circuit is opened and the moment the load is reset.  If the supply voltage is 24 or 48 V, insert the surge protector in parallel with the load. If the supply voltage is 100 to 200 V, insert the surge protector between the contacts.	The capacitance of the capacitor must be 1 to $0.5~\mu F$ per contact current of 1 A and resistance of the resistor must be $0.5$ to 1 $\Omega$ per contact voltage of 1 V. These values, however, vary with the load and the characteristics of the relay. Decide these values from experiments, and take into consideration that the capacitance suppresses spark discharge when the contacts are separated and the resistance limits the current that flows into the load when the circuit is closed again. The dielectric strength of the capacitor must be 200 to 300 V. If the circuit is an AC circuit, use a capacitor with no polarity.	

Circuit Current		rent	Characteristic	Required element	
	AC	DC			
Diode method  Power  Power	No	Yes	The diode connected in parallel with the load changes energy accumulated by the coil into a current, which then flows into the coil so that the current will be converted into Joule heat by the resistance of the inductive load.	The reversed dielectric strength value of the diode must be at least 10 times as large as the circuit voltage value. The forward current of the diode must be the same as or larger than the load current.	
supply			This time lag, between the moment the circuit is opened and the moment the load is reset, caused by this method is longer than that caused by the CR method.	The reversed dielectric strength value of the diode may be two to three times larger than the supply voltage if the surge protector is applied to electronic circuits with low circuit voltages.	
Varistor method  Power supply  Power supply	Yes	Yes	The varistor method prevents the imposition of high voltage between the contacts by using the constant voltage characteristic of the varistor. There is time lag between the moment the circuit is opened and the moment the load is reset.  If the supply voltage is 24 or 48 V, insert the varistor in parallel with the load. If the supply voltage is 100 to 200 V, insert the varistor between the contacts.		

When switching a load with a high inrush current such as an incandescent lamp, suppress the inrush current as shown below.





Providing a dark current of approx. one-third of the rated value through an incandescent lamp

#### Countermeasure 2

Providing a limiting resistor

The following Unit and Cables can be used with the FQM1-series Flexible Motion Controller.

Name	Model	Cable length
Relay Unit	XW2B-80J7-1A	
Controller Connect-	XW2Z-050J-A28	0.5 m
ing Cables	XW2Z-100J-A28	1 m
	XW2Z-050J-A30	0.5 m
	XW2Z-100J-A30	1 m
	XW2Z-050J-A31	0.5 m
	XW2Z-100J-A31	1 m

Data Backup 5

## 5 Data Backup

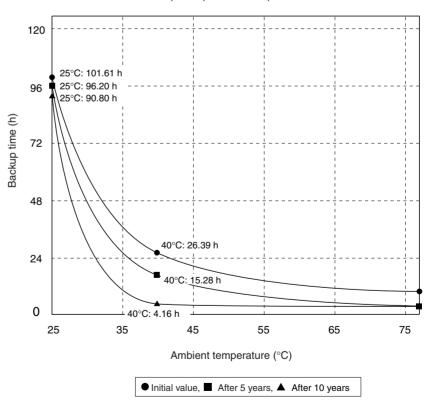
The user programs, I/O memories, and other data in the Coordinator Module and Motion Control Modules is backed up either by a super capacitor or flash memory, as listed in the following table.

Module	Data	Data backup
Coordinator Module	Error log	RAM with super
Motion Control Module	DM Area words D30000 to D32767	capacitor
	Error log	
Coordinator Module	User program	Flash memory
	System Setup	
	DM Area words D20000 to D32767	
Motion Control Module	User program	
	System Setup	
	DM Area words D00000 to D29999 (Auxiliary Area bit must be set.)	

The data backup time of the super capacitor is given in the following table and shown in the following graph.

Temperature	Initial	After 5 years	After 10 years
Ta = 25°C	101.61 hours (4.23 days)		90.8 hours (3.78 days)
Ta = 40°C	26.39 hours (1.09 days)	15.28 hours	4.16 hours

Super Capacitor Backup Times



Note 1. The times give above assume that the capacitor is completely charged. Power must be supply to the FQM1 for at least 20 minutes to completely charge the capacitor.

Data Backup 5

2. The backup time of the super capacitor is reduced as the capacitor ages. It is also affected by the ambient temperature. Use portion of the DM Area backed up by the super capacitor only for data that is to be held during momentary power interruptions. For operating parameters and other long-term data, use the portion of DM Area stored in flash memory in the Coordinator Module and transfer it to the Motion Control Modules before starting operation.

The data in the DM Area and error log will become unstable or corrupted if the power to the system is OFF for longer than the backup time.

If the power supply is to be turned OFF for an extended period of time, use D20000 to D32767 in the Coordinator Module and D00000 to D29999 in the Motion Control Module, which is backed up in flash memory, to store data.

Otherwise, the Memory Not Held Flag (A316.14) can be used as the input condition for programming using data in areas stored for power interruptions to perform suitable processing.

A316.14: Turns ON when power is turned ON if data stored for power interruptions in the DM Area or error log is corrupted.

```
Processing for corruption of data backed up for power interruptions
```

#### **Backing Up DM Area Data in Flash Memory**

DM Area words D20000 to D32767 for the Coordinator Module and D00000 to D29999 for the Motion Control Modules are read from flash memory when the power supply is turned ON. (A Setup parameter must be set to read DM Area data for the Motion Control Modules.)

# **SECTION 1 Introduction**

This section provides information on general instruction characteristics as well as the errors that can occur during instruction execution.

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	1-1-2	Differentiated Instructions	2
	1-1-3	Instruction Variations	3
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1-2	Instruct	tion Execution Checks	8
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#### 1-1 General Instruction Characteristics

#### 1-1-1 **Program Capacity**

The program capacity tells the size of the user program area each Module and is expressed as the number of program steps. The number of steps required in the user program area for each instruction varies from 1 to 7 steps, depending upon the instruction and the operands used with it.

Model		Model	Program capacity
Coordinator Module		FQM1-CM002	10K steps
Motion Control Modules Pulse I/O		FQM1-MMP22	
	Analog I/O	FQM1-MMA22	

Note The number of steps in a program is not the same as the number of instructions, i.e., each instruction contains from 1 to 7 steps. For example, LD and OUT require 1 step each, but MOV(021) requires 3 steps. The number of steps required by an instruction is also increased by one step for each doublelength operand used in it. For example, MOVL(498) normally requires 3 steps, but 4 steps will be required if a constant is specified for the source word operand, S. Refer to SECTION 4 Instruction Execution Times and Number of Steps for the number of steps required for each instruction.

#### 1-1-2 **Differentiated Instructions**

Most instructions in the FQM1 are provided with both non-differentiated and upwardly differentiated variations, and some are also provided with downwardly differentiated variations.

- A non-differentiated instruction is executed every time it is scanned.
- An upwardly differentiated instruction is executed only once after its execution condition goes from OFF to ON.
- A downwardly differentiated instruction is executed only once after its execution condition goes from ON to OFF.

Variation	Instruction type	Operation	Format	Example
Non- differentiated	Output instructions (instructions requiring an execution condi- tion)	The instruction is executed every cycle while the execution condition is true (ON).	Output instruction executed each cycle	Н-[моv ]—
	Input instructions (instructions used as execution conditions)	The bit processing (such as read, comparison, or test) is performed every cycle. The execution condition is true while the result is ON.	Input instruction executed each cycle	<u></u>
Upwardly differentiated (with @ prefix)	Output instructions	The instruction is executed just once when the execution condition goes from OFF to ON.	@Instruction executed once for upward differentiation	MOV(021) executed once for each OFF to ON transition in CIO 0001.02.
	Input instructions (instructions used as execution conditions)	The bit processing (such as read, comparison, or test) is performed every cycle. The execution condition is true for one cycle when the result goes from OFF to ON.	Upwardly differentiated input instruction	ON execution condition created for one cycle only for each OFF to ON transition in CIO 0001.03.

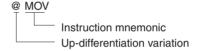
Variation	Instruction type	Operation	Format	Example
Downwardly differentiated (with % prefix)	Output instructions	The instruction is executed just once when the execution condition goes from ON to OFF.	%Instruction executed once for downward differentiation	0001.02 SET executed once for each ON to OFF transition in CIO 0001.02.
	Input instructions (instructions used as execution conditions)	The bit processing (such as read, comparison, or test) is performed every cycle. The execution condition is true for one cycle when the result goes from ON to OFF.	Downwardly differentiated input instruction	ON execution condition created for one cycle only for each ON to OFF transition in CIO 0001.03.

**Note** The downwardly differentiated option (%) is available only for the LD, AND, OR, and RSET instructions. To create downwardly differentiated variations of other instructions, control the execution of the instruction with work bits controlled with DIFD(014).

#### 1-1-3 Instruction Variations

The variation prefixes (@ and %) can be added to certain instructions to create a differentiated instruction.

Variation		Prefix	Operation
Differentiation	Upwardly dif- ferentiated	@	Creates an upwardly differentiated instruction.
	Downwardly differentiated	%	Creates a downwardly differentiated instruction.



#### 1-1-4 Instruction Location and Execution Conditions

The following table shows the locations in which instructions can be programmed. The table also shows when an instruction requires an execution condition and when it does not. Refer to SECTION 2 Summary of Instructions for details on specific instructions.

Ins	truction type	Location	Execution condition	Format	Examples
Input	Instructions that start logic conditions (load instructions)	start of an instruction	Not required	Hami	LD and input comparison instructions such as LD >
	Connecting instructions	Between a starting instruction and output instruction	Required	1	AND, OR, and input comparison instructions, such as AND >
Output	i	At the right bus	Required	<del>                                    </del>	The majority of instructions (such as OUT and MOV)
			Not required		Instructions such as END, JME, and ILC

In addition to these instructions, the FQM1 is equipped with block programming instructions. Refer to the description of the block programming instructions for details.

**Note** If an execution condition does not precede an instruction that requires one, a program error will occur when the program is checked from the CX-Programmer.

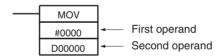
## 1-1-5 Inputting Data in Operands

Operands are parameters that are set in advance with the I/O memory addresses or constants to be used when the instruction is executed. There are basically three kinds of operands: Source operands, destination operands, and numbers.



Operand		Usual code		Contents
Source	Address containing the data or the data	S	Source operand	Source data other than control data
itself		С	Control data	Control data with a bit or bits controlling instruction execution
Destination	Address where the data will be stored	D		
Number	Contains a number, such as a jump number or subroutine number.	N		

**Note** An instruction's operands may also be referred to by their position in the instruction (first operand, second operand, ...). The codes used for the operand vary with the specific function of the operand.



#### **Specifying Bit Addresses**

Description	Example	Instruction example
To specify a bit address, specify the word address and bit address directly.  Bit number (00 to 15)  Word address	0001.02 — Bit 02 — Word CIO 0001	0001 02 ├─ <b>│</b>
Note The word address + bit number format is not used for Timer/Counter Completion Flags or Task Flags.		

#### **Specifying Word Addresses**

Description	Example	Instruction example
To specify a word address, specify the word address directly. Each word contains 16 bits.	0003 Word CIO 0003	MOV 0003 D00200
Word address	D <u>00200</u> Word D00200	

#### **Specifying Indirect DM Addresses in Binary Mode**

Description	Example	Instruction example
When the @ prefix is input before a DM address, the contents of that word specifies another word that is used as the operand. The contents can be 0000 to 7FFF (0 to 32,767), corresponding to the desired word address in the DM Area.		
@ <u>D                                   </u>		
Content 00000 to 32767 (0000 to 7FFF)		
When the contents of @DDDDDD is between 0000 and 7FFF (00000 to 32,767), the corresponding word between D00000 and D32767 is specified.	@ D00300  0 1 0 0  Decimal: 256  Specifies D00256.  Add the @ prefix.	MOV #0001 @ D00300

#### **Specifying Indirect DM Addresses in BCD Mode**

Method	Description	Example	Instruction example
Indirect DM addressing (BCD mode)	When the * prefix is input before a DM address, the BCD contents of that word specify another word that is used as the operand. The contents can be 0000 to 9999, corresponding to the desired word address in the DM Area.  *DDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDD	*D00200  0 1 0 0  Specifies D00100.  Add the * prefix.	MOV #0001 *D00200

#### **Specifying Constants**

Method	Applicable operands	Data format	Code	Range
Constant, 16-bit data	All binary data and binary data within a range	Unsigned binary	#	#0000 to #FFFF
		Signed decimal	±	-32,768 to +32,767
		Unsigned decimal	&	&0 to &65,535
	All BCD data and BCD data within a range	BCD	#	#0000 to #9999
Constant, 32-bit data	All binary data and binary data within a range	Unsigned binary	#	#0000 0000 to #FFFF FFFF
		Signed decimal	+	-2,147,483,648 to +2,147,483,647
		Unsigned decimal	&	&0 to &4,294,967,295
	All BCD data and BCD data within a range	BCD	#	#0000 0000 to #9999 9999

## **Specifying Text Strings**

Method	Description	Code	Examples
Text strings	Text is stored in ASCII (1 byte/character excluding special characters) in the order from the higher to lower byte and lowest to highest word. If there is an odd number of characters, 00 (NULL) is stored in the higher byte of the last word in the range.  If there is an even number of characters, 0000 (two NULLs) are stored in the word after the last in the range.		"ABCDE"  "A" "B"  "C" "D"  "E" NUL      41

The following diagram shows the characters that can be expressed in ASCII.

						L	eftm	ost	bit				_				
		0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Ε	F
	0			S <sub>P</sub>	0	@	Р	,	р				_	タ	=		
	1			!	1	Α	a	а	q			0	ア	チ	ム		
	2			"	2	В	R	b	r			Γ	1	ツ	メ		
	3			#	3	C	S	C	s				ウ	テ	Ŧ		
	4			\$	4	D	T	d	t				I	۲	ヤ		
<b> </b>	5			%	5	Е	כ	Φ	u			•	オ	ナ	ユ		
st bi	6			&	6	F	>	f	٧			ヲ	カ	=	3		
tmo	7			,	7	G	W	g	w			ア	キ	ヌ	ラ		
Rightmost bit	8			(	8	Н	Х	h	Х			1	ク	ネ	リ		
-	9			)	9	ı	Υ	i	У			ウ	ケ	ノ	ル		
	Α			*	:	J	Ζ	j	z			エ	コ	<b>/</b> \	レ		
	В			+	;	K	[	k	{			オ	サ	ヒ	П		
	С			,	<	L	¥	Ī				ヤ	シ	フ	ワ		
	D			_	=	М	]	m	}			ュ	ス	^	ン		
	Ε				>	N	^	n	~			∄	セ	ホ	*		
	F			/	?	0		0				ツ	ソ	マ	٥		

## 1-1-6 Data Formats

The following table shows the data formats that can be used in the FQM1.

Name								I	Forr	nat								Decimal range	Hexadecimal range
Unsigned binary data		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0 to 65,535	0000 to FFFF
	Binary	2 <sup>15</sup>	2 <sup>14</sup>	2 <sup>13</sup>	2 <sup>12</sup>	211	2 <sup>10</sup>	2 <sup>9</sup>	2 <sup>8</sup>	2 <sup>7</sup>	2 <sup>6</sup>	<b>2</b> <sup>5</sup>	2 <sup>4</sup>	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	2 <sup>0</sup>		
	Decimal	32768	8 1638	34 819	2 4096	2048	1024	512	256	128	64	32	16	8	4	2	1		
	Hexa- decimal	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	2 <sup>0</sup>	23	<b>2</b> <sup>2</sup>	21	20	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	20	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	20		
Signed binary data		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	-32,768 to +32,767	8000 to 7FFF
J. G.	Binary	2 <sup>15</sup>	214	2 <sup>13</sup>	2 <sup>12</sup>	211	210	2 <sup>9</sup>	2 <sup>8</sup>	2 <sup>7</sup>	2 <sup>6</sup>	2 <sup>5</sup>	24	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	20		
	Decimal	: -32768	8 163	84 819	24096	2048	1024	512	256	128	64	32	16	8	4	2	1		
	Hexa- decimal	2 <sup>3</sup>	2 <sup>2</sup>	2 <sup>1</sup> Sign 0: Po 1: Ne	sitive		2 <sup>2</sup>	21	20	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	21	2 <sup>0</sup>	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	21	2 <sup>0</sup>		
BCD data		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	0 to 9,999	0000 to 9999
	BCD	23	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	<b>2</b> <sup>0</sup>	2 <sup>3</sup>	2 <sup>2</sup>	21	<b>2</b> <sup>0</sup>	23	<b>2</b> <sup>2</sup>	21	20	2 <sup>3</sup>	2 <sup>2</sup>	2 <sup>1</sup>	20		
	Decimal		0 1	to 9			0 to	9	:		0 t	o 9			0 t	o 9	:		

Name	Format	Decimal range	Hexadecimal range
Floating- point deci- mal	Sign of mantissa  Value = (-1) <sup>Sign</sup> x 1.[Mantissa] x 2 <sup>Exponent</sup> Sign (bit 31)  1: negative or 0: positive  Mantissa  The mantissa includes 23 bits from bit 00 to bit 22 and indicates this portion below the decimal point in 1.□□□ in binary.  Exponent  The exponent includes 8 bits from bit 23 to bit 30 and indicates n plus 127 in 2 <sup>n</sup> in binary.  Note  This format conforms to IEEE754 standards for single-precision floating-point data and is used only with instructions that convert or calculate floating-point data. It can be used to set or monitor from the I/O memory Edit and Monitor Screen on the CX-Programmer. As such, users do not need to know this format although they do need to know that the formatting takes up two words.		
Double- precision floating- point deci- mal	Sign of Exponent Binary  Value = (-1) <sup>Sign</sup> x 1.[Mantissa] x 2 <sup>Exponent</sup> Sign (bit 63) 1: negative or 0: positive  Mantissa The mantissa includes 52 bits from bit 00 to bit 51 and indicates this portion below the decimal point in 1. Indicates this value.  Exponent The exponent includes 11 bits from bit 52 to bit 62 and indicates n plus 127 in 2n in binary. The actual value will be 2 <sup>n-1023</sup> .  Note This format conforms to IEEE754 standards for double-precision floating-point data and is used only with instructions that convert or calculate floating-point data. It can be used to set or monitor from the I/O memory Edit and Monitor Screen on the CX-Programmer. As such, users do not need to know this format although they do need to know that the formatting takes up four words.		

#### **Signed Binary Numbers**

Negative signed-binary numbers are expressed as the 2's complement of the absolute hexadecimal value. For a decimal value of -12,345, the absolute value is equivalent to 3039 hexadecimal. The 2's complement is 10000 - 3039 (both hexadecimal) or CFC7.

To convert from a negative signed binary number (CFC7) to decimal, take the 2's complement of that number (10000 - CFC7 = 3039), convert to decimal (3039 + 2345 = 12345 =

## 1-2 Instruction Execution Checks

## 1-2-1 Errors Occurring at Instruction Execution

An instruction's operands and placement are checked when an instruction is input from the CX-Programmer or a program check is performed from the CX-

Programmer, but these are not final checks. The following errors can occur when an instruction is executed.

Error	Flag	Fatal/Non-fatal
Instruction Processing Error	ER Flag ON	Non-fatal
Illegal Instruction Error	Illegal Instruction Error Flag (A295.14)	Fatal (program error)
UM (User Program Memory) Overflow Error	UM Overflow Error Flag (A295.15)	Fatal (program error)

## 1-2-2 Fatal Errors (Program Errors)

Program execution will be stopped when one of the following program errors occurs. All errors for which the Error Flag or Access Error Flag turns ON is treated as a program error. The following table lists program errors. The System Setup can be set to stop program execution when one of these errors occurs

Error type	Description	Related flags
No END Instruction	There is no END(001) instruction in the program.	No END Error Flag (A295.11)
Task Error	An interrupt was generated but the corresponding interrupt task does not exist.	Task Error Flag (A295.12)
Instruction Processing Error	The CPU attempted to execute an instruction, but the data provided in the instruction's operand was incorrect.	Error (ER) Flag, Instruction Processing Error Flag (A295.08)
Differentiation Overflow Error	Differentiated instructions were repeatedly inserted and deleted during online editing (over 131,072 times).	Differentiation Overflow Error Flag (A295.13)
UM Overflow Error	The last address in UM (user program memory) has been exceeded.	UM Overflow Error Flag (A295.15)
Illegal Instruction Error	The program contains an instruction that cannot be executed.	Illegal Instruction Error Flag (A295.14)

# **SECTION 2 Summary of Instructions**

This section provides a summary of instructions used with the FQM1.

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## 2-1 Instruction Classifications by Function

The following table lists the FQM1 instructions by function. (The instructions appear by order of their function in *Section 3 Instructions*.)

Classifica- tion	Sub-class	Mnemonic	Instruction	Mnemonic	Instruction	Mnemonic	Instruction
Sequence		LD	LOAD	LD NOT	LOAD NOT	AND	AND
input instructions		AND NOT	AND NOT	OR	OR	OR NOT	OR NOT
		AND LD	AND LOAD	OR LD	OR LOAD	NOT	NOT
		UP	CONDITION ON	DOWN	CONDITION OFF		
	Bit test	LD TST	LD BIT TEST	LD TSTN	LD BIT TEST NOT	AND TST	AND BIT TEST NOT
		AND TSTN	AND BIT TEST NOT	OR TST	OR BIT TEST	OR TSTN	OR BIT TEST NOT
Sequence		OUT	OUTPUT	OUT NOT	OUTPUT NOT	KEEP	KEEP
output instructions		DIFU	DIFFERENTI- ATE UP	DIFD	DIFFERENTI- ATE DOWN	OUTB	SINGLE BIT OUTPUT
	Set/Reset	SET	SET	RSET	RESET	SETA	MULTIPLE BIT SET
		RSTA	MULTIPLE BIT RESET	SETB	SINGLE BIT SET	RSTB	SINGLE BIT RESET
Sequence control		END	END	NOP	NO OPERA- TION		
instructions	Interlock	IL	INTERLOCK	ILC	INTERLOCK CLEAR		
	Jump	JMP	JUMP	JME	JUMP END	CJP	CONDI- TIONAL JUMP
		CJPN	CONDI- TIONAL JUMP	JMP0	MULTIPLE JUMP	JME0	MULTIPLE JUMP END
	Repeat	FOR	FOR-NEXT LOOPS	BREAK	BREAK LOOP	NEXT	FOR-NEXT LOOPS
Timer and counter instructions	Timer (with timer num- bers)	TIM	TIMER	TIMH	HIGH-SPEED TIMER	ТМНН	ONE-MS TIMER
(BCD)	Counter (with counter num- bers)	CNT	COUNTER	CNTR	REVERSIBLE TIMER		
Comparison instructions	Symbol comparison	LD, AND, OR + =, <>, <, <=, >, >=	Symbol com- parison (unsigned)	LD, AND, OR + =, <>, <, <=, >, >= + L	Symbol com- parison (dou- ble-word, unsigned)	LD, AND, OR + =, <>, <, <=, >, >= +S	Symbol comparison (signed)
		LD, AND, OR + =, <>, <, <=, >, >= + SL	Symbol com- parison (dou- ble-word, signed)				
	Data comparison (Condition Flags)	CMP	UNSIGNED COMPARE	CMPL	DOUBLE UNSIGNED COMPARE	CPS	SIGNED BINARY COMPARE
		CPSL	DOUBLE SIGNED BINARY COMPARE	ZCP	AREA RANGE COMPARE	ZCPL	DOUBLE AREA RANGE COMPARE
	Table compare	MCMP	MULTIPLE COMPARE	TCMP	TABLE COM- PARE	BCMP	UNSIGNED BLOCK COM- PARE
		BCMP2	EXPANDED BLOCK COM- PARE				

Classifica- tion	Sub-class	Mnemonic	Instruction	Mnemonic	Instruction	Mnemonic	Instruction
Data movement	Single/ double-word	MOV	MOVE	MOVL	DOUBLE MOVE	MVN	MOVE NOT
instructions		MVNL	DOUBLE MOVE NOT				
	Bit/digit	MOVB	MOVE BIT	MOVD	MOVE DIGIT		
	Exchange	XCHG	DATA EXCHANGE	XCGL	DOUBLE DATA EXCHANGE		
	Block/bit transfer	XFRB	MULTIPLE BIT TRANS- FER	XFER	BLOCK TRANSFER	BSET	BLOCK SET
	Distribute/collect	DIST	SINGLE WORD DIS- TRIBUTE	COLL	DATA COL- LECT		
	Index register	MOVR	MOVE TO REGISTER	MOVRW	MOVE TIMER/ COUNTER PV TO REGIS- TER		
Data shift instructions	1-bit shift	SFT	SHIFT REG- ISTER	SFTR	REVERSIBLE SHIFT REG- ISTER	ASLL	DOUBLE SHIFT LEFT
		ASL	ARITHMETIC SHIFT LEFT	ASR	ARITHMETIC SHIFT RIGHT	ASRL	DOUBLE SHIFT RIGHT
	0000 hex asynchronous	ASFT	ASYNCHRO- NOUS SHIFT REGISTER				
	Word shift	WSFT	WORD SHIFT				
	1-bit rotate	ROL	ROTATE LEFT	ROLL	DOUBLE ROTATE LEFT	RLNC	ROTATE LEFT WITHOUT CARRY
		RLNL	DOUBLE ROTATE LEFT WITHOUT CARRY	ROR	ROTATE RIGHT	RORL	DOUBLE ROTATE RIGHT
		RRNC	ROTATE RIGHT WITH- OUT CARRY	RRNL	DOUBLE ROTATE RIGHT WITH- OUT CARRY		
	1 digit shift	SLD	ONE DIGIT SHIFT LEFT	SRD	ONE DIGIT SHIFT RIGHT		
	Shift n-bit data	NASL	SHIFT N-BIT DATA LEFT	NSLL	DOUBLE SHIFT N-BIT DATA LEFT	NASR	SHIFT N-BIT DATA RIGHT
		NSRL	DOUBLE SHIFT N-BIT DATA RIGHT				
Increment/ decrement instructions	BCD	++B	INCREMENT BCD	++BL	DOUBLE INCREMENT BCD	B	DECRE- MENT BCD
		– –BL	DOUBLE DECRE- MENT BCD				
	Binary	++	INCREMENT BINARY	++L	DOUBLE INCREMENT BINARY		DECRE- MENT BINARY
		L	DOUBLE DECRE- MENT BINARY				

Classifica- tion	Sub-class	Mnemonic	Instruction	Mnemonic	Instruction	Mnemonic	Instruction
Symbol math instructions	Binary add	+	SIGNED BINARY ADD WITHOUT CARRY	+L	DOUBLE SIGNED BINARY ADD WITHOUT CARRY	+C	SIGNED BINARY ADD WITH CARRY
		+CL	DOUBLE SIGNED BINARY ADD WITH CARRY				
	BCD add	+B	BCD ADD WITHOUT CARRY	+BL	DOUBLE BCD ADD WITHOUT CARRY	+BC	BCD ADD WITH CARRY
		+BCL	DOUBLE BCD ADD WITH CARRY				
	Binary subtract	_	SIGNED BINARY SUB- TRACT WITHOUT CARRY	-L	DOUBLE SIGNED BINARY SUBTRACT WITHOUT CARRY	-C	SIGNED BINARY SUBTRACT WITH CARRY
		-CL	DOUBLE SIGNED BINARY WITH CARRY				
	BCD subtract	-В	BCD SUBTRACT WITHOUT CARRY	-BL	DOUBLE BCD SUBTRACT WITHOUT CARRY	-BC	BCD SUBTRACT WITH CARRY
		-BCL	DOUBLE BCD SUBTRACT WITH CARRY				
	Binary multiply	*	SIGNED BINARY MULTIPLY	*L	DOUBLE SIGNED BINARY MULTIPLY	*U	UNSIGNED BINARY MULTIPLY
		*UL	DOUBLE UNSIGNED BINARY MULTIPLY				
	BCD multiply	*B	BCD MULTIPLY	*BL	DOUBLE BCD MULTIPLY		
	Binary divide	/	SIGNED BINARY DIVIDE	/L	DOUBLE SIGNED BINARY DIVIDE	/U	UNSIGNED BINARY DIVIDE
		/UL	DOUBLE UNSIGNED BINARY DIVIDE				
	BCD divide	/В	BCD DIVIDE	/BL	DOUBLE BCD DIVIDE		
Conversion instructions	BCD/Binary convert	BIN	BCD-TO- BINARY	BINL	DOUBLE BCD-TO- DOUBLE BINARY	BCD	BINARY-TO- BCD
		BCDL	DOUBLE BINARY-TO- DOUBLE BCD	NEG	2'S COMPLE- MENT	NEGL	DOUBLE 2'S COMPLE- MENT
	ASCII/HEX convert	ASC	ASCII CON- VERT	HEX	ASCII TO HEX		

Classifica- tion	Sub-class	Mnemonic	Instruction	Mnemonic	Instruction	Mnemonic	Instruction
Logic instructions	Logical AND/OR	ANDW	LOGICAL AND	ANDL	DOUBLE LOGICAL AND	ORW	LOGICAL OR
		ORWL	DOUBLE LOGICAL OR	XORW	EXCLUSIVE OR	XORL	DOUBLE EXCLUSIVE OR
		XNRW	EXCLUSIVE NOR	XNRL	DOUBLE EXCLUSIVE NOR		
	Complement	СОМ	COMPLE- MENT	COML	DOUBLE COMPLE- MENT		
Special math instructions		APR	ARITHMETIC PROCESS	BCNT	BIT COUNTER	AXIS	VIRTUAL AXIS
Floating- point math	Floating point/ binary convert	FIX	FLOATING TO 16-BIT	FIXL	FLOATING TO 32-BIT	FLT	16-BIT TO FLOATING
instructions		FLTL	32-BIT TO FLOATING				
	Floating- point basic math	+F	FLOATING- POINT ADD	-F	FLOATING- POINT SUBTRACT	/F	FLOATING- POINT DIVIDE
		*F	FLOATING- POINT MULTIPLY				
	Floating- point trigonometric	RAD	DEGREES TO RADIANS	DEG	RADIANS TO DEGREES	SIN	SINE
		COS	COSINE	TAN	TANGENT	ASIN	ARC SINE
		ACOS	ARC COSINE	ATAN	ARC TAN- GENT		
	Floating- point math	SQRT	SQUARE ROOT	EXP	EXPONENT	LOG	LOGARITHM
		PWR	EXPONEN- TIAL POWER				
	Symbol comparison and conversion*	LD, AND, OR + =, <>, <, <=, >, >= + F	Symbol com- parison (sin- gle-precision floating point)				

Classifica- tion	Sub-class	Mnemonic	Instruction	Mnemonic	Instruction	Mnemonic	Instruction
Double-pre- cision float- ing- point	Floating point/ binary convert	FIXD	DOUBLE FLOATING TO 16-BIT	FIXLD	DOUBLE FLOATING TO 32-BIT	DBL	16-BIT TO DOUBLE FLOATING
instruc- tions*		DBLL	32-BIT TO DOUBLE FLOATING				
	Floating- point basic math	+D	DOUBLE FLOATING- POINT ADD	-D	DOUBLE FLOATING- POINT SUBTRACT	/D	DOUBLE FLOATING- POINT DIVIDE
		*D	DOUBLE FLOATING- POINT MULTIPLY				
	Floating- point trigonometric	RADD	DOUBLE DEGREES TO RADIANS	DEGD	DOUBLE RADIANS TO DEGREES	SIND	DOUBLE SINE
		COSD	DOUBLE COSINE	TAND	DOUBLE TANGENT	ASIND	DOUBLE ARC SINE
		ACOSD	DOUBLE ARC COSINE	ATAND	DOUBLE ARC TANGENT		
	Floating- point math	SQRTD	DOUBLE SQUARE ROOT	EXPD	DOUBLE EXPONENT	LOGD	DOUBLE LOGARITHM
		PWRD	DOUBLE EXPONEN- TIAL POWER				
	Symbol comparison	LD, AND, OR + =, <>, <, <=, >, >= + D	Symbol com- parison (dou- ble-precision floating point)				
Table data processing instructions	Record-to-word processing	MAX	FIND MAXIMUM	MIN	FIND MINIMUM		
Data control instructions		SCL	SCALING	SCL2	SCALING 2	SCL3	SCALING 3
Subroutines instructions		SBS	SUBROU- TINE CALL	MCRO	MACRO	SBN	SUBROU- TINE ENTRY
instructions		RET	SUBROU- TINE RETURN	JSB	JUMP TO SUBROUTINE		
Interrupt control instructions		MSKS	SET INTERRUPT MASK	MSKR	READ INTER- RUPT MASK	CLI	CLEAR INTERRUPT
		DI	DISABLE INTERRUPTS	EI	ENABLE INTERRUPTS	STIM	INTERVAL TIMER
High-speed counter/ pulse out-		INI	MODE CON- TROL	PRV	HIGH-SPEED COUNTER PV READ		
put instruc- tions		CTBL	COMPARI- SON TABLE LOAD	SPED	SPEED OUT- PUT	PULS	SET PULSES
		PLS2	PULSE OUT- PUT	ACC	ACCELERA- TION CON- TROL		
Step instructions		STEP	STEP DEFINE	SNXT	STEP START		
I/O Refresh instructions		IORF	I/O REFRESH				
Serial com- munica- tions instructions		TXD	TRANSMIT	RXD	RECEIVE	STUP	CHANGE SERIAL PORT SETUP
Debugging instructions		TRSM	TRACE MEMORY SAMPLING				

Classifica- tion	Sub-class	Mnemonic	Instruction	Mnemonic	Instruction	Mnemonic	Instruction
Failure diagnosis instructions		FAL	FAILURE ALARM	FALS	SEVERE FAILURE ALARM		
Other instructions		STC	SET CARRY	CLC	CLEAR CARRY		
Block program-	Define block pro- gram area	BPRG	BLOCK PRO- GRAM BEGIN	BEND	BLOCK PRO- GRAM END	-	
ming instructions	IF branch processing	IF bit_address	CONDI- TIONAL BLOCK BRANCHING	IF NOT bit_address	CONDI- TIONAL BLOCK BRANCHING (NOT)	ELSE	CONDI- TIONAL BLOCK BRANCHING (ELSE)
		IEND	CONDI- TIONAL BLOCK BRANCHING END				
Special Function Block Instructions		GETID	GET VARI- ABLE ID				

## 2-2 Instruction Functions

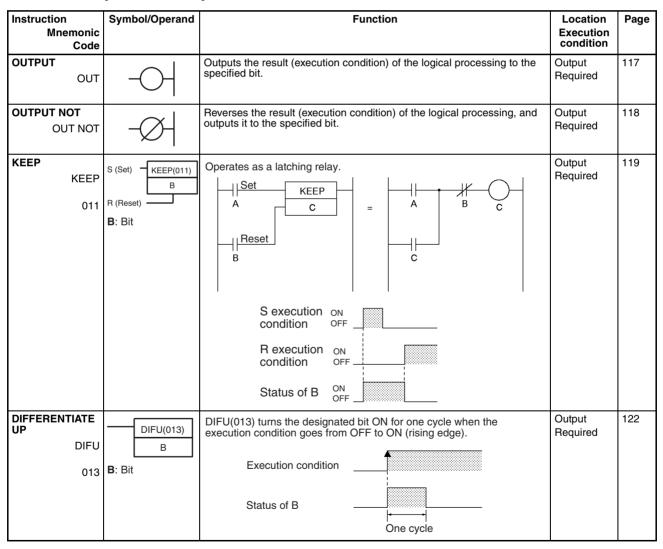
## 2-2-1 Sequence Input Instructions

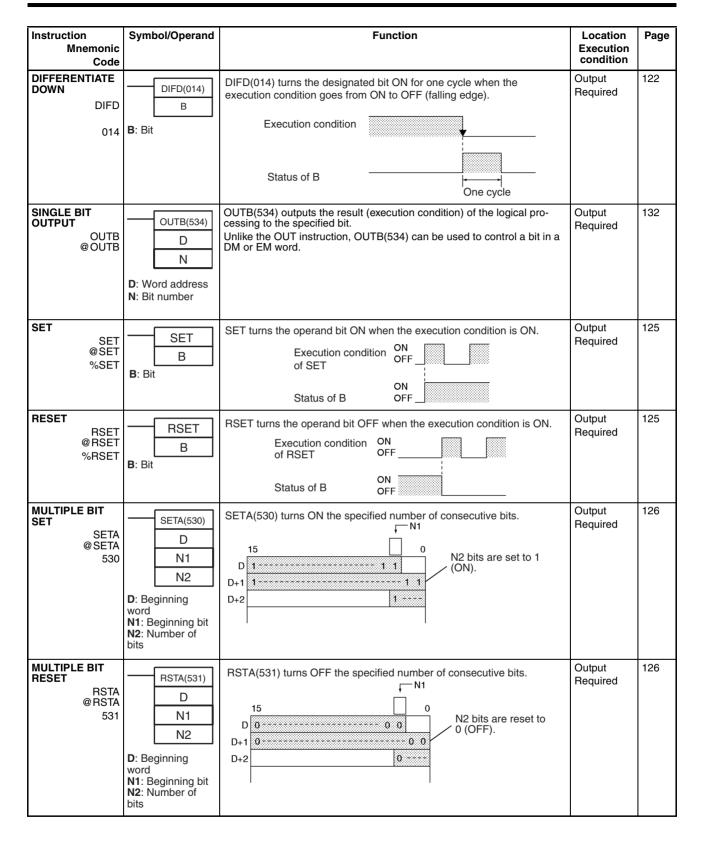
Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
LOAD  LD  @ LD  % LD	Bus bar  Starting point of block	Indicates a logical start and creates an ON/OFF execution condition based on the ON/OFF status of the specified operand bit.	Start of logic Not required	95
LOAD NOT  LD NOT  @ LD NOT  %LD NOT	Starting point of block	Indicates a logical start and creates an ON/OFF execution condition based on the reverse of the ON/OFF status of the specified operand bit.	Start of logic Not required	97
AND AND @ AND %AND	$\dashv$ $\vdash$	Takes a logical AND of the status of the specified operand bit and the current execution condition.	Continues on rung Required	99
AND NOT  AND NOT  @ AND NOT  % AND NOT	#	Reverses the status of the specified operand bit and takes a logical AND with the current execution condition.	Continues on rung Required	101
OR OR @OR %OR	Bus bar	Takes a logical OR of the ON/OFF status of the specified operand bit and the current execution condition.	Continues on rung Required	102
OR NOT OR NOT @OR NOT %OR NOT	Bus bar	Reverses the status of the specified bit and takes a logical OR with the current execution condition	Continues on rung Required	104
AND LOAD AND LD	Logic block Logic block	Takes a logical AND between logic blocks.  LD to Logic block A  LD Logic block B  to  AND LD Serial connection between logic block A and logic block B.	Continues on rung Required	105

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
OR LOAD OR LD	Logic block Logic block	Takes a logical OR between logic blocks.  LD to Logic block A  LD Logic block B to  OR LD Parallel connection between logic block A and logic block B.	Continues on rung Required	107
NOT NOT 520		Reverses the execution condition.	Continues on rung Required	111
CONDITION ON UP 521	UP(521)	UP(521) turns ON the execution condition for one cycle when the execution condition goes from OFF to ON.	Continues on rung Required	112
CONDITION OFF DOWN 522	DOWN(522)	DOWN(522) turns ON the execution condition for one cycle when the execution condition goes from ON to OFF.	Continues on rung Required	112
BIT TEST  LD TST  350	TST(350) S N S: Source word N: Bit number	LD TST(350), AND TST(350), and OR TST(350) are used in the program like LD, AND, and OR; the execution condition is ON when the specified bit in the specified word is ON and OFF when the bit is OFF.	Continues on rung Not required	113
BIT TEST LD TSTN 351	TSTN(351) S N S: Source word N: Bit number	LD TSTN(351), AND TSTN(351), and OR TSTN(351) are used in the program like LD NOT, AND NOT, and OR NOT; the execution condition is OFF when the specified bit in the specified word is ON and ON when the bit is OFF.	Continues on rung Not required	113
BIT TEST AND TST 350	AND TST(350) S N S: Source word N: Bit number	LD TST(350), AND TST(350), and OR TST(350) are used in the program like LD, AND, and OR; the execution condition is ON when the specified bit in the specified word is ON and OFF when the bit is OFF.	Continues on rung Required	113
BIT TEST AND TSTN 351	AND TSTN(351) S N S: Source word N: Bit number	LD TSTN(351), AND TSTN(351), and OR TSTN(351) are used in the program like LD NOT, AND NOT, and OR NOT; the execution condition is OFF when the specified bit in the specified word is ON and ON when the bit is OFF.	Continues on rung Required	113

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
OR TST 350	TST(350) S N S: Source word N: Bit number	LD TST(350), AND TST(350), and OR TST(350) are used in the program like LD, AND, and OR; the execution condition is ON when the specified bit in the specified word is ON and OFF when the bit is OFF.	Continues on rung Required	113
OR TSTN 351	TSTN(351) S N S: Source word N: Bit number	LD TSTN(351), AND TSTN(351), and OR TSTN(351) are used in the program like LD NOT, AND NOT, and OR NOT; the execution condition is OFF when the specified bit in the specified word is ON and ON when the bit is OFF.	Continues on rung Required	113

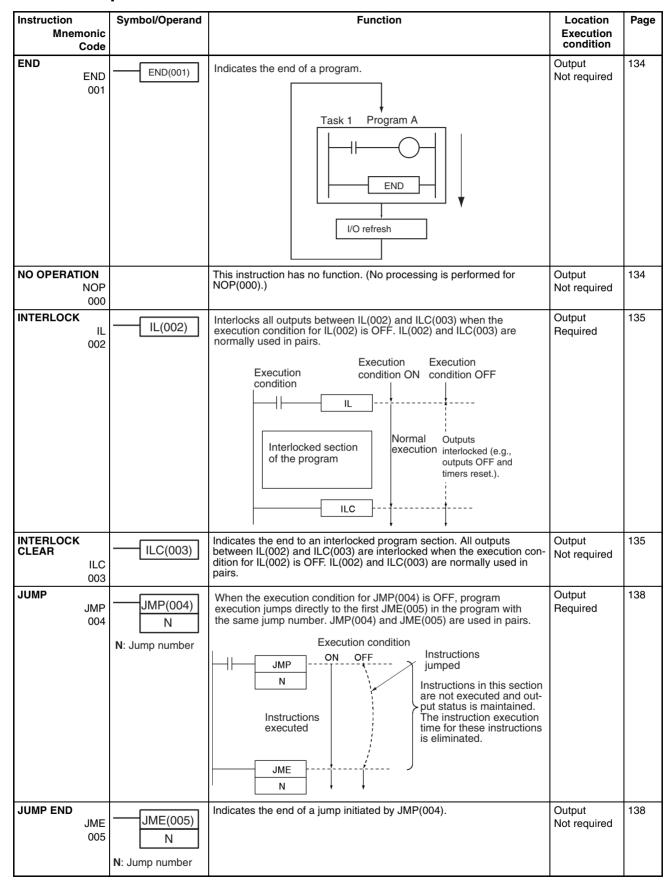
### 2-2-2 Sequence Output Instructions

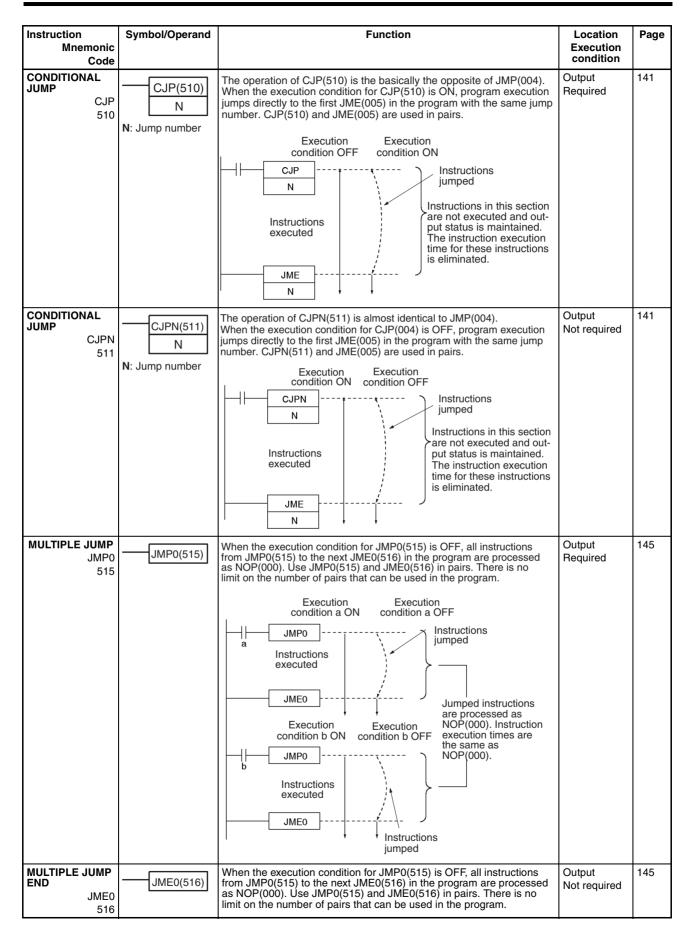


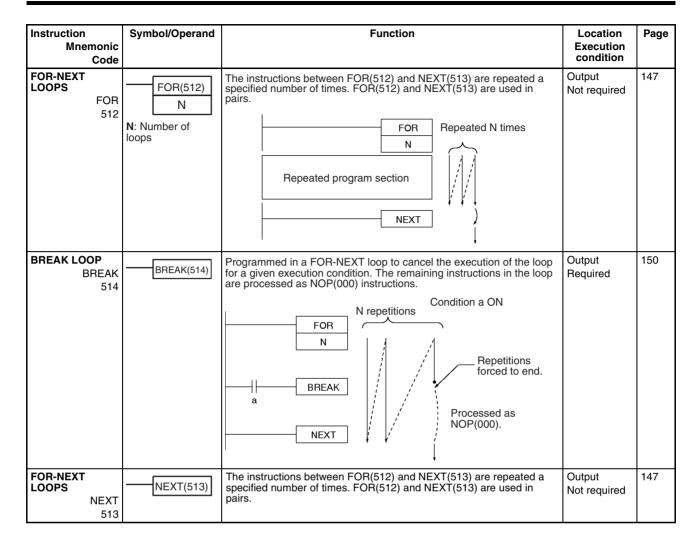


Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
SINGLE BIT SET SETB @ SETB	SETB(532)  D  N  D: Word address N: Bit number	SETB(532) turns ON the specified bit in the specified word when the execution condition is ON.  Unlike the SET instruction, SETB(532) can be used to set a bit in a DM or EM word.	Output Required	129
SINGLE BIT RESET RSTB @ RSTB	RSTB(533) D N D: Word address N: Bit number	RSTB(533) turns OFF the specified bit in the specified word when the execution condition is ON.  Unlike the RSET instruction, RSTB(533) can be used to reset a bit in a DM or EM word.	Output Required	129

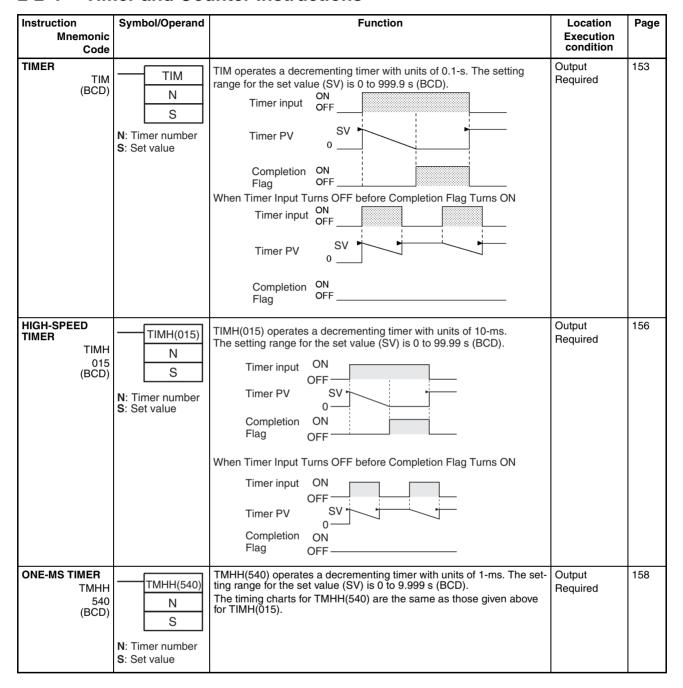
#### 2-2-3 Sequence Control Instructions

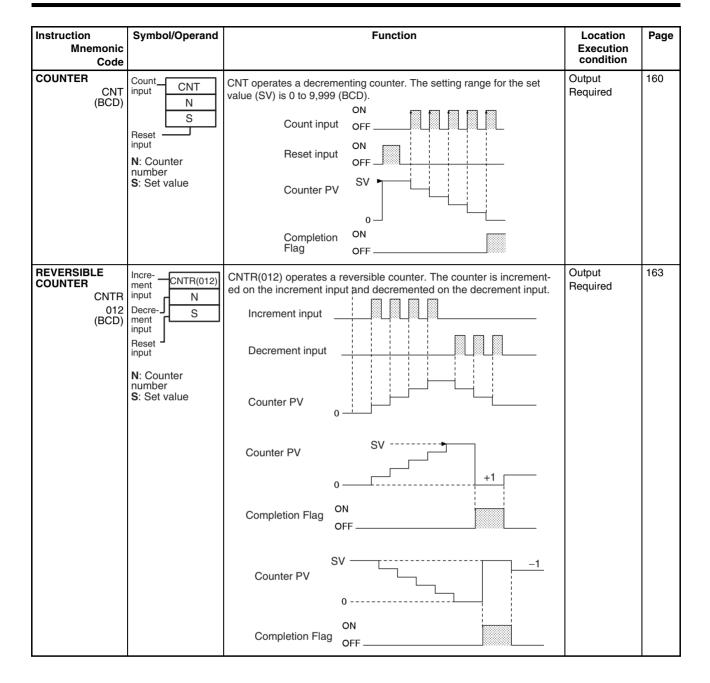






#### 2-2-4 Timer and Counter Instructions

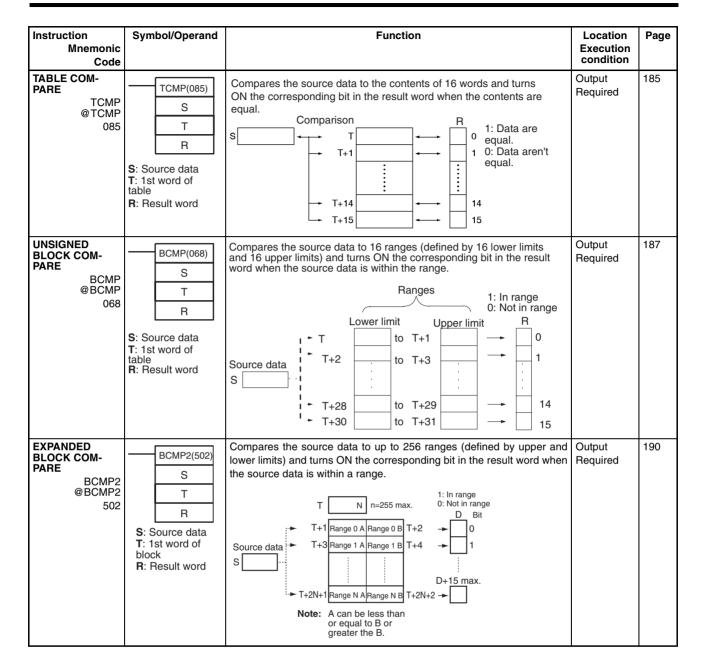




## 2-2-5 Comparison Instructions

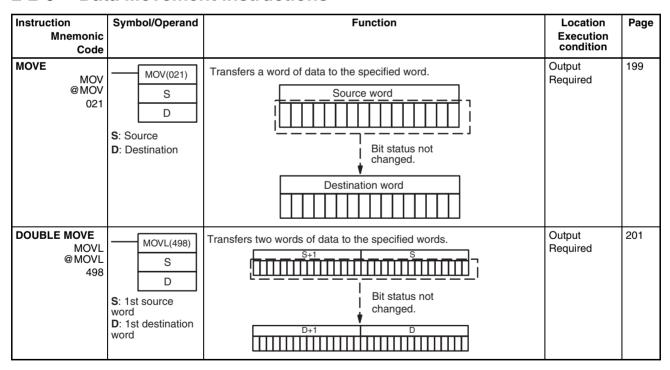
Instruction Mnemonic	Symbol/Operand	Function	Location Execution condition	Page
Code  Symbol Comparison (Unsigned)  LD, AND, OR + =,	Symbol & options S1 S2 S1: Comparison data 1 S2: Comparison data 2	Symbol comparison instructions (unsigned) compare two values (constants and/or the contents of specified words) in 16-bit binary data and create an ON execution condition when the comparison condition is true. There are three types of symbol comparison instructions, LD (LOAD), AND, and OR.  LD ON execution condition when comparison result is true.  ON execution condition when comparison result is true.  ON execution condition when comparison result is true.  ON execution condition when comparison result is true.	LD: Start of logic, Not required AND, OR: Continues on rung, Required	167
Symbol Comparison (Double-word, unsigned) LD, AND, OR + =, <>, <, <=, >, >= + L 301 (=) 306 (<>) 311 (<) 316 (<=) 321 (>) 326 (>=)	S <sub>1</sub> : Comparison data 1 S <sub>2</sub> : Comparison data 2	Symbol comparison instructions (double-word, unsigned) compare two values (constants and/or the contents of specified double-word data) in unsigned 32-bit binary data and create an ON execution condition when the comparison condition is true. There are three types of symbol comparison instructions, LD (LOAD), AND, and OR.	LD: Start of logic, Not required AND, OR: Continues on rung, Required	167
Symbol Comparison (Signed)  LD, AND, OR + =,	S <sub>1</sub> : Comparison data 1 S <sub>2</sub> : Comparison data 2	Symbol comparison instructions (signed) compare two values (constants and/or the contents of specified words) in signed 16-bit binary (4-digit hexadecimal) and create an ON execution condition when the comparison condition is true. There are three types of symbol comparison instructions, LD (LOAD), AND, and OR.	LD: Start of logic, Not required AND, OR: Continues on rung, Required	167

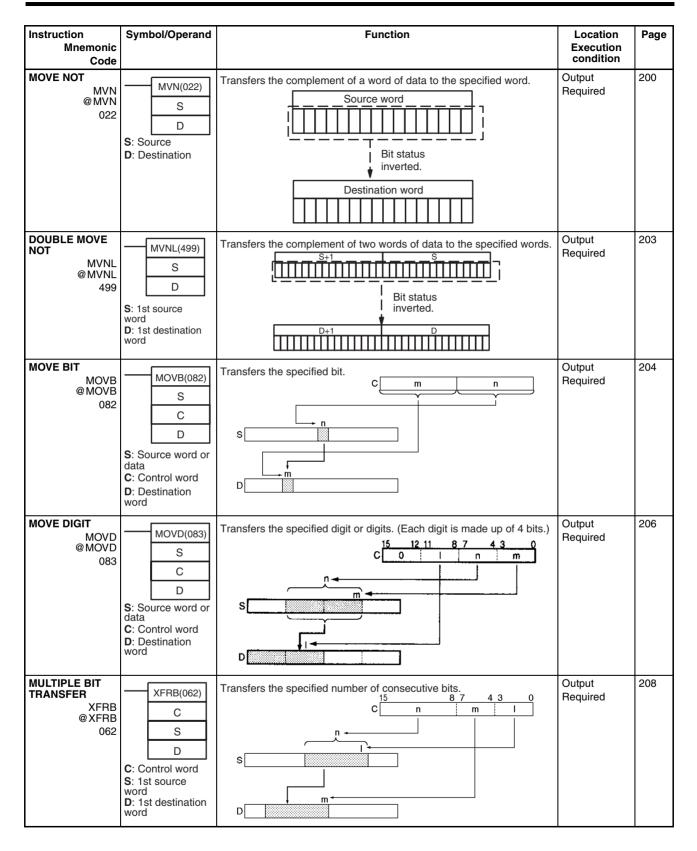
Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
Symbol Comparison (Doubleword, signed)  LD, AND, OR + =,	S <sub>1</sub> : Comparison data 1 S <sub>2</sub> : Comparison data 2	Symbol comparison instructions (double-word, signed) compare two values (constants and/or the contents of specified double-word data) in signed 32-bit binary (8-digit hexadecimal) and create an ON execution condition when the comparison condition is true. There are three types of symbol comparison instructions, LD (LOAD), AND, and OR.	LD: Start of logic, Not required AND, OR: Continues on rung, Required	167
UNSIGNED COM- PARE  CMP 020	S1: Comparison data 1 S2: Comparison data 2	Compares two unsigned binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.  Unsigned binary comparison  S1  Arithmetic Flags (>, >=, =, <=, <, >)	Output Required	172
DOUBLE UNSIGNED COMPARE CMPL 060	CMPL(060) S <sub>1</sub> S <sub>2</sub> S1: Comparison data 1 S2: Comparison data 2	Compares two double unsigned binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.  Unsigned binary comparison  S1+1  S1  Arithmetic Flags (>, >=, =, <=, <, >)	Output Required	175
SIGNED BINARY COMPARE CPS 114	CPS(114) S <sub>1</sub> S <sub>2</sub> S1: Comparison data 1 S2: Comparison data 2	Compares two signed binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.  Signed binary comparison  S1  Arithmetic Flags (>, >=, =, <=, <, >>)	Output Required	177
DOUBLE SIGNED BINARY COMPARE CPSL 115	CPSL(115) S <sub>1</sub> S <sub>2</sub> S1: Comparison data 1 S2: Comparison data 2	Compares two double signed binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.  Signed binary comparison  S1+1  S1  Arithmetic Flags (>, >=, =, <=, <, <>)	Output Required	180
MULTIPLE COM- PARE  MCMP @MCMP 019	MCMP(019)  S <sub>1</sub> S <sub>2</sub> R  S1: 1st word of set 1  S2: 1st word of set 2  R: Result word	Compares 16 consecutive words with another 16 consecutive words and turns ON the corresponding bit in the result word where the contents of the words <b>are not</b> equal.  Comparison  S1  S1  S1+1  S2+1  S2+1  S2+1  S2+1  S2+14  S1+15  S2+14  S2+15  T1  14  S2+15  T5	Output Required	182

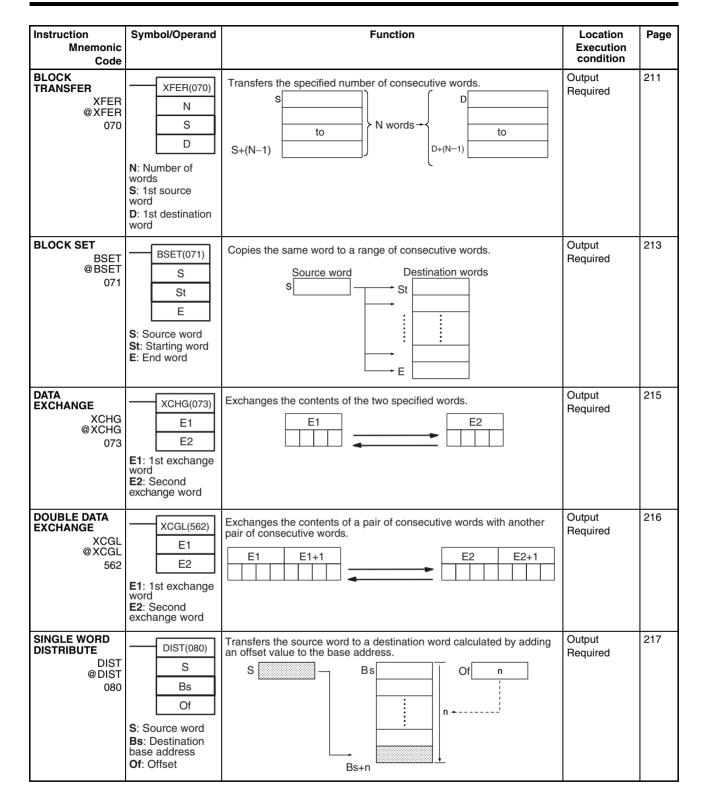


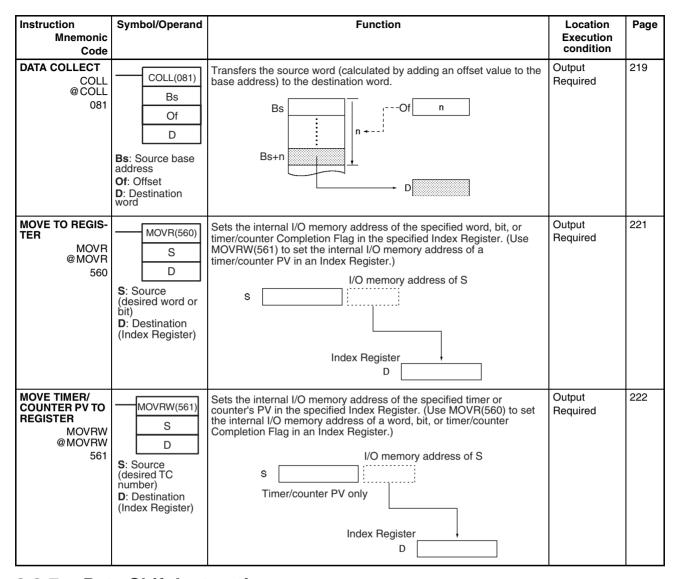
Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
AREA RANGE COMPARE  ZCP 088	ZCP(088) CD LL UL CD: Compare data (1 word) LL: Lower limit of range UL: Upper limit of range	Compares the 16-bit unsigned binary value in CD (word contents or constant) to the range defined by LL and UL and outputs the results to the Arithmetic Flags in the Auxiliary Area.	Output Required	193
DOUBLE AREA RANGE COM- PARE  ZCPL 116	ZCPL(116) CD LL UL CD: Compare data (2 words) LL: Lower limit of range UL: Upper limit of range	Compares the 32-bit unsigned binary value in CD and CD+1 (word contents or constant) to the range defined by LL and UL and outputs the results to the Arithmetic Flags in the Auxiliary Area.	Output Required	196

### 2-2-6 Data Movement Instructions



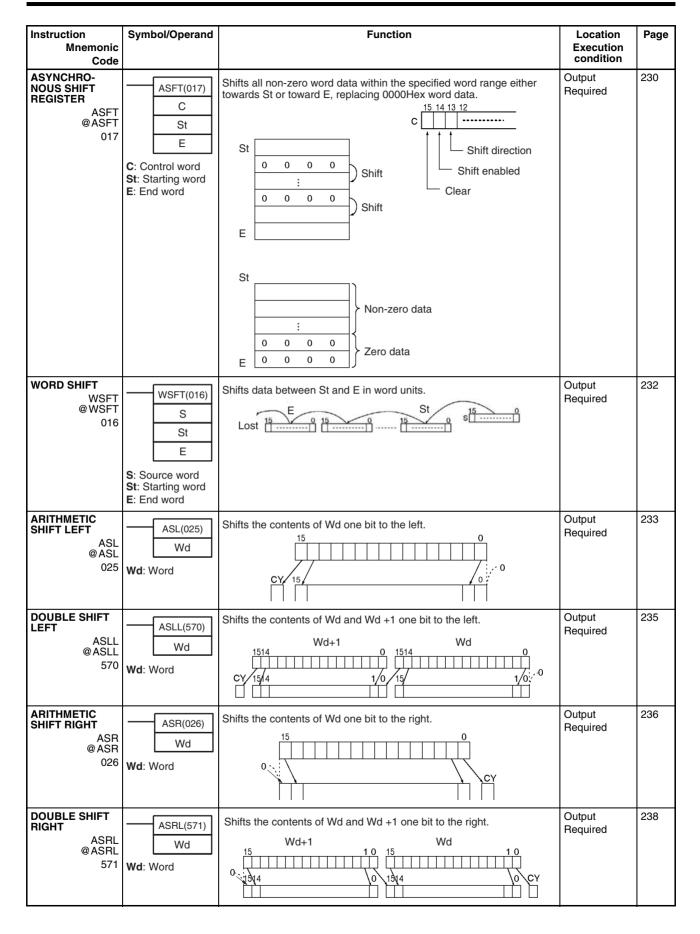




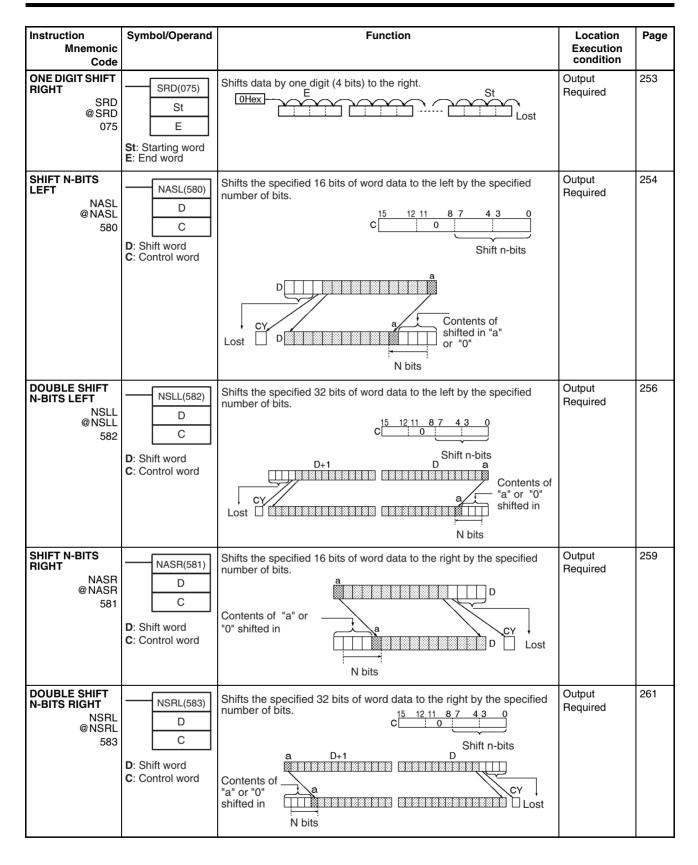


#### 2-2-7 Data Shift Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
SHIFT REGISTER SFT 010	input - SFT(010)	Operates a shift register.    Status of data input for each shift input	Output Required	225
REVERSIBLE SHIFT REGISTER SFTR @SFTR 084	SFTR(084) C St E C: Control word St: Starting word E: End word	Creates a shift register that shifts data to either the right or the left.  CY 15 E 0 15 0 15 St 0 Data input  Data 15 E 0 15 0 15 St 0 CY  Input 15 St 0 CY	Output Required	227



Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
ROTATE LEFT ROL @ ROL 027	ROL(027) Wd Wd: Word	Shifts all Wd bits one bit to the left including the Carry Flag (CY).  CY 15 14 1 0	Output Required	239
DOUBLE ROTATE LEFT ROLL @ ROLL 572	ROLL(572) Wd Wd: Word	Shifts all Wd and Wd + 1 bits one bit to the left including the Carry Flag (CY).  CY 1514  1 0 1514  Vd  1 0	Output Required	241
ROTATE LEFT WITHOUT CARRY RLNC @RLNC 574	RLNC(574) Wd Wd: Word	Shifts all Wd bits one bit to the left not including the Carry Flag (CY).  CY 15 14 Wd 1 0	Output Required	245
DOUBLE ROTATE LEFT WITHOUT CARRY  RLNL @ RLNL 576	RLNL(576) Wd Wd: Word	Shifts all Wd and Wd +1 bits one bit to the left not including the Carry Flag (CY).  CY 1514 Wd+1 0 1514 Wd 1 0	Output Required	247
ROTATE RIGHT ROR @ ROR 028	ROR(028) Wd Wd: Word	Shifts all Wd bits one bit to the right including the Carry Flag (CY).  15 14 Wd 10 CY D Wd 10 CY	Output Required	242
DOUBLE ROTATE RIGHT RORL @ RORL 573	RORL(573) Wd: Word	Shifts all Wd and Wd +1 bits one bit to the right including the Carry Flag (CY).  1514 Wd+1 0 1514 Wd 0 CY	Output Required	244
ROTATE RIGHT WITHOUT CARRY RRNC @RRNC 575	RRNC(575) Wd Wd: Word	Shifts all Wd bits one bit to the right not including the Carry Flag (CY). The contents of the rightmost bit of Wd shifts to the leftmost bit and to the Carry Flag (CY).	Output Required	248
DOUBLE ROTATE RIGHT WITHOUT CARRY RRNL @RRNL 577	RRNL(577) Wd Wd: Word	Shifts all Wd and Wd +1 bits one bit to the right not including the Carry Flag (CY). The contents of the rightmost bit of Wd +1 is shifted to the leftmost bit of Wd, and to the Carry Flag (CY).  Wd+1  0  15  Wd  CY	Output Required	250
ONE DIGIT SHIFT LEFT SLD @ SLD 074	SLD(074) St E St: Starting word E: End word	Shifts data by one digit (4 bits) to the left.  St OHex	Output Required	251



### 2-2-8 Increment/Decrement Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
INCREMENT BINARY  ++ @++ 590	++(590) Wd <b>Wd</b> : Word	Increments the 4-digit hexadecimal content of the specified word by 1.  Wd +1 Wd  Wd	Output Required	265
DOUBLE INCRE- MENT BINARY  ++L @++L 591	++L(591) Wd Wd: Word	Increments the 8-digit hexadecimal content of the specified words by 1.  Wd+1 Wd +1 Wd Wd+1 Wd	Output Required	267
DECREMENT BINARY @ 592	(592) Wd <b>Wd</b> : Word	Decrements the 4-digit hexadecimal content of the specified word by 1.  Wd -1 Wd	Output Required	269
DOUBLE DEC- REMENT BINARY  L @L 593	L(593) Wd Wd: 1st word	Decrements the 8-digit hexadecimal content of the specified words by 1.  Wd+1 Wd -1 Wd+1 Wd	Output Required	271
INCREMENT BCD ++B @++B 594	++B(594) Wd: Word	Increments the 4-digit BCD content of the specified word by 1.  Wd +1 Wd	Output Required	273
DOUBLE INCRE- MENT BCD ++BL @++BL 595	++BL(595) Wd Wd: 1st word	Increments the 8-digit BCD content of the specified words by 1.  Wd+1 Wd +1 Wd Wd+1 Wd	Output Required	275
DECREMENT BCDB @B 596	B(596) Wd Wd: Word	Decrements the 4-digit BCD content of the specified word by 1.  Wd —1 — Wd	Output Required	277
DOUBLE DEC- REMENT BCD BL @BL 597	BL(597) Wd Wd: 1st word	Decrements the 8-digit BCD content of the specified words by 1.  Wd+1 Wd −1 ── Wd+1 Wd	Output Required	279

## 2-2-9 Symbol Math Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
SIGNED BINARY ADD WITHOUT CARRY + @+ 400	+(400) Au Ad R  Au: Augend word Ad: Addend word R: Result word	Adds 4-digit (single-word) hexadecimal data and/or constants.  Au (Signed binary)  + Ad (Signed binary)  CY will turn ON when there is a carry.  (Signed binary)	Output Required	282
DOUBLE SIGNED BINARY ADD WITHOUT CARRY +L @+L 401	+L(401) Au Ad R  Au: 1st augend word Ad: 1st addend word R: 1st result word	Adds 8-digit (double-word) hexadecimal data and/or constants.  Au+1 Au (Signed binary)  + Ad+1 Ad (Signed binary)  CY will turn ON when there is a carry.	Output Required	283
SIGNED BINARY ADD WITH CARRY +C @+C 402	+C(402) Au Ad R Au: Augend word Ad: Addend word R: Result word	Adds 4-digit (single-word) hexadecimal data and/or constants with the Carry Flag (CY).  Au (Signed binary)  Ad (Signed binary)  + CY  CY will turn ON when there is a carry.	Output Required	285
DOUBLE SIGNED BINARY ADD WITH CARRY +CL @+CL 403	+CL(403) Au Ad R Au: 1st augend word Ad: 1st addend word R: 1st result word	Adds 8-digit (double-word) hexadecimal data and/or constants with the Carry Flag (CY).  Au+1 Au (Signed binary)  Ad+1 Ad (Signed binary)  + CY Will turn ON when there is a CY R+1 R (Signed binary)	Output Required	287
BCD ADD WITH- OUT CARRY +B @+B 404	+B(404) Au Ad R  Au: Augend word Ad: Addend word R: Result word	Adds 4-digit (single-word) BCD data and/or constants.  Au (BCD)  + Ad (BCD)  CY will turn ON when there is a carry.	Output Required	289

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
DOUBLE BCD ADD WITHOUT CARRY +BL @+BL 405	+BL(405) Au Ad R  Au: 1st augend word Ad: 1st addend word R: 1st result word	Adds 8-digit (double-word) BCD data and/or constants.  Au+1 Au (BCD)  + Ad+1 Ad (BCD)  CY will turn ON when there is a carry.	Output Required	290
BCD ADD WITH CARRY +BC @+BC 406	+BC(406) Au Ad R Au: Augend word Ad: Addend word R: Result word	Adds 4-digit (single-word) BCD data and/or constants with the Carry Flag (CY).  Au (BCD)  Ad (BCD)  CY will turn ON when there is a carry.  CY R (BCD)	Output Required	292
DOUBLE BCD ADD WITH CARRY +BCL @+BCL 407	+BCL(407) Au Ad R  Au: 1st augend word Ad: 1st addend word word R: 1st result word	Adds 8-digit (double-word) BCD data and/or constants with the Carry Flag (CY).  Au+1 Au (BCD) Ad+1 Ad (BCD)  + CY Will turn ON when there CY R+1 R (BCD)	Output Required	293
SIGNED BINARY SUBTRACT WITHOUT CARRY	——————————————————————————————————————	Subtracts 4-digit (single-word) hexadecimal data and/or constants.  Mi (Signed binary)  - Su (Signed binary)  CY will turn ON when there is a borrow.	Output Required	295
DOUBLE SIGNED BINARY SUBTRACT WITHOUT CARRY  -L @-L 411	- L(411) Mi Su R  Mi: Minuend word Su: Subtrahend word R: Result word	Subtracts 8-digit (double-word) hexadecimal data and/or constants.  Mi+1 Mi (Signed binary)  - Su+1 Su (Signed binary)  CY will turn ON when there is a borrow.	Output Required	296

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
SIGNED BINARY SUBTRACT WITH CARRY  -C @-C 412	—C(412)  Mi Su R  Mi: Minuend word Su: Subtrahend word R: Result word	Subtracts 4-digit (single-word) hexadecimal data and/or constants with the Carry Flag (CY).  Mi (Signed binary)  Su (Signed binary)  - CY  CY will turn ON when there is a borrow.  R (Signed binary)	Output Required	300
DOUBLE SIGNED BINARY WITH CARRY -CL @-CL 413	—CL(413)  Mi Su R  Mi: Minuend word Su: Subtrahend word R: Result word	Subtracts 8-digit (double-word) hexadecimal data and/or constants with the Carry Flag (CY).  Mi+1  Mi  (Signed binary)  Su+1  CY  CY will turn ON when there is a borrow.  CY  R+1  R  (Signed binary)	Output Required	302
BCD SUBTRACT WITHOUT CARRY  -B @-B 414	—B(414)  Mi Su R  Mi: Minuend word Su: Subtrahend word Word R: Result word	Subtracts 4-digit (single-word) BCD data and/or constants.  Mi (BCD)  - Su (BCD)  CY will turn ON when there is a carry.	Output Required	304
DOUBLE BCD SUBTRACT WITHOUT CARRY  -BL @-BL 415	—BL(415)  Mi Su R  Mi: 1st minuend word Su: 1st subtrahend word R: 1st result word	Subtracts 8-digit (double-word) BCD data and/or constants.  Mi +1 Mi (BCD)  - Su+1 Su (BCD)  CY will turn ON when there is a borrow.	Output Required	306
BCD SUBTRACT WITH CARRY  -BC @-BC 416	BC(416) Mi Su R Mi: Minuend word Su: Subtrahend word R: Result word	Subtracts 4-digit (single-word) BCD data and/or constants with the Carry Flag (CY).  Mi (BCD)  Su (BCD)  CY will turn ON when there is a borrow.	Output Required	309

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
DOUBLE BCD SUBTRACT WITH CARRY  -BCL @-BCL 417	—BCL(417)  Mi Su R  Mi: 1st minuend word Su: 1st subtrahend word R: 1st result word	Subtracts 8-digit (double-word) BCD data and/or constants with the Carry Flag (CY).  Mi +1  Mi  (BCD)  Su+1  Su  (BCD)  CY  Will turn ON CY  when there is a CY  B+1  R  (BCD)	Output Required	310
SIGNED BINARY MULTIPLY  * @ * 420	*(420)  Md  Mr  R  Md: Multiplicand word Mr: Multiplier word R: Result word	Multiplies 4-digit signed hexadecimal data and/or constants.  Md (Signed binary)  × Mr (Signed binary)  R +1 R (Signed binary)	Output Required	312
DOUBLE SIGNED BINARY MULTIPLY  *L @*L 421	*L(421)  Md  Mr  R  Md: 1st multiplicand word Mr: 1st multiplier word R: 1st result word	Multiplies 8-digit signed hexadecimal data and/or constants.  Md + 1	Output Required	314
UNSIGNED BINARY MULTIPLY  *U @*U 422	*U(422)  Md  Mr  R  Md: Multiplicand word Mr: Multiplier word R: Result word	Multiplies 4-digit unsigned hexadecimal data and/or constants.  Md (Unsigned binary)  × Mr (Unsigned binary)  R+1 R (Unsigned binary)	Output Required	315
DOUBLE UNSIGNED BINARY MULTIPLY *UL @*UL 423	*UL(423)  Md  Mr  R  Md: 1st multiplicand word Mr: 1st multiplier word R: 1st result word	Multiplies 8-digit unsigned hexadecimal data and/or constants.  Md + 1	Output Required	317

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
BCD MULTIPLY  *B @*B 424	*B(424) Md Mr R  Md: Multiplicand word Mr: Multiplier word R: Result word	Multiplies 4-digit (single-word) BCD data and/or constants.  Md (BCD)  × Mr (BCD)  R+1 R (BCD)	Output Required	318
DOUBLE BCD MULTIPLY *BL @*BL 425	*BL(425) Md Mr R  Md: 1st multiplicand word Mr: 1st multiplier word R: 1st result word	Multiplies 8-digit (double-word) BCD data and/or constants.  Md + 1	Output Required	320
SIGNED BINARY DIVIDE // @// 430	/(430) Dd Dr R  Dd: Dividend word Dr: Divisor word R: Result word	Divides 4-digit (single-word) signed hexadecimal data and/or constants.  Dd (Signed binary)  ÷ Dr (Signed binary)  R+1 R (Signed binary)  Remainder Quotient	Output Required	321
DOUBLE SIGNED BINARY DIVIDE /L @/L 431	/L(431) Dd Dr R  Dd: 1st dividend word Dr: 1st divisor word R: 1st result word	Divides 8-digit (double-word) signed hexadecimal data and/or constants.	Output Required	323
UNSIGNED BINARY DIVIDE /U @/U 432	Dd: Dividend word Dr: Divisor word R: Result word	Divides 4-digit (single-word) unsigned hexadecimal data and/or constants.  Dd (Unsigned binary)  + Dr (Unsigned binary)  R+1 R (Unsigned binary)  Remainder Quotient	Output Required	324

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
DOUBLE UNSIGNED	/UL(433)	Divides 8-digit (double-word) unsigned hexadecimal data and/or constants.	Output Required	326
BINARY DIVIDE /UL @/UL	Dd Dr	Dd + 1 Dd (Unsigned binary)		
433	R	÷ Dr + 1 Dr (Unsigned binary)		
	<b>Dd</b> : 1st dividend word <b>Dr</b> : 1st divisor	R+3 R+2 R+1 R (Unsigned binary)		
	word R: 1st result word	Remainder Quotient		
BCD DIVIDE /B @/B 434	/B(434) Dd Dr R  Dd: Dividend word Dr: Divisor word R: Result word	Divides 4-digit (single-word) BCD data and/or constants.  Dd (BCD)  + Dr (BCD)  R+1 R (BCD)  Remainder Quotient	Output Required	328
DOUBLE BCD DIVIDE /BL @/BL 435	/BL(435) Dd Dr R  Dd: 1st dividend word Dr: 1st divisor word R: 1st result word	Divides 8-digit (double-word) BCD data and/or constants.  Dd + 1	Output Required	329

## 2-2-10 Conversion Instructions

Instruction Mnemonic Code		Function	Location Execution condition	Page
BCD-TO-BINARY BIN @ BIN 023	S	Converts BCD data to binary data.  S (BCD) → R (BIN)	Output Required	331
DOUBLE BCD- TO-DOUBLE BINARY  BINL @ BINL 058	R	Converts 8-digit BCD data to 8-digit hexadecimal (32-bit binary) data.    S (BCD)   S+1 (BCD)    R  (BIN)  R+1  (BIN)	Output Required	333

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
BINARY-TO-BCD BCD @ BCD 024	BCD(024) S R S: Source word R: Result word	Converts a word of binary data to a word of BCD data.  s (BIN) → R (BCD)	Output Required	334
DOUBLE BINARY-TO- DOUBLE BCD BCDL @ BCDL 059	BCDL(059) S R S: 1st source word R: 1st result word	Converts 8-digit hexadecimal (32-bit binary) data to 8-digit BCD data.  S (BIN) S+1 (BIN) R (BCD) (BCD)	Output Required	336
2'S COMPLE- MENT NEG @NEG 160	NEG(160) S R S: Source word R: Result word	Calculates the 2's complement of a word of hexadecimal data.  2's complement (Complement + 1)  (S) → (R)	Output Required	338
DOUBLE 2'S COMPLEMENT NEGL @ NEGL 161	NEGL(161) S R S: 1st source word R: 1st result word	Calculates the 2's complement of two words of hexadecimal data.  2's complement (Complement + 1)  (S+1, S)	Output Required	339
ASCII CONVERT ASC @ ASC 086	ASC(086) S Di D S: Source word Di: Digit designator D: 1st destination word	Converts 4-bit hexadecimal digits in the source word into their 8-bit ASCII equivalents.  Di 0 1/0 n m  First digit to convert  M  S 1 2 3  HEX Number of digits (n+1) ASCII  Left (1) Right (0)  D 33  31 32	Output Required	341

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
ASCII TO HEX HEX @ HEX 162	HEX(162) S Di D S: 1st source word Di: Digit designator D: Destination word	Converts up to 4 bytes of ASCII data in the source word to their hexadecimal equivalents and writes these digits in the specified destination word.  Di 0 0/1 n m  First byte to convert  Left (1) Right (0)  S 33 32  S+1 34  ASCII  Number of digits (n+1)  First digit to write  HEX  D 4 3 2	Output Required	345
16-BIT TO 32-BIT SIGNED BINARY SIGN @ SIGN 600	SIGN(600) S R S: Source word R: 1st result word	Expands a 16-bit signed binary value to its 32-bit equivalent.  MSB S MSB = 0: 00000 Hex D+1 D D = Contents of S	Output Required	349

# 2-2-11 Logic Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
LOGICAL AND ANDW @ ANDW 034	ANDW(034)  I <sub>1</sub> I <sub>2</sub> R  I <sub>1</sub> : Input 1  I <sub>2</sub> : Input 2  R: Result word	Takes the logical AND of corresponding bits in single words of word data and/or constants. $\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Output Required	351
DOUBLE LOGICAL AND ANDL @ ANDL 610	ANDL(610)  I <sub>1</sub> I <sub>2</sub> R  I <sub>1</sub> : Input 1  I <sub>2</sub> : Input 2  R: Result word	Takes the logical AND of corresponding bits in double words of word data and/or constants. $ \begin{array}{c cccc} (I_1,I_1+1), & (I_2,I_2+1) \rightarrow (R,R+1) \\ \hline & I_1,I_1+1 & I_2,I_2+1 & R,R+1 \\ \hline & 1 & 1 & 1 \\ \hline & 1 & 0 & 0 \\ \hline & 0 & 1 & 0 \\ \hline & 0 & 0 & 0 \\ \hline \end{array} $	Output Required	353
LOGICAL OR ORW @ ORW 035	ORW(035)  I <sub>1</sub> I <sub>2</sub> R  I1: Input 1  I2: Input 2  R: Result word	Takes the logical OR of corresponding bits in single words of word data and/or constants. $\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Output Required	354
DOUBLE LOGICAL OR ORWL @ ORWL 611	ORWL(611)  I <sub>1</sub> I <sub>2</sub> R  I <sub>1</sub> : Input 1 I <sub>2</sub> : Input 2 R: Result word	Takes the logical OR of corresponding bits in double words of word data and/or constants.	Output Required	356
EXCLUSIVE OR XORW @ XORW 036	XORW(036)  I <sub>1</sub> I <sub>2</sub> R  I <sub>1</sub> : Input 1 I <sub>2</sub> : Input 2 R: Result word	Takes the logical exclusive OR of corresponding bits in single words of word data and/or constants. $I_1.T_2+T_1.I_2\rightarrow R$ $\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Output Required	358

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
DOUBLE EXCLU- SIVE OR  XORL @XORL 612	XORL(612)  I <sub>1</sub> I <sub>2</sub> R  I <sub>1</sub> : Input 1 I <sub>2</sub> : Input 2 R: Result word	Takes the logical exclusive OR of corresponding bits in double words of word data and/or constants. $ \begin{aligned} & \textbf{(I_1.I_1+1).} & \textbf{(I_2.I_2+1)} + \textbf{(I_1.I_1+1).} & \textbf{(I_2.I_2+1)} \rightarrow \textbf{(R,R+1)} \\ & \textbf{I_1.I_1+1} & \textbf{I_2.I_2+1} & \textbf{R,R+1} \\ & 1 & 1 & 0 \\ & 1 & 0 & 1 \\ & 0 & 1 & 1 \\ & 0 & 0 & 0 \end{aligned} $	Output Required	360
EXCLUSIVE NOR  XNRW  @ XNRW  037	XNRW(037)  I1  I2  R  I1: Input 1 I2: Input 2 R: Result word	Takes the logical exclusive NOR of corresponding single words of word data and/or constants. $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Output Required	362
DOUBLE EXCLU- SIVE NOR XNRL @ XNRL 613	$\begin{array}{c c} & \text{XNRL}(613) \\ & I_1 \\ & I_2 \\ & R \\ \\ I_1: \text{Input 1} \\ I_2: \text{Input 2} \\ & R: \text{1st result word} \\ \end{array}$	Takes the logical exclusive NOR of corresponding bits in double words of word data and/or constants.	Output Required	363
COMPLEMENT COM @COM 029	COM(029) Wd: Word	Turns OFF all ON bits and turns ON all OFF bits in Wd. $\overline{\text{Wd}} \rightarrow \text{Wd} : 1 \rightarrow 0 \text{ and } 0 \rightarrow 1$	Output Required	365
DOUBLE COM- PLEMENT  COML @COML 614	COML(614) Wd: Word	Turns OFF all ON bits and turns ON all OFF bits in Wd and Wd+1 $\overline{(Wd+1,Wd)} \rightarrow (Wd+1,Wd)$	Output Required	366

### 2-2-12 Special Math Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
ARITHMETIC PROCESS  APR @ APR 069	APR(069) C S R C: Control word S: Source data R: Result word	Calculates the sine, cosine, or a linear extrapolation of the source data. The linear extrapolation function allows any relationship between X and Y to be approximated with line segments.	Output Required	368
BIT COUNTER  BCNT  BCNT  067	BCNT(067)  N S R N: Number of words S: 1st source word R: Result word	Counts the total number of ON bits in the specified word(s).  S  N words Counts the number of ON bits.  Binary result	Output Required	375
VIRTUAL AXIS AXIS 981	M: Mode designation C: Processing cycle T: 1st settings table word	Produces a virtual pulse output for trapezoidal acceleration/deceleration.	Output Required	376

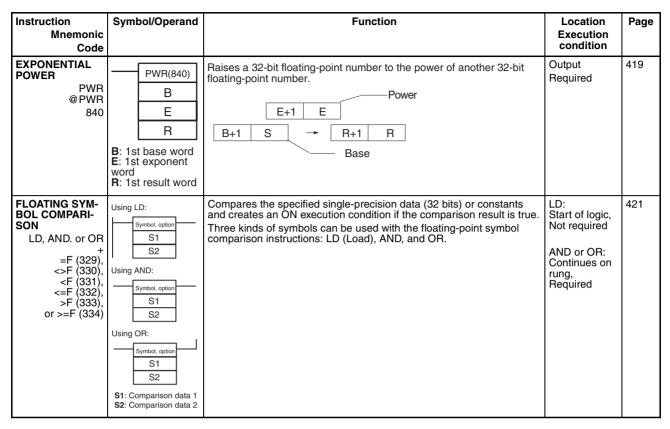
# 2-2-13 Floating-point Math Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
FLOATING TO 16-BIT FIX @ FIX 450	FIX(450) S R S: 1st source word R: Result word	Converts a 32-bit floating-point value to 16-bit signed binary data and places the result in the specified result word.  S+1 S Floating-point data (32 bits)  R Signed binary data (16 bits)	Output Required	386
FLOATING TO 32-BIT FIXL @ FIXL 451	FIXL(451) S R S: 1st source word R: 1st result word	Converts a 32-bit floating-point value to 32-bit signed binary data and places the result in the specified result words.  S+1 S Floating-point data (32 bits)  R+1 R Signed binary data (32 bits)	Output Required	388

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
16-BIT TO FLOATING FLT @ FLT 452	FLT(452) S R S: Source word R: 1st result word	Converts a 16-bit signed binary value to 32-bit floating-point data and places the result in the specified result words.  Signed binary data (16 bits)  R+1 R Floating-point data (32 bits)	Output Required	389
32-BIT TO FLOATING FLTL @ FLTL 453	FLTL(453) S R S: 1st source word R: 1st result word	Converts a 32-bit signed binary value to 32-bit floating-point data and places the result in the specified result words.  S+1 S Signed binary data (32 bits)  R+1 R Floating-point data (32 bits)	Output Required	390
FLOATING- POINT ADD +F @+F 454	+F(454) Au Ad R Au: 1st augend word AD: 1st addend word R: 1st result word	Adds two 32-bit floating-point numbers and places the result in the specified result words.  Au+1 Au Au Augend (floating-point data, 32 bits)  Addend (floating-point data, 32 bits)  R+1 R Result (floating-point data, 32 bits)	Output Required	392
FLOATING-POINT SUBTRACT  -F @-F 455	—F(455)  Mi Su R  Mi: 1st Minuend word Su: 1st Subtrahend word R: 1st result word	Subtracts one 32-bit floating-point number from another and places the result in the specified result words.  Mi+1  Mi  Minuend (floating-point data, 32 bits)  Subtrahend (floating-point data, 32 bits)  R+1  R  Result (floating-point data, 32 bits)	Output Required	394
FLOATING- POINT MULTIPLY  *F @*F 456	*F(456) Md Mr R  Md: 1st Multiplicand word Mr: 1st Multiplier word R: 1st result word	Multiplies two 32-bit floating-point numbers and places the result in the specified result words.  Md+1  Md  Multiplicand (floating-point data, 32 bits)  Mr+1  Mr  Multiplier (floating-point data, 32 bits)  R+1  R  Result (floating-point data, 32 bits)	Output Required	396

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
FLOATING- POINT DIVIDE	/F(457)	Divides one 32-bit floating-point number by another and places the result in the specified result words.	Output Required	397
@/F 457	Dd Dr	Dd+1 Dd Dividend (floating-point data, 32 bits)		
	Dd: 1st Dividend	Divisor (floating-point data, 32 bits)		
	word Dr: 1st Divisor word R: 1st result word	R+1 R Result (floating-point data, 32 bits)		
DEGREES TO RADIANS RAD @ RAD	RAD(458)	Converts a 32-bit floating-point number from degrees to radians and places the result in the specified result words.	Output Required	400
458	R	S+1 S Source (degrees, 32-bit floating-point data)		
	S: 1st source word R: 1st result word	R+1 R Result (radians, 32-bit floating-point data)		
RADIANS TO DEGREES DEG @DEG 459		Converts a 32-bit floating-point number from radians to degrees and places the result in the specified result words.  S+1 S Source (radians, 32-bit floating-point data)  R+1 R Result (degrees, 32-bit floating-point data)	Output Required	401
SINE SIN @ SIN 460	SIN(460) S R S: 1st source word R: 1st result word	Calculates the sine of a 32-bit floating-point number (in radians) and places the result in the specified result words.  SIN (S+1 S)  R+1 R	Output Required	403
COSINE COS @COS 461	COS(461) S R S: 1st source word R: 1st result word	Calculates the cosine of a 32-bit floating-point number (in radians) and places the result in the specified result words.  COS(S+1 S)  R+1 R	Output Required	404
TANGENT TAN @ TAN 462	S	Calculates the tangent of a 32-bit floating-point number (in radians) and places the result in the specified result words.  TAN ( S+1 S )  R+1 R	Output Required	406

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
ARC SINE  ASIN @ASIN 463	ASIN(463) S R	Calculates the arc sine of a 32-bit floating-point number and places the result in the specified result words. (The arc sine function is the inverse of the sine function; it returns the angle that produces a given sine value between –1 and 1.)	Output Required	408
	S: 1st source word R: 1st result word	SIN <sup>-1</sup> ( S+1 S ) R+1 R		
ARC COSINE  ACOS @ ACOS 464	ACOS(464) S R	Calculates the arc cosine of a 32-bit floating-point number and places the result in the specified result words. (The arc cosine function is the inverse of the cosine function; it returns the angle that produces a given cosine value between –1 and 1.)	Output Required	410
	S: 1st source word R: 1st result word	COS <sup>-1</sup> ( S+1 S )		
ARC TANGENT ATAN @ ATAN 465	ATAN(465) S R S: 1st source word R: 1st result word	Calculates the arc tangent of a 32-bit floating-point number and places the result in the specified result words. (The arc tangent function is the inverse of the tangent function; it returns the angle that produces a given tangent value.)  TAN <sup>-1</sup> (S+1 S)  R+1 R	Output Required	412
SQUARE ROOT SQRT @ SQRT 466	SQRT(466) S R S: 1st source word R: 1st result word	Calculates the square root of a 32-bit floating-point number and places the result in the specified result words.  S+1  R+1  R	Output Required	413
EXPONENT  EXP @EXP 467	EXP(467) S R S: 1st source word R: 1st result word	Calculates the natural (base e) exponential of a 32-bit floating-point number and places the result in the specified result words.  S+1 S  R+1 R	Output Required	415
LOGARITHM LOG @LOG 468	LOG(468) S R S: 1st source word R: 1st result word	Calculates the natural (base e) logarithm of a 32-bit floating-point number and places the result in the specified result words.  loge S+1 S R+1 R	Output Required	417



#### 2-2-14 Double-precision Floating-point Instructions

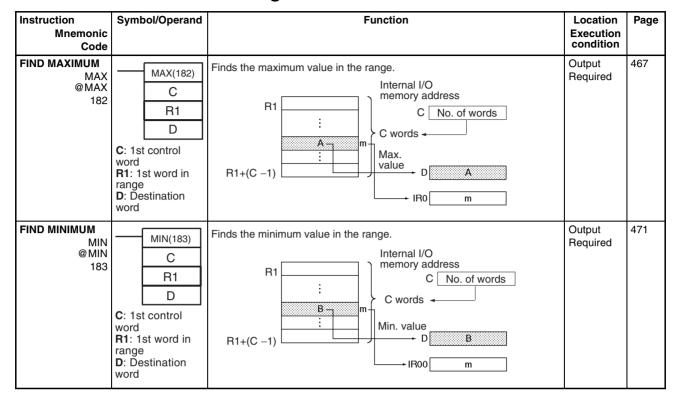
Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
DOUBLE FLOAT- ING TO 16-BIT BINARY FIXD @ FIXD 841	FIXD(841) S D S: 1st source word D: Destination word	Converts the specified double-precision floating-point data (64 bits) to 16-bit signed binary data and outputs the result to the destination word.  S+3 S+2 S+1 S Floating-point data (64 bits)  D V Signed binary data (16 bits)	Output Required	430
DOUBLE FLOAT- ING TO 32-BIT BINARY FIXLD @ FIXLD 842	FIXLD(842) S D S: 1st source word D: 1st destination word	Converts the specified double-precision floating-point data (64 bits) to 32-bit signed binary data and outputs the result to the destination words.  S+3 S+2 S+1 S Floating-point data (64 bits) D+1 D Signed binary data (32 bits)	Output Required	432
16-BIT BINARY TO DOUBLE FLOATING  DBL @DBL 843	DBL(843) S D S: Source word D: 1st destination word	Converts the specified 16-bit signed binary data to double-precision floating-point data (64 bits) and outputs the result to the destination words.  S Signed binary data (16 bits)  D+3 D+2 D+1 D Floating-point data (64 bits)	Output Required	433

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
32-BIT BINARY TO DOUBLE FLOATING  DBLL @ DBLL 844	DBLL(844) S D S: 1st source word D: 1st destination word	Converts the specified 32-bit signed binary data to double-precision floating-point data (64 bits) and outputs the result to the destination words.  S+1 S Signed binary data (32 bits)  D+3 D+2 D+1 D  Floating-point data 64 bits)	Output Required	434
DOUBLE FLOAT- ING-POINT ADD +D @+D 845	+D(845) Au Ad R Au: 1st augend word Ad: 1st addend word R: 1st result word	Adds the specified double-precision floating-point values (64 bits each) and outputs the result to the result words.  S1+3 S1+2 S1+1 S1 Augend (floating-point data, 64 bits)  S2+3 S2+2 S2+1 S2 + Addend (floating-point data, 64 bits)  D+3 D+2 D+1 D Result (floating-point data, 64 bits)	Output Required	436
DOUBLE FLOAT-ING-POINT SUB-TRACT  -D @-D 846	-D(846) Mi Su R Mi: 1st minuend word Su: 1st subtrahend word R: 1st result word	Subtracts the specified double-precision floating-point values (64 bits each) and outputs the result to the result words.  S1+3 S1+2 S1+1 S1  Minuend (floating-point data, 64 bits)  S2+3 S2+2 S2+1 S2  Subtrahend (floating-point data, 64 bits)  D+3 D+2 D+1 D  Result (floating-point data, 64 bits)	Output Required	437
DOUBLE FLOAT- ING-POINT MUL- TIPLY  *D @*D 847	*D(847) Md Mr R Md: 1st multiplicand word Mr: 1st multiplier word R: 1st result word	Multiplies the specified double-precision floating-point values (64 bits each) and outputs the result to the result words.  S1+3 S1+2 S1+1 S1  Multiplicand (floating-point data, 64 bits)  S2+3 S2+2 S2+1 S2  Multiplier (floating-point data, 64 bits)  D+3 D+2 D+1 D  Result (floating-point data, 64 bits)	Output Required	439
DOUBLE FLOAT- ING-POINT DIVIDE //D @//D 848	/D(848) Dd Dr R  Dd: 1st Dividend word Dr: 1st divisor word R: 1st result word	Divides the specified double-precision floating-point values (64 bits each) and outputs the result to the result words.  S1+3 S1+2 S1+1 S1  Dividend (floating-point data, 64 bits)  S2+3 S2+2 S2+1 S2  Divisor (floating-point data, 64bits)  D+3 D+2 D+1 D  Result (floating-point data, 64 bits)	Output Required	441

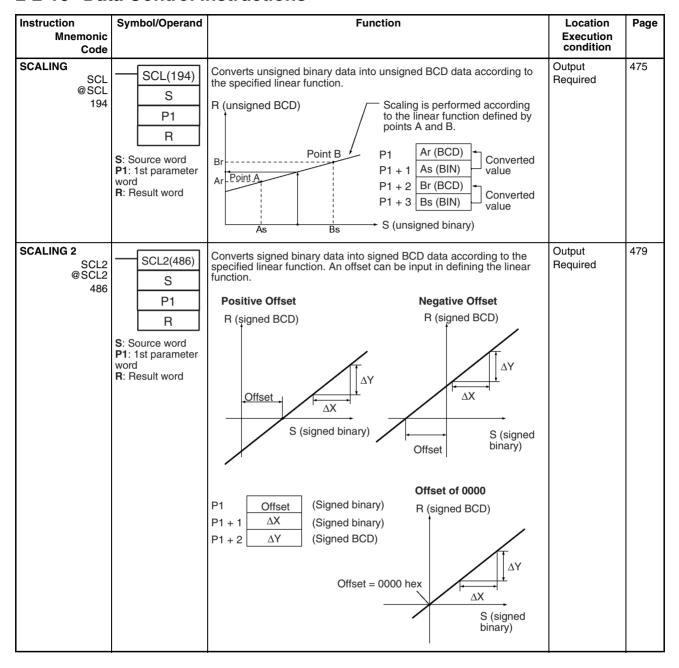
Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
DOUBLE DEGREES TO RADIANS RADD @ RADD 849	RADD(849) S R S: 1st source word R: 1st result word	Converts the specified double-precision floating-point data (64 bits) from degrees to radians and outputs the result to the result words.  S+3 S+2 S+1 S  Source (degrees, 64-bit floating-point data)  D+3 D+2 VD+1 D  Result (radians, 64-bit floating-point data)	Output Required	443
DOUBLE RADI- ANS TO DEGREES  DEGD @ DEGD 850	DEGD(850) S R S: 1st source word R: 1st result word	Converts the specified double-precision floating-point data (64 bits) from radians to degrees and outputs the result to the result words.  S+3 S+2 S+1 S  Source (radians, 64-bit floating-point data)  D+3 D+2 VD+1 D  Result (degrees, 64-bit floating-point data)	Output Required	444
DOUBLE SINE SIND @ SIND 851	SIND(851) S R S: 1st source word R: 1st result word	Calculates the sine of the angle (radians) in the specified double-precision floating-point data (64 bits) and outputs the result to the result words. SIN ( $\boxed{\text{S+3} \ \text{S+2} \ \text{S+1} \ \text{S}}$ ) $\rightarrow \boxed{\text{D+3} \ \text{D+2} \ \text{D+1} \ \text{D}}$	Output Required	446
DOUBLE COSINE COSD @ COSD 852	COSD(852) S R S: 1st source word R: 1st result word	Calculates the cosine of the angle (radians) in the specified double-precision floating-point data (64 bits) and outputs the result to the result words. $ COS\left( \boxed{\texttt{S+3} \ \texttt{S+2} \ \texttt{S+1} \ \texttt{S}} \right) \rightarrow \boxed{\texttt{D+3} \ \texttt{D+2} \ \texttt{D+1} \ \texttt{D}} $	Output Required	447
DOUBLE TAN- GENT TAND @ TAND 853	TAND(853) S: 1st source word R: 1st result word	Calculates the tangent of the angle (radians) in the specified double-precision floating-point data (64 bits) and outputs the result to the result words. TAN (	Output Required	449
DOUBLE ARC SINE ASIND @ ASIND 854	ASIND(854) S R S: 1st source word R: 1st result word	Calculates the angle (in radians) from the sine value in the specified double-precision floating-point data (64 bits) and outputs the result to the result words. (The arc sine function is the inverse of the sine function; it returns the angle that produces a given sine value between -1 and 1.) $SIN^{-1}\left( \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Output Required	450
DOUBLE ARC COSINE ACOSD @ ACOSD 855	ACOSD(855) S R S: 1st source word R: 1st result word	Calculates the angle (in radians) from the cosine value in the specified double-precision floating-point data (64 bits) and outputs the result to the result words. (The arc cosine function is the inverse of the cosine function; it returns the angle that produces a given cosine value between -1 and 1.) $COS^{-1}\left( \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Output Required	452

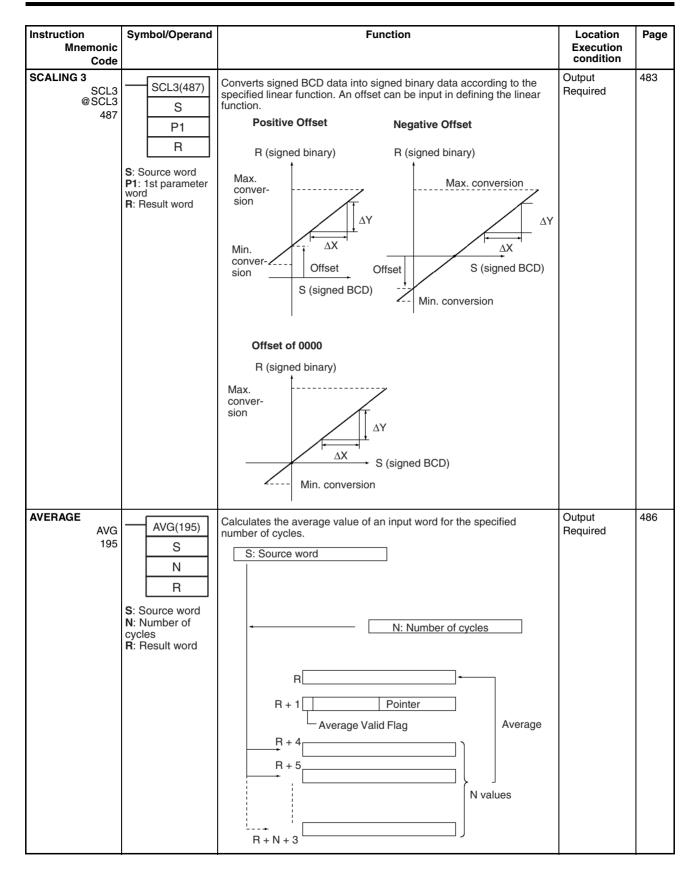
Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
DOUBLE ARC TANGENT ATAND @ ATAND 856	ATAND(856) S R S: 1st source word R: 1st result word	Calculates the angle (in radians) from the tangent value in the specified double-precision floating-point data (64 bits) and outputs the result to the result words. (The arc tangent function is the inverse of the tangent function; it returns the angle that produces a given tangent value.)	Output Required	454
DOUBLE SQUARE ROOT SQRTD @ SQRTD 857	SQRTD(857) S R S: 1st source word R: 1st result word	Calculates the square root of the specified double-precision floating-point data (64 bits) and outputs the result to the result words. $  $ S+3                                  $	Output Required	456
DOUBLE EXPONENT  EXPD @ EXPD 858	EXPD(858) S R S: 1st source word R: 1st result word	Calculates the natural (base e) exponential of the specified double-precision floating-point data (64 bits) and outputs the result to the result words.	Output Required	457
DOUBLE LOGA- RITHM LOGD @LOGD 859	LOGD(859) S R S: 1st source word R: 1st result word	Calculates the natural (base e) logarithm of the specified double-precision floating-point data (64 bits) and outputs the result to the result words. $   \log_e \boxed{ \text{S+3} \text{ S+2} \text{ S+1} \text{ S} } \rightarrow \boxed{ \text{D+3} \text{ D+2} \text{ D+1} \text{ D} } $	Output Required	459
DOUBLE EXPONENTIAL POWER  PWRD @ PWRD 860	PWRD(860) B E R B: 1st base word E: 1st exponent word R: 1st result word	Raises a double-precision floating-point number (64 bits) to the power of another double-precision floating-point number and outputs the result to the result words.  Power  S2+3S2+2 S2+1  S2  Base	Output Required	461
DOUBLE SYMBOL COMPARISON  LD, AND. or OR  =D (335), <>D (336), <d (337),="" (338),="" <="D">D (339), or &gt;=D (340)</d>	Using LD:  Symbol, option S1 S2  Using AND:  Symbol, option S1 S2  Using OR:  Symbol, option S1 S2  Using OR:  Symbol, option S1 S2  Using OR:  Symbol option S1 S2  Comparison data 1 S2: Comparison data 2	Compares the specified double-precision data (64 bits) and creates an ON execution condition if the comparison result is true.  Three kinds of symbols can be used with the floating-point symbol comparison instructions: LD (Load), AND, and OR.	LD: Not required AND or OR: Required	462

#### 2-2-15 Table Data Processing Instructions

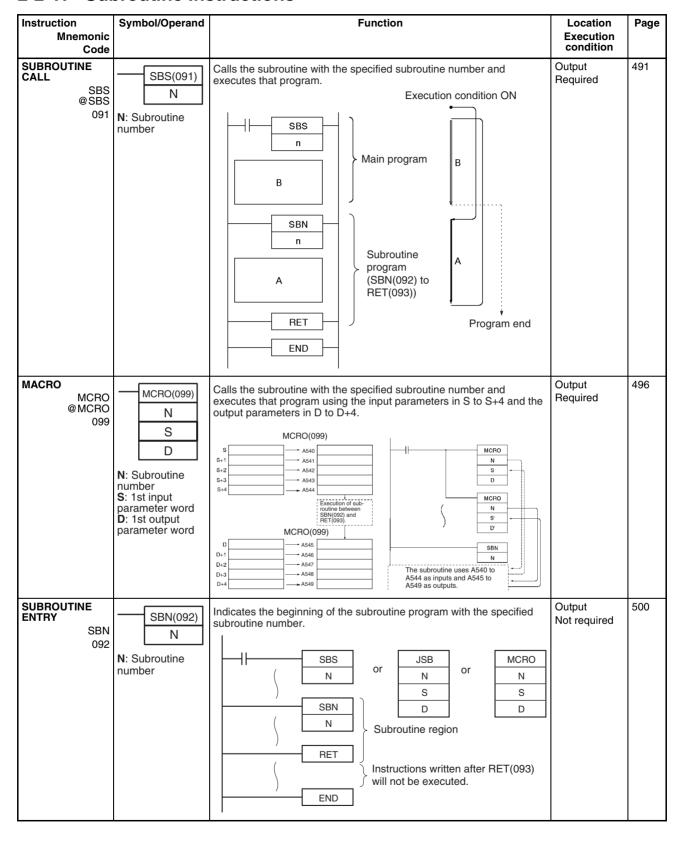


#### 2-2-16 Data Control Instructions





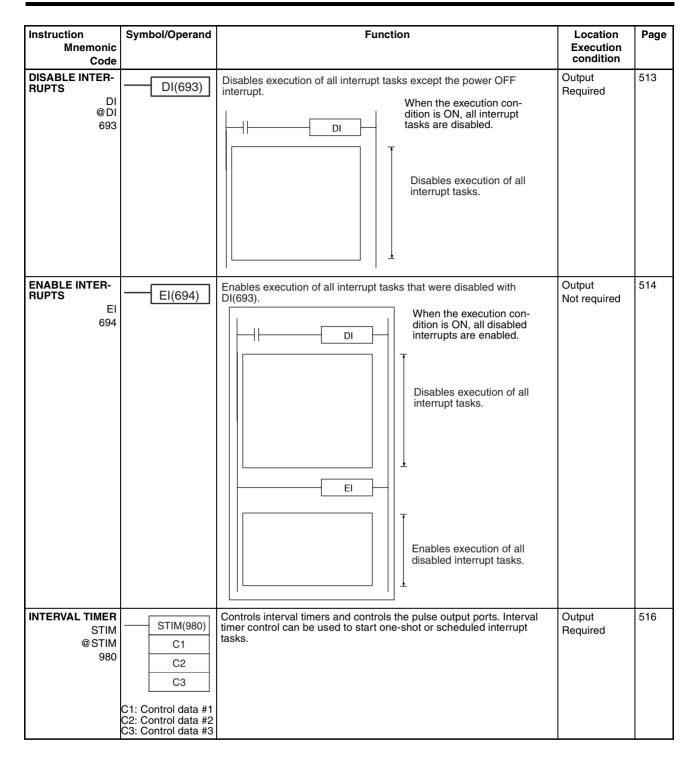
#### 2-2-17 Subroutine Instructions



Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
SUBROUTINE RETURN RET 093	RET(093)	Indicates the end of a subroutine program.	Output Not required	503
JUMP TO SUB- ROUTINE  JSB 982	N: Subroutine number S: 1st input parameter word D: 1st output parameter word	Calls the subroutine with the specified subroutine number regardless of the status of the input condition and executes that program. Data beginning with the word specified in S is passed to the subroutine. After execution of the subroutine, the result data is passed to the area beginning with the word specified in D. The ON/OFF status of the input condition is set in an Auxiliary Area bit so that it can be referenced from within the subroutine program.	Output Required	503

# 2-2-18 Interrupt Control Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
SET INTERRUPT MASK MSKS @ MSKS 690	MSKS(690)  N S  N: Interrupt identifier S: Interrupt data	Sets up interrupt processing for I/O interrupts. Both I/O interrupt tasks are masked (disabled) when the FQM1 is first turned ON. MSKS(690) can be used to unmask or mask I/O interrupts.  Built-in inputs 0 to 3  I/O interrupt  Mask (1) or unmask (0) interrupt inputs 0 to 3.	Output Required	508
READ INTERRUPT MASK MSKR @MSKR 692	MSKR(692)  N D N: Interrupt identifier D: Destination word	Reads the current interrupt processing settings that were set with MSKS(690).	Output Required	510
CLEAR INTERRUPT CLI @ CLI 691	CLI(691)  N S  N: Interrupt identifier S: Interrupt data	Clears or retains recorded interrupt inputs for I/O interrupts.  N = 0 to 3  Interrupt input n input n input n input n input n status  Recorded interrupt cleared Recorded interrupt retained	Output Required	512



# 2-2-19 High-speed Counter and Pulse Output Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
MODE CONTROL INI @ INI 880	P: Port specifier C: Control data NV: 1st word with new PV	INI(880) is used to start and stop target value comparison, to change the present value (PV) of a high-speed counter, to change the circular maximum count for a high-speed counter or pulse output counter, to change the PV of a pulse output, or to stop pulse output.  INI(880) is also used, for example, to change the circular maximum count or present value for a sampling counter.	Output Required	521
HIGH-SPEED COUNTER PV READ PRV @ PRV 881	PRV(881) P C D P: Port specifier C: Control data D: 1st destination word	PRV(881) is used to read the present value (PV) of a high-speed counter, pulse output, or high-speed counter latch. PRV(881) is used to read analog I/O values for the FQM1-MMA22.	Output Required	527
COMPARISON TABLE LOAD CTBL @CTBL 882	P: Port specifier C: Control data TB: 1st comparison table word	CTBL(882) is used to perform target value or range comparisons for the present value (PV) of a high-speed counter. It is also used to start high-speed analog sampling.	Output Required	530
SPEED OUTPUT SPED @ SPED 885	P: Port specifier M: Output mode F: 1st pulse frequency word	SPED(885) is used to specify the frequency and perform pulse output without acceleration or deceleration.  SPED(885) is also used to produce analog outputs for the FQM1-MMA22.	Output Required	537
SET PULSES PULS @ PULS 886	PULS(886) P T N  P: Port specifier T: Pulse type N: Number of pulses	PULS(886) is used to set the number of pulses for pulse output. PULS(886) also executes pulse outputs for absolute positions.	Output Required	543

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
PULSE OUTPUT PLS2 @ PLS2 887	PLS2(887) P M S P: Port specifier M: Output mode S: 1st word of settings table	PLS2(887) is used to set the pulse frequency and acceleration/deceleration rates, and to perform pulse output with acceleration/deceleration (with different acceleration/deceleration rates). Only positioning is possible.	Output Required	550
ACCELERATION CONTROL ACC @ ACC 888	ACC(888) P M S P: Port specifier M: Output mode S: 1st word of settings table	ACC(888) is used to set the pulse frequency and acceleration/deceleration rates, and to perform pulse output with acceleration/deceleration (with the same acceleration/deceleration rate). Both positioning and speed control are possible.  ACC(888) is also used to produce slopped analog outputs for the FQM1-MMA22.	Output Required	555

# 2-2-20 Step Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
STEP DEFINE STEP 008	STEP(008) B: Bit	STEP(008) functions in following 2 ways, depending on its position and whether or not a control bit has been specified.  (1)Starts a specific step.  (2)Ends the step programming area (i.e., step execution).  The step programming area extends from the first STEP(008) with a step number and the first STEP(008) without a step number.	Output Required	563
STEP START SNXT 009	SNXT(009) B B: Bit	SNXT(009) is used in the following three ways: (1)To start step programming execution. (2)To proceed to the next step control bit. (3)To end step programming execution.	Output Required	563

#### 2-2-21 I/O Refresh Instructions

Instruction Mnemonic Code		Function	Location Execution condition	Page
VO REFRESH IORF @ IORF 097	IORF(097) St E St: Starting word E: End word	Refreshes the specified I/O words of the Module's built-in I/O.  Built-in I/O  St  I/O Bit Area  St  I/O refreshing  E	Output Required	580

### 2-2-22 Serial Communications Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
TRANSMIT TXD @TXD 236	TXD(236) S C N S: 1st source word C: Control word N: Number of bytes 0000 to 0100 hex (0 to 256 decimal)	Outputs the specified number of bytes of data starting from the specified word from the RS-232C or RS-422A port (no-protocol mode) built into the Coordinator Module without conversion and using the start and end codes specified in the System Setup.	Output Required	582
RECEIVE RXD @ RXD 235	RXD(235)  D C N D: 1st destination word C: Control word N: Number of bytes to store 0000 to 0100 hex (0 to 256 decimal)	Receives the specified number of bytes of data from the RS-232C or RS-422A port (no-protocol mode) built into the Coordinator Module without conversion and using the start and end codes specified in the System Setup and store the data starting from the specified word.	Output Required	587
CHANGE SERIAL PORT SETUP STUP 237	STUP(237) C S C: Control word (port) S: First source word	Changes the communications parameters of the built-in serial port on the Coordinator Module during operation.	Output Required	592

# 2-2-23 Debugging Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
TRACE MEMORY SAMPLING	TRSM(045)	When TRSM(045) is executed, the status of a preselected bit or word is sampled and stored in Trace Memory. TRSM(045) can be used anywhere in the program, any number of times.	Output Not required	596
TRSM 045				

# 2-2-24 Failure Diagnosis Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
FAILURE ALARM FAL @ FAL 006	FAL(006)  N C N: FAL number C: Error code to generate (#0000 to #FFFF)	Generates or clears user-defined non-fatal errors. Non-fatal errors do not stop FQM1 operation.  Execution of FAL (006) generates a non-fatal error code stored. Error code written to Error Log Area. number N.  ERR indicator flashes.	Output Required	600
SEVERE FAILURE ALARM FALS 007	FALS(007)  N S N: FALS number S: Error code to generate (#0000 to #FFFF)	Generates user-defined fatal errors. Fatal errors stop FQM1 operation.  Execution of FALS (007) generates a fatal error with FALS number N.  FALS Error Flag ON.  Error code stored. Error code written to Error Log Area.  ERR indicator lit.	Output Required	603

#### 2-2-25 Other Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
SET CARRY STC @STC 040	STC(040)	Sets the Carry Flag (CY).	Output Required	606
CLEAR CARRY CLC @CLC 041	CLC(041)	Turns OFF the Carry Flag (CY).	Output Required	606

# 2-2-26 Block Programming Instructions

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
BLOCK PROGRAM BEGIN BPRG 096	BPRG(096) N N: Block program number	Define a block programming area. For every BPRG(096) there must be a corresponding BEND(801).  BPRG N Block program Executed when the execution condition is ON.	Output Required	611
BLOCK PROGRAM END BEND 801		Define a block programming area. For every BPRG(096) there must be a corresponding BEND(801).	Block program Required	611

Instruction Mnemonic Code	Symbol/Operand	Function	Location Execution condition	Page
CONDITIONAL BLOCK BRANCHING IF 802	IF (802)	If the execution condition is ON, the instructions between IF(802) and ELSE(803) will be executed and if the execution condition is OFF, the instructions between ELSE(803) and IEND(804) will be executed.    Execution condition   NO condition ON?   YES   A   "A" executed (between IF and ELSE).   B   IEND   IEN	Block program Required	613
CONDITIONAL BLOCK BRANCHING IF 802	IF (802) B B: Bit operand	If the operand bit is ON, the instructions between IF(802) and ELSE(803) will be executed. If the operand bit is OFF, the instructions between ELSE(803) and IEND(804) will be executed.  Operand bit ON?  IF R (IF NOT R)  A  ELSE  "A" executed (between IF and ELSE).  B  IEND  IEND	Block program Required	613
CONDITIONAL BLOCK BRANCHING (NOT)  IF NOT 802	IF (802) NOT B	If the operand bit is OFF, the instructions between IF(802) and ELSE(803) will be executed. If the operand bit is ON, the instructions between ELSE(803) and IEND(804) will be executed.	Block program Required	613
CONDITIONAL BLOCK BRANCHING (ELSE) ELSE 803		If the ELSE(803) instruction is omitted and the operand bit is ON, the instructions between IF(802) and IEND(804) will be executed	Block program Required	613
CONDITIONAL BLOCK BRANCHING END IEND 804		If the operand bit is OFF, only the instructions after IEND(804) will be executed.	Block program Required	613

# 2-2-27 Special Function Block Instructions

Instruction Mnemonic Code		Function	Location Execution condition	Page
GET VARIABLE ID GETID @ GETID 286	GETID(286) S D1 D2 S: Variable or address D1: ID code D2: Destination word	Outputs the FINS command variable type (data area) code and word address for the specified variable or address. This instruction is generally used to get the assigned address of a variable in a function block.	Output Required	618

# 2-3 Alphabetical List of Instructions by Mnemonic

Α

Mnemonic	Instruction	Function code	Upward Differentiation	Downward Differentiation	Page
ACC	ACCELERATION CONTROL	888	@ACC		555
ACOS	ARC COSINE	464	@ ACOS		410
ACOSD	DOUBLE ARC COSINE	855	@ACOSD		452
AND	AND		@AND	%AND	99
AND <	AND LESS THAN	310			167
AND <>	AND NOT EQUAL	305			167
AND <>D	AND DOUBLE FLOATING NOT EQUAL	336			462
AND <>F	AND FLOATING NOT EQUAL	330			421
AND <>L	AND DOUBLE NOT EQUAL	306			167
AND <>S	AND SIGNED NOT EQUAL	307			167
AND <>SL	AND DOUBLE SIGNED NOT EQUAL	308			167
AND <d< td=""><td>AND DOUBLE FLOATING LESS THAN</td><td>337</td><td></td><td></td><td>462</td></d<>	AND DOUBLE FLOATING LESS THAN	337			462
AND <f< td=""><td>AND FLOATING LESS THAN</td><td>331</td><td></td><td></td><td>421</td></f<>	AND FLOATING LESS THAN	331			421
AND <l< td=""><td>AND DOUBLE LESS THAN</td><td>311</td><td></td><td></td><td>167</td></l<>	AND DOUBLE LESS THAN	311			167
AND <s< td=""><td>AND SIGNED LESS THAN</td><td>312</td><td></td><td></td><td>167</td></s<>	AND SIGNED LESS THAN	312			167
AND <sl< td=""><td>AND DOUBLE SIGNED LESS THAN</td><td>313</td><td></td><td></td><td>167</td></sl<>	AND DOUBLE SIGNED LESS THAN	313			167
AND =	AND EQUAL	300			167
AND =D	AND DOUBLE FLOATING EQUAL	335			462
AND =F	AND FLOATING EQUAL	329			421
AND =L	AND DOUBLE EQUAL	301			167
AND =S	AND SIGNED EQUAL	302			167
AND =SL	AND DOUBLE SIGNED EQUAL	303			167
AND >	AND GREATER THAN	320			167
AND >D	AND DOUBLE FLOATING GREATER THAN	339			462
AND >F	AND FLOATING GREATER THAN	333			421
AND >L	AND DOUBLE GREATER THAN	321			167
AND >S	AND SIGNED GREATER THAN	322			167
AND >SL	AND DOUBLE SIGNED GREATER THAN	323			167
AND LD	AND LOAD				105
AND NOT	AND NOT				101
AND TST	AND BIT TEST	350			113
AND TSTN	AND BIT TEST	351			113
AND <=	AND LESS THAN OR EQUAL	315			167
AND <=D	AND DOUBLE FLOATING LESS THAN OR EQUAL	338			462
AND <=F	AND FLOATING LESS THAN OR EQUAL	332			421
AND <=L	AND DOUBLE LESS THAN OR EQUAL	316			167
AND <=S	AND SIGNED LESS THAN OR EQUAL	317			167
AND <=SL	AND DOUBLE SIGNED LESS THAN OR EQUAL	318			167
AND >=	AND GREATER THAN OR EQUAL	325			167
AND >=D	AND DOUBLE FLOATING GREATER THAN OR EQUAL	340			462
AND >=F	AND FLOATING GREATER THAN OR EQUAL	334			421
AND >=L	AND DOUBLE GREATER THAN OR EQUAL	326			167
AND >=S	AND SIGNED GREATER THAN OR EQUAL	327			167
AND >=SL	AND DOUBLE SIGNED GREATER THAN OR EQUAL	328			167

Mnemonic	Instruction	Function code	Upward Differentiation	Downward Differentiation	Page
ANDL	DOUBLE LOGICAL AND	610	@ANDL		353
ANDW	LOGICAL AND	034	@ANDW		351
APR	ARITHMETIC PROCESS	069	@APR		368
ASC	ASCII CONVERT	086	@ASC		341
ASFT	ASYNCHRONOUS SHIFT REGISTER	017	@ASFT		230
ASIN	ARC SINE	463	@ ASIN		408
ASIND	DOUBLE ARC SINE	854	@ASIND		450
ASL	ARITHMETIC SHIFT LEFT	025	@ASL		233
ASLL	DOUBLE SHIFT LEFT	570	@ ASLL		235
ASR	ARITHMETIC SHIFT RIGHT	026	@ASR		236
ASRL	DOUBLE SHIFT RIGHT	571	@ASRL		238
ATAN	ARC TANGENT	465	@ ATAN		412
ATAND	DOUBLE ARC TANGENT	856	@ ATAND		454
AVG	AVERAGE	195			486
AXIS	VIRTUAL AXIS	981			376

#### В

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
BCD	BINARY-TO-BCD	024	@BCD		334
BCDL	DOUBLE BINARY-TO-DOUBLE BCD	059	@BCDL		336
ВСМР	UNSIGNED BLOCK COMPARE	068	@BCMP		187
BCMP2	EXPANDED BLOCK COMPARE	502	@BCMP2		190
BCNT	BIT COUNTER	067	@BCNT		375
BEND	BLOCK PROGRAM END	801			611
BIN	BCD-TO-BINARY	023	@BIN		331
BINL	DOUBLE BCD-TO-DOUBLE BINARY	058	@BINL		333
BPRG	BLOCK PROGRAM BEGIN	096			611
BREAK	BREAK LOOP	514			150
BSET	BLOCK SET	071	@BSET		213

# С

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
CJP	CONDITIONAL JUMP	510			141
CJPN	CONDITIONAL JUMP	511			141
CLC	CLEAR CARRY	041	@CLC		606
CLI	CLEAR INTERRUPT	691	@CLI		512
CMP	COMPARE	020			172
CMPL	DOUBLE COMPARE	060			175
CNT	COUNTER				160
CNTR	REVERSIBLE COUNTER	012			163
COLL	DATA COLLECT	081	@COLL		219
СОМ	COMPLEMENT	029	@COM		365
COML	DOUBLE COMPLEMENT	614	@COML		366
cos	COSINE	461	@COS		404
COSD	DOUBLE COSINE	852	@COSD		447
CPS	SIGNED BINARY COMPARE	114			177
CPSL	DOUBLE SIGNED BINARY COMPARE	115			180
CTBL	COMPARISON TABLE LOAD	882	@CTBL		530

D

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
DBL	16-BIT BINARY TO DOUBLE FLOATING	843	@DBL		433
DBLL	32-BIT BINARY TO DOUBLE FLOATING	844	@DBLL		434
DEG	RADIANS-TO DEGREES	459	@DEG		401
DEGD	DOUBLE RADIANS TO DEGREES	850	@RADD		444
DI	DISABLE INTERRUPTS	693	@DI		513
DIFD	DIFFERENTIATE DOWN	014			122
DIFU	DIFFERENTIATE UP	013			122
DIST	SINGLE WORD DISTRIBUTE	080	@ DIST		217
DOWN	CONDITION OFF	522			112

Ε

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
EI	ENABLE INTERRUPTS	694			514
ELSE	ELSE	803			613
END	END	001			134
EXP	EXPONENT	467	@EXP		415
EXPD	DOUBLE EXPONENT	858	@EXPD		457

F

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
FAL	FAILURE ALARM	006	@FAL		600
FALS	SEVERE FAILURE ALARM	007			603
FIX	FLOATING TO 16-BIT	450	@FIX		386
FIXD	DOUBLE FLOATING TO 16-BIT BINARY	841	@FIXD		430
FIXL	FLOATING TO 32-BIT	451	@FIXL		388
FIXLD	DOUBLE FLOATING TO 32-BIT BINARY	842	@FIXLD		432
FLT	16-BIT TO FLOATING	452	@FLT		389
FLTL	32-BIT TO FLOATING	453	@FLTL		390
FOR	FOR-NEXT LOOPS	512			147

G

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
GETID	GET VARIABLE ID	286	@GETID		618

Н

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
HEX	ASCII TO HEX	162	@HEX		345

ı

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
IEND	IF END	804			613
IF NOT (oper- and)	IF NOT	802			613
IF (input condition)	IF	802			613
IF (operand)	IF	802			613
IL	INTERLOCK	002			135
ILC	INTERLOCK CLEAR	003			135

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
INI	MODE CONTROL	880	@INI		521
IORF	I/O REFRESH	097	@IORF		580

#### J

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
JME	JUMP END	005			138
JME0	MULTIPLE JUMP END	516			145
JMP	JUMP	004			138
JMP0	MULTIPLE JUMP	515			145
JSB	JUMP TO SUBROUTINE	982			503

#### K

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
KEEP	KEEP	011			119

#### L

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
LD	LOAD		@LD	%LD	95
LD <	LOAD LESS THAN	310			167
LD <d< td=""><td>LOAD DOUBLE FLOATING LESS THAN</td><td>337</td><td></td><td></td><td>462</td></d<>	LOAD DOUBLE FLOATING LESS THAN	337			462
LD <f< td=""><td>LOAD FLOATING LESS THAN</td><td>331</td><td></td><td></td><td>421</td></f<>	LOAD FLOATING LESS THAN	331			421
LD <>	LOAD NOT EQUAL	305			167
LD <>D	LOAD DOUBLE FLOATING NOT EQUAL	336			462
LD <>F	LOAD FLOATING NOT EQUAL	330			421
LD <>L	LOAD DOUBLE NOT EQUAL	306			167
LD <>S	LOAD SIGNED NOT EQUAL	307			167
LD <>SL	LOAD DOUBLE SIGNED NOT EQUAL	308			167
LD <l< td=""><td>LOAD DOUBLE LESS THAN</td><td>311</td><td></td><td></td><td>167</td></l<>	LOAD DOUBLE LESS THAN	311			167
LD <s< td=""><td>LOAD SIGNED LESS THAN</td><td>312</td><td></td><td></td><td>167</td></s<>	LOAD SIGNED LESS THAN	312			167
LD <sl< td=""><td>LOAD DOUBLE SIGNED LESS THAN</td><td>313</td><td></td><td></td><td>167</td></sl<>	LOAD DOUBLE SIGNED LESS THAN	313			167
LD =	LOAD EQUAL	300			167
LD =D	LOAD DOUBLE FLOATING EQUAL	335			462
LD =F	LOAD FLOATING EQUAL	329			421
LD =L	LOAD DOUBLE EQUAL	301			167
LD =S	LOAD SIGNED EQUAL	302			167
LD =SL	LOAD DOUBLE SIGNED EQUAL	303			167
LD >	LOAD GREATER THAN	320			167
LD >D	LOAD DOUBLE FLOATING GREATER THAN	339			462
LD >F	LOAD FLOATING GREATER THAN	333			421
LD >L	LOAD DOUBLE GREATER THAN	321			167
LD >S	LOAD SIGNED GREATER THAN	322			167
LD >SL	LOAD DOUBLE SIGNED GREATER THAN	323			167
LD NOT	LOAD NOT				97
LD TST	LOAD BIT TEST	350			113
LD TSTN	LOAD BIT TEST	351			113
LD <=	LOAD LESS THAN OR EQUAL	315			167
LD <=D	LOAD DOUBLE FLOATING LESS THAN OR EQUAL	338			462
LD <=F	LOAD FLOATING LESS THAN OR EQUAL	332			421
LD <=L	LOAD DOUBLE LESS THAN OR EQUAL	316			167

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
LD <=S	LOAD SIGNED LESS THAN OR EQUAL	317			167
LD <=SL	LOAD DOUBLE SIGNED LESS THAN OR EQUAL	318			167
LD >=	LOAD GREATER THAN OR EQUAL	325			167
LD >=D	LOAD DOUBLE FLOATING GREATER THAN OR EQUAL	340			462
LD >=F	LOAD FLOATING GREATER THAN OR EQUAL	334			421
LD >=L	LOAD DOUBLE GREATER THAN OR EQUAL	326			167
LD >=S	LOAD SIGNED GREATER THAN OR EQUAL	327			167
LD >=SL	LOAD DOUBLE SIGNED GREATER THAN OR EQUAL	328			167
LOG	LOGARITHM	468	@LOG		417
LOGD	DOUBLE LOGARITHM	859	@LOGD		459

#### М

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
MAX	FIND MAXIMUM	182	@MAX		467
MCMP	MULTIPLE COMPARE	019	@MCMP		182
MCRO	MACRO	099	@MCRO		496
MIN	FIND MINIMUM	183	@MIN		471
MOV	MOVE	021	@MOV		199
MOVB	MOVE BIT	082	@MOVB		204
MOVD	MOVE DIGIT	083	@MOVD		206
MOVL	DOUBLE MOVE	498	@MOVL		201
MOVR	MOVE TO REGISTER	560	@MOVR		221
MOVRW	MOVE TIMER/COUNTER PV TO REGISTER	561			222
MSKR	READ INTERRUPT MASK	692	@MSKR		510
MSKS	SET INTERRUPT MASK	690	@MSKS		508
MVN	MOVE NOT	022	@MVN		200
MVNL	DOUBLE MOVE NOT	499	@MVNL		203

#### N

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
NASL	SHIFT N-BITS LEFT	580	@NASL		254
NASR	SHIFT N-BITS RIGHT	581	@NASR		259
NEG	2'S COMPLEMENT	160	@NEG		338
NEGL	DOUBLE 2'S COMPLEMENT	161	@NEGL		339
NEXT	FOR-NEXT LOOPS	513			147
NOP	NO OPERATION	000			134
NOT	NOT	520			111
NSLL	DOUBLE SHIFT N-BITS LEFT	582	@NSLL		256
NSRL	DOUBLE SHIFT N-BITS RIGHT	583	@NSRL		261

#### 0

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
OR	OR		@OR	%OR	102
OR <	OR LESS THAN	310			167

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
OR <>	OR NOT EQUAL	305			167
OR <>D	OR DOUBLE FLOATING NOT EQUAL	336			462
OR <>F	OR FLOATING NOT EQUAL	330			421
OR <>L	OR DOUBLE NOT EQUAL	306			167
OR <>S	OR SIGNED NOT EQUAL	307			167
OR <>SL	OR DOUBLE SIGNED NOT EQUAL	308			167
OR <d< td=""><td>OR DOUBLE FLOATING LESS THAN</td><td>337</td><td></td><td></td><td>462</td></d<>	OR DOUBLE FLOATING LESS THAN	337			462
OR <f< td=""><td>OR FLOATING LESS THAN</td><td>331</td><td></td><td></td><td>421</td></f<>	OR FLOATING LESS THAN	331			421
OR <l< td=""><td>OR DOUBLE LESS THAN</td><td>311</td><td></td><td></td><td>167</td></l<>	OR DOUBLE LESS THAN	311			167
OR <s< td=""><td>OR SIGNED LESS THAN</td><td>312</td><td></td><td></td><td>167</td></s<>	OR SIGNED LESS THAN	312			167
OR <sl< td=""><td>OR DOUBLE SIGNED LESS THAN</td><td>313</td><td></td><td></td><td>167</td></sl<>	OR DOUBLE SIGNED LESS THAN	313			167
OR =	OR EQUAL	300			167
OR =D	OR DOUBLE FLOATING EQUAL	335			462
OR =F	OR FLOATING EQUAL	329			421
OR =L	OR DOUBLE EQUAL	301			167
OR =S	OR SIGNED EQUAL	302			167
OR =SL	OR DOUBLE SIGNED EQUAL	303			167
OR >	OR GREATER THAN	320			167
OR >D	OR DOUBLE FLOATING GREATER THAN	339			462
OR >F	OR FLOATING GREATER THAN	333			421
OR >L	OR DOUBLE GREATER THAN	321			167
OR >S	OR SIGNED GREATER THAN	322			167
OR >SL	OR DOUBLE SIGNED GREATER THAN	323			167
OR LD	OR LOAD				107
OR NOT	OR NOT				104
OR TST	OR BIT TEST	350			113
OR TSTN	OR BIT TEST	351			113
OR <=	OR LESS THAN OR EQUAL	315			167
OR <=D	OR DOUBLE FLOATING LESS THAN OR EQUAL	338			462
OR <=F	OR FLOATING LESS THAN OR EQUAL	332			421
OR <=L	OR DOUBLE LESS THAN OR EQUAL	316			167
OR <=S	OR SIGNED LESS THAN OR EQUAL	317			167
OR <=SL	OR DOUBLE SIGNED LESS THAN OR EQUAL	318			167
OR >=	OR GREATER THAN OR EQUAL	325			167
OR >=D	OR DOUBLE FLOATING GREATER THAN OR EQUAL	340			462
OR >=F	OR FLOATING GREATER THAN OR EQUAL	334			421
OR >=L	OR DOUBLE GREATER THAN OR EQUAL	326			167
OR >=S	OR SIGNED GREATER THAN OR EQUAL	327			167
OR >=SL	OR DOUBLE SIGNED GREATER THAN OR EQUAL	328			167
ORW	LOGICAL OR	035	@ORW	@ORW	
ORWL	DOUBLE LOGICAL OR	611	@ORWL		356
OUT	ОИТРИТ				117
OUT NOT	OUTPUT NOT				118
OUTB	SINGLE BIT OUTPUT	534	@OUTB		132

Р

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
PRV	HIGH-SPEED COUNTER PV READ	881	@PRV		527
PULS	SET PULSES	886	@PULS		543
PLS2	PULSE OUTPUT	887	@PLS2		550
PWR	EXPONENTIAL POWER	840	@PWR		419
PWRD	DOUBLE EXPONENTIAL POWER	860	@PWRD		461

R

Mnemonic	Instruction	Instruction FUN code Upward Downward Differentiation Differentiation		Page	
RAD	DEGREES TO RADIANS	458	@RAD		400
RADD	DOUBLE DEGREES TO RADIANS	849	@RADD		443
RET	SUBROUTINE RETURN	093			503
RLNC	ROTATE LEFT WITHOUT CARRY	574	@RLNC		245
RLNL	DOUBLE ROTATE LEFT WITHOUT CARRY	576	@RLNL		247
ROL	ROTATE LEFT	027	@ROL		239
ROLL	DOUBLE ROTATE LEFT	572	@ROLL		241
ROR	ROTATE RIGHT	028	@ROR		242
RORL	DOUBLE ROTATE RIGHT	573	@RORL		244
RRNC	ROTATE RIGHT WITHOUT CARRY	575	@RRNC		248
RRNL	DOUBLE ROTATE RIGHT WITHOUT CARRY	577	@RRNL		250
RSET	RESET		@RSET	%RSET	125
RSTA	MULTIPLE BIT RESET	531	@RSTA		126
RSTB	SINGLE BIT RESET	533	@RSTB		129
RXD	RECEIVE	235	@RXD		587

s

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
SBN	SUBROUTINE ENTRY	092			500
SBS	SUBROUTINE CALL	091	@SBS		491
SCL	SCALING	194	@SCL		475
SCL2	SCALING 2	486	@SCL2		479
SCL3	SCALING 3	487	@SCL3		483
SET	SET		@SET	%SET	125
SETA	MULTIPLE BIT SET	530	@SETA		126
SETB	SINGLE BIT SET	532	@SETB		129
SFT	SHIFT REGISTER	010			225
SFTR	REVERSIBLE SHIFT REGISTER	084	@SFTR		227
SIN	SINE	460	@SIN		403
SIND	DOUBLE SINE	851	@SIND		446
SLD	ONE DIGIT SHIFT LEFT	074	@SLD		251
SNXT	STEP START	009			563
SPED	SPEED OUTPUT	885	@SPED		537
SQRT	SQUARE ROOT	466	@SQRT		413
SQRTD	DOUBLE SQUARE ROOT	857	@SQRTD		456
SRD	ONE DIGIT SHIFT RIGHT	075	@SRD		253
STC	SET CARRY	040	@STC		606
STIM	INTERVAL TIMER	980	@STIM		516
STEP	STEP DEFINE	008			563
STUP	CHANGE SERIAL PORT SETUP	237	@STUP		592

T

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
TAN	TANGENT	462	@TAN		406
TAND	DOUBLE TANGENT	853	@TAND		449
TCMP	TABLE COMPARE	085	@TCMP		185
TIM	TIMER				153
TIMH	HIGH-SPEED TIMER	015			156
ТМНН	ONE-MS TIMER	540			158
TRSM	TRACE MEMORY SAMPLING	045			596
TXD	TRANSMIT	236	@TXD		582

U

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
UP	CONDITION ON	521			112

#### W

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
WSFT	WORD SHIFT	016	@WSFT		232

X

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
XCGL	DOUBLE DATA EXCHANGE	562	@XCGL		216
XCHG	DATA EXCHANGE	073	@XCHG		215
XFER	BLOCK TRANSFER	070	@XFER		211
XFRB	MULTIPLE BIT TRANSFER	062	@XFRB		208
XNRL	DOUBLE EXCLUSIVE NOR	613	@XNRL		363
XNRW	EXCLUSIVE NOR	037	@XNRW		362
XORL	DOUBLE EXCLUSIVE OR	612	@XORL		360
XORW	EXCLUSIVE OR	036	@XORW		358

Z

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
ZCP	AREA RANGE COMPARE	088			193
ZCPL	DOUBLE AREA RANGE COMPARE	116			196

#### Symbols

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
+	SIGNED BINARY ADD WITHOUT CARRY	400	@+		282
++	INCREMENT BINARY	590	@++		265
++B	INCREMENT BCD	594	@++B		273
++BL	DOUBLE INCREMENT BCD	595	@++BL		275
++L	DOUBLE INCREMENT BINARY	591	@++L		267
+B	BCD ADD WITHOUT CARRY	404	@+B		289
+BC	BCD ADD WITH CARRY	406	@+BC		292
+BCL	DOUBLE BCD ADD WITH CARRY	407	@+BCL		293
+BL	DOUBLE BCD ADD WITHOUT CARRY	405	@+BL		290
+C	SIGNED BINARY ADD WITH CARRY	402	@+C		285
+CL	DOUBLE SIGNED BINARY ADD WITH CARRY	403	@+CL		287
+D	DOUBLE FLOATING-POINT ADD	845	@+D		436

Mnemonic	Instruction	FUN code	Upward Differentiation	Downward Differentiation	Page
+F	FLOATING-POINT ADD	454	@+F		392
+L	DOUBLE SIGNED BINARY ADD WITHOUT CARRY	401	@+L		283
_	SIGNED BINARY SUBTRACT WITHOUT CARRY	410	@-		295
	DECREMENT BINARY	592	@		269
B	DECREMENT BCD	596	@B		277
BL	DOUBLE DECREMENT BCD	597	@BL		279
L	DOUBLE DECREMENT BINARY	593	@L		271
-В	BCD SUBTRACT WITHOUT CARRY	414	@-B		304
-BC	BCD SUBTRACT WITH CARRY	416	@-BC		309
-BCL	DOUBLE BCD SUBTRACT WITH CARRY	417	@-BCL		310
-BL	DOUBLE BCD SUBTRACT WITHOUT CARRY	415	@-BL		306
-C	SIGNED BINARY SUBTRACT WITH CARRY	412	@-C		300
-CL	DOUBLE SIGNED BINARY SUBTRACT WITH CARRY	413	@-CL		302
–D	DOUBLE FLOATING-POINT SUBTRACT	846	@-D		437
-F	FLOATING-POINT SUBTRACT	455	@-F		394
*	SIGNED BINARY MULTIPLY	420	@*		312
*B	BCD MULTIPLY	424	@*B		318
*BL	DOUBLE BCD MULTIPLY	425	@*BL		320
*D	DOUBLE FLOATING-POINT MULTIPLY	847	@*D		439
*F	FLOATING-POINT MULTIPLY	456	@*F		396
*L	DOUBLE SIGNED BINARY MULTIPLY	421	@*L		314
*U	UNSIGNED BINARY MULTIPLY	422	@*U		315
*UL	DOUBLE UNSIGNED BINARY MULTIPLY	423	@*UL		317
-L	DOUBLE SIGNED BINARY SUBTRACT WITHOUT CARRY	411	@-L		296
/	SIGNED BINARY DIVIDE	430	@/		321
/B	BCD DIVIDE	434	@/B		328
/BL	DOUBLE BCD DIVIDE	435	@/BL		329
/D	DOUBLE FLOATING-POINT DIVIDE	848	@/D		441
/F	FLOATING-POINT DIVIDE	457	@/F		397
/L	DOUBLE SIGNED BINARY DIVIDE	431	@/L		
/U	UNSIGNED BINARY DIVIDE	432	@/U		324
/UL	DOUBLE UNSIGNED BINARY DIVIDE	433	@/UL		326

# 2-4 List of Instructions by Function Code

Function code	Mnemonic	Instruction	Upward Differentiation	Downward Differentiation	Page
	LD	LOAD	@LD	%LD	95
	LD NOT	LOAD NOT			97
	AND	AND	@AND	%AND	99
	AND NOT	AND NOT			101
	OR	OR	@OR	%OR	102
	OR NOT	OR NOT			104
	AND LD	AND LOAD			105
	OR LD	OR LOAD			107
	OUT	OUTPUT			117
	OUT NOT	OUTPUT NOT			118
	SET	SET	@SET	%SET	125
	RSET	RESET	@RSET	%RSET	125
	TIM	TIMER			153
	CNT	COUNTER			160
000	NOP	NO OPERATION			134
001	END	END			134
002	IL	INTERLOCK			135
003	ILC	INTERLOCK CLEAR			135
004	JMP	JUMP			138
005	JME	JUMP END			138
006	FAL	FAILURE ALARM	@ FAL		600
007	FALS	SEVERE FAILURE ALARM			603
008	STEP	STEP DEFINE			563
009	SNXT	STEP START		 	563
010	SFT	SHIFT REGISTER	1	 	225
011	KEEP	KEEP	1	 	119
012	CNTR	REVERSIBLE COUNTER			163
013	DIFU	DIFFERENTIATE UP	 	1	122
014	DIFD	DIFFERENTIATE DOWN			122
015	TIMH	HIGH-SPEED TIMER	1	<del></del>	156
016	WSFT	WORD SHIFT	@WSFT	 	232
017	ASFT	ASYNCHRONOUS SHIFT REGISTER	@ASFT		230
019	MCMP	MULTIPLE COMPARE	@MCMP	 	182
020	CMP		@ IVICIVIF		172
		UNSIGNED COMPARE	@MOV		
021	MOV	MOVE			199 200
022	MVN	MOVE NOT	@MVN		
023	BIN	BCD-TO-BINARY	@BIN		331
024	BCD	BINARY-TO-BCD	@BCD		334
025	ASL	ARITHMETIC SHIFT LEFT	@ ASL		233
026	ASR	ARITHMETIC SHIFT RIGHT	@ASR		236
027	ROL	ROTATE DIQUE	@ ROL		239
028	ROR	ROTATE RIGHT	@ ROR		242
029	COM	COMPLEMENT	@COM		365
034	ANDW	LOGICAL AND	@ ANDW		351
035	ORW	LOGICAL OR	@ORW		354
036	XORW	EXCLUSIVE OR	@ XORW		358
037	XNRW	EXCLUSIVE NOR	@XNRW		362
040	STC	SET CARRY	@STC		606
041	CLC	CLEAR CARRY	@ CLC		606
045	TRSM	TRACE MEMORY SAMPLING			596

Function code	Mnemonic	Instruction	Upward Differentiation	Downward Differentiation	Page
058	BINL	DOUBLE BCD-TO-DOUBLE BINARY	@BINL		333
059	BCDL	DOUBLE BINARY-TO-DOUBLE BCD	@BCDL		336
060	CMPL	DOUBLE UNSIGNED COMPARE			175
062	XFRB	MULTIPLE BIT TRANSFER	@XFRB		208
067	BCNT	BIT COUNTER	@BCNT		375
068	BCMP	UNSIGNED BLOCK COMPARE	@BCMP		187
069	APR	ARITHMETIC PROCESS	@APR		368
070	XFER	BLOCK TRANSFER	@XFER		211
071	BSET	BLOCK SET	@BSET		213
073	XCHG	DATA EXCHANGE	@XCHG		215
074	SLD	ONE DIGIT SHIFT LEFT	@SLD		251
075	SRD	ONE DIGIT SHIFT RIGHT	@SRD		253
080	DIST	SINGLE WORD DISTRIBUTE	@ DIST		217
081	COLL	DATA COLLECT	@COLL		219
082	MOVB	MOVE BIT	@MOVB		204
083	MOVD	MOVE DIGIT	@MOVD		206
084	SFTR	REVERSIBLE SHIFT REGISTER	@SFTR		227
085	TCMP	TABLE COMPARE	@TCMP		185
086	ASC	ASCII CONVERT	@ASC		341
088	ZCP	AREA RANGE COMPARE			193
091	SBS	SUBROUTINE CALL	@SBS		491
092	SBN	SUBROUTINE ENTRY			500
093	RET	SUBROUTINE RETURN			503
096	BPRG	BLOCK PROGRAM BEGIN			611
097	IORF	I/O REFRESH	@IORF		580
	<u> </u>	<u> </u>		 	
099	MCRO	MACRO	@MCRO		496
114	CPS	SIGNED BINARY COMPARE			177
115	CPSL	DOUBLE SIGNED BINARY COMPARE			180
116	ZCPL	DOUBLE AREA RANGE COMPARE			196
160	NEG	2'S COMPLEMENT	@NEG		338
161	NEGL	DOUBLE 2'S COMPLEMENT	@NEGL		339
162	HEX	ASCII TO HEX	@HEX		345
182	MAX	FIND MAXIMUM	@MAX		467
183	MIN	FIND MINIMUM	@MIN		471
194	SCL	SCALING	@ SCL		475
195	AVG	AVERAGE			486
235	RXD	RECEIVE	@RXD		587
236	TXD	TRANSMIT	@TXD		582
237	STUP	CHANGE SERIAL PORT SETUP	@STUP		592
286	GETID	GET VARIABLE ID	@GETID		618
300	AND =	AND EQUAL			167
300	LD =	LOAD EQUAL			167
300	OR =	OR EQUAL			167
301	AND =L	AND DOUBLE EQUAL			167
301	LD =L	LOAD DOUBLE EQUAL			167
301	OR =L	OR DOUBLE EQUAL			167
302	AND =S	AND SIGNED EQUAL			167
302	LD =S	LOAD SIGNED EQUAL			167
302	OR =S	OR SIGNED EQUAL			167
303	AND =SL	AND DOUBLE SIGNED EQUAL			167
202	LD =SL	LOAD DOUBLE SIGNED EQUAL			167
303	LD -OL	EOND DOODLE CIGINED EQUILE			

Function code	Mnemonic	Instruction	Upward Differentiation	Downward Differentiation	Page
305	AND <>	AND NOT EQUAL			167
305	LD <>	LOAD NOT EQUAL			167
305	OR <>	OR NOT EQUAL			167
306	AND <>L	AND DOUBLE NOT EQUAL			167
306	LD <>L	LOAD DOUBLE NOT EQUAL			167
306	OR <>L	OR DOUBLE NOT EQUAL			167
307	AND <>S	AND SIGNED NOT EQUAL			167
307	LD <>S	LOAD SIGNED NOT EQUAL			167
307	OR <>S	OR SIGNED NOT EQUAL			167
308	AND <>SL	AND DOUBLE SIGNED NOT EQUAL			167
308	LD <>SL	LOAD DOUBLE SIGNED NOT EQUAL			167
308	OR <>SL	OR DOUBLE SIGNED NOT EQUAL			167
310	AND <	AND LESS THAN			167
310	LD <	LOAD LESS THAN			167
310	OR <	OR LESS THAN			167
311	AND <l< td=""><td>AND DOUBLE LESS THAN</td><td></td><td></td><td>167</td></l<>	AND DOUBLE LESS THAN			167
311	LD <l< td=""><td>LOAD DOUBLE LESS THAN</td><td></td><td></td><td>167</td></l<>	LOAD DOUBLE LESS THAN			167
311	OR <l< td=""><td>OR DOUBLE LESS THAN</td><td></td><td></td><td>167</td></l<>	OR DOUBLE LESS THAN			167
312	AND <s< td=""><td>AND SIGNED LESS THAN</td><td></td><td></td><td>167</td></s<>	AND SIGNED LESS THAN			167
312	LD <s< td=""><td>LOAD SIGNED LESS THAN</td><td></td><td></td><td>167</td></s<>	LOAD SIGNED LESS THAN			167
312	OR <s< td=""><td>OR SIGNED LESS THAN</td><td></td><td></td><td>167</td></s<>	OR SIGNED LESS THAN			167
313	AND <sl< td=""><td>AND DOUBLE SIGNED LESS THAN</td><td></td><td></td><td>167</td></sl<>	AND DOUBLE SIGNED LESS THAN			167
313	LD <sl< td=""><td>LOAD DOUBLE SIGNED LESS THAN</td><td></td><td></td><td>167</td></sl<>	LOAD DOUBLE SIGNED LESS THAN			167
313	OR <sl< td=""><td>OR DOUBLE SIGNED LESS THAN</td><td></td><td></td><td>167</td></sl<>	OR DOUBLE SIGNED LESS THAN			167
315	AND <=	AND LESS THAN OR EQUAL			167
315	LD <=	LOAD LESS THAN OR EQUAL			167
315	OR <=	OR LESS THAN OR EQUAL			167
316	AND <=L	AND DOUBLE LESS THAN OR EQUAL			167
316	LD <=L	LOAD DOUBLE LESS THAN OR EQUAL			167
316	OR <=L	OR DOUBLE LESS THAN OR EQUAL			167
317	AND <=S	AND SIGNED LESS THAN OR EQUAL			167
317	LD <=S	LOAD SIGNED LESS THAN OR EQUAL			167
317	OR <=S	OR SIGNED LESS THAN OR EQUAL			167
318	AND <=SL	AND DOUBLE SIGNED LESS THAN OR			167
310	AND <=3L	EQUAL			107
318	LD <=SL	LOAD DOUBLE SIGNED LESS THAN OR EQUAL			167
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845	+D	DOUBLE FLOATING-POINT ADD	@+D		436
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847	*D	DOUBLE FLOATING-POINT MULTIPLY	@*D		439
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849	RADD	DOUBLE DEGREES TO RADIANS	@RADD		443
850	DEGD	DOUBLE RADIANS TO DEGREES	@RADD		444
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852	COSD	DOUBLE COSINE	@COSD		447
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855	ACOSD	DOUBLE ARC COSINE	@ACOSD		452
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# **SECTION 3 Instructions**

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	3-26-2	CLEAR CARRY: CLC(041)	606
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# 3-1 Notation and Layout of Instruction Descriptions

Instructions are described in groups by function. Refer to *2-3 Alphabetical List of Instructions by Mnemonic* for a list of instructions by mnemonic that lists the page number in this section for each instruction.

The description of each instruction is organized as described in the following table.

Item			Contents	
Name and Mnemonic	The heading of each section consists of the name of the instruction followed by the mnemonic with the function code in parentheses. Example: MOVE BIT: MOVB(082)			
Purpose	The basic purpos	se of the instruction	on is described after the se	ction heading.
Ladder Symbol and Operand Names	The ladder symbol used to represent the instruction on the CX-Programmer is shown, as in the example for the MOVE BIT instruction given below. The name of each operand is also provided with the ladder symbol.			
		MOVB(082)		
		S	S: Source word or data	
		С	C: Control word	
		D	<b>D</b> : Destination word	
Variations  The variations that can be used to control execution of the instruction unconditions are given using the mnemonic form. Any variation that is not an instruction is given as "Not supported."  Executed Each Cycle for ON Condition: The instruction is executed as it receives an ON execution condition.  Executed Once for Upward Differentiation: The instruction is execute the next cycle only after the execution condition changes from OFF to Executed Once for Downward Differentiation: The instruction is executing the next cycle only after the execution condition changes from ON  Always Executed: The instruction does not require an execution condition executed each cycle.  Creates ON Condition: The instruction is executed each cycle to describe the execution condition for the next instruction.		xecuted as long as is executed during om OFF to ON. on is executed dur- s from ON to OFF. ution condition and		
	Variations	Executed E	ach Cycle for ON Condition	MOVB(082)
		Executed O tion	nce for Upward Differentia-	@ MOVB(082)
		Executed O ation	nce for Downward Differenti	Not supported
Applicable Program Areas  The program areas in the areas in which the				
	Block program	Step progra	m Subroutines	Interrupt tasks
	areas	areas		

Item		Cor	ntents		
Operands	Where necessary, the as control words, is g		and bits used in spe	cific operands, such	
	C	8 7 m	0 n		
		Destination bit: (0 to 15 decimal			
Operand Specifications	The memory areas a like the following one same as those used not be specific for an	. The letters used in in the ladder symbo	the column headings	d are listed in a table s on the left are the cate when an area can-	
	Area	S	С	D	
	CIO Area	CIO 0000 to CIO 64	13		
	Work Area	W000 to W255		<u></u>	
	Auxiliary Bit Area	A000 to A447 A448 to A899		A448 to A899	
	Timer Area	T0000 to T0255			
	Counter Area	C0000 to C0255			
	DM Area D000000 to D32767				
Description	The function of the in described.	ction of the instruction and the operands used in the instruction are ed.			
Flags	of the instruction. An "OFF" indicates that a tion regardless of the	y flags that are not li a flag is turned OFF results of executing	sted are not affected immediately after ex the instruction.	ecution of the instruc-	
	Name	Label	•	ration	
	Error Flag	ER	ON if control data is OFF in all other case	-	
	Equals Flag	=	OFF		
	Negative Flag	N	OFF		
Precautions	Special precautions r	required in using the instruction are provided. Be sure to read cautions.			
Example	An example of using explain the function of	g the instruction with specific operands is provided to further of the instruction.			

### **Constants**

Constants input for operands are given as listed below.

### **Operand Descriptions and Operand Specifications**

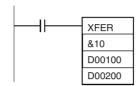
- Operands Specifying Bit Strings (Normally Input as Hexadecimal):
   Only the hexadecimal form is given for operands specifying bit strings,
   e.g., only "#0000 to #FFFF" is specified as the S operand for the
   MOV(021) instruction. On the CX-Programmer, however, bit strings can
   be input in decimal form by using the & prefix.
- Operands Specifying Numeric Values (Normally Input as Decimal, Including Jump Numbers):

Both the decimal and hexadecimal forms are given for operands specifying numeric values, e.g., "#0000 to #FFFF" and "&0 to &65535" are given for the N operand for the XFER(070) instruction.

 Operands Indicating Control Numbers (Except for Jump Numbers):
 The decimal form is given for control numbers, e.g., "0 to 255" is given for the N operand for the SBS(091) instruction.

### **Examples**

In the examples, constants are given using the CX-Programmer notation, e.g., operands specifying numeric values are given in decimal with an & prefix, as shown in the following example.



The input methods for constants from the CX-Programmer are given in the following table.

Operand	CX-Programmer
Operands specifying bit strings (normally input as hexadecimal)	Input as decimal with an & prefix or input as hexadecimal with an #
Operands specifying numeric values (normally input as decimal)	prefix. (See note.)
Operands specifying control numbers (except for jump numbers)	Input as decimal with an # prefix. (See note.)

**Note** When operands are input on the CX-Programmer, the input ranges will be displayed along with the appropriate prefixes.

### **Condition Flags**

With the CX-Programmer, the condition flags are registered in advance as global symbols with "P\_" in front of the symbol name.

Flag	Label used in this manual	CX-Programmer label
Error Flag	ER	P_ER
Access Error Flag	AER	P_AER
Carry Flag	CY	P_CY
Greater Than Flag	>	P_GT
Equals Flag	=	P_EQ
Less Than Flag	<	P_LT
Negative Flag	N	P_N
Overflow Flag	OF	P_OF
Underflow Flag	UF	P_UF
Greater Than or Equals Flag	>=	P_GE
Not Equal Flag	<>	P_NE
Less Than or Equals Flag	<=	P_LE
Always ON Flag	ON	P_On
Always OFF Flag	OFF	P_Off

# 3-2 Sequence Input Instructions

This section describes the sequence input instructions.

Instruction	Mnemonic	Function code	Page
LOAD	LD		95
LOAD NOT	LD NOT		97
AND	AND		99
AND NOT	AND NOT		101
OR	OR		102
OR NOT	OR NOT		104
AND LOAD	AND LD		105
OR LOAD	OR LD		107
NOT	NOT	520	111
UP	UP	521	112
DOWN	DOWN	522	112
LOAD BIT TEST	LD TST	350	113
LOAD BIT TEST NOT	LD TSTN	351	113
AND BIT TEST	AND TST	350	113
AND BIT TEST NOT	AND TSTN	351	113
OR BIT TEST	OR TST	350	113
OR BIT TEST NOT	OR TSTN	351	113

# 3-2-1 LOAD: LD

# **Purpose**

Indicates a logical start and creates an ON/OFF execution condition based on the ON/OFF status of the specified operand bit.

# **Ladder Symbol**



### **Variations**

Variations	Restarts Logic and Creates ON Each Cycle Operand Bit is ON	LD
	Restarts Logic and Creates ON Once for Upward Differentiation	@LD
	Restarts Logic and Creates ON Once for Downward Differentiation	%LD

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	LD operand bit
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A000.00 to A959.15
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255

Area	LD operand bit
Task Flag	TK0000
Condition Flags	ER, CY, N, OF, UF, >, =, <, >=, <>, <=, ON, OFF, AER
Clock Pulses	0.02 s, 0.1 s, 0.2 s, 1 s, 1 min
TR Area	TR0 to TR15
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Registers	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	DR0 to DR15, IR0 to DR0 to DR15, IR15
	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

**Note** TR bits are used only when inputting programs in mnemonic form. It is not necessary to input them when programming in ladder diagram form.

### **Description**

LD is used for the first normally open bit from the bus bar or for the first normally open bit of a logic block. The specified bit in I/O memory is read. LD is used in the following circumstances as an instruction for indicating a logical start.

- When directly connecting to the bus bar.
- When logic blocks are connected by AND LD or OR LD, i.e., at the beginning of a logic block.

The AND LOAD and OR LOAD instructions are used to connect in series or in parallel logic blocks beginning with LD or LD NOT.

At least one LOAD or LOAD NOT instruction is required for the execution condition when output-related instructions cannot be connected directly to the bus bar. If there is no LOAD or LOAD NOT instruction, a programming error will occur with the program check by the CX-Programmer.

When logic blocks are connected by AND LOAD or OR LOAD instructions, the total number of AND LOAD/OR LOAD instructions must match the total number of LOAD/LOAD NOT instructions minus1. If they do not match, a programming error will occur. For details, refer to 3-2-7 AND LOAD: AND LD and 3-2-8 OR LOAD: OR LD.

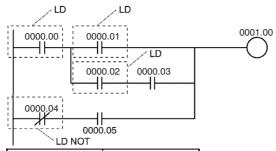
### **Flags**

There are no flags affected by this instruction.

#### **Precautions**

Differentiate up (@) or differentiate down (%) can be specified for LD. If differentiate up (@) is specified, the execution condition is turned ON for one cycle only after the status of the operand bit goes from OFF to ON. If differentiate down (%) is specified, the execution condition is turned ON for one cycle only after the status of the operand bit goes from ON to OFF.

# Example



Instruction	Operand	
LD	0000.00	AND LD
LD	0000.01	OR LD AND LD
LD	0000.02	
AND	0000.03	ORLD
OR LD		
AND LD		]
LD NOT	0000.04	
AND	0000.05	
OR LD		]-
OUT	0001.00	

# 3-2-2 LOAD NOT: LD NOT

# **Purpose**

Indicates a logical start and creates an ON/OFF execution condition based on the reverse of the ON/OFF status of the specified operand bit.

# **Ladder Symbol**



### **Variations**

Variations	Restarts Logic and Creates ON Each Cycle Operand Bit is OFF	LD NOT
	Restarts Logic and Creates ON Once for Upward Differentiation	@LD NOT
	Restarts Logic and Creates ON Once for Downward Differentiation	%LD NOT

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	LD NOT bit operand
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A000.00 to A959.15
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
Task Flag	TK0000

Area	LD NOT bit operand
Condition Flags	ER, CY, N, OF, UF, >, =, <, >=, <>, <=, ON, OFF, AER
Clock Pulses	0.02 s, 0.1 s, 0.2 s, 1 s, 1 min
TR Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,–(– –)IR0 to , –(– –)IR15

**Note** TR bits are used only when inputting programs in mnemonic form. It is not necessary to input them when programming in ladder diagram form.

### **Description**

LD NOT is used for the first normally closed bit from the bus bar, or for the first normally closed bit of a logic block. The specified bit in I/O memory is read and reversed. LD NOT is used in the following circumstances as an instruction for indicating a logical start.

- · When directly connecting to the bus bar.
- When logic blocks are connected by AND LD or OR LD. (Used at the beginning of a logic block.)

The AND LOAD and OR LOAD instructions are used to connect in series or in parallel logic blocks beginning with LD or LD NOT.

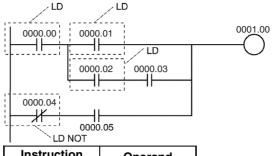
At least one LOAD or LOAD NOT instruction is required for the execution condition when output-related instructions cannot be connected directly to the bus bar. If there is no LOAD or LOAD NOT instruction, a program error will occur with the program check by the CX-Programmer.

When logic blocks are connected by AND LOAD or OR LOAD instructions, the total number of AND LOAD/OR LOAD instructions must match the total number of LOAD/LOAD NOT instructions minus 1. If they do not match, a programming error will occur.

**Flags** 

There are no flags affected by this instruction.

# Example



Instruction	Operand	
LD	0000.00	AND LD
LD	0000.01	OR LD AND LD
LD	0000.02	
AND	0000.03	
OR LD		
AND LD		]
LD NOT	0000.04	
AND	0000.05	]
OR LD		]-
OUT	0001.00	]

# 3-2-3 AND: AND

**Purpose** 

Takes a logical AND of the status of the specified operand bit and the current execution condition.

**Ladder Symbol** 



**Variations** 

Variations	Creates ON Each Cycle AND Result is ON	AND
	Creates ON Once for Upward Differentiation	@AND
	Creates ON Once for Downward Differentiation	%AND

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	AND bit operand
CIO Area	CIO 0000.00 to CIO 6413.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A000.00 to A959.15
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
Task Flag	TK0000
Condition Flags	ER, CY, N, OF, UF, >, =, <, >=, <>, <=, ON, OFF, AER
Clock Pulses	0.02 s, 0.1 s, 0.2 s, 1 s, 1 min
TR Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing using Index Registers	,IR0 to ,IR15  -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15  DR0 to DR15, IR0 to DR0 to DR15, IR15  ,IR0+(++) to ,IR15+(++)  ,-()IR0 to , -()IR15

**Description** 

**Flags** 

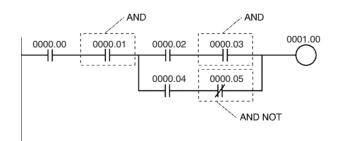
**Precautions** 

**Example** 

AND is used for a normally open bit connected in series. AND cannot be directly connected to the bus bar, and cannot be used at the beginning of a logic block. The specified bit in I/O memory is read.

There are no flags affected by this instruction.

Differentiate up (@) or differentiate down (%) can be specified for AND. If differentiate up (@) is specified, the execution condition is turned ON for one cycle only after the status of the operand bit goes from OFF to ON. If differentiate down (%) is specified, the execution condition is turned ON for one cycle only after the status of the operand bit goes from ON to OFF.



Instruction	Operand
LD	0000.00
AND	0000.01
LD	0000.02
AND	0000.03
LD	0000.04
AND NOT	0000.05

Instruction	Operand
OR LD	
AND LD	
OUT	0001.00

# 3-2-4 AND NOT: AND NOT

**Purpose** 

Reverses the status of the specified operand bit and takes a logical AND with the current execution condition.

**Ladder Symbol** 



**Variations** 

Variations	Creates ON Each Cycle AND NOT Result is ON	AND NOT
	Creates ON Once for Upward Differentiation	@AND NOT
	Creates ON Once for Downward Differentiation	%AND NOT

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	AND NOT bit operand
CIO Area	CIO 0000.00 to CIO 6413.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A000.00 to A959.15
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
Task Flag	TK0000
Condition Flags	ER, CY, N, OF, UF, >, =, <, >=, <>, <=, ON, OFF, AER
Clock Pulses	0.02 s, 0.1 s, 0.2 s, 1 s, 1 min
TR Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

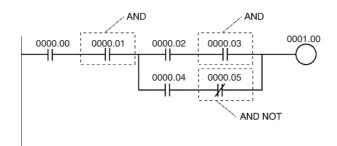
Description

AND NOT is used for a normally closed bit connected in series. AND NOT cannot be directly connected to the bus bar, and cannot be used at the beginning of a logic block. The specified bit in I/O memory is read.

**Flags** 

There are no flags affected by this instruction.

# **Example**



Instruction	Operand
LD	0000.00
AND	0000.01
LD	0000.02
AND	0000.03
LD	0000.04
AND NOT	0000.05
OR LD	
AND LD	
OUT	0001.00

# 3-2-5 OR: OR

# **Purpose**

Takes a logical OR of the ON/OFF status of the specified operand bit and the current execution condition.

# **Ladder Symbol**



### **Variations**

Variations	Creates ON Each Cycle OR Result is ON	OR
	Creates ON Once for Upward Differentiation	@OR
	Creates ON Once for Downward Differentiation	%OR

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	OR bit operand
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A000.00 to A959.15
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
Task Flag	TK0000
Condition Flags	ER, CY, N, OF, UF, >, =, <, >=, <>, <=, ON, OFF, AER
Clock Pulses	0.02 s, 0.1 s, 0.2 s, 1 s, 1 min
DM Area	
Indirect DM addresses in binary	

Area	OR bit operand	
Indirect DM addresses in BCD		
Constants		
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

### **Description**

OR is used for a normally open bit connected in parallel. A normally open bit is configured to form a logical OR with a logic block beginning with a LOAD or LOAD NOT instruction (connected to the bus bar or at the beginning of the logic block). The specified bit in I/O memory is read.

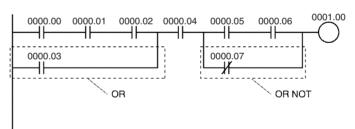
### **Flags**

There are no flags affected by this instruction.

### **Precautions**

Differentiate up (@) or differentiate down (%) can be specified for OR. If differentiate up (@) is specified, the execution condition is turned ON for one cycle only after the status of the operand bit goes from OFF to ON. If differentiate down (%) is specified, the execution condition is turned ON for one cycle only after the status of the operand bit goes from ON to OFF.

### Example



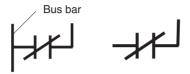
Instruction	Operand
LD	0000.00
AND	0000.01
AND	0000.02
OR	0000.03
AND	0000.04
LD	0000.05
AND	0000.06
OR NOT	0000.07
AND LD	
OUT	0001.00

# **3-2-6** OR NOT: OR NOT

**Purpose** 

Reverses the status of the specified bit and takes a logical OR with the current execution condition.

**Ladder Symbol** 



**Variations** 

Variations	Creates ON Each Cycle OR NOT Result is ON OR NOT	
	Creates ON Once for Upward Differentiation @ OR NOT	
	Creates ON Once for Downward Differentiation	%OR NOT

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	OR NOT bit operand
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A000.00 to A959.15
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
Task Flag	TK0000
Condition Flags	ER, CY, N, OF, UF, >, =, <, >=, <>, <=, ON, OFF, AER
Clock Pulses	0.02 s, 0.1 s, 0.2 s, 1 s, 1 min
TR Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,–(– –)IR0 to , –(– –)IR15

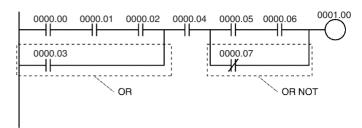
**Description** 

OR NOT is used for a normally closed bit connected in parallel. A normally closed bit is configured to form a logical OR with a logic block beginning with a LOAD or LOAD NOT instruction (connected to the bus bar or at the beginning of the logic block). The specified bit in I/O memory is read.

**Flags** 

There are no flags affected by this instruction.

### **Example**



Instruction	Operand
LD	0000.00
AND	0000.01
AND	0000.02
OR	0000.03
AND	0000.04
LD	0000.05
AND	0000.06
OR NOT	0000.07
AND LD	
OUT	0001.00

### 3-2-7 AND LOAD: AND LD

**Purpose** 

Takes a logical AND between logic blocks.

**Ladder Symbol** 



**Variations** 

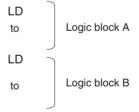
Variations Creates ON Each Cycle AND Result is ON	AND LD
---	--------

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Description**

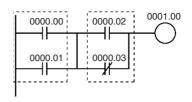
AND LD connects in series the logic block just before this instruction with another logic block.



AND LD ...... Serial connection between logic block A and logic block B.

The logic block consists of all the instructions from a LOAD or LOAD NOT instruction until just before the next LOAD or LOAD NOT instruction on the same rungs.

In the following diagram, the two logic blocks are indicated by dotted lines. Studying this example shows that an ON execution condition will be produced when either of the execution conditions in the left logic block is ON (i.e., when either CIO 0000.00 or CIO 0000.01 is ON) **and** either of the execution conditions in the right logic block is ON (i.e., when either CIO 0000.02 is ON or CIO 0000.03 is OFF).



### Coding

Address	Instruction	Operand
000000	LD	0000.00
000001	OR	0000.01
000002	LD	0000.02
000003	OR NOT	0000.03
000004	AND LD	
000005	OUT	0001.00

Second LD: Used for first bit of next block connected in series to previous block.

**Flags** 

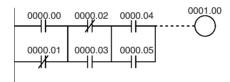
**Precautions** 

There are no flags affected by this instruction.

Three or more logic blocks can be connected in series using this instruction to first connect two of the logic blocks and then to connect the next and subsequent ones in order. It is also possible to continue placing this instruction after three or more logic blocks and connect them together in series.

When a logic block is connected by AND LOAD or OR LOAD instructions, the total number of AND LOAD/OR LOAD instructions must match the total number of LOAD/LOAD NOT instructions minus 1. If they do not match, a program error will occur.

# **Example**



### Coding Example (1)

Instruction	Operand
LD	0000.00
OR NOT	0000.01
LD NOT	0000.02
OR	0000.03
AND LD	
LD	0000.04
OR	0000.05
AND LD	
OUT	0001.00

### Coding Example (2)

Instruction	Operand
LD	00.000
OR NOT	0000.01

Instruction	Operand
LD NOT	0000.02
OR	0000.03
LD	0000.04
OR	0000.05
AND LD	
AND LD	
	-
OUT	0001.00

The AND LOAD instruction can be used repeatedly. In programming method (2) above, however, the number of AND LOAD instructions becomes one less than the number of LOAD and LOAD NOT instructions before that.

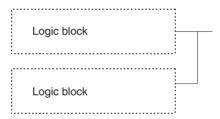
In method (2), make sure that the total number of LOAD and LOAD NOT instructions before AND LOAD is not more than eight. To use nine or more, program using method (1). If there are nine or more with method (2), then a program error will occur during the program check by the CX-Programmer.

### 3-2-8 OR LOAD: OR LD

### **Purpose**

Takes a logical OR between logic blocks.

### **Ladder Symbol**



**Variations** 

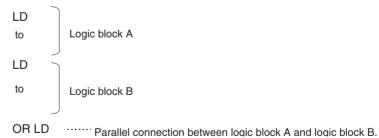
Variations	OR LD
------------	-------

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Description**

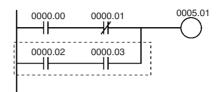
AND LD connects in parallel the logic block just before this instruction with another logic block.



The logic block consists of all the instructions from a LOAD or LOAD NOT instruction until just before the next LOAD or LOAD NOT instruction on the same rungs.

The following diagram requires an OR LOAD instruction between the top logic block and the bottom logic block. An ON execution condition would be produced either when CIO 0000.00 is ON and CIO 0000.01 is OFF or when

CIO 0000.02 and CIO 0000.03 are both ON. The operation of and mnemonic code for the OR LOAD instruction is exactly the same as those for a AND LOAD instruction except that the current execution condition is ORed with the last unused execution condition.



### Coding

Address	Instruction	Operand
000100	LD	0000.00
000101	AND NOT	0000.01
000102	LD	0000.02
000103	AND	0000.03
000104	OR LD	
000105	OUT	0005.01

Second LD: Used for first bit of next block connected in parallel to previous block.

Flags

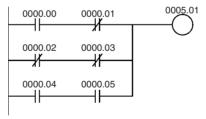
**Precautions** 

There are no flags affected by this instruction.

Three or more logic blocks can be connected in parallel using this instruction to first connect two of the logic blocks and then to connect the next and subsequent ones in order. It is also possible to continue placing this instruction after three or more logic blocks and connect them together in parallel.

When a logic block is connected by AND LOAD or OR LOAD instructions, the total number of AND LOAD/OR LOAD instructions must match the total number of LOAD/LOAD NOT instructions minus 1. If they do not match, a programming error will occur.

Example



### Coding Example (1)

Instruction	Operand
LD	00.000
AND NOT	0000.01
LD NOT	0000.02
AND NOT	0000.03
OR LD	
LD	0000.04
AND	0000.05
OR LD	

Instruction	Operand
•	•
OUT	0005.01

### Coding Example (2)

Instruction	Operand
LD	0000.00
AND NOT	0000.01
LD NOT	0000.02
AND NOT	0000.03
LD	0000.04
AND	0000.05
•	
OR LD	
OR LD	
OUT	0005.01

The OR LOAD instruction can be used repeatedly. In programming method (2) above, however, the number of OR LOAD instructions becomes one less than the number of LOAD and LOAD NOT instructions before that.

In method (2), make sure that the total number of LOAD and LOAD NOT instructions before OR LOAD is not more than eight. To use nine or more, program using method (1). If there are nine or more with method (2), then a program error will occur during the program check by the Peripheral Device.

### 3-2-9 Differentiated Instructions

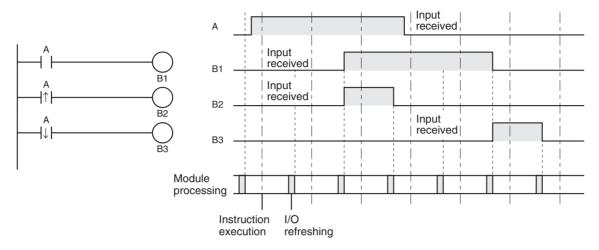
The LOAD, AND, and OR instructions have differentiated variations in addition to their ordinary forms. The I/O timing for data handled by instructions differs for ordinary and differentiated instructions.

Ordinary and differentiated instructions are executed using data input by previous I/O refresh processing, and the results are output with the next I/O processing. Here "I/O refreshing" means the data exchanged between the internal memory and the built-in I/O.

Instruction variation	Mnemonic	Function	I/O refresh
Ordinary	LD, AND, OR, LD NOT, AND NOT, OR NOT	The ON/OFF status of the specified bit is taken by the Module with cyclic refreshing, and it is reflected in the next instruction execution.	Cyclic refreshing
	OUT, OUT NOT	After the instruction is executed, the ON/OFF status of the specified bit is output with the next cyclic refreshing.	
Differentiated up	@LD, @AND, @OR	The instruction is executed once when the specified bit turns from OFF to ON and the ON state is held for one cycle.	
Differentiated down	%LD, %AND, %OR	The instruction is executed once when the specified bit turns from ON to OFF and the ON state is held for one cycle.	

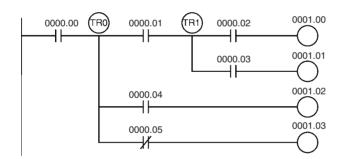
# 3-2-10 Operation Timing for I/O Instructions

The following chart shows the differences in the timing of instruction operations for a program configured from LD and OUT.



### 3-2-11 TR Bits

TR bits are used to temporarily retain the ON/OFF status of execution conditions in a program when programming in mnemonic code. They are not used when programming directly in ladder program form because the processing is automatically executed by the CX-Programmer. The following diagram shows a simple application using two TR bits.

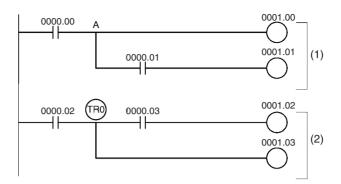


Address	Instruction	Operands
000000	LD	0000.00
000001	OUT	TR0
000002	AND	0000.01
000003	OUT	TR1
000004	AND	0000.02
000005	OUT	0001.00
000006	LD	TR1
000007	AND	0000.03
800000	OUT	0001.01
000009	LD	TR0
000010	AND	0000.04
000011	OUT	0001.02
000012	LD	TR0
000013	AND NOT	0000.05
000014	OUT	0001.03

### Using TR0 to TR15

TR0 to TR15 are used only with LOAD and OUTPUT instructions. There are no restrictions on the order in which the bit addresses are used.

Sometimes it is possible to simplify a program by rewriting it so that TR bits are not required. The following diagram shows one case in which a TR bit is unnecessary and one in which a TR bit is required.

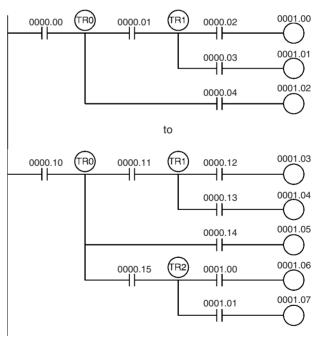


In instruction block (1), the ON/OFF status at point A is the same as for output CIO 0001.00, so AND 0000.01 and OUT 0001.01 can be coded without requiring a TR bit. In instruction block (2), the status of the branching point and that of output CIO 0001.02 are not necessarily the same, so a TR bit must be used. In this case, the number of steps in the program could be reduced by using instruction block (1) in place of instruction block (2).

TR0 to TR15 Considerations TR bits are used only for retaining (OUT TR0 to TR15) and restoring (LD TR0 to TR15) the ON/OFF status of branching points in programs with many output branches. They are thus different from general bits, and cannot be used with AND or OR instructions, or with instructions that include NOT.

TR0 to TR15 output Duplication

A TR bit address cannot be repeated within the same block in a program with many output branches, as shown in the following diagram. It can, however, be used again in a different block.



# 3-2-12 NOT: NOT(520)

**Purpose** Reverses the execution condition.

Ladder Symbol

NOT(520)

**Variations** 

Variations Reverses the Execution Condition Each Cycle	NOT(520)
--	----------

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

**Description** 

NOT(520) is placed between an execution condition and another instruction to

invert the execution condition.

**Flags** 

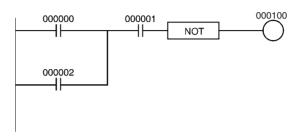
There are no flags affected by NOT(520)

**Precautions** 

NOT(520) is an intermediate instruction, i.e., it cannot be used as a right-hand instruction. Be sure to program a right-hand instruction after NOT(520).

**Example** 

NOT(520) reverses the execution condition in the following example.



The following table shows the operation of this program section.

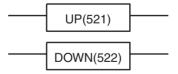
Input bit status			Output bit status
CIO 000000	CIO 000001	CIO 000002	CIO 000100
1	1	1	0
1	1	0	0
1	0	1	1
0	1	1	0
1	0	0	1
0	1	0	1
0	0	1	1
0	0	0	1

# 3-2-13 CONDITION ON/OFF: UP(521) and DOWN(522)

**Purpose** 

UP(521) turns ON the execution condition for the next instruction for one cycle when the execution condition it receives goes from OFF to ON. DOWN(522) turns ON the execution condition for the next instruction for one cycle when the execution condition it receives goes from ON to OFF.

**Ladder Symbols** 



**Variations** 

Variations	Creates ON Once for Upward Differentiation	UP(521)
Variations	Creates ON Once for Downward Differentiation	UP(522)

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	ОК	OK	OK

### **Description**

UP(521) is placed between an execution condition and another instruction to turn the execution condition into an up-differentiated condition. UP(521) causes the connecting instruction to be executed just once when the execution condition goes from OFF to ON.

DOWN(522) is placed between an execution condition and another instruction to turn the execution condition into a down-differentiated condition. DOWN(522) causes the connecting instruction to be executed just once when the execution condition goes from ON to OFF.

The DIFU(013) and DIFD(014) instructions can also be used for the same purpose, but they require work bits. UP(521) and DOWN(522) simplify programming by reducing the number of work bits and program addresses needed.

**Flags** 

There are no flags affected by UP(521) and DOWN(522).

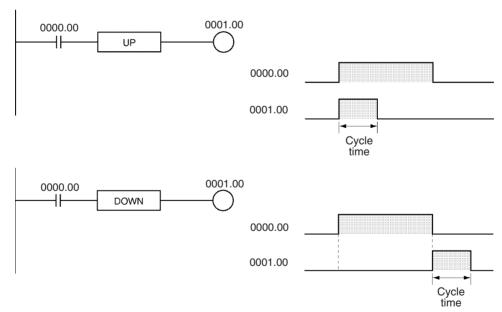
**Precautions** 

UP(521) and DOWN(522) are intermediate instructions, i.e., they cannot be used as right-hand instructions. Be sure to program a right-hand instruction after UP(521) or DOWN(522).

The operation of UP(521) and DOWN(522) depends on the execution condition for the instruction as well as the execution condition for the program section when it is programmed in an interlocked program section, a jumped program section, or a subroutine. Refer to 3-4-3 INTERLOCK and INTER-LOCK CLEAR: IL(002) and ILC(003), 3-4-4 JUMP and JUMP END: JMP(004) and JME(005), and 3-19 Interrupt Control Instructions for details.

### **Examples**

When CIO 0000.00 goes from OFF to ON in the following example, CIO 0001.00 is turned ON for just one cycle.



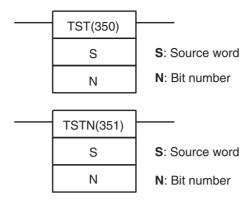
# 3-2-14 BIT TEST: TST(350) and TSTN(351)

#### **Purpose**

LD TST(350), AND TST(350), and OR TST(350) are used in the program like LD, AND, and OR; the execution condition is ON when the specified bit in the specified word is ON, and OFF when the bit is OFF.

LD TSTN(351), AND TSTN(351), and OR TSTN(351) are used in the program like LD NOT, AND NOT, and OR NOT; the execution condition is OFF when the specified bit in the specified word is ON, and ON when the bit is OFF.

### **Ladder Symbols**



### **Variations**

Variations	Executed Each Cycle	TST(350)
Variations	Executed Each Cycle	TSTN(351)

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operands**

### N: Bit number

The bit number must be between 0000 and 000F hexadecimal or between &0000 and &0015 decimal. Only the rightmost bit (0 to F hexadecimal) of the contents of the word is valid when a word address is specified.

### **Operand Specifications**

Area	S	N	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants		#0000 to #000F (binary) or &0 to &15	
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 , IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

### **Description**

LD TST(350), AND TST(350), and OR TST(350) can be used in the program like LD, AND, and OR; the execution condition is ON when the specified bit in the specified word is ON and OFF when the bit is OFF. Unlike LD, AND, and OR, bits in the DM area can be used as operands in TST(350).

LD TSTN(351), AND TSTN(351), and OR TSTN(351) can be used in the program like LD NOT, AND NOT, and OR NOT; the execution condition is OFF

when the specified bit in the specified word is ON and ON when the bit is OFF. Unlike LD NOT, AND NOT, and OR NOT, bits in the DM area can be used as operands in TSTN(351).

### **Flags**

Name	Label	Operation
Error Flag	ER	Unchanged
Equals Flag	=	Unchanged
Negative Flag	N	Unchanged

#### **Precautions**

TST(350) and TSTN(351) are intermediate instructions, i.e., they cannot be used as right-hand instructions. Be sure to program a right-hand instruction after TST(350) or TSTN(351).

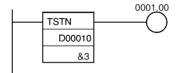
### **Examples**

### LD TST(350) and LD TSTN(351)

In the following example, CIO 0001.00 is turned ON when bit 3 of D00010 is ON.

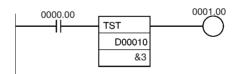


In the following example, CIO 0001.00 is turned ON when bit 3 of D00010 is OFF.

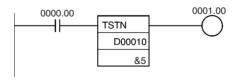


### AND TST(350) and AND TSTN(351)

In the following example, CIO 0001.00 is turned ON when CIO 0000.00 and bit 3 of D00010 are both ON.

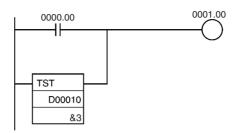


In the following example, CIO 0001.00 is turned ON when CIO 0000.00 is ON and bit 5 of D00010 is OFF.

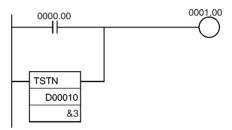


# OR TST(350) and OR TSTN(351)

In the following example, CIO 0001.00 is turned ON when CIO 0000.00 or bit 3 of D00010 is ON.



In the following example, CIO 0001.00 is turned ON when CIO 0000.00 is ON or bit 3 of D00010 is OFF.



# 3-3 Sequence Output Instructions

This section describes the sequence output instructions.

Instruction	Mnemonic	Function code	Page
OUTPUT	OUT		117
OUTPUT NOT	OUT NOT		118
KEEP	KEEP	011	119
DIFFERENTIATE UP	DIFU	013	122
DIFFERENTIATE DOWN	DIFD	014	122
SET	SET		125
RESET	RSET		125
MULTIPLE BIT SET	SETA	530	126
MULTIPLE BIT RESET	RSTA	531	126
SINGLE BIT SET	SETB	532	129
SINGLE BIT RESET	RSTB	533	129
SINGLE BIT OUTPUT	OUTB	534	132

# 3-3-1 OUTPUT: OUT

**Purpose** 

Outputs the result (execution condition) of the logical processing to the specified bit.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	OUT
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

Area	OUT bit operand
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A448.00 to A959.15
Timer Area	
Counter Area	
TR Area	TR0 to TR15
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	

Area	OUT bit operand	
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

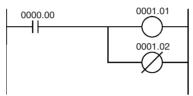
**Description** 

The status of the execution condition (power flow) is written to the specified bit in I/O memory.

**Flags** 

There are no flags affected by this instruction.

**Example** 



Instruction	Operand
LD	0000.00
OUT	0001.01
OUT NOT	0001.02

# 3-3-2 OUTPUT NOT: OUT NOT

**Purpose** 

Reverses the result (execution condition) of the logical processing, and outputs it to the specified bit.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	OUT NOT
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

Area	OUT bit operand
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A448.00 to A959.15
Timer Area	
Counter Area	
TR Area	TR0 to TR15
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	

Area	OUT bit operand
Constants	
Data Resisters	
Index Registers	
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

Note The TR Area is used only when programming with mnemonic code. It is not used for ladder programs.

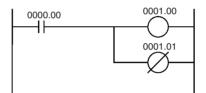
**Description** 

The status of the execution condition (power flow) is reversed and written to a specified bit in I/O memory.

**Flags** 

There are no flags affected by this instruction.

Example



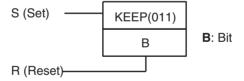
Instruction	Operand
LD	0000.00
OUT	0001.00
OUT NOT	0001.01

#### KEEP: KEEP(011) 3-3-3

**Purpose** 

Operates as a latching relay.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	KEEP(011)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

Area	В
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A448.00 to A959.15
Timer Area	

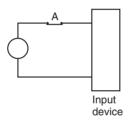
Area	В
Counter Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing using Index Registers	,IR0 to ,IR15
	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

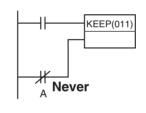
### **Flags**

### **Precautions**

There are no flags affected by this instruction.

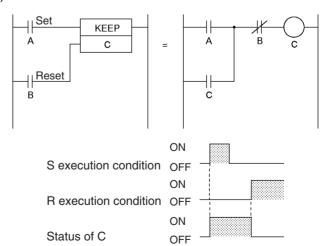
Do not use the input from an external device that has a normally closed contact for the Reset input of KEEP(011). If the AC power supply is interrupted or a momentary power interruption occurs, there will be a delay in shutting down the FQM1's internal DC power supply, which can cause the operand bit of KEEP(011) to be reset.



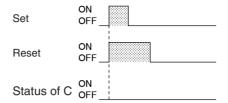


### **Description**

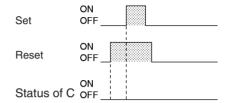
When S turns ON, the designated bit will go ON and stay ON until reset, regardless of whether S stays ON or goes OFF. When R turns ON, the designated bit will go OFF. The relationship between execution conditions and KEEP(011) bit status is shown below.



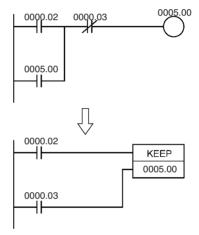
If S and R are ON simultaneously, the reset input takes precedence.



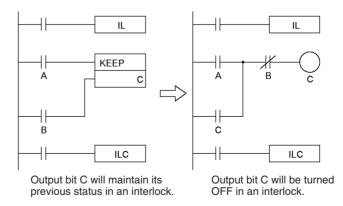
The set input (S) cannot be received while R is ON.



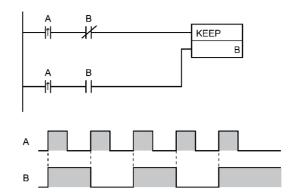
KEEP(011) operates like the self-maintaining bit, but a self-maintaining bit programmed with KEEP(011) requires one less instruction.



Self-maintaining bits programmed with KEEP(011) will maintain status even in an interlock program section, unlike the self-maintaining bit programmed without KEEP(011).



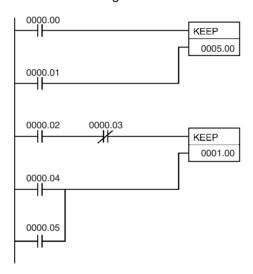
KEEP(011) can be used to create flip-flops as shown below.



### Example

When CIO 0000.00 goes ON in the following example, CIO 0005.00 is turned ON. CIO 0005.00 remains ON until CIO 0000.01 goes ON.

When CIO 0000.02 goes ON and CIO 0000.03 goes OFF in the following example, CIO 0001.00 is turned ON. CIO 0001.00 remains ON until CIO 0000.04 or CIO 0000.05 goes ON.



## Coding

Address	Instruction	Operand
000100	LD	0000.00
000101	LD	0000.01
000102	KEEP (011)	0005.00
000103	LD	0000.02
000104	AND NOT	0000.03
000105	LD	0000.04
000106	OR	0000.05
000107	KEEP (011)	0001.00

**Note** KEEP(011) is input in different orders on in ladder and mnemonic form. In ladder form, input the set input, KEEP(011), and then the reset input. In mnemonic form, input the set input, the reset input, and then KEEP(011).

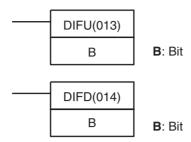
# 3-3-4 DIFFERENTIATE UP/DOWN: DIFU(013) and DIFD(014)

### **Purpose**

 $\mathsf{DIFU}(013)$  turns the designated bit ON for one cycle when the execution condition goes from OFF to ON (rising edge).

DIFD(014) turns the designated bit ON for one cycle when the execution condition goes from ON to OFF (falling edge).

# **Ladder Symbols**



### **Variations**

Variations	Executed Each Cycle for ON Condition	Not supported
	Executed Once for Upward Differentiation	DIFU(013)
	<b>Executed Once for Downward Differentiation</b>	Not supported

Variations	Executed Each Cycle for ON Condition	Not supported
	<b>Executed Once for Upward Differentiation</b>	Not supported
	<b>Executed Once for Downward Differentiation</b>	DIFD(014)

# **Applicable Program Areas**

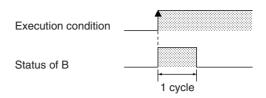
Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

# **Operand Specifications**

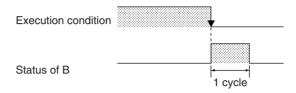
Area	В	
CIO Area	CIO 0000.00 to CIO 6143.15	
Work Area	W000.00 to W255.15	
Auxiliary Bit Area	A448.00 to A959.15	
Timer Area		
Counter Area		
DM Area		
Indirect DM addresses in binary		
Indirect DM addresses in BCD		
Constants		
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

# **Description**

When the execution condition goes from OFF to ON, DIFU(013) turns B ON. When DIFU(013) is reached in the next cycle, B is turned OFF.



When the execution condition goes from ON to OFF, DIFD(014) turns B ON. When DIFD(014) is reached in the next cycle, B is turned OFF.



### **Flags**

No flags are affected by DIFU(013) and DIFD(014).

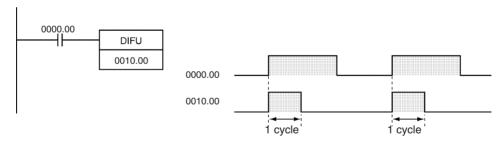
### **Precautions**

The operation of DIFU(013) or DIFD(014) depends on the execution condition for the instruction itself as well as the execution condition for the program section when it is programmed in an interlocked program section, a jumped program section, or a subroutine. Refer to 3-4-3 INTERLOCK and INTERLOCK CLEAR: IL(002) and ILC(003), 3-4-4 JUMP and JUMP END: JMP(004) and JME(005), and 3-19 Interrupt Control Instructions for details.

### **Examples**

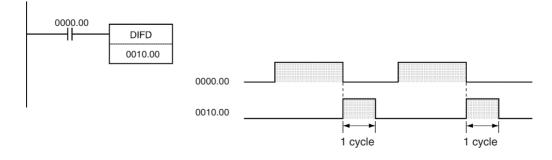
### Operation of DIFU(013)

When CIO 0000.00 goes from OFF to ON in the following example, CIO 0010.00 is turned ON for one cycle.



### Operation of DIFD(014)

When CIO 0000.00 goes from ON to OFF in the following example, CIO 0010.00 is turned ON for one cycle.

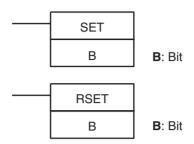


## 3-3-5 SET and RESET: SET and RSET

## **Purpose**

SET turns the operand bit ON when the execution condition is ON. RSET turns the operand bit OFF when the execution condition is ON.

## **Ladder Symbols**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	SET
	Executed Once for Upward Differentiation	@SET
	<b>Executed Once for Downward Differentiation</b>	%SET

Variations	Executed Each Cycle for ON Condition	RSET
	Executed Once for Upward Differentiation	@RSET
	Executed Once for Downward Differentiation	%RSET

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

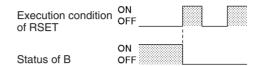
Area	В
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A448.00 to A959.15
Timer Area	
Counter Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

## **Description**

SET turns the operand bit ON when the execution condition is ON, and does not affect the status of the operand bit when the execution condition is OFF. Use RSET to turn OFF a bit that has been turned ON with SET.



RSET turns the operand bit OFF when the execution condition is ON, and does not affect the status of the operand bit when the execution condition is OFF. Use SET to turn ON a bit that has been turned OFF with RSET.



The set and reset inputs for a KEEP(011) instruction must be programmed with the instruction, but the SET and RSET instructions can be programmed completely independently. Furthermore, the same bit may be used as the operand in any number of SET or RSET instructions.

**Flags** 

No flags are affected by SET and RSET.

**Precautions** 

SET and RSET cannot be used to set and reset timers and counters.

When SET or RSET is programmed between IL(002) and ILC(003) or JMP(004) and JME(005), the status of the specified bit will not be changed if the execution condition for IL(002) or JMP(004) is OFF.

Example

#### Differences between OUT/OUT NOT and SET/RSET

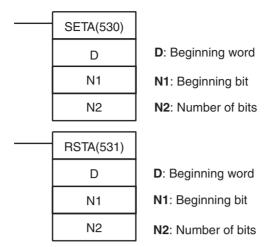
The operation of SET differs from that of OUT because the OUT instruction turns the operand bit OFF when its execution condition is OFF. Likewise, RSET differs from OUT NOT because OUT NOT turns the operand bit ON when its execution condition is OFF.

# 3-3-6 MULTIPLE BIT SET/RESET: SETA(530)/RSTA(531)

**Purpose** 

SETA(530) turns ON the specified number of consecutive bits. RSTA(531) turns OFF the specified number of consecutive bits.

## **Ladder Symbols**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	SETA(530)
	Executed Once for Upward Differentiation	@SETA(530)
	<b>Executed Once for Downward Differentiation</b>	Not supported

Variations	Executed Each Cycle for ON Condition	RSTA(531)
	Executed Once for Upward Differentiation	@RSTA(531)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

#### **D: Beginning Word**

Specifies the first word in which bits will be turned ON or OFF.

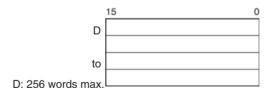
## N1: Beginning Bit

Specifies the first bit which will be turned ON or OFF. N1 must be #0000 to #000F (&0 to &15).

#### N2: Number of Bits

Specifies the number of bits which will be turned ON or OFF. N2 must be #0000 to #FFFF (&0 to &65535).

**Note** The bits being turned ON or OFF must be in the same data area. (The range of words is roughly D to D+N2÷16.)



## **Operand Specifications**

Area	D	N1	N2	
CIO Area	CIO 0000 to CIO 6143			
Work Area	W000 to W255	W000 to W255		
Auxiliary Bit Area	A448 to A959 A000 to A959			
Timer Area	T0000 to T0255			
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767			

Area	D	N1	N2
Indirect DM addresses in binary	@ D00000 to @ I	D32767	
Indirect DM addresses in BCD	*D00000 to *D32	767	
Constants		#0000 to #000F (binary) or &0 to &15	#0000 to #FFFF (binary) or &0 to &65535
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15  -2048 to +2047, IR0 to -2048 to +2047, IR15  DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-() IR0 to , -() IR15		

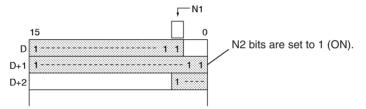
#### **Description**

The operation of SETA(530) and RSTA(531) are described separately below.

## Operation of SETA(530)

SETA(530) turns ON N2 bits, beginning from bit N1 of D, and continuing to the left (more-significant bits). All other bits are left unchanged. (No changes will be made if N2 is set to 0.)

Bits turned ON by SETA(530) can be turned OFF by any other instructions, not just RSTA(531).

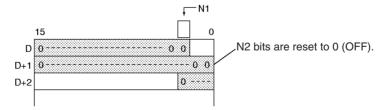


SETA(530) can be used to turn ON bits in data areas that are normally accessed by words only, such as the DM area.

#### Operation of RSTA(531)

RSTA(531) turns OFF N2 bits, beginning from bit N1 of D, and continuing to the left (more-significant bits). All other bits are left unchanged. (No changes will be made if N2 is set to 0.)

Bits turned OFF by RSTA(531) can be turned ON by any other instructions, not just SETA(530).



RSTA(531) can be used to turn OFF bits in data areas that are normally accessed by words only, such as the DM area.

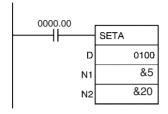
#### **Flags**

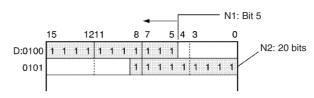
Name	Label	Operation
Error Flag	ER	ON if N1 is not within the specified range of 0000 to 000F.
		OFF in all other cases.

## **Examples**

## SETA(530) Example

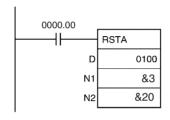
When CIO 0000.00 is turned ON in the following example, the 20 bits (0014 hexadecimal) beginning with bit 5 of CIO 0100 are turned ON.

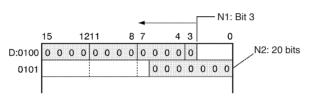




#### RSTA(531) Example

When CIO 0000.00 is turned ON in the following example, the 20 bits (0014 hexadecimal) beginning with bit 3 of CIO 0100 are turned OFF.





## 3-3-7 SINGLE BIT SET/RESET: SETB(532)/RSTB(533)

**Purpose** 

SETB(532) turns ON the specified bit. RSTB(533) turns OFF the specified bit.

**Ladder Symbols** 



D: Word address

N: Bit number

PSTB(533)

D

N

D: Word address

N: Bit number

#### **Variations**

Variations	Executed Each Cycle for ON Condition	SETB(532)
	<b>Executed Once for Upward Differentiation</b>	@SETB(532)
	<b>Executed Once for Downward Differentiation</b>	Not supported
Combined Variations	Executed Once and Bit Refreshed Immediately for Upward Differentiation (See note.)	!@SETB(532)
	Executed Once and Bit Refreshed Immediately for Downward Differentiation	Not supported
Variations	Executed Each Cycle for ON Condition	RSTB(533)
	<b>Executed Once for Upward Differentiation</b>	@RSTB(533)
	<b>Executed Once for Downward Differentiation</b>	Not supported
Combined Variations	Executed Once and Bit Refreshed Immediately for Upward Differentiation (See note.)	!@RSTB(533)
	Executed Once and Bit Refreshed Immediately for Downward Differentiation	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operands**

#### D: Word Address

Specifies the word in which the bit will be turned ON or OFF.

## N: Beginning Bit

Specifies the bit which will be turned ON or OFF. N must be #0000 to #000F (&0 to &15).

#### **Operand Specifications**

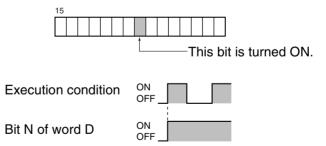
Area	D	N	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A448 to A959	A000 to A959	
Timer Area	T0000 to T255		
Counter Area	C0000 to C255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #000F (binary) or &0 to &15		
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing using	,IR0 to ,IR15		
Index Registers	-2048 to +2047, IR0 to -2048 to +2047, IR15		
	DR0 to DR15, IR0 to DR0	to DR15, IR15	
	,IR0+(++) to ,IR15+(++)		
	,-() IR0 to , -() IR15		

## **Description**

The functions of SETB(532) and RSTB(533) are described separately below.

#### Operation of SETB(532)

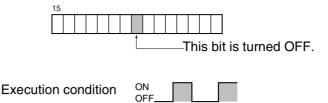
SETB(532) turns ON bit N of word D when the execution condition is ON. The status of the bit is not affected when the execution condition is OFF. Unlike SET, SETB(532) can turn ON a bit in the DM area.



Bits turned ON by SETB(532) can be turned OFF by any other instruction, not just RSTB(533).

#### Operation of RSTB(533)

RSTB(533) turns OFF bit N of word D when the execution condition is ON. The status of the bit is not affected when the execution condition is OFF. (Use SETB(532) to turn ON the bit.) Unlike RST, RSTB(533) can turn OFF a bit in the DM area.



Bits turned OFF by RSTB(533) can be turned ON by any other instruction, not just SETB(532).

#### **Flags**

Name	Label	Operation
Error Flag		ON if N is not within the specified range of 0000 to 000F (&0 to &15).  OFF in all other cases.

#### **Precautions**

SETB(532) and RSTB(533) cannot set/reset timers and counters.

Bit N of word D

When SETB(532) or RSTB(533) is programmed between IL(002) and ILC(003) or JMP(004) and JME(005), the status of the specified bit will not be changed if the program section is interlocked or jumped, i.e., when the interlock condition or jump condition is OFF.

SETB(532) and RSTB(533) have immediate refreshing variations (!SETB(532) and !RSTB(533)). When an external output bit has been specified in one of these instructions, any changes to the specified bit will be refreshed when the instruction is executed and reflected immediately in the output bit. (The changes will not be reflected immediately if the bit is allocated to a Group-2 High-density I/O Unit, High-density Special I/O Unit, or a Unit mounted in a SYSMAC BUS Remote I/O Slave Rack.)

#### <u>Differences between SET/RSET and SETB(532)/RSTB(533)</u>

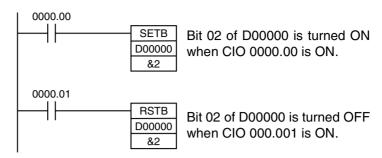
The SET and RSET instructions operate somewhat differently from SETB(532) and RSTB(533).

- 1. The instructions operate in the same way when the specified bit is in the CIO, W, H, or A Area.
- 2. The SETB(532) and RSTB(533) instructions can control bits in the DM Area, unlike SET and RSET.

#### <u>Differences between OUTB(534) and SETB(532)/RSTB(533)</u>

The OUTB(534) instruction operates somewhat differently from SETB(532) and RSTB(533).

- The SETB(532) and RSTB(533) instructions change the status of the specified bit only when their execution condition is ON. These instructions have no effect on the status of the specified bit when their execution condition is OFF.
- The OUTB(534) instruction turns ON the specified bit when its execution condition is ON and turns OFF the specified bit when its execution condition is OFF.
- 3. The set and reset inputs for a KEEP(011) instruction must be programmed with the instruction, but the SETB(532) and RSTB(533) instructions can be programmed completely independently. Furthermore, the same bit may be used as the operand in any number of SETB(532) and RSTB(533) instructions.



## 3-3-8 SINGLE BIT OUTPUT: OUTB(534)

#### **Purpose**

OUTB(534) outputs the status of the instruction's execution condition to the specified bit. OUTB(534) can control a bit in the DM Area, unlike OUT.

#### **Ladder Symbols**



D: Word address

N: Bit number

#### **Variations**

Variations	Executed Each Cycle for ON Condition	OUTB(534)
	Executed Once for Upward Differentiation	@OUTB(534)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

#### **Operands**

#### D: Word Address

Specifies the word containing the bit to be controlled.

## N: Beginning Bit

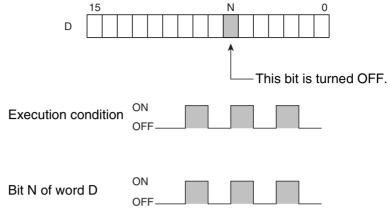
Specifies the bit to be controlled. N must be #0000 to #000F (&0 to &15).

#### **Operand Specifications**

Area	D	N	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A448 to A959	A000 to A959	
Timer Area	T0000 to T255		
Counter Area	C0000 to C255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants		#0000 to #000F (binary) or &0 to &15	
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15  -2048 to +2047, IR0 to -2048 to +2047, IR15  DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-() IR0 to , -() IR15		

### **Description**

When the execution condition is ON, OUTB(534) turns ON bit N of word D. When the execution condition is OFF, OUTB(534) turns OFF bit N of word D.



If the immediate refreshing version is not used, the status of the execution condition (power flow) is written to the specified bit in I/O memory. If the immediate refreshing version is used, the status of the execution condition (power flow) is written to the Basic Output Unit's output terminal as well as the output bit in I/O memory.

**Flags** 

**Precautions** 

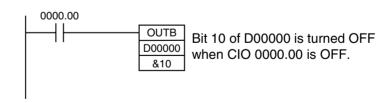
There are no flags affected by this instruction.

Immediate refreshing (!OUTB(534)) can be specified. An immediate refresh instruction updates the status of the output terminal just after the instruction is executed on an output bit allocated to a Basic Output Unit (but not for C200H Group 2 Multi-point Output Units or Basic Output Units on Slave Racks), at the same time as it writes the status of the execution condition (power flow) to the specified output bit in I/O memory.

When OUTB(534) is programmed between IL(002) and ILC(003), the specified bit will be turned OFF if the program section is interlocked. (This is the same as an OUT instruction in an interlocked program section.)

When a word is specified for the bit number (N), only bits 00 to 03 of N are used. For example, if N contains FFFA hex, OUTB(534) will control bit 10 of word D.

Example



# 3-4 Sequence Control Instructions

This section describes the sequence control instructions.

Instruction	Mnemonic	Function code	Page
END	END	001	134
NO OPERATION	NOP	000	134
INTERLOCK/INTERLOCK CLEAR	IL/ILC	002/003	135
JUMP/JUMP END	JMP/JME	004/005	138
CONDITIONAL JUMP	CJP/CJPN	510/511	141
MULTIPLE JUMP/JUMP END	JMP0/JME0	515/516	145
FOR-NEXT LOOPS	FOR	512	147
	NEXT	513	147
BREAK LOOP	BREAK	514	150

## 3-4-1 END: END(001)

Purpose

Indicates the end of a program.

**Ladder Symbol** 



**Variations** 

Variations Executed Each Cycle for ON Condition	END(001)
---	----------

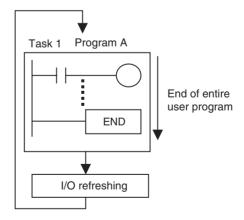
## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	Not allowed	Not allowed	OK

**Description** 

END(001) completes the execution of a program for that cycle. No instructions written after END(001) will be executed.

Execution proceeds to the program with the next task number. When the program being executed has the highest task number in the program, END(001) marks the end of the overall main program.



**Precautions** 

Always place END(001) at the end of each program. A programming error will occur if there is not an END(001) instruction in the program.

# 3-4-2 NO OPERATION: NOP(000)

**Purpose** This instruction has no function. (No processing is performed for NOP(000).)

**Ladder Symbol** There is no ladder symbol associated with NOP(000).

#### **Variations**

Variations	Executed Each Cycle for ON Condition	NOP(000)
	,	` '

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

**Description** 

No processing is performed for NOP(000), but this instruction can be used to set aside lines in the program where instructions will be inserted later. When the instructions are inserted later, there will be no change in program addresses.

Flags No flags are affected by NOP(000).

**Precautions** NOP(000) can only be used with mnemonic displays, not with ladder pro-

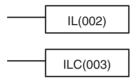
grams.

## 3-4-3 INTERLOCK and INTERLOCK CLEAR: IL(002) and ILC(003)

Purpose Interlocks all outputs between IL(002) and ILC(003) when the execution con-

dition for IL(002) is OFF. IL(002) and ILC(003) are normally used in pairs.

**Ladder Symbols** 



**Variations** 

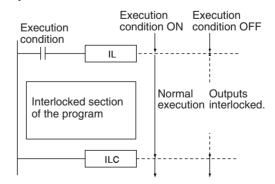
Variations	Interlocks when OFF/Does Not interlock when ON	IL(002)
Variations	Executed Each Cycle for ON Condition	ILC(003)

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	Not allowed	OK	OK

### **Description**

When the execution condition for IL(002) is OFF, the outputs for all instructions between IL(002) and ILC(003) are interlocked. When the execution condition for IL(002) is ON, the instructions between IL(002) and ILC(003) are executed normally.



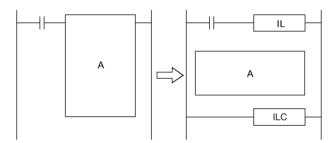
The following table shows the treatment of various outputs in an interlocked section between IL(002) and ILC(003).

Instruction		Treatment
Bits specified in OUT or OUT NOT		OFF
TIM, TIMH(015), and TMHH(540) Completion Flag		OFF (reset)
	PV	Time set value (reset)
Bits/words specified in all other instructions (See note.)		Retain previous status.

**Note** Bits and words in all other instructions including SET, RSET, CNT, CNTR(012), SFT, and KEEP(011) retain their previous status.

If there are bits which you want to keep ON in an interlocked program section, set these bits to ON with SET just before IL(002).

It is often more efficient to switch a program section with IL(002) and ILC(003). When several processes are controlled with the same execution condition, it takes fewer program steps to put these processes between IL(002) and ILC(003).



The following table shows the differences between IL(002)/ILC(003) and JMP(004)/JME(005).

Item	Treatment in IL(002)/ILC(003)	Treatment in JMP(004)/JME(005)
Instruction execution	Instructions other than OUT, OUT NOT, and timer instructions are not executed.	No instructions are executed.
Output status in instructions	Except for outputs in OUT, OUT NOT, and timer instructions, all outputs retain their previous status.	All outputs retain their previous status.
Bits in OUT, OUT NOT	OFF	All outputs retain their previous status.
Status of timer instructions	Reset	Operating timers (TIM, TIMH(015), TMHH(540), only) continue timing because the PVs are updated even when the timer instruction is not being executed.

### **Flags**

There are no flags affected by this instruction.

#### **Precautions**

The cycle time is not shortened when a section of the program is interlocked because the interlocked instructions are executed internally.

The operation of DIFU(013), DIFD(014), and differentiated instructions is not dependent solely on the status of the execution condition when they are programmed between IL(002) and ILC(003). Changes in the execution condition for DIFU(013), DIFD(014), or a differentiated instruction are not recorded if the DIFU(013) or DIFD(014) is in an interlocked section and the execution condition for the IL(002) is OFF.

Example: DIFU(013)

If the execution condition for DIFU(013) is OFF when an interlock is started and is ON when the interlock is cleared, DIFU(013) will be executed when the interlock is cleared.

```
1. Assume that CIO 0000.01, the input condition for DIFU, is OFF when CIO 0000.00 turns OFF to start the interlock.

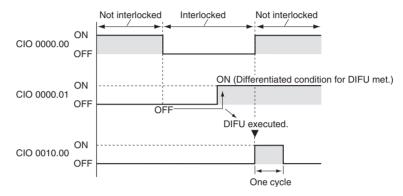
2. Assume that CIO 0000.01, the input condition for DIFU, turns ON while CIO 0000.00 is OFF.

3. When CIO 0000.00 turns ON, the interlock will be cleared and DIFU will be executed because CIO 0000.01 is ON.

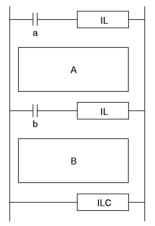
DIFU

0010.00
```

## **Timing Chart**



In general, IL(002) and ILC(003) are used in pairs, although it is possible to use more than one IL(002) with a single ILC(003) as shown in the following diagram. If IL(002) and ILC(003) are not paired, an error message will appear when the program check is performed but the program will be executed properly.



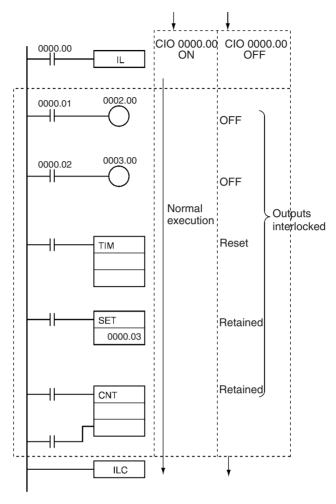
Execution condition		Program section	
а	b	Α	В
OFF	ON	Interlocked	Interlocked
OFF	OFF	Interlocked	Interlocked
ON	OFF	Not interlocked	Interlocked
ON	ON	Not interlocked	Not interlocked

IL(002) and ILC(003) cannot be nested.

## **Examples**

When CIO 0000.00 is OFF in the following example, all outputs between IL(002) and ILC(003) are interlocked. When CIO 0000.00 is ON in the follow-

ing example, the instructions between IL(002) and ILC(003) are executed normally.



# 3-4-4 JUMP and JUMP END: JMP(004) and JME(005)

#### **Purpose**

When the execution condition for JMP(004) is OFF, program execution jumps directly to the first JME(005) in the program with the same jump number. JMP(004) and JME(005) are used in pairs.

## **Ladder Symbols**



#### **Variations**

Variations	Jumps when OFF/Does Not Jump when ON	JMP(004)
Variations	Executed Each Cycle for ON Condition	JME(005)

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	Not allowed	ОК	OK

### **Operands**

## N: Jump Number

The jump number must be 0000 to 00FF (&0 to &255 decimal).

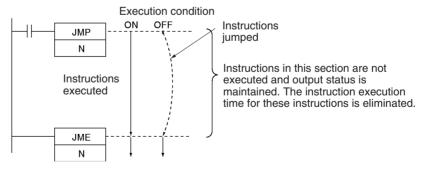
#### **Operand Specifications**

Area	N	
	JMP(004)	JME(005)
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A000 to A959	
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 to #00FF (binary) or &0 to &255	#0000 to #00FF (binary) or &0 to &255
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing using	,IR0 to ,IR15	
Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	

### **Description**

When the execution condition for JMP(004) is ON, no jump is made and the program is executed consecutively as written.

When the execution condition for JMP(004) is OFF, program execution jumps directly to the first JME(005) in the program with the same jump number. The instructions between JMP(004) and JME(005) are not executed, so the status of outputs between JMP(004) and JME(005) is maintained. In block programs, the instructions between JMP(004) and JME(005) are skipped regardless of the status of the execution condition.



Because all of instructions between JMP(004) and JME(005) are skipped when the execution condition for JMP(004) is OFF, the cycle time is reduced by the total execution time of the skipped instructions.

#### Flags (JMP)

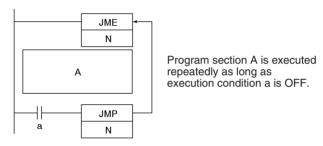
Name	Label	Operation
Error Flag	ER	ON if N is not within the specified range of 0000 to 00FF.
		ON if there is a JMP(004) in the program without a JME(005) with the same jump number.
		ON if there is a JMP(004) in the task without a JME(005) with the same jump number in the same task.
		OFF in all other cases.

#### **Precautions**

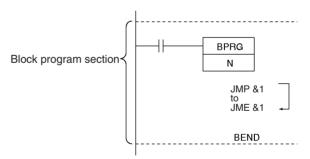
All of the outputs (bits and words) in jumped instructions retain their previous status. Operating timers (TIM, TIMH(015), and TMHH(540)) continue timing because the PVs are updated even when the timer instruction is not being executed.

When there are two or more JME(005) instructions with the same jump number, only the instruction with the lower address will be valid. The JME(005) with the higher program address will be ignored.

When JME(005) precedes JMP(004) in the program, the instructions between JME(005) and JMP(004) will be executed repeatedly as long as the execution condition for JMP(004) is OFF. A Cycle Time Too Long error will occur if the execution condition is not turned ON or END(001) is not executed within the maximum cycle time.



In block programs, the instructions between JMP(004) and JME(005) are always skipped regardless of the status of the execution condition for JMP(004).



JMP(004) and JME(005) pairs must be in the same task because jumps between tasks are not allowed. An error will occur if a JME(005) instruction is not programmed in the same task as its corresponding JMP(004) instruction.

The operation of DIFU(013), DIFD(014), and differentiated instructions is not dependent solely on the status of the execution condition when they are programmed between JMP(004) and JME(005). When DIFU(013), DIFD(014), or a differentiated instruction is executed in an jumped section immediately after the execution condition for the JMP(004) has gone ON, the execution condition for the DIFU(013), DIFD(014), or differentiated instruction will be compared to the execution condition that existed before the jump became effective (i.e., before the execution condition for JMP(004) went OFF).

## JMP(004) Specifications

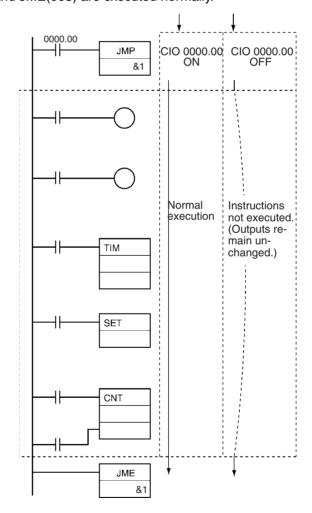
Item	JMP-JME
Execution condition for jumping	OFF
Number of JMP instructions	256 max.
Instruction processing when jumping	Not executed
Execution time when jumping	0
Outputs while jumping	Retains previous status
PV of active timer, while jumping	Continues timing
Processing in block program area	Jumps unconditionally

## **Examples**

#### **Basic Operation**

When CIO 0000.00 is OFF in the following example, the instructions between JMP(004) and JME(005) are not executed and the outputs maintain their previous status.

When CIO 0000.00 is ON in the following example, the instructions between JMP(004) and JME(005) are executed normally.



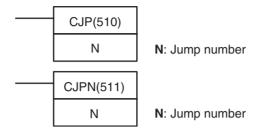
# 3-4-5 CONDITIONAL JUMP: CJP(510)/CJPN(511)

#### **Purpose**

The operation of CJP(510) is the basically the opposite of JMP(004). When the execution condition for CJP(510) is ON, program execution jumps directly to the first JME(005) in the program with the same jump number. CJP(510) and JME(005) are used in pairs.

The operation of CJPN(511) is almost identical to JMP(004). When the execution condition for CJP(004) is OFF, program execution jumps directly to the first JME(005) in the program with the same jump number. CJPN(511) and JME(005) are used in pairs.

## **Ladder Symbols**



#### **Variations**

Variations	Jumps when ON/Does Not Jump when OFF	CJP(510)
Variations	Jumps when OFF/Does Not Jump when ON	CJPN(511)
Variations	Executed Each Cycle for ON Condition	JME(005)

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	Not allowed	OK	OK

#### **Operands**

### **N: Jump Number**

The jump number must be 0000 to 00FF (0 to 255 decimal).

## **Operand Specifications**

Area	N		
	CJP(510)	CJPN(511)	JME(005)
CIO Area	CIO 0000 to CIO 614	13	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #00FF (binary) or &0 to &255		#0000 to #00FF (binary) or &0 to &255
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047, IR0 to -2048 to +2047, IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15		

#### **Description**

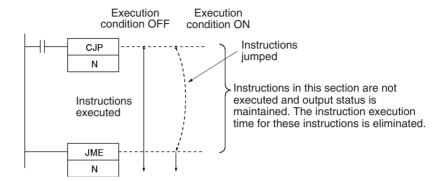
The operation of CJP(510) and CJPN(511) differs only in the execution condition. CJP(510) jumps to the first JME(005) when the execution condition is ON and CJPN(511) jumps to the first JME(005) when the execution condition is OFF.

Because the jumped instructions are not executed, the cycle time is reduced by the total execution time of the jumped instructions.

#### Operation of CJP(510)

When the execution condition for CJP(510) is OFF, no jump is made and the program is executed consecutively as written.

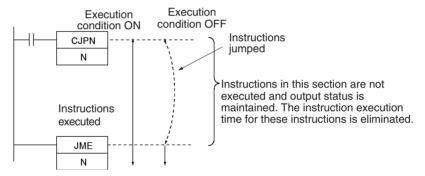
When the execution condition for CJP(510) is ON, program execution jumps directly to the first JME(005) in the program with the same jump number.



## Operation of CJPN(511)

When the execution condition for CJPN(511) is ON, no jump is made and the program is executed consecutively as written.

When the execution condition for CJPN(511) is OFF, program execution jumps directly to the first JME(005) in the program with the same jump number.



The following table shows the flags affected by CJP(510) and CJPN(511).

Name	Label	Operation
Error Flag	ER	ON if there is not a JME(005) with the same jump number as CJP(510) or CJPN(511). (See note.)
		ON if N is not within the specified range of 0 to 255 decimal (0000 to 00FF hex).
		ON if there is a CJP(510) or CJPN(511) instruction in a task without a JME(005) with the same jump number.
		OFF in all other cases.

**Note** The jump number must be between the range 0 to 255 (0000 to 00FF hex).

#### **Precautions**

**Flags** 

All of the outputs (bits and words) in jumped instructions retain their previous status. Operating timers (TIM, TIMX(550), TIMH(015), TIMHX(551), TMHH(540), and TMHHX(552)) continue timing be-cause the PVs are updated even when the timer instruction is not being executed.

When there are two or more JME(005) instructions with the same jump number, only the instruction with the lower address will be valid. The JME(005) with the higher program address will be ignored.

When JME(005) precedes the CJP(510) or CJPN(511) instruction in the program, the instructions in-between will be executed repeatedly as long as the

execution condition remains OFF (CJP(510)) or ON (CJPN(511)). A Cycle Time Too Long error will occur if the jump is not completed by changing the execution condition executing END(001) within the maximum cycle time.

The CJP(510) or CJPN(511) instructions will operate normally in block programs.

When the execution condition for the CJP(510) is ON or the execution condition for CJPN(511) is OFF, program execution will jump directly to the JME instruction without executing instructions between CJP(510)/CJPN(511) and JME. No execution time will be required for these instructions and the cycle time will thus be reduced.

When the execution condition for the JMP0 is OFF, NOP processing is executed between the JMP0 and JME0, requiring execution time. Therefore, the cycle time will not be reduced.

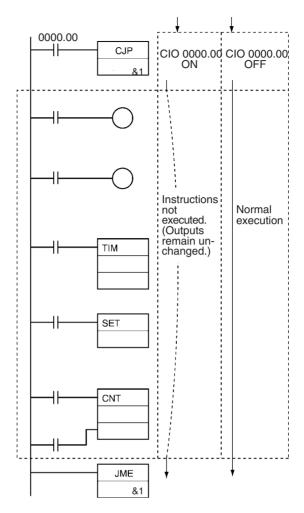
When a CJP(510) or CJPN(511) instruction is programmed in a task, there must be a JME(005) with the same jump number because jumps between tasks are not allowed. An error will occur if a corresponding JME(005) instruction is not programmed in the same task.

The operation of DIFU(013), DIFD(014), and differentiated instructions is not dependent solely on the status of the execution condition when they are programmed in a jumped program section. When DIFU(013), DIFD(014), or a differentiated instruction is executed in an jumped section immediately after the execution condition for the CJP(510) has gone OFF (ON for CJPN(511)), the execution condition for the DIFU(013), DIFD(014), or differentiated instruction will be compared to the execution condition that existed before the jump became effective.

When CIO 0000.00 is ON in the following example, the instructions between CJP(510) and JME(005) are not executed and the outputs maintain their previous status.

When CIO 0000.00 is OFF in the following example, the instructions between CJP(510) and JME(005) are executed normally.

Example



Note For CJPN(511), the ON/OFF status of CIO 000000 would be reversed.

# 3-4-6 MULTIPLE JUMP and JUMP END: JMP0(515) and JME0(516)

**Purpose** 

When the execution condition for JMP0(515) is OFF, all instructions from JMP0(515) to the next JME0(516) in the program are processed as NOP(000). Use JMP0(515) and JME0(516) in pairs. There is no limit on the number of pairs that can be used in the program.

**Ladder Symbols** 



**Variations** 

Variations	Jumps when OFF/Does Not Jump when ON	JMP0(515)
Variations	Executed Each Cycle for ON Condition	JME0(516)

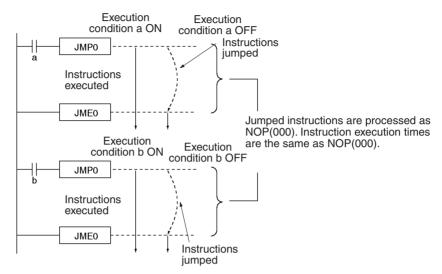
## **Applicable Program Areas**

Block program areas	lock program areas Step program areas		Interrupt tasks
Not allowed	Not allowed	OK	OK

### **Description**

When the execution condition for JMP0(515) is ON, no jump is made and the program executed consecutively as written.

When the execution condition for JMP0(515) is OFF, all instructions from JMP0(515) to the next JME0(516) in the program are processed as NOP(000). Unlike JMP(004), CJP(510), and CJPN(511), JMP0(515) does not use jump numbers, so these instructions can be placed anywhere in the program.



Unlike JMP(004), CJP(510), and CJPN(511) which jump directly to the first JME(005) instruction in the program, all of the instructions between JMP0(515) and JME0(516) are executed as NOP(000). The execution time of the jumped instructions will be reduced, but not eliminated. The jumped instructions themselves are not executed and their outputs (bits and words) maintain their previous status.

Multiple pairs of JMP0(515) and JME0(516) instructions can be used in the program, but the pairs cannot be nested.

JMP0(515) and JME0(516) cannot be used in block programs.

JMP0(515) and JME0(516) pairs must be in the same tasks because jumps between tasks are not allowed.

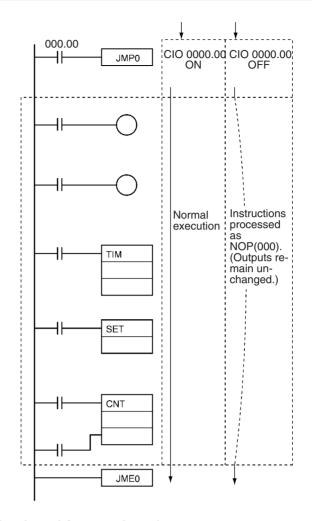
The operation of DIFU(013), DIFD(014), and differentiated instructions is not dependent solely on the status of the execution condition when they are programmed between JMP0(515) and JME0(516). When DIFU(013), DIFD(014), or a differentiated instruction is executed in an jumped section immediately after the execution condition for the JMP0(515) has gone ON, the execution condition for the DIFU(013), DIFD(014), or differentiated instruction will be compared to the execution condition that existed before the jump became effective (i.e., before the execution condition for JMP0(515) went OFF).

When CIO 0000.00 is OFF in the following example, the instructions between JMP0(515) and JME0(516) are processed as NOP(000) instructions and the outputs maintain their previous status.

When CIO 0000.00 is ON in the following example, the instructions between JMP0(515) and JME0(516) are executed normally.

#### **Precautions**

#### Example

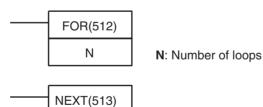


# **3-4-7 FOR-NEXT LOOPS: FOR(512)/NEXT(513)**

**Purpose** 

The instructions between FOR(512) and NEXT(513) are repeated a specified number of times. FOR(512) and NEXT(513) are used in pairs.

**Ladder Symbols** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	FOR(512)
	Executed Each Cycle for ON Condition	NEXT(513)

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

## Operands

## **N: Number of Loops**

The number of loops must be 0000 to FFFF (0 to 65,535 decimal).

## **Operand Specifications**

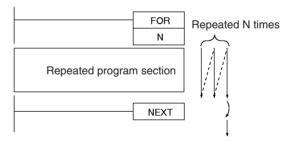
Area	N
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A000 to A959
Timer Area	T0000 to T255
Counter Area	C0000 to C255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	#0000 to #FFFF (binary) or &0 to &65,535
Data Registers	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047, IR0 to -2048 to +2047, IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-() IR0 to , -() IR15

## **Description**

The instructions between FOR(512) and NEXT(513) are executed N times and then program execution continues with the instruction after NEXT(513). The BREAK(514) instruction can be used to cancel the loop.

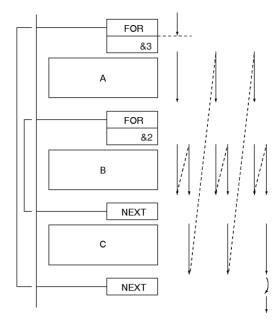
If N is set to 0, the instructions between FOR(512) and NEXT(513) are processed as NOP(000) instructions.

Loops can be used to process tables of data with a minimum amount of programming.

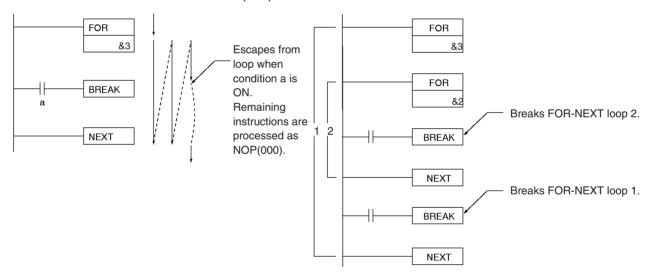


FOR-NEXT loops can be nested up to 15 levels. In the example below, program sections A, B, and C are executed as follows:

$$A \rightarrow B \rightarrow B \rightarrow C$$
,  $A \rightarrow B \rightarrow B \rightarrow C$ , and  $A \rightarrow B \rightarrow B \rightarrow C$ 



Use BREAK(514) to escape from a FOR-NEXT loop. Several BREAK(514) instructions (the number of levels nested) are required to escape from nested loops. The remaining instructions in the loop after BREAK(514) are processed as NOP(000) instructions.



## **Alternative Looping Methods**

There are two ways to repeat a program section until a given execution condition is input.

#### 1,2,3... 1. FOR-NEXT Loop with BREAK

Start a FOR-NEXT loop with a maximum of N repetitions. Program BREAK(514) within the loop with the desired execution condition. The loop will end before N repetitions if the execution condition is input.

2. JME(005)-JMP(004) Loop

Program a loop with JME(005) before JMP(004). The instructions between JME(005) and JMP(004) will be executed repeatedly as long as the execution condition for JMP(004) is OFF. (A Cycle Time Too Long error will occur if the execution condition is not turned ON or END(001) is not executed within the maximum cycle time.)

## **Flags**

Name	Label	Operation
Error Flag	ER	ON if more than 15 loops are nested.
		OFF in all other cases.
Equals Flag	=	OFF
Negative Flag	N	OFF

#### **Precautions**

Program FOR(512) and NEXT(513) in the same task. Execution will not be repeated if these instructions are not in the same task.

A jump instruction such as JMP(004) may be executed within a FOR-NEXT loop, but do not jump beyond the FOR-NEXT loop.

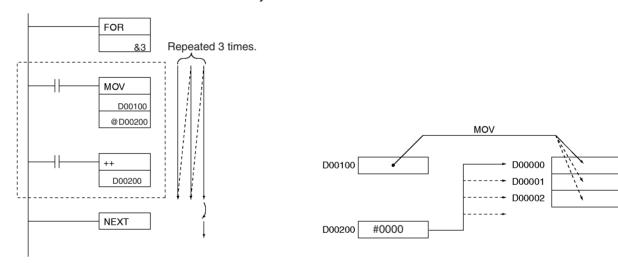
The following instructions cannot be used within FOR-NEXT loops:

- Block programming instructions
- MULTIPLE JUMP and JUMP END: JMP(515) and JME(516)
- STEP DEFINE and STEP START: STEP(008)/SNXT(009)

**Note** If a loop repeats in one cycle and a differentiated bit is used in the FOR-NEXT loop, that bit will be always ON or always OFF within that loop.

#### Example

In the following example, the looped program section transfers the content of D00100 to the address indicated in D00200 and then increments the content of D00200 by 1.



# **3-4-8 BREAK LOOP: BREAK(514)**

## **Purpose**

Programmed in a FOR-NEXT loop to cancel the execution of the loop for a given execution condition. The remaining instructions in the loop are processed as NOP(000) instructions.

## **Ladder Symbol**



#### **Variations**

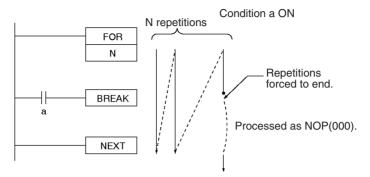
Variations	Executed Each Cycle for ON Condition	BREAK(514)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

## **Description**

Program BREAK(514) between FOR(512) and NEXT(513) to cancel the FOR-NEXT loop when BREAK(514) is executed. When BREAK(514) is executed, the rest of the instructions up to NEXT(513) are processed as NOP(000).



## **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	OFF
Negative Flag	N	OFF

#### **Precautions**

A BREAK(514) instruction cancels only one loop, so several BREAK(514) instructions (the number of levels nested) are required to escape from nested loops.

BREAK(514) can be used only in a FOR-NEXT loop.

## 3-5 Timer and Counter Instructions

This section describes instructions used to define and handle timers and counters.

Instruction	Mnemonic	Function code	Page
TIMER	TIM		153
HIGH-SPEED TIMER	TIMH	015	156
ONE-MS TIMER	TMHH	540	158
COUNTER	CNT		160
REVERSIBLE COUNTER	CNTR	012	163

## **Refresh Methods for Timer/Counter PV**

#### **■** Overview

The timer and counter instructions all use BCD data and all set values for them are input using BCD.

## **Basic Timer Specifications**

The following table shows the basic specifications of the timers.

Item		TIM	TIMH(015)	TMHH(540)
Timing method	d	Decrementing	Decrementing	Decrementing
Timing units		0.1 s	0.01 s	0.001 s
Max. SV		999.9 s	99.99 s	9.999 s
Outputs/instru	Outputs/instruction		1	1
Timer numbers		Used	Used	Used
Comp. flag refreshing		At execution	At execution	By interrupt every 1 ms
Timer PV refreshing		See note 1.	See note 2.	Every 1 ms
Value after	Comp. flags	OFF	OFF	OFF
reset	PVs	SV	SV	SV

#### Note

- 1. TIM PVs are refreshed at execution, at the end of program execution each cycle, or every 80 ms by interrupt if the cycle time exceeds 80 ms.
- 2. TIMH(015) PVs are refreshed at execution, at the end of program execution each cycle, and every 10 ms by interrupt.

## **Timer Operation**

The following table shows the effects of operating and programming conditions on the operation of the timers.

Ite	em	TIM	TIMH(015)	TMHH(540)
Operating mod	le change	PV = 0		
		Completion Flag :	= OFF	
Power interrup	t/reset	PV = 0		
		Completion Flag :	= OFF	
Operation in jumped program section		Operating timers continue timing.		
(JMP(004)-JME(005))				
Operation in in	terlocked pro-	PV = SV		
gram section		Completion Flag = OFF		
(IL(002)-ILC(003))				
Forced set	Comp. flags	ON		
	PVs	Set to 0.		

Item		TIM	TIMH(015)	TMHH(540)
Forced reset	Comp. flags	OFF		
	PVs	Reset to SV.		

## 3-5-1 TIMER: TIM

## **Purpose**

TIM operates a decrementing timer with units of 0.1-s. The setting range for the set value (SV) is 0 to 999.9 s. The timer accuracy is -0.01 to 0 s.

## **Ladder Symbol**

Symbol			Operands
			N: 0 to 0255 (decimal)
	TIM		S: #0000 to #9999 (BCD)
	N	N: Timer number	
	S	S: Set value	

#### **Variations**

Variations	Executed Each Cycle for ON Condition	TIM
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	Not allowed

#### **Operands**

#### **N: Timer Number**

The timer number must be between 0000 and 0255 (decimal).

#### S: Set Value

The set value must be between #0000 and #9999 (BCD). (If the set value is set to #0000, the Completion Flag will be turned ON when TIM is executed.)

## **Operand Specifications**

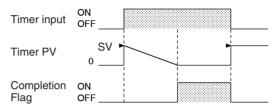
Area	N	S	
CIO Area		CIO 0000 to CIO 6143	
Work Area		W000 to W255	
Auxiliary Bit Area		A000 to A959	
Timer Area	0 to 0255 (decimal)	T0000 to T0255	
Counter Area		C0000 to C0255	
DM Area		D00000 to D32767	
Indirect DM addresses in binary		@ D00000 to @ D32767	
Indirect DM addresses in BCD		*D00000 to *D32767	
Constants	#0000 to #9999 (BCD) "&" cannot be used.		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15		

### **Description**

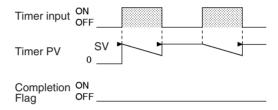
When the timer input is OFF, the timer specified by N is reset, i.e., the timer's PV is reset to the SV and its Completion Flag is turned OFF.

When the timer input goes from OFF to ON, TIM starts decrementing the PV. The PV will continue timing down as long as the timer input remains ON and the timer's Completion Flag will be turned ON when the PV reaches 0000.

The status of the timer's PV and Completion Flag will be maintained after the timer times out. To restart the timer, the timer input must be turned OFF and then ON again or the timer's PV must be changed to a non-zero value (by MOV(021), for example).



The following timing chart shows the behavior of the timer's PV and Completion Flag when the timer input is turned OFF before the timer times out.



## **Flags**

Name	Label	Operation	
Error Flag	ER	ON if N is indirectly addressed through an Index Register but the address in the Index Register is not the PV address of a timer.	
		ON if S does not contain BCD data.	
		OFF in all other cases.	

## Precautions

Timer numbers are shared by the TIM, TIMH(015), and TMHH(540) instructions. Two timers can share the same timer number only if they are not executed at the same time. A duplication error will occur when the program is checked, but the timers will operate normally as long as they are not executed at the same time. Timers which share the same timer number will not operate properly if they are executed simultaneously.

Timers will be reset or paused in the following cases. (When a timer is reset, its PV is reset to the SV and its Completion Flag is turned OFF.)

Condition	PV	Completion Flag
Operating mode changed from RUN or MONITOR mode to PROGRAM mode or vice versa.	0000	OFF
Power supply interrupted and reset	0000	OFF
Operation in interlocked program section (IL(002)–ILC(003))	Reset to SV.	OFF
Operation in jumped program section (JMP(004)–JME(005))	PV continues decrementing.	Retains previous status.

Note The PV will be set to the SV when TIM is executed.

When TIM is in a program section between IL(002) and ILC(003) and the program section is interlocked, the PV will be reset to the SV and the Completion Flag will be turned OFF.

When an operating TIM timer is in a jumped program section (JMP(004) and JME(005)), the timer's PV will continue timing. The jumped TIM instruction will not be executed, but the PV will be refreshed each cycle after all tasks have been executed.

When a TIM timer is forced set, its Completion Flag will be turned ON and its PV will be set to 0000. When a TIM timer is forced reset, its Completion Flag will be turned OFF and its PV will be reset to the SV.

The timer's Completion Flag is refreshed only when TIM is executed, so a delay of up to one cycle may be required for the Completion Flag to be turned ON after the timer times out.

If online editing is used to convert a timer to another kind of timer with the same timer number (such as TIM  $\leftrightarrow$  TIMH(015) or TIM  $\leftrightarrow$  TMHH(540)), be sure to reset the Completion Flag. The timer will not operate properly unless the Completion Flag is reset.

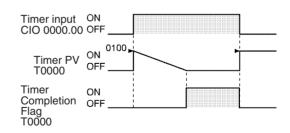
A TIM instruction's PV and Completion Flag are refreshed in the following ways.

Execution of TIM	The PV is updated every time that TIM is executed.
	The Completion Flag is turned ON if the PV is 0000.
	The Completion Flag is turned OFF if the PV is not 0000.

When timer input CIO 0000.00 goes from OFF to ON in the following example, the timer PV will begin counting down from the SV. Timer Completion Flag T0000 will be turned ON when the PV reaches 0000.

When CIO 0000.00 goes OFF, the timer PV will be reset to the SV and the Completion Flag will be turned OFF.

```
0000.00 TIM 0000 #0100
```



Example

# 3-5-2 HIGH-SPEED TIMER: TIMH(015)

#### **Purpose**

TIMH(015) operates a decrementing timer with units of 10-ms. The setting range for the set value (SV) is 0 to 99.99 s for TIMH(015). The timer accuracy is -0.01 to 0 s.

## **Ladder Symbol**

Symbol		Operands
TIMH(015)		N: 0 to 255 (decimal) S: #0000 to #9999 (BCD)
N	N: Timer number	
S	S: Set value	

#### **Variations**

Variations	Executed Each Cycle for ON Condition	TIMH(015)
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	Not allowed

## **Operands**

#### **N: Timer Number**

The timer number must be between 0000 and 0255 (decimal).

#### S: Set Value

The set value must be between #0000 and #9999 (BCD).

#### **Operand Specifications**

Area	N	S
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A000 to A959
Timer Area	0 to 255 (decimal)	T0000 to T0255
Counter Area		C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ D32767
Indirect DM addresses in BCD		*D00000 to *D32767
Constants		#0000 to #9999 (BCD) "&" cannot be used.
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15	

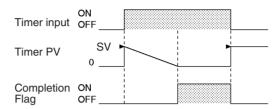
#### **Description**

When the timer input is OFF, the timer specified by N is reset, i.e., the timer's PV is reset to the SV and its Completion Flag is turned OFF.

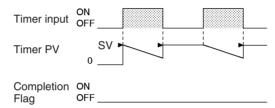
When the timer input goes from OFF to ON, TIMH(015) starts decrementing the PV. The PV will continue timing down as long as the timer input remains

ON and the timer's Completion Flag will be turned ON when the PV reaches 0000.

The status of the timer's PV and Completion Flag will be maintained after the timer times out. To restart the timer, the timer input must be turned OFF and then ON again or the timer's PV must be changed to a non-zero value (by MOV(021), for example).



The following timing chart shows the behavior of the timer's PV and Completion Flag when the timer input is turned OFF before the timer times out.



**Flags** 

Name	Label	Operation
Error Flag	ER	ON if N is indirectly addressed through an Index Register but the address in the Index Register is not the PV address of a timer.
		ON if S does not contain BCD data.
		OFF in all other cases.

**Precautions** 

Timer numbers are shared by the TIM, TIMH(015), and TMHH(540) instructions. Two timers can share the same timer number only if they are not executed at the same time. A duplication error will occur when the program is checked, but the timers will operate normally as long as they are not executed at the same time. Timers which share the same timer number will not operate properly if they are executed simultaneously.

The Completion Flags for TIMH(015) timers will be updated when the instruction is executed.

Timers will be reset or paused in the following cases. (When a timer is reset, its PV is reset to the SV and its Completion Flag is turned OFF.)

Condition	PV	Completion Flag
Operating mode changed from RUN or MONITOR mode to PROGRAM mode or vice versa.	0000	OFF
Power supply interrupted and reset	0000	OFF
Operation in interlocked program section (IL(002)–ILC(003))	Reset to SV.	OFF
Operation in jumped program section (JMP(004)–JME(005))	PV continues decrementing.	Retains previous status.

Note The PV will be set to the SV when TIMH(015) is executed.

When an operating TIMH(015) timer is in a jumped program section (JMP(004), and JME(005)), the timer's PV will continue timing. (The jumped TIMH(015) instruction will not be executed, but the PV will be refreshed every 10 ms and each cycle after all tasks have been executed.)

When TIMH(015)) is in a program section between IL(002) and ILC(003) and the program section is interlocked, the PV will be reset to the SV and the Completion Flag will be turned OFF.

When a TIMH(015) timer is forced set, its Completion Flag will be turned ON and its PV will be set to 0000. When a TIMH(015) timer is forced reset, its Completion Flag will be turned OFF and its PV will be reset to the SV.

The timer's Completion Flag is refreshed only when TIMH(015) is executed, so a delay of up to one cycle may be required for the Completion Flag to be turned ON after the timer times out.

If online editing is used to convert a timer to another kind of timer with the same timer number (such as TIMH(015)  $\leftrightarrow$  TIM or TIMH(015)  $\leftrightarrow$  TMHH(540)), be sure to reset the Completion Flag. The timer will not operate properly unless the Completion Flag is reset.

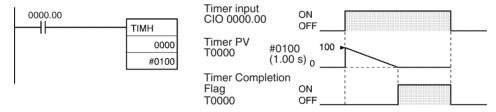
A TIMH(015) instruction's PV and Completion Flag are refreshed in the following ways.

	The Completion Flag is turned ON if the PV is 0000. The Completion Flag is turned OFF if the PV is not 0000.
10-ms interval refreshing	The timer's PV is updated every 10 ms.

#### Example

When timer input CIO 0000.00 goes from OFF to ON in the following example, the timer PV will begin counting down from the SV. The Timer Completion Flag, T0000, will be turned ON when the PV reaches 0000.

When CIO 0000.00 goes OFF, the timer PV will be reset to the SV and the Completion Flag will be turned OFF.



# 3-5-3 ONE-MS TIMER: TMHH(540)

#### **Purpose**

TMHH(540) operates a decrementing timer with units of 1-ms. The setting range for the set value (SV) is 0 to 9.999 s for TMHH(540). The timer accuracy is -0.001 to 0 s.

#### **Ladder Symbol**

Symbol		Operands	
		N: 0 to 15 (decimal)	
TMHH(540)		S: #0000 to #9999 (BCD)	
N	N: Timer number		
S	<b>S</b> : Set value		

#### **Variations**

Variations	Executed Each Cycle for ON Condition	TMHH(540)
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	Not allowed

### **Operands**

#### **N: Timer Number**

The timer number must be between 0 and 15 (decimal).

#### S: Set Value

The set value must be between #0000 and #9999 (BCD).

#### **Operand Specifications**

Area	N	S	
CIO Area		CIO 0000 to CIO 6143	
Work Area		W000 to W255	
Auxiliary Bit Area		A000 to A959	
Timer Area	0 to 15 (decimal)	T0000 to T0255	
Counter Area		C0000 to C0255	
DM Area		D00000 to D32767	
Indirect DM addresses in binary		@ D00000 to @ D32767	
Indirect DM addresses in BCD		*D00000 to *D32767	
Constants	#0000 to #9999 (BCD) "&" cannot be used.		
Data Resisters		DR0 to DR15	
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15		

### **Description**

When the timer input is OFF, the timer specified by N is reset, i.e., the timer's PV is reset to the SV and its Completion Flag is turned OFF.

When the timer input goes from OFF to ON, TMHH(540) starts decrementing the PV. The PV will continue timing down as long as the timer input remains ON and the timer's Completion Flag will be turned ON when the PV reaches 0000.

The status of the timer's PV and Completion Flag will be maintained after the timer times out. To restart the timer, the timer input must be turned OFF and then ON again or the timer's PV must be changed to a non-zero value (by MOV(021), for example).

## **Flags**

Name	Label	Operation
Error Flag	ER	ON if N is indirectly addressed through an Index Register but the address in the Index Register is not the PV address of a timer.
		ON if S does not contain BCD data.
		OFF in all other cases.

#### **Precautions**

Timer numbers are shared by the TIM, TIMH(015), and TMHH(540) instructions. Two timers can share the same timer number only if they are not executed at the same time. A duplication error will occur when the program is checked, but the timers will operate normally as long as they are not executed at the same time. Timers which share the same timer number will not operate properly if they are executed simultaneously.

The Completion Flag is updated only when TMHH(540) is executed. The Completion Flag can thus be delayed by up to one cycle time from the actual set value.

Timers will be reset or paused in the following cases. (When a timer is reset, its PV is reset to the SV and its Completion Flag is turned OFF.)

Condition	PV	Completion Flag
Operating mode changed from RUN or MONITOR mode to PROGRAM mode or vice versa.	0000	OFF
Power supply interrupted and reset	0000	OFF
Operation in interlocked program section (IL(002)–ILC(003))	Reset to SV.	OFF
Operation in jumped program section (JMP(004)–JME(005))	PV continues decrementing.	Retains previous status.

**Note** The PV will be set to the SV when TMHH(540) is executed.

When an operating TMHH(540) timer is in a jumped program section (JMP(004), JME(005)), the timer's PV will continue timing. (The jumped TMHH(540) instruction will not be executed, but the PV will be refreshed every 1 ms.)

When TMHH(540) is in a program section between IL(002) and ILC(003) and the program section is interlocked, the PV will be reset to the SV and the Completion Flag will be turned OFF.

When a TMHH(540) timer is forced set, its Completion Flag will be turned ON and its PV will be set to 0000. When a TMHH(540) timer is forced reset, its Completion Flag will be turned OFF and its PV will be reset to the SV.

If online editing is used to convert a timer to another kind of timer with the same timer number (such as TMHH(540)  $\leftrightarrow$  TIM or TMHH(540)  $\leftrightarrow$  TIMH(015)), be sure to reset the Completion Flag. The timer will not operate properly unless the Completion Flag is reset.

A TMHH(540) instruction's PV and Completion Flag are refreshed as shown in the following table.

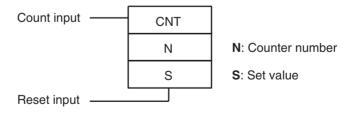
	The Completion Flag is turned ON if the PV is 0000. The Completion Flag is turned OFF if the PV is not 0000.
1-ms interval refreshing	The timer's PV is updated every 1 ms.

#### 3-5-4 COUNTER: CNT

**Purpose** 

CNT operates a decrementing counter. The setting range 0 to 9,999 for CNT.

Ladder Symbol



**Variations** 

Variations	Executed Each Cycle for ON Condition	CNT
	<b>Executed Once for Upward Differentiation</b>	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas Step program areas		Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

# **Operands**

#### **N: Counter Number**

The counter number must be between 0 and 255 (decimal).

### S: Set Value

The set value must be between #0000 and #9999 (BCD).

# **Operand Specifications**

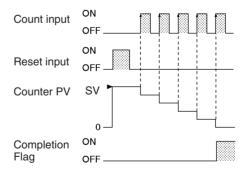
Area	N	S
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A000 to A959
Timer Area		T0000 to T0255
Counter Area	0 to 255 (decimal)	C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ D32767
Indirect DM addresses in BCD		*D00000 to *D32767
Constants		#0000 to #9999 (BCD) "&" cannot be used.
Data Resisters		DR0 to DR15
Index Registers		
Indirect address- ing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15	

# **Description**

The counter PV is decremented by 1 every time that the count input goes from OFF to ON. The Completion Flag is turned ON when the PV reaches 0.

Once the Completion Flag is turned ON, reset the counter by turning the reset input ON. Otherwise, the counter cannot be restarted.

The counter is reset and the count input is ignored when the reset input is ON. (When a counter is reset, its PV is reset to the SV and the Completion Flag is turned OFF.)



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if N is indirectly addressed through an Index Register but the address in the Index Register is not the PV address of a counter.  ON if S does not contain BCD data.
		OFF in all other cases.

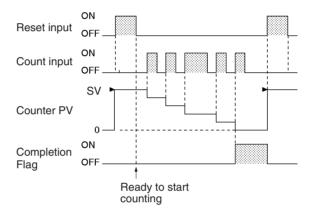
#### **Precautions**

Counter numbers are shared by the CNT, and CNTR(012) instructions. Two counters can share the same timer number only if they are not executed at the same time. A duplication error will occur when the program is checked, but the counters will operate normally as long as they are not executed at the same time. Counters which share the same counter number will not operate properly if they are executed simultaneously.

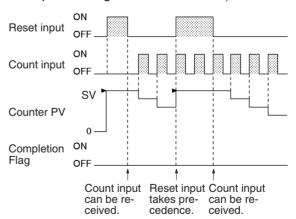
A counter's PV is refreshed when the count input goes from OFF to ON and the Completion Flag is refreshed each time that CNT is executed. The Completion Flag is turned ON if the PV is 0 and it is turned OFF if the PV is not 0.

When a CNT counter is forced set, its Completion Flag will be turned ON and its PV will be reset to 0000. When a CNT counter is forced reset, its Completion Flag will be turned OFF and its PV will be set to the SV.

Be sure to reset the counter by turning the reset input from OFF  $\rightarrow$  ON  $\rightarrow$  OFF before beginning counting with the count input, as shown in the following diagram. The count input will not be received if the reset input is ON.



The reset input will take precedence and the counter will be reset if the reset input and count input are both ON at the same time. (The PV will be reset to the SV and the Completion Flag will be turned OFF.)



**Note** If online editing is used to add a counter, the counter must be reset before it will work properly. If the counter is not reset, the previous value will be used as the counter's present value (PV), and the counter may not operate properly after it is written.

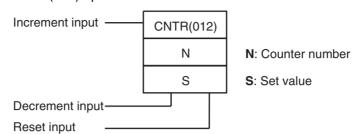
Counter PVs are not retained through a power interruption.

# 3-5-5 REVERSIBLE COUNTER: CNTR(012)

**Purpose** 

CNTR(012) operates a reversible counter.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	CNTR(012)
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

# **Operands**

### **N: Counter Number**

The counter number must be between 0 and 255 (decimal).

### S: Set Value

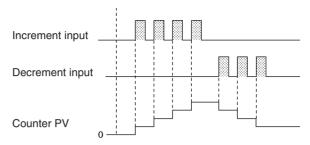
The set value must be between #0000 and #9999 (BCD).

# **Operand Specifications**

Area	N	S
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A000 to A959
Timer Area		T0000 to T0255
Counter Area	0 to 255 (decimal)	C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ D32767
Indirect DM addresses in BCD		*D00000 to *D32767
Constants		#0000 to #9999 (BCD) "&" cannot be used.
Data Resisters		DR0 to DR15
Index Registers		
Indirect address- ing using Index Registers	,IR0 to ,IR15 –2048 to +2047 ,IR0 to –2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15	

## **Description**

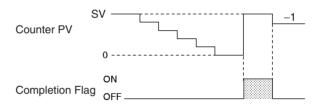
The counter PV is incremented by 1 every time that the increment input goes from OFF to ON and it is decremented by 1 every time that the decrement input goes from OFF to ON. The PV can fluctuate between 0 and the SV.



When incrementing, the Completion Flag will be turned ON when the PV is incremented from the SV back to 0 and it will be turned OFF again when the PV is incremented from 0 to 1.



When decrementing, the Completion Flag will be turned ON when the PV is decremented from 0 up to the SV and it will be turned OFF again when the PV is decremented from the SV to SV-1.



**Flags** 

Name	Label	Operation
Error Flag	ER	ON if N is indirectly addressed through an Index Register but the address in the Index Register is not the PV address of a counter.
		ON in BCD mode and S does not contain BCD data.
		OFF in all other cases.

# **Precautions**

Counter numbers are shared by the CNT and CNTR(012) instructions. Two counters can share the same timer number only if they are not executed at the same time. A duplication error will occur when the program is checked, but the counters will operate normally as long as they are not executed at the same time. Counters which share the same counter number will not operate properly if they are executed simultaneously.

The PV will not be changed if the increment and decrement inputs both go from OFF to ON at the same time. When the reset input is ON, the PV will be reset to 0 and both count inputs will be ignored.

The Completion Flag will be ON only when the PV has been incremented from the SV to 0 or decremented from 0 to the SV; it will be OFF in all other cases.

When inputting the CNTR(012) instruction with mnemonics, first enter the increment input (II), then the decrement input (DI), the reset input (R), and finally the CNTR(012) instruction. When entering with the ladder diagrams,

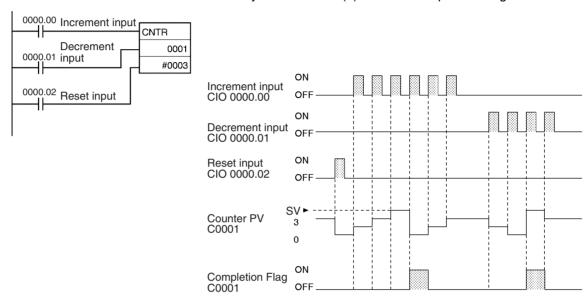
first input the increment input (II), then the CNTR(012) instruction, the decrement input (DI), and finally the reset input (R).

#### **Examples**

### **Basic Operation of CNTR(012)**

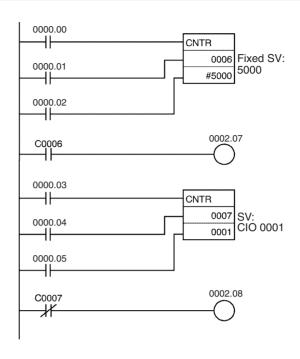
The counter PV is reset to 0 by turning the reset input (CIO 0000.02) ON and OFF. The PV is incremented by 1 each time that the increment input (CIO 0000.00) goes from OFF to ON. When the PV is incremented from the SV (3), it is automatically reset to 0 and the Completion Flag is turned ON.

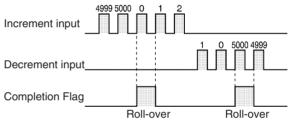
Likewise, the PV is decremented by 1 each time that the decrement input (CIO 0000.01) goes from OFF to ON. When the PV is decremented from 0, it is automatically set to the SV (3) and the Completion Flag is turned ON.



### Specifying the SV in a Word

In the following example, the SV for CNTR(012) 0007 is determined by the content of CIO 0001. When the content of CIO 0001 is controlled by an external switch, the set value can be changed manually from the switch.





# Coding

Address	Instruction	Operand
000000	LD	0000.00
000001	LD	0000.01
000002	LD	0000.02
000003	CNTR(012)	6
		#5000
000004	LD	C0006
000005	OUT	0002.07
000006	LD	0000.03
000007	LD	0000.04
000008	LD	0000.05
000009	CNTR(012)	7
		0001
000010	LD NOT	C0007
000011	OUT	0002.08

# 3-6 Comparison Instructions

This section describes instructions used to compare data of various lengths and in various ways.

Instruction	Mnemonic	Function code	Page
Input Comparison Instructions	=, <>, <, <=, >, >=	300 to 328	167
	(S, L) (LD, AND, OR)		
COMPARE	CMP	020	172
DOUBLE COMPARE	CMPL	060	175
SIGNED BINARY COMPARE	CPS	114	177
DOUBLE SIGNED BINARY COMPARE	CPSL	115	180
MULTIPLE COMPARE	MCMP	019	182
TABLE COMPARE	TCMP	085	185
BLOCK COMPARE	ВСМР	068	187
EXPANDED BLOCK COMPARE	BCMP2	502	190
AREA RANGE COMPARE	ZCP	088	193
DOUBLE AREA RANGE COM- PARE	ZCPL	116	196

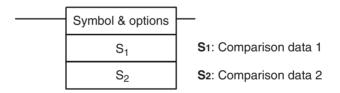
# 3-6-1 Input Comparison Instructions (300 to 328)

### **Purpose**

Input comparison instructions compare two values (constants and/or the contents of specified words) and create an ON execution condition when the comparison condition is true. Input comparison instructions are available to compare signed or unsigned data of one-word or double length data.

**Note** Refer to 3-14-21 Single-precision Floating-point Comparison Instructions for details on single-precision floating-point input comparison instructions.

# **Ladder Symbol**



#### **Variations**

Variations	Creates ON Each Cycle Comparison is True	Input compari-
		son instruction

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Operand Specifications for Instructions for Oneword Data

Area	S <sub>1</sub>	S <sub>2</sub>
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A000 to A959	
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	

Area	S <sub>1</sub>	S <sub>2</sub>
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 to #FFFF	
	(binary)	
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

Operand Specifications for Instructions for Double-length Data

Area	S <sub>1</sub>	S <sub>2</sub>
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF (I	oinary)
Data Resisters		
Index Registers	IR0 to IR1 (for unsigned data	only)
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048	to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to D	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

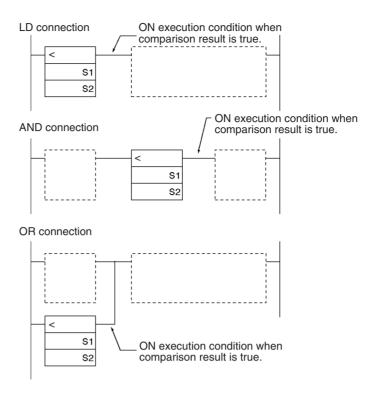
### **Description**

The input comparison instruction compares  $S_1$  and  $S_2$  as signed or unsigned values and creates an ON execution condition when the comparison condition is true. Unlike instructions such as CMP(020) and CMPL(060), the result of an input comparison instruction is reflected directly as an execution condition, so it is not necessary to access the result of the comparison through an Arithmetic Flag and the program is simpler and faster.

### **Inputting the Instructions**

The input comparison instructions are treated just like the LD, AND, and OR instructions to control the execution of subsequent instructions.

Input type	Operation
LD	The instruction can be connected directly to the left bus bar.
AND	The instruction cannot be connected directly to the left bus bar.
OR	The instruction can be connected directly to the left bus bar.



# **Options**

The input comparison instructions can compare signed or unsigned data and they can compare one-word or double values. If no options are specified, the comparison will be for one-word unsigned data. With the three input types for each of 6 symbols and two options, there are 72 different input comparison instructions.

	Symbol	Option (data format)	Option (data length)
=	(Equal)	None: Unsigned data	None: One-word data
<>	(Not equal)	S: Signed data	L: Double-length data
<	(Less than)		
<=	(Less than or equal)		
>	(Greater than)		
>=	(Greater than or equal)		

Unsigned input comparison instructions (i.e., instructions without the S option) can handle unsigned binary or BCD data. Signed input comparison instructions (i.e., instructions with the S option) handle signed binary data.

# **Summary of Input Comparison Instructions**

The following table shows the function codes, mnemonics, names, and functions of the 72 input comparison instructions. (For one-word comparisons  $C1=S_1$  and  $C2=S_2$ ; for double comparisons  $C1=S_1+1$ ,  $S_1$  and  $C2=S_2+1$ ,  $S_2$ .)

Code	Mnemonic	Name	Function
300	LD=	LOAD EQUAL	True if
	AND=	AND EQUAL	C1 = C2
	OR=	OR EQUAL	
301	LD=L	LOAD DOUBLE EQUAL	
	AND=L	AND DOUBLE EQUAL	
	OR=L	OR DOUBLE EQUAL	
302	LD=S	LOAD SIGNED EQUAL	
	AND=S	AND SIGNED EQUAL	
	OR=S	OR SIGNED EQUAL	
303	LD=SL	LOAD DOUBLE SIGNED EQUAL	
	AND=SL	AND DOUBLE SIGNED EQUAL	
	OR=SL	OR DOUBLE SIGNED EQUAL	
305	LD<>	LOAD NOT EQUAL	True if
	AND<>	AND NOT EQUAL	C1 ≠ C2
	OR<>	OR NOT EQUAL	
306	LD<>L	LOAD DOUBLE NOT EQUAL	
	AND<>L	AND DOUBLE NOT EQUAL	
	OR<>L	OR DOUBLE NOT EQUAL	
307	LD<>S	LOAD SIGNED NOT EQUAL	
	AND<>S	AND SIGNED NOT EQUAL	
	OR<>S	OR SIGNED NOT EQUAL	
308	LD<>SL	LOAD DOUBLE SIGNED NOT EQUAL	
	AND<>SL	AND DOUBLE SIGNED NOT EQUAL	
	OR<>SL	OR DOUBLE SIGNED NOT EQUAL	
310	LD<	LOAD LESS THAN	True if
	AND<	AND LESS THAN	C1 < C2
	OR<	OR LESS THAN	
311	LD <l< td=""><td>LOAD DOUBLE LESS THAN</td><td></td></l<>	LOAD DOUBLE LESS THAN	
	AND <l< td=""><td>AND DOUBLE LESS THAN</td><td></td></l<>	AND DOUBLE LESS THAN	
	OR <l< td=""><td>OR DOUBLE LESS THAN</td><td></td></l<>	OR DOUBLE LESS THAN	
312	LD <s< td=""><td>LOAD SIGNED LESS THAN</td><td></td></s<>	LOAD SIGNED LESS THAN	
	AND <s< td=""><td>AND SIGNED LESS THAN</td><td></td></s<>	AND SIGNED LESS THAN	
	OR <s< td=""><td>OR SIGNED LESS THAN</td><td></td></s<>	OR SIGNED LESS THAN	
313	LD <sl< td=""><td>LOAD DOUBLE SIGNED LESS THAN</td><td></td></sl<>	LOAD DOUBLE SIGNED LESS THAN	
	AND <sl< td=""><td>AND DOUBLE SIGNED LESS THAN</td><td></td></sl<>	AND DOUBLE SIGNED LESS THAN	
	OR <sl< td=""><td>OR DOUBLE SIGNED LESS THAN</td><td></td></sl<>	OR DOUBLE SIGNED LESS THAN	
315	LD<=	LOAD LESS THAN OR EQUAL	True if C1 ≤ C2
	AND<=	AND LESS THAN OR EQUAL	U1 ≤ 02
-16	OR<=	OR LESS THAN OR EQUAL	
316	LD<=L	LOAD DOUBLE LESS THAN OR EQUAL	
	AND<=L	AND DOUBLE LESS THAN OR EQUAL	
	OR<=L	OR DOUBLE LESS THAN OR EQUAL	
317	LD<=S	LOAD SIGNED LESS THAN OR EQUAL	
	AND<=S	AND SIGNED LESS THAN OR EQUAL	
	OR<=S	OR SIGNED LESS THAN OR EQUAL	

Code	Mnemonic	Name	Function
318	LD<=SL	LOAD DOUBLE SIGNED LESS THAN OR EQUAL	True if
	AND<=SL	AND DOUBLE SIGNED LESS THAN OR EQUAL	C1 ≤ C2
	OR<=SL	OR DOUBLE SIGNED LESS THAN OR EQUAL	
320	LD>	LOAD GREATER THAN	True if
	AND>	AND GREATER THAN	C1 > C2
	OR>	OR GREATER THAN	
321	LD>L	LOAD DOUBLE GREATER THAN	
	AND>L	AND DOUBLE GREATER THAN	
	OR>L	OR DOUBLE GREATER THAN	
322	LD>S	LOAD SIGNED GREATER THAN	
	AND>S	AND SIGNED GREATER THAN	
	OR>S	OR SIGNED GREATER THAN	
323	LD>SL	LOAD DOUBLE SIGNED GREATER THAN	
	AND>SL	AND DOUBLE SIGNED GREATER THAN	
	OR>SL	OR DOUBLE SIGNED GREATER THAN	
325	LD>=	LOAD GREATER THAN OR EQUAL	True if
	AND>=	AND GREATER THAN OR EQUAL	C1 ≥ C2
	OR>=	OR GREATER THAN OR EQUAL	
326	LD>=L	LOAD DOUBLE GREATER THAN OR EQUAL	
	AND>=L	AND DOUBLE GREATER THAN OR EQUAL	
	OR>=L	OR DOUBLE GREATER THAN OR EQUAL	
327	LD>=S	LOAD SIGNED GREATER THAN OR EQUAL	
	AND>=S	AND SIGNED GREATER THAN OR EQUAL	
	OR>=S	OR SIGNED GREATER THAN OR EQUAL	
328	8 LD>=SL LOAD DBL SIGNED GREATER THAN OR EQUA		
	AND>=SL	AND DBL SIGNED GREATER THAN OR EQUAL	
	OR>=SL	OR DBL SIGNED GREATER THAN OR EQUAL	

# Flags

Name	Label	Operation
Greater Than	>	ON if $S_1 > S_2$ with one-word data.
Flag		ON if $S_1+1$ , $S_1 > S_2+1$ , $S_2$ with double-length data.
		OFF in all other cases.
Greater Than or	>=	ON if $S_1 \ge S_2$ with one-word data.
Equal Flag		ON if $S_1+1$ , $S_1 \ge S_2+1$ , $S_2$ with double-length data.
		OFF in all other cases.
Equal Flag	=	ON if $S_1 = S_2$ with one-word data.
		ON if $S_1+1$ , $S_1=S_2+1$ , $S_2$ with double-length data.
		OFF in all other cases.
Not Equal Flag	<b>&lt;&gt;</b>	ON if $S_1 \neq S_2$ with one-word data.
		ON if $S_1+1$ , $S_1 \neq S_2+1$ , $S_2$ with double-length data.
		OFF in all other cases.
Less Than Flag	<	ON if $S_1 < S_2$ with one-word data.
		ON if $S_1+1$ , $S_1 < S_2+1$ , $S_2$ with double-length data.
OFF in all other ca		OFF in all other cases.
		ON if $S_1 \le S_2$ with one-word data.
Equal Flag		ON if $S_1+1$ , $S_1 \le S_2+1$ , $S_2$ with double-length data.
		OFF in all other cases.

#### **Precautions**

Input comparison instructions cannot be used as right-hand instructions, i.e., another instruction must be used between them and the right bus bar.

Make sure to program an output instruction or special instruction other than intermediate instructions after input comparison instructions as a right-hand instruction.

#### **Examples**

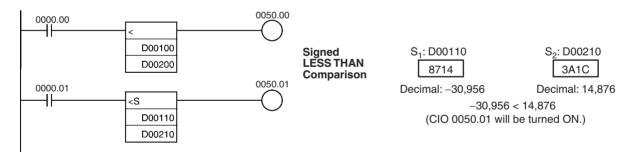
### AND LESS THAN: AND<(310)

When CIO 0000.00 is ON in the following example, the contents of D00100 and D00200 are compared as unsigned binary data. If the content of D00100 is less than that of D00200, CIO 0050.00 is turned ON and execution proceeds to the next line. If the content of D00100 is not less than that of D00200, the remainder of the instruction line is skipped and execution moves to the next instruction line.



### AND SIGNED LESS THAN: AND<S(312)

When CIO 0000.01 is ON in the following example, the contents of D00110 and D00210 are compared as signed binary data. If the content of D00110 is less than that of D00210, CIO 0050.01 is turned ON and execution proceeds to the next line. If the content of D00110 is not less than that of D00210, the remainder of the instruction line is skipped and execution moves to the next instruction line.

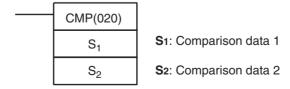


# 3-6-2 COMPARE: CMP(020)

### **Purpose**

Compares two unsigned binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	CMP(020)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

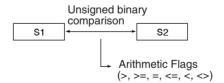
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S <sub>1</sub>	S <sub>2</sub>	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	n *D00000 to *D32767		
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing using	,IR0 to ,IR15		
Index Registers	-2048 to +2047 ,IR0 to -204	8 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to	DR15, IR15	
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

CMP(020) compares the unsigned binary data in  $S_1$  and  $S_2$  and outputs the result to Arithmetic Flags (the Greater Than, Greater Than or Equal, Equal, Less Than or Equal, Less Than, and Not Equal Flags) in the Auxiliary Area.



#### **Condition Flag Status**

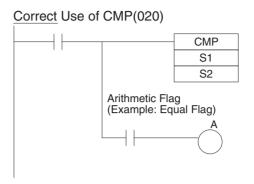
The following table shows the status of the Arithmetic Flags after execution of CMP(020). (A status of "---" indicates that the Flag may be ON or OFF.)

CMP(020)	Flag status					
Result	>	>=	=	<=	<	<>
$S_1 > S_2$	ON	ON	OFF	OFF	OFF	ON
$S_1 = S_2$	OFF	ON	ON	ON	OFF	OFF
$S_1 < S_2$	OFF	OFF	OFF	ON	ON	ON

# Using CMP(020) Results in the Program

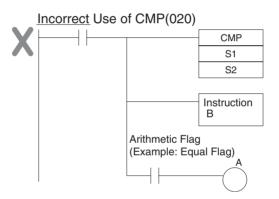
When CMP(020) is executed, the result is reflected in the Arithmetic Flags. Control the desired output or right-hand instruction with a branch from the

same input condition that controls CMP(020), as shown in the following diagram. In this case, the Equals Flag and output A will be turned ON when  $S_1 = S_2$ .



# Using CMP(020) Results in the Program

Do not program another instruction between CMP(020) and the instruction controlled by the Arithmetic Flag because the other instruction might change the status of the Arithmetic Flag. In this case, the results of instruction B might change the results of CMP(020).



### **Flags**

Name	CX-Programmer label	Label	Operation
Greater Than Flag	P_GT	>	ON if $S_1 > S_2$ .
			OFF in all other cases.
Greater Than or Equal Flag	P_GE	>=	ON if $S_1 \ge S_2$ .
			OFF in all other cases.
Equal Flag	P_EQ	=	ON if $S_1 = S_2$ .
			OFF in all other cases.
Not Equal Flag	P_NE	<>	ON if $S_1 \neq S_2$ .
			OFF in all other cases.
Less Than Flag	P_LT	<	ON if $S_1 < S_2$ .
			OFF in all other cases.
Less Than or Equal Flag	P_LE	<=	ON if $S_1 \leq S_2$ .
			OFF in all other cases.

### **Precautions**

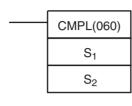
Do not program another instruction between CMP(020) and an input condition that accesses the result of CMP(020) because the other instruction might change the status of the Arithmetic Flags.

# 3-6-3 DOUBLE COMPARE: CMPL(060)

### **Purpose**

Compares two double unsigned binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.

# **Ladder Symbol**



S1: Comparison data 1

S2: Comparison data 2

#### **Variations**

Variations	Executed Each Cycle for ON Condition	CMPL(060)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

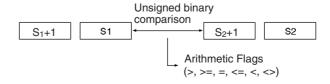
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S <sub>1</sub>	S <sub>2</sub>
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF	
	(binary)	
Data Resisters		
Index Registers	IR0 to IR15	
Indirect addressing using	,IR0 to ,IR15	
Index Registers	-2048 to +2047 ,IR0 to -204	8 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

### **Description**

CMPL(060) compares the unsigned binary data in  $S_1$  +1,  $S_1$  and  $S_2$ +1,  $S_2$  and outputs the result to Arithmetic Flags (the Greater Than, Greater Than or Equal, Equal, Less Than or Equal, Less Than, and Not Equal Flags) in the Auxiliary Area.



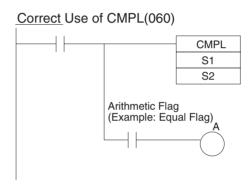
# **Arithmetic Flag Status**

The following table shows the status of the Arithmetic Flags after execution of CMPL(060). (A status of "---" indicates that the Flag may be ON or OFF.)

CMPL(060)Result	Flag status					
	>	>=	=	<=	<	<b>&lt;&gt;</b>
$S_1 + 1, S_1 > S_2 + 1, S_2$	ON	ON	OFF	OFF	OFF	ON
$S_1+1, S_1 = S_2+1, S_2$	OFF	ON	ON	ON	OFF	OFF
$S_1+1, S_1 < S_2+1, S_2$	OFF	OFF	OFF	ON	ON	ON

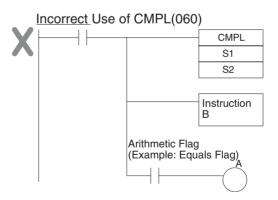
# Using CMPL(060) Results in the Program

When CMPL(060) is executed, the result is reflected in the Arithmetic Flags. Control the desired output or right-hand instruction with a branch from the same input condition that controls CMPL(060), as shown in the following diagram. Here, the Equals Flag and output A will be turned ON when  $S_1 + 1$ ,  $S_1 = S_2 + 1$ ,  $S_2$ .



# Using CMPL(060) Results in the Program

Do not program another instruction between CMPL(060) and the instruction controlled by the Arithmetic Flag because the other instruction might change the status of the Arithmetic Flag. In this case, the results of instruction B might change the results of CMPL(060).



#### **Flags**

Name	CX-Programmer label	Label	Operation
Greater Than Flag	P_GT	>	ON if $S_1 + 1$ , $S_1 > S_2 + 1$ , $S_2$ .
			OFF in all other cases.
Greater Than or Equal Flag	P_GE	>=	ON if $S_1 + 1$ , $S_1 \ge S_2 + 1$ , $S_2$ .
			OFF in all other cases.

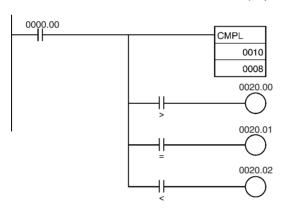
Name	CX-Programmer label	Label	Operation
Equal Flag	P_EQ	=	ON if $S_1 + 1$ , $S_1 = S_2 + 1$ , $S_2$ .
			OFF in all other cases.
Not Equal Flag	P_NE	<>	ON if $S_1 + 1$ , $S_1 \neq S_2 + 1$ , $S_2$ .
			OFF in all other cases.
Less Than Flag	P_LT	<	ON if $S_1 + 1$ , $S_1 < S_2 + 1$ , $S_2$ .
			OFF in all other cases.
Less Than or Equal Flag	P_LE	<=	ON if $S_1 + 1$ , $S_1 \le S_2 + 1$ , $S_2$ .
			OFF in all other cases.

#### **Precautions**

Do not program another instruction between CMPL(060) and an input condition that accesses the result of CMPL(060) because the other instruction might change the status of the Arithmetic Flags.

#### Example

When CIO 0000.00 is ON in the following example, the eight-digit unsigned binary data in CIO 0011 and CIO 0010 is compared to the eight-digit unsigned binary data in CIO 0009 and CIO 0008 and the result is output to the Arithmetic Flags. The results recorded in the Greater Than, Equals, and Less Than Flags are immediately saved to CIO 0002.00 (Greater Than), CIO 0002.01 (Equals), and CIO 0002.02 (Less Than).



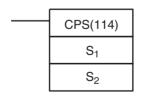
S <sub>1+1</sub> = CIO 0011	S1 = CIO 0010		Flag status		
1234	5678 Result		>	OFF	(0)
1	Comparison —	<del></del>	=	OFF	(0)
S2+1 = CIO 0009   S2 = CIO 0008			<	ON	(1)
ABCD EF12					

# 3-6-4 SIGNED BINARY COMPARE: CPS(114)

#### **Purpose**

Compares two signed binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.

#### **Ladder Symbol**



S1: Comparison data 1

S2: Comparison data 2

### **Variations**

Variations	<b>Executed Each Cycle for ON Condition</b>	CPS(114)
	<b>Executed Once for Upward Differentiation</b>	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

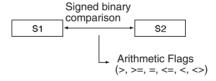
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S <sub>1</sub>	S <sub>2</sub>
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A000 to A959	
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 to #FFFF	
	(binary)	
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing using	,IR0 to ,IR15	
Index Registers	-2048 to +2047 ,IR0 to -204	8 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

# **Description**

CPS(114) compares the signed binary data in  $S_1$  and  $S_2$  and outputs the result to Arithmetic Flags (the Greater Than, Greater Than or Equal, Equal, Less Than or Equal, Less Than, and Not Equal Flags) in the Auxiliary Area.



**Note** CPS(114) treats the data in  $S_1$  and  $S_2$  as signed binary data which ranges from 8000 to 7FFF (-32,768 to 32,767 decimal).

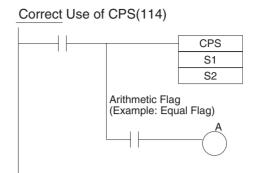
### **Arithmetic Flag Status**

The following table shows the status of the Arithmetic Flags after execution of CPS(114). (A status of "---" indicates that the Flag may be ON or OFF.)

CPS(114)	Flag status					
Result	>	>=	=	<=	<	<>
$S_1 > S_2$	ON	ON	OFF	OFF	OFF	ON
$S_1 = S_2$	OFF	ON	ON	ON	OFF	OFF
$S_1 < S_2$	OFF	OFF	OFF	ON	ON	ON

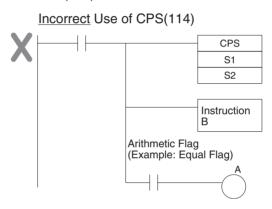
# **Using CPS(114) Results in the Program**

When CPS(114) is executed, the result is reflected in the Arithmetic Flags. Control the desired output or right-hand instruction with a branch from the same input condition that controls CPS(114), as shown in the following diagram. In this case, the Equals Flag and output A will be turned ON when  $S_1 = S_2$ .



# Using CPS(114) Results in the Program

Do not program another instruction between CPS(114) and the instruction controlled by the Arithmetic Flag because the other instruction might change the status of the Arithmetic Flag. In this case, the results of instruction B might change the results of CPS(114).



# Flags

Name	Label	Operation
Greater Than Flag	>	ON if $S_1 > S_2$ .
		OFF in all other cases.
Greater Than or Equal Flag	>=	ON if $S_1 \ge S_2$ .
		OFF in all other cases.
Equal Flag	=	ON if $S_1 = S_2$ .
		OFF in all other cases.
Not Equal Flag	<>	ON if $S_1 \neq S_2$ .
		OFF in all other cases.
Less Than Flag	<	ON if $S_1 < S_2$ .
		OFF in all other cases.
Less Than or Equal Flag	<=	ON if $S_1 \leq S_2$ .
		OFF in all other cases.

### **Precautions**

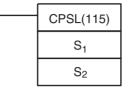
Do not program another instruction between CPS(114) and an input condition that accesses the result of CPS(114) because the other instruction might change the status of the Arithmetic Flags.

# 3-6-5 DOUBLE SIGNED BINARY COMPARE: CPSL(115)

### **Purpose**

Compares two double signed binary values (constants and/or the contents of specified words) and outputs the result to the Arithmetic Flags in the Auxiliary Area.

# **Ladder Symbol**



S1: Comparison data 1

S2: Comparison data 2

#### **Variations**

Variations	Executed Each Cycle for ON Condition	CPSL(115)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

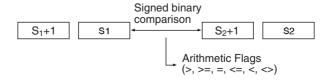
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S <sub>1</sub>	S <sub>2</sub>
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF	
	(binary)	
Data Resisters		
Index Registers		
Indirect addressing using	,IR0 to ,IR15	
Index Registers	-2048 to +2047 ,IR0 to -204	8 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

#### **Description**

CPSL(115) compares the double signed binary data in  $S_1$  +1,  $S_1$  and  $S_2$ +1,  $S_2$  and outputs the result to Arithmetic Flags (the Greater Than, Greater Than or Equal, Equal, Less Than or Equal, Less Than, and Not Equal Flags) in the Auxiliary Area.



**Note** CPSL(115) treats the data in  $S_1$  and  $S_2$  as double signed binary data which ranges from 8000 0000 to 7FFF FFFF (-2,147,483,648 to 2,147,483,647 decimal).

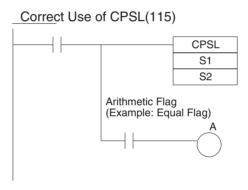
# **Arithmetic Flag Status**

The following table shows the status of the Arithmetic Flags after execution of CPSL(115). (A status of "---" indicates that the Flag may be ON or OFF.)

CPSL(115)Result	Flag status					
	>	>=	=	<=	<	<>
$S_1 + 1, S_1 > S_2 + 1, S_2$	ON	ON	OFF	OFF	OFF	ON
$S_1+1, S_1 = S_2+1, S_2$	OFF	ON	ON	ON	OFF	OFF
$S_1+1, S_1 < S_2+1, S_2$	OFF	OFF	OFF	ON	ON	ON

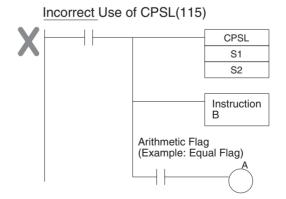
# Using CPSL(115) Results in the Program

When CPSL(115) is executed, the result is reflected in the Arithmetic Flags. Control the desired output or right-hand instruction with a branch from the same input condition that controls CPSL(115), as shown in the following diagram. Here, the Equals Flag and output A will be turned ON when  $S_1 + 1$ ,  $S_1 = S_2 + 1$ ,  $S_2$ .



### Using CPSL(115) Results in the Program

Do not program another instruction between CPSL(115) and the instruction controlled by the Arithmetic Flag because the other instruction might change the status of the Arithmetic Flag. In this case, the results of instruction B might change the results of CPSL(115).



### **Flags**

Name	Label	Operation
Greater Than Flag	>	ON if $S_1 + 1$ , $S_1 > S_2 + 1$ , $S_2$ .
		OFF in all other cases.
Greater Than or Equal Flag	>=	ON if $S_1 + 1$ , $S_1 \ge S_2 + 1$ , $S_2$ .
		OFF in all other cases.
Equal Flag	=	ON if $S_1 + 1$ , $S_1 = S_2 + 1$ , $S_2$ .
		OFF in all other cases.
Not Equal Flag	<>	ON if $S_1 + 1$ , $S_1 \neq S_2 + 1$ , $S_2$ .
		OFF in all other cases.
Less Than Flag	<	ON if $S_1 + 1$ , $S_1 < S_2 + 1$ , $S_2$ .
		OFF in all other cases.
Less Than or Equal Flag	<=	ON if $S_1 + 1$ , $S_1 \le S_2 + 1$ , $S_2$ .
		OFF in all other cases.

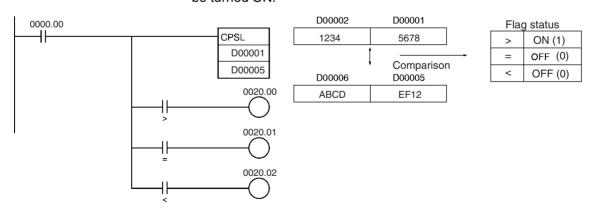
### **Precautions**

Do not program another instruction between CPSL(115) and an input condition that accesses the result of CPSL(115) because the other instruction might change the status of the Arithmetic Flags.

### Example

When CIO 0000.00 is ON in the following example, the eight-digit signed binary data in D00002 and D00001 is compared to the eight-digit signed binary data in D00006 and D00005 and the result is output to the Arithmetic Flags.

- If the content of D00002 and D00001 is greater than that of D00006 and D00005, the Greater Than Flag will be turned ON, causing CIO 0020.00 to be turned ON.
- If the content of D00002 and D00001 is equal to that of D00006 and D00005, the Equals Flag will be turned ON, causing CIO 0020.01 to be turned ON.
- If the content of D00002 and D00001 is less than that of D00006 and D00005, the Less Than Flag will be turned ON, causing CIO 0020.02 to be turned ON.

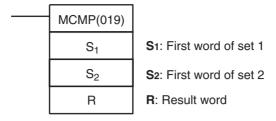


# 3-6-6 MULTIPLE COMPARE: MCMP(019)

### **Purpose**

Compares 16 consecutive words with another 16 consecutive words and turns ON the corresponding bit in the result word where the contents of the words **are not** equal.

# **Ladder Symbol**



### **Variations**

Variations	Executed Each Cycle for ON Condition	MCMP(019)
	<b>Executed Once for Upward Differentiation</b>	@MCMP(019)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

# S<sub>1</sub>: First word of set 1

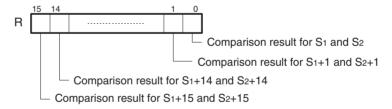
Specifies the beginning of the first 16-word range.  $S_1$  and  $S_1+15$  must be in the same data area.

# S<sub>2</sub>: First word of set 2

Specifies the beginning of the second 16-word range.  $S_2$  and  $S_2+15$  must be in the same data area.

#### R: Result word

Each bit of R contains the result of a comparison between two words in the 16-word sets. Bit n of R (n = 00 to 15) contains the result of the comparison between words  $S_1+n$  and  $S_2+n$ .



### **Operand Specifications**

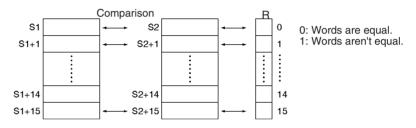
Area	S <sub>1</sub>	S <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6128		CIO 0000 to CIO 6143
Work Area	W000 to W240		W000 to W255
Auxiliary Bit Area	A000 to A944		A448 to A959
Timer Area	T0000 to T0240		T0000 to T0255
Counter Area	C0000 to C0240		C0000 to C0255
DM Area	D00000 to D32752		D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	<b>3</b> 7	
Constants			
Data Resisters			DR0 to DR15

Area	S <sub>1</sub>	S <sub>2</sub>	R	
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	-(++)			
,-()IR0 to , -()IR15				

### **Description**

MCMP(019) compares the contents of the 16 words  $S_1$  through  $S_1+15$  to the contents of the 16 words  $S_2$  through  $S_2+15$ , and turns ON the corresponding bit in word R when the contents **are not** equal.

The content of  $S_1$  is compared to the content of  $S_2$ , the content of  $S_{1+1}$  to the content of  $S_{2+1}$ , ..., and the content of  $S_{1+1}$ 5 to the content of  $S_{2+1}$ 5. Bit n of R is turned OFF if the content of  $S_{1+1}$  is equal to the content of  $S_{2+1}$ ; bit n of R is turned ON if the contents are not equal. If the contents of all 16 pairs of words are the same, the Equals Flag will turn ON after the instruction has been executed.

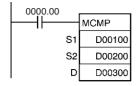


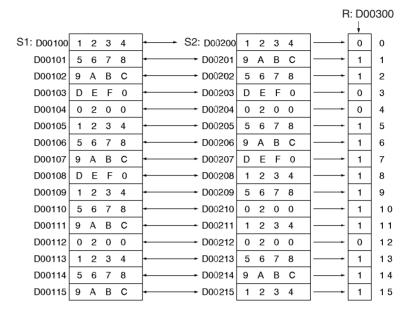
# **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the result word is 0000. (The two 16-word sets contain the same data.) OFF in all other cases.

### Example

When CIO 0000.00 is ON in the following example, MCMP(019) compares words D00100 through D00115 in order to words D00200 through D00215 and turns ON the corresponding bits in D00300 when the words **are not** equal.



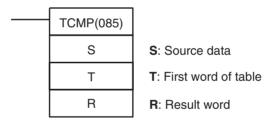


# 3-6-7 TABLE COMPARE: TCMP(085)

### **Purpose**

Compares the source data to the contents of 16 consecutive words and turns ON the corresponding bit in the result word when the contents of the words **are** equal.

#### **Ladder Symbol**



### **Variations**

Variations	Executed Each Cycle for ON Condition	TCMP(085)
	Executed Once for Upward Differentiation	@TCMP(085)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

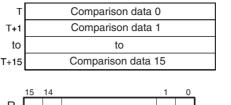
### **Operands**

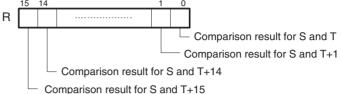
## T: First word of table

Specifies the beginning of the 16-word table. T and T+15 must be in the same data area.

#### R: Result word

Each bit of R contains the result of a comparison between S and a word in the 16-word table. Bit n of R (n = 00 to 15) contains the result of the comparison between S and T+n.





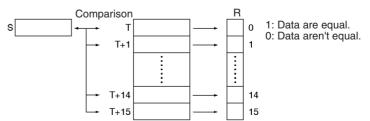
# **Operand Specifications**

Area	S	Т	R
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6128	CIO 0000 to CIO 6143
Work Area	W000 to W255	W000 to W240	W000 to W255
Auxiliary Bit Area	A000 to A959	A000 to A944	A448 to A959
Timer Area	T0000 to T0255	T0000 to T0240	T0000 to T0255
Counter Area	C0000 to C0255	C0000 to C0240	C0000 to C0255
DM Area	D00000 to D32767	D00000 to D32752	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D3276	67	
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		DR0 to DR15
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15		

## **Description**

TCMP(085) compares the source data (S) to each of the 16 words T through T+15 and turns ON the corresponding bit in word R when the data **are** equal. Bit n of R is turned ON if the content of T+n is equal to S and it is turned OFF if they are not equal.

S is compared to the content of T and bit 00 of R is turned ON if they are equal or OFF if they are not equal, S is compared to the content of T+1 and bit 01 of R is turned ON if they are equal or OFF if they are not equal, ..., and S is compared to the content of T+15 and bit 15 of R is turned ON if they are equal or OFF if they are not equal.

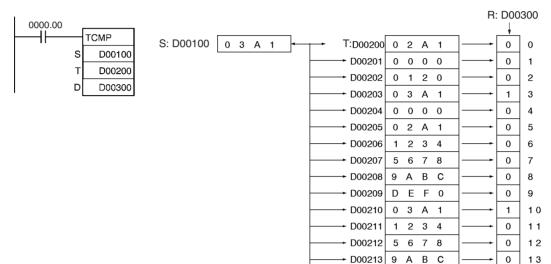


### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the result word is 0000. (None of the 16 words in the table equals S.) OFF in all other cases.

#### Example

When CIO 0000.00 is ON in the following example, TCMP(085) compares the content of D00100 with the contents of words D00200 through D00215 and turns ON the corresponding bits in D00300 when the contents are equal or OFF when the contents are not equal.



# 3-6-8 BLOCK COMPARE: BCMP(068)

### **Purpose**

Compares the source data to 16 ranges (defined by 16 lower limits and 16 upper limits) and turns ON the corresponding bit in the result word when the source data is within a range.

→ D00214

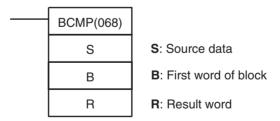
E F 0

→ D00215 0 3 A 1

0 | 14

1 | 15

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	BCMP(068)
	Executed Once for Upward Differentiation	@BCMP(068)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

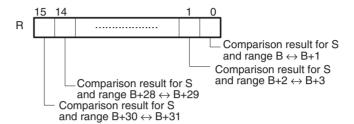
# **Operands**

#### B: First word of block

Specifies the beginning of a 32-word block (16 lower/upper limit pairs). B and B+31 must be in the same data area.

#### R: Result word

Each bit of R contains the result of a comparison between S and one of the 16 ranges defined the 32-word block. Bit n of R (n = 00 to 15) contains the result of the comparison between S and the  $n^{th}$  pair of words.



# **Operand Specifications**

Area	S	В	R	
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6112	CIO 0000 to CIO 6143	
Work Area	W000 to W255	W0000 to W224	W000 to W255	
Auxiliary Bit Area	A000 to A959	A000 to A928	A448 to A959	
Timer Area	T0000 to T0255	T0000 to T0224	T0000 to T0255	
Counter Area	C0000 to C0255	C0000 to C0224	C0000 to C0255	
DM Area	D00000 to D32767	D00000 to D32736	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants	#0000 to #FFFF (binary)			
Data Resisters	DR0 to DR15		DR0 to DR15	
Index Registers				
Indirect addressing using Index Registers	,IR0 to ,IR15  -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15  DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15			

### **Description**

BCMP(068) compares the source data (S) to the 16 ranges defined by pairs of lower and upper limit values in B through B+31. The first word in each pair (B+2n) provides the lower limit and the second word (B+2n+1) provides the upper limit of range n (n = 0 to 15). If S is within any of these ranges (inclusive of the upper and lower limits), the corresponding bit in R is turned ON. The rest of the bits in R will be turned OFF.

В	$\leq$ S $\leq$	B+1	Bit 00 of R
B+2	$\leq$ S $\leq$	B+3	Bit 01 of R
B+4	$\leq$ S $\leq$	B+5	Bit 02 of R
B+6	$\leq$ S $\leq$	B+7	Bit 03 of R
B+8	$\leq$ S $\leq$	B+9	Bit 04 of R
B+10	$\leq$ S $\leq$	B+11	Bit 05 of R
B+12	$\leq$ S $\leq$	B+13	Bit 06 of R
B+14	$\leq$ S $\leq$	B+15	Bit 07 of R

B+16	≤S≤	B+17	Bit 08 of R
B+18	$\leq$ S $\leq$	B+19	Bit 09 of R
B+20	$\leq$ S $\leq$	B+21	Bit 10 of R
B+22	$\leq$ S $\leq$	B+23	Bit 11 of R
B+24	$\leq$ S $\leq$	B+25	Bit 12 of R
B+26	$\leq$ S $\leq$	B+27	Bit 13 of R
B+28	$\leq$ S $\leq$	B+29	Bit 14 of R
B+30	$\leq$ S $\leq$	B+31	Bit 15 of R

For example, bit 00 of R is turned ON if S is within the first range (B  $\leq$  S  $\leq$  B+1), bit 01 of R is turned ON if S is within the second range (B+2  $\leq$  S  $\leq$  B+3), ..., and bit 15 of R is turned ON if S is within the fifteenth range (B+30  $\leq$  S  $\leq$  B+31). All other bits in R are turned OFF.

# **Flags**

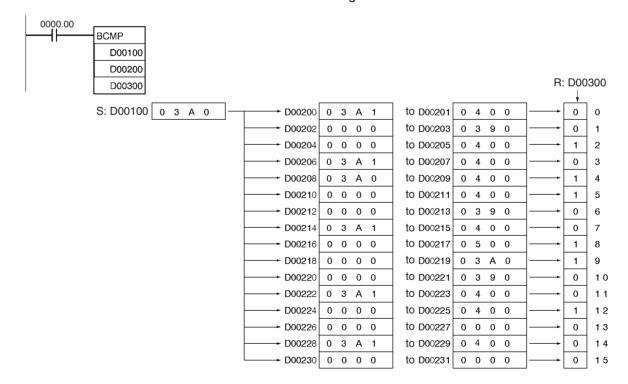
Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the result word is 0000. (S is not within any of the 16 ranges.) OFF in all other cases.

### **Precautions**

An error will not occur if the lower limit is greater than the upper limit, but 0 (not within the range) will be output to the corresponding bit of R.

### Example

When CIO 0000.00 is ON in the following example, BCMP(068) compares the content of D00100 with the 16 ranges defined in D00200 through D00231 and turns ON the corresponding bits in D00300 when S is within the range or OFF when S is not within the range.

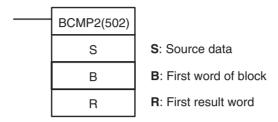


# 3-6-9 EXPANDED BLOCK COMPARE: BCMP2(502)

### **Purpose**

Compares the source data to up to 256 ranges (defined by 256 lower limits and 256 upper limits) and turns ON the corresponding bit in the result word when the source data is within a range.

# **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	BCMP2(502)
	Executed Once for Upward Differentiation	@BCMP2(502)
	<b>Executed Once for Downward Differentiation</b>	Not supported

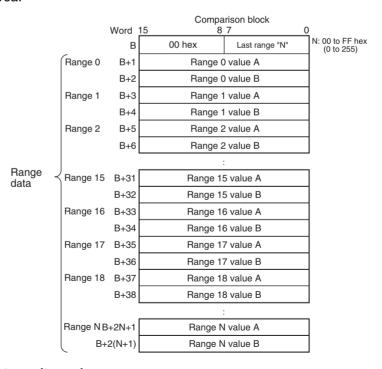
### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

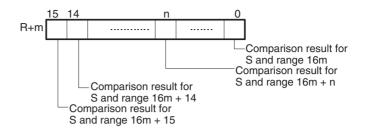
#### B: First word of block

Specifies the beginning of a comparison block containing up to 513 words including up to 256 lower/upper limit pairs). All words must be in the same data area.



## R: First result word

Each bit of each R word contains the result of a comparison between S and one of the ranges defined by the comparison block. The maximum number of result words is 16, i.e., m equals 0 to 15.



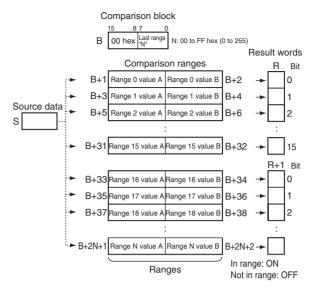
### **Operand Specifications**

Area	S	В	R
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

BCMP2(502) compares the source data (S) to the ranges defined by pairs of lower and upper limit values in the comparison block. If S is within any of these ranges (inclusive of the upper and lower limits), the corresponding bits in the result words (R to R+15 max.) are turned ON. The rest of the bits in R will be turned OFF.

The number of ranges is determined by the value N set in the lower byte of B. N can be between 0 and 255. The upper byte of B must be 00 hex.



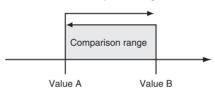
### **Number of Ranges**

The number of ranges in the comparison block is set in the first word of the block. Up to 256 ranges can be set.

# **Setting Ranges**

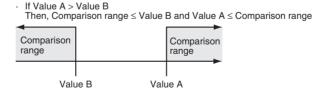
The values A and B for each range will determine how the comparison operates depending on which value is larger, as shown below.

· If Value A  $\leq$  Value B Then, Value A  $\leq$  Comparison range  $\leq$  Value B



### Example

When Value A  $\leq$  Value B If B+1  $\leq$  S  $\leq$  B+2, then bit 0 of R will turn ON, If B+3  $\leq$  S  $\leq$  B+4, then bit 1 of R will turn ON, If S < B+5 and B+6 < S, then bit 2 of R will turn OFF, and If S < B+7 and B+8 < S, then bit 3 of R will turn OFF.



## **Example**

When Value A > Value B

If  $S \le B+2$  and  $B+1 \le S$ , then bit 0 of R will turn ON,

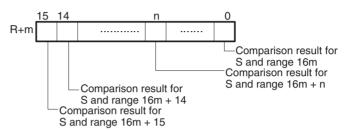
If  $S \le B+4$  and  $B+3 \le S$ , then bit 1 of R will turn ON,

If B+6 < S < B+5, then bit 2 of R will turn OFF, and

If B+8 < S < B+7, then bit 3 of R will turn OFF.

#### **Results Storage Location**

The results are output to corresponding bits in word R. If there are more than 16 comparison ranges, consecutive words following R will be used. The maximum number of result words is 16, i.e., m equals 0 to 15.

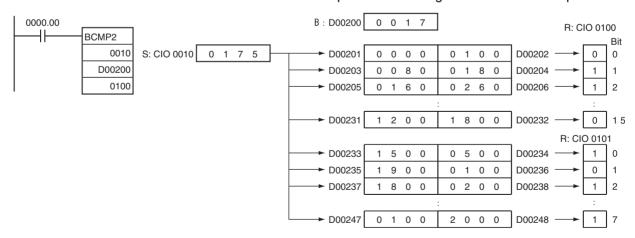


#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF

#### Example

When CIO 0000.00 is ON in the following example, BCMP2(502) compares the content of CIO 0010 with the 24 ranges defined in D00200 through D00247 (N = 17 hex = 23 decimal, i.e., 24 ranges) and turns ON the corresponding bits in CIO 0100 and CIO 0101 when S is within the range and OFF when S is not within the range. For example, if the source data in CIO 0010 is in the range defined by D00201 and D00202, then bit 00 of CIO 0100 is turned ON and if it in not in the range, then bit 00 of CIO 0100 is turned OFF. Likewise, the source data in CIO 0010 is compared to the ranges defined by D00203 and D00204, D00247 and D00248, and the other words in the comparison block, and bit 1 in CIO 0100, bit 7 in CIO 0101, and the other bits in the result words are manipulated according to the results of comparison.



# 3-6-10 AREA RANGE COMPARE: ZCP(088)

#### **Purpose**

Compares a 16-bit unsigned binary value (CD) with the range defined by lower limit LL and upper limit UL. The results are output to the Arithmetic Flags.

# **Ladder Symbol**

CD LL UL

**CD**: Comparison Data **LL**: Lower limit of range **UL**: Upper limit of range

#### **Variations**

Variations	Executed Each Cycle for ON Condition	ZCP(088)
	Executed Once for Upward Differentiation	Not supported
	Executed Once for Downward Differentiation	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	CD	LL	UL
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D3276	57	
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing using	,IR0 to ,IR15		
Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+	+(++)	
	,-()IR0 to , -(	-)IR15	

### **Description**

ZCP(088) compares the 16-bit unsigned binary data in CD with the range defined by LL and UL and outputs the result to the Greater Than, Equals, and Less Than Flags in the Auxiliary Area. (The Less Than or Equal, Greater Than or Equal, and Not Equal Flags are left unchanged.)

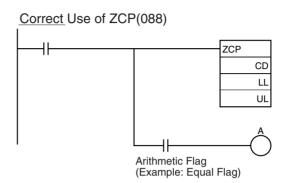
### **Arithmetic Flag Status**

The following table shows the status of the Arithmetic Flags after execution of ZCP(088).

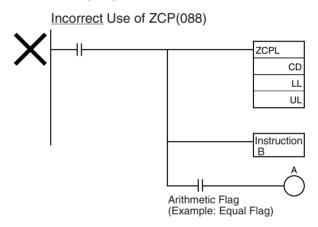
ZCP(088)Result	Flag status		
	>	=	<
CD > UL	ON	OFF	OFF
CD = UL	OFF	ON	
LL < CD < UL			
CD = LL			
CD < LL		OFF	ON

# Using ZCP(088) Results in the Program

When ZCP(088) is executed, the result is reflected in the Arithmetic Flags. Control the desired output or right-hand instruction with a branch from the same input condition that controls ZCP(088), as shown in the following diagram. In this case, the Equals Flag and output A will be turned ON when  $LL \le CD \le UL$ .



Do not program another instruction between ZCP(088) and the instruction controlled by the Arithmetic Flag because the other instruction might change the status of the Arithmetic Flag. In this case, the results of instruction B might change the results of ZCP(088).



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if LL > UL.
Greater Than Flag	>	ON if CD > UL.
		OFF in all other cases.
Greater Than or Equal Flag	>=	Left unchanged.
Equal Flag	=	ON if $LL \le CD \le UL$ .
		OFF in all other cases.
Not Equal Flag	<>	Left unchanged.
Less Than Flag	<	ON if CD < LL.
		OFF in all other cases.
Less Than or Equal Flag	<=	Left unchanged.
Negative Flag	N	Left unchanged.

#### **Precautions**

Do not program another instruction between ZCP(088) and an input condition that accesses the result of ZCP(088) because the other instruction might change the status of the Arithmetic Flags.

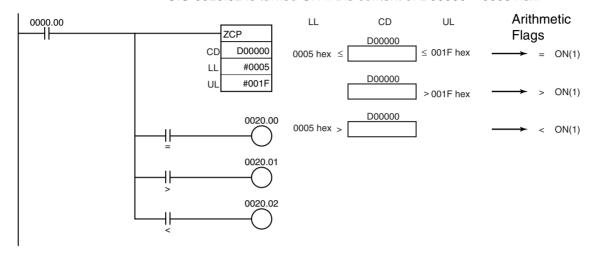
### **Example**

When CIO 0000.00 is ON in the following example, the 16-bit unsigned binary data in D00000 is compared to the range 0005 to 001F hex (5 to 31 decimal) and the result is output to the Arithmetic Flags.

CIO 0020.00 is turned ON if 0005 hex  $\leq$  content of D00000  $\leq$  001F hex.

CIO 0020.01 is turned ON if the content of D00000 > 001F hex.

CIO 0020.02 is turned ON if the content of D00000 < 0005 hex.



# 3-6-11 DOUBLE AREA RANGE COMPARE: ZCPL(116)

## **Purpose**

Compares a 32-bit unsigned binary value (CD+1, CD) with the range defined by lower limit (LL+1, LL) and upper limit (UL+1, UL). The results are output to the Arithmetic Flags.

### **Ladder Symbol**



CD: First word of Comparison Data

**LL**: First word of Lower Limit **UL**: First word of Upper Limit

#### **Variations**

Variations	Executed Each Cycle for ON Condition	ZCPL(116)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	CD	LL	UL
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	

Area	CD	LL	UL
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers	IR0 to IR15		
Indirect addressing using	,IR0 to ,IR15		
Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0  to , -()IR15		

ZCPL(116) compares the 32-bit unsigned binary data in CD+1, CD with the range defined by LL+1, LL and UL+1, UL and outputs the result to the Greater Than, Equals, and Less Than Flags in the Auxiliary Area. (The Less Than or Equal, Greater Than or Equal, and Not Equal Flags are left unchanged.)

## **Arithmetic Flag Status**

The following table shows the status of the Arithmetic Flags after execution of ZCPL(116).

ZCPL(116) result	Flag status			
	>	=	<b>~</b>	
CD+1, CD > UL+1, UL	ON	OFF	OFF	
CD+1, CD = UL+1, UL	OFF	ON		
LL+1, LL < CD+1, CD < UL+1, UL				
CD+1, CD = LL+1, LL				
CD+1, CD < LL+1, LL		OFF	ON	

#### <u>Using ZCPL(116) Results in the Program</u>

When ZCPL(116) is executed, the result is reflected in the Arithmetic Flags. Control the desired output or right-hand instruction with a branch from the same input condition that controls ZCPL(116).

Do not program another instruction between ZCPL(116) and the instruction controlled by the Arithmetic Flag because the other instruction might change the status of the Arithmetic Flag.

The operation of ZCPL(116) is almost identical to that of ZCP(088) except that ZCPL(116) compares 32-bit values instead of 16-bit values. Refer to 3-6-10 AREA RANGE COMPARE: ZCP(088) for diagrams showing how to use results in the program and an example program section.

## Flags

Name	Label	Operation
Error Flag	ER	ON if LL+1, LL > UL+1, UL.
Greater Than Flag	>	ON if CD+1, CD > UL+1, UL.
	OFF in all other cases.	
Greater Than or Equal Flag	>=	Left unchanged.
Equal Flag	=	ON if LL+1, LL $\leq$ CD+1, CD $\leq$ UL+1, UL.
	OFF in all other cases.	
Not Equal Flag	<b>&lt;&gt;</b>	Left unchanged.
Less Than Flag	<	ON if CD+1, CD < LL+1, LL.
		OFF in all other cases.

Name	Label	Operation
Less Than or Equal Flag	<=	Left unchanged.
Negative Flag	N	Left unchanged.

## **Precautions**

Do not program another instruction between ZCPL(116) and an input condition that accesses the result of ZCPL(116) because the other instruction might change the status of the Arithmetic Flags.

## 3-7 Data Movement Instructions

This section describes instructions used to move data in various ways.

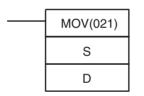
Instruction	Mnemonic	Function code	Page
MOVE	MOV	021	199
DOUBLE MOVE	MOVL	498	201
MOVE NOT	MVN	022	200
DOUBLE MOVE NOT	MVNL	499	203
MOVE BIT	MOVB	082	204
MOVE DIGIT	MOVD	083	206
MULTIPLE BIT TRANSFER	XFRB	062	208
BLOCK TRANSFER	XFER	070	211
BLOCK SET	BSET	071	213
DATA EXCHANGE	XCHG	073	215
SINGLE WORD DISTRIBUTE	DIST	080	217
DATA COLLECT	COLL	081	219
DOUBLE DATA EXCHANGE	XCGL	562	216
MOVE TO REGISTER	MOVR	560	221
MOVE TIMER/COUNTER PV TO REGISTER	MOVRW	561	222

## 3-7-1 MOVE: MOV(021)

**Purpose** 

Transfers a word of data to the specified word.

**Ladder Symbol** 



S: Source

D: Destination

**Variations** 

Variations	Executed Each Cycle for ON Condition	MOV(021)
	Executed Once for Upward Differentiation	@MOV(021)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	S	D
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A000 to A959	A448 to A959
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 to #FFFF (binary)	

Area	S	D
Data Registers	DR0 to DR15	
Index Registers		
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 DR0 to DR15,IR0 to DR0 to I ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15	

Transfers S to D. If S is a constant, the value can be used for a data setting.

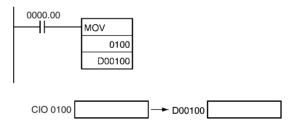


#### **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON if the data being transferred is 0000.	
		OFF in all other cases.	
Negative Flag	N	ON if the leftmost bit of the data being transferred is 1.	
		OFF in all other cases.	

## **Example**

When CIO 0000.00 is ON in the following example, the content of CIO 0100 is copied to D00100.

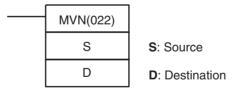


# 3-7-2 MOVE NOT: MVN(022)

## **Purpose**

Transfers the complement of a word of data to the specified word.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	MVN(022)
	<b>Executed Once for Upward Differentiation</b>	@MVN(022)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	S	D
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	

Area	S	D
Auxiliary Bit Area	A000 to A959	A448 to A959
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 to #FFFF (binary)	
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 , IR0 to -204	8 to +2047 ,IR15
	DR0 to DR15,IR0 to IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

MVN(022) inverts the bits in S and transfers the result to D. The content of S is left unchanged.

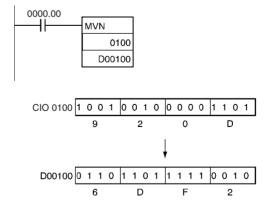


#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the content of D is 0000 after execution.
		OFF in all other cases.
Negative Flag	N	ON if the leftmost bit of D is 1 after execution.
		OFF in all other cases.

## Example

When CIO 0000.00 is ON in the following example, the status of the bits in CIO 0100 is inverted and the result is copied to D00100.

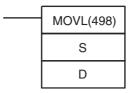


# 3-7-3 DOUBLE MOVE: MOVL(498)

## **Purpose**

Transfers two words of data to the specified words.

## **Ladder Symbol**



S: First source word

D: First destination word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	MOVL(498)
	Executed Once for Upward Differentiation	@MOVL(498)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

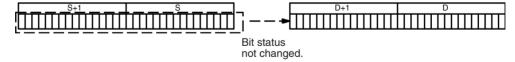
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF (binary)	
Data Resisters		
Index Registers	IR0 to IR15	
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

## **Description**

MOVL(498) transfers S+1 and S to D+1 and D. If S+1 and S are constants, the value can be used for a data setting.

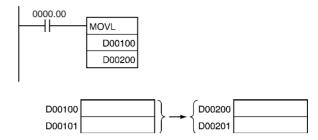


## **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the contents of D+1 and D are 0000 0000 after execution.
		OFF in all other cases.
Negative Flag	N	ON if the leftmost bit of D+1 is 1 after execution.
		OFF in all other cases.

## Example

When CIO 0000.00 is ON in the following example, the content of D00101 and D00100 are copied to D00201 and D00200.

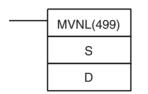


## 3-7-4 DOUBLE MOVE NOT: MVNL(499)

#### **Purpose**

Transfers the complement of two words of data to the specified words.

#### **Ladder Symbol**



S: First source word

D: First destination word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	MVNL(499)
	<b>Executed Once for Upward Differentiation</b>	@MVNL(499)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

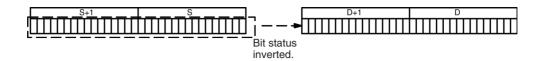
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF (binary)	
Data Resisters		
Index Registers		
Indirect addressing using Index Registers	,IR0 to ,IR15	
doing mack registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15	

#### **Description**

MVNL(499) inverts the bits in S+1 and S and transfers the result to D+1 and D. The contents of S+1 and S are left unchanged.

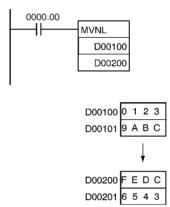


#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the contents of D+1 and D are 0000 0000 after execution.
		OFF in all other cases.
Negative Flag	N	ON if the leftmost bit of D+1 is 1 after execution.
		OFF in all other cases.

#### **Examples**

When CIO 0000.00 is ON in the following example, the status of the bits in D00101 and D00100 are inverted and the result is copied to D00201 and D00200. (The original contents of D00101 and D00100 are left unchanged.)

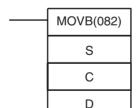


## 3-7-5 MOVE BIT: MOVB(082)

**Purpose** 

Transfers the specified bit.

**Ladder Symbol** 



S: Source word or data

C: Control word

D: Destination word

**Variations** 

Variations	Executed Each Cycle for ON Condition	MOVB(082)
	Executed Once for Upward Differentiation	@MOVB(082)
	<b>Executed Once for Downward Differentiation</b>	Not supported

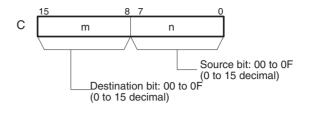
#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### Operands

#### C: Control Word

The rightmost two digits of C indicate which bit of S is the source bit and the leftmost two digits of C indicate which bit of D is the destination bit.

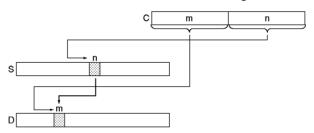


## **Operand Specifications**

Area	S	С	D	
CIO Area	CIO 0000 to CIO 6143			
Work Area	W000 to W255			
Auxiliary Bit Area	A000 to A959		A448 to A959	
Timer Area	T0000 to T0255			
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767	7		
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants	#0000 to #FFFF (binary)	Specified values only		
Data Resisters	DR0 to DR15	•		
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -(-	–)IR15		

## Description

MOVB(082) copies the specified bit (n) from S to the specified bit (m) in D. The other bits in the destination word are left unchanged.



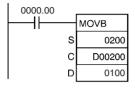
**Note** The same word can be specified for both S and D to copy a bit within a word.

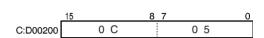
## Flags

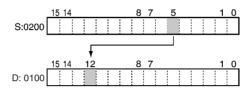
Name	Label	Operation
Error Flag	ER	ON if the rightmost and leftmost two digits of C are not within the specified range of 00 to 0F.
		OFF in all other cases.

### **Examples**

When CIO 0000.00 is ON in the following example, the  $5^{th}$  bit of the source word (CIO 0200) is copied to the  $12^{th}$  bit of the destination word (CIO 0100) in accordance with the control word's value of 0C05.





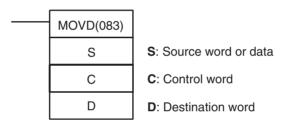


## 3-7-6 MOVE DIGIT: MOVD(083)

#### **Purpose**

Transfers the specified digit or digits. (Each digit is made up of 4 bits.)

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	MOVD(083)
	Executed Once for Upward Differentiation	@MOVD(083)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

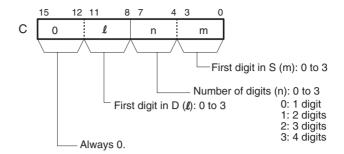
#### **Operands**

#### S: Source Word

The source digits are read from right to left, wrapping back to the rightmost digit (digit 0) if necessary.

#### C: Control Word

The first three digits of C indicate the first source digit (m), the number of digits to transfer (n), and the first destination digit ( $\ell$ ), as shown in the following diagram.



#### **D: Destination Word**

The destination digits are written from right to left, wrapping back to the right-most digit (digit 0) if necessary.

	15	12	11	8	7	4	3	0
D	Digit	3	Digit 2	2	Digit	1	Dig	jit O

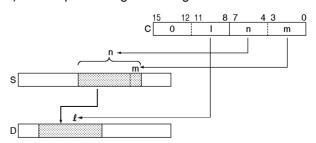
## **Operand Specifications**

Area	S	С	D	
CIO Area	CIO 0000 to CIO 6143			
Work Area	W000 to W255			
Auxiliary Bit Area	A000 to A959		A448 to A959	
Timer Area	T0000 to T0255		•	
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767	7		
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants	#0000 to #FFFF (binary)	Specified values only		
Data Resisters	DR0 to DR15		<u>.</u>	
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -(-	–)IR15		

## **Description**

MOVD(083) copies the content of n digits from S (beginning at digit m) to D (beginning at digit  $\ell$ ). Only the specified digits are changed; the rest are left unchanged.

If the number of digits being read or written exceeds the leftmost digit of S or D, MOVD(083) will wrap to the rightmost digit of the same word.



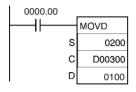
#### **Flags**

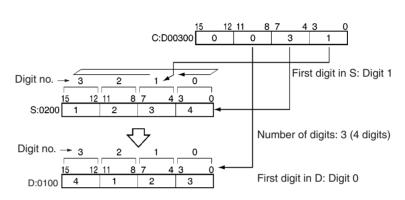
Name	Label	Operation
Error Flag	ER	ON if one of the first three digits of C is not within the specified range of 0 to 3.  OFF in all other cases.

#### **Examples**

#### **Four-digit Transfer**

When CIO 0000.00 is ON in the following example, four digits of data are copied from CIO 0200 to CIO 0100. The transfer begins with the digit 1 of CIO 0200 and digit 0 or CIO 0100, in accordance with the control word's value of 0031.

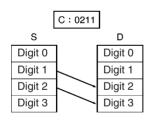


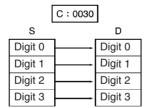


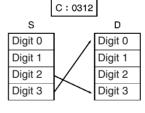
**Note** After reading the leftmost digit of S (digit 3), MOVD(083) wraps to the rightmost digit (digit 0).

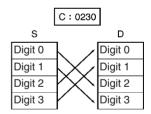
#### **Examples of C**

The following diagram shows examples of data transfers for various values of C.







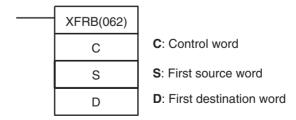


## 3-7-7 MULTIPLE BIT TRANSFER: XFRB(062)

**Purpose** 

Transfers the specified number of consecutive bits.

**Ladder Symbol** 



#### **Variations**

Variations	Executed Each Cycle for ON Condition	XFRB(062)
	Executed Once for Upward Differentiation	@XFRB(062)
	<b>Executed Once for Downward Differentiation</b>	Not supported

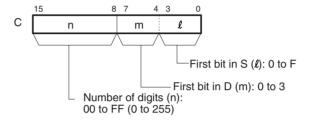
## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

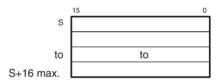
#### C: Control Word

The first three digits of C indicate the first source digit (m), the number of digits to transfer (n), and the first destination digit ( $\ell$ ), as shown in the following diagram.



#### S: First Source Word

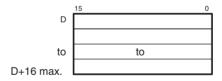
Specifies the first source word. Bits are read from right to left, continuing with consecutive words (up to S+16) when necessary.



Note The source words must be in the same data area.

#### **D: First Destination Word**

Specifies the first destination word. Bits are written from right to left, continuing with consecutive words (up to D+16) when necessary.



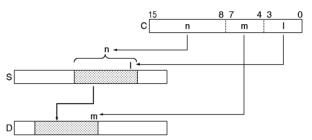
Note The destination words must be in the same data area.

Area	С	S	D
CIO Area	CIO 0000 to CIO 6	143	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	

Area	С	S	D	
Indirect DM addresses in BCD	*D00000 to *D3276	37		
Constants	Specified values only			
Data Registers	DR0 to DR15			
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047, IR0 to -2048 to +2047, IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to 5+(++)			
,-() IR0 to , -() IR15				

XFRB(062) transfers up to 255 consecutive bits from the source words (beginning with bit  $\ell$  of S) to the destination words (beginning with bit m of D). Bits in the destination words that are not overwritten by the source bits are left unchanged.

The beginning bits and number of bits are specified in C, as shown in the following diagram.



It is possible for the source words and destination words to overlap. By transferring data overlapping several words, the data can be packed more efficiently in the data area. (This is particularly useful when handling position data for position control.)

Since the source words and destination words can overlap, XFRB(062) can be combined with ANDW(034) to shift m bits by n spaces.

#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF

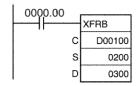
#### **Precautions**

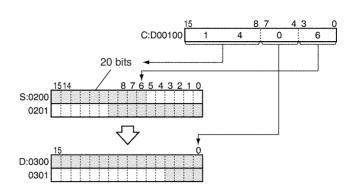
Up to 255 bits of data can be transferred per execution of XFRB(062).

Be sure that the source words and destination words do not exceed the end of the data area.

#### **Examples**

When CIO 0000.00 is ON in the following example, the 20 bits beginning with CIO 020006 are copied to the 20 bits beginning with CIO 030000.



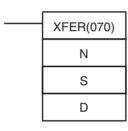


## 3-7-8 BLOCK TRANSFER: XFER(070)

**Purpose** 

Transfers the specified number of consecutive words.

**Ladder Symbol** 



- N: Number of words
- S: First source word
- D: First destination word

**Variations** 

Variations	<b>Executed Each Cycle for ON Condition</b>	XFER(070)
	<b>Executed Once for Upward Differentiation</b>	@XFER(070)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

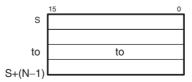
#### **Operands**

#### **N: Number of Words**

Specifies the number of words to be transferred. The possible range for N is 0000 to FFFF (0 to 65,535 decimal).

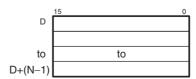
#### S: First Source Word

Specifies the first source word.



#### **D: First Destination Word**

Specifies the first destination word.

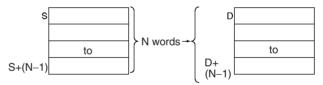


## **Operand Specifications**

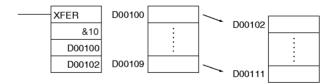
Area	N	S	D
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF (binary) or &0 to &65535		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

#### **Description**

XFER(070) copies N words beginning with S (S to S+(N-1)) to the N words beginning with D (D to D+(N-1)).



It is possible for the source words and destination words to overlap, so XFER(070) can perform word-shift operations.



## **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	

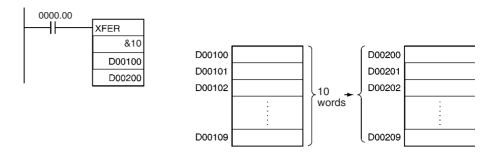
### **Precautions**

Be sure that the source words (S to S+N-1) and destination words (D to D+N-1) do not exceed the end of the data area.

Some time will be required to complete XFER(070) when a large number of words is being transferred. In this case, the XFER(070) transfer might not be completed if a power interruption occurs during execution of the instruction.

#### Example

When CIO 0000.00 is ON in the following example, the 10 words D00100 through D00109 are copied to D00200 through D00209.

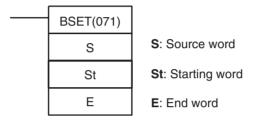


## 3-7-9 BLOCK SET: BSET(071)

## **Purpose**

Copies the same word to a range of consecutive words.

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	BSET(071)
	<b>Executed Once for Upward Differentiation</b>	@BSET(071)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

#### S: Source Word

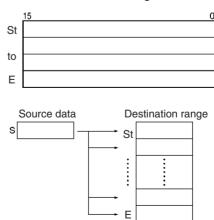
Specifies the source data or the word containing the source data.

## St: Starting Word

Specifies the first word in the destination range.

## E: End Word

Specifies the last word in the destination range.



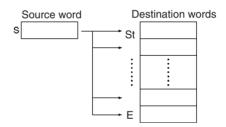
Note St and E must be in the same data area.

## **Operand Specifications**

Area	S	St	Е
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959	A448 to A959	
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF (binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

#### **Description**

BSET(071) copies the same source word (S) to all of the destination words in the range St to E.



## Flags

Name	Label	Operation	
Error Flag	ER	ON if St is greater than E.	
		OFF in all other cases.	

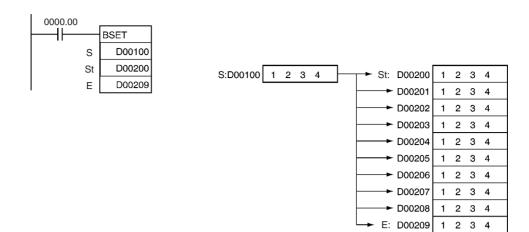
#### **Precautions**

Be sure that the starting word (St) and end word (E) are in the same data area and that  $St \le E$ .

Some time will be required to complete BSET(071) when the source data is being transferred to a large number of words. In this case, the BSET(071) transfer might not be completed if a power interruption occurs during execution of the instruction.

## **Example**

When CIO 0000.00 is ON in the following example, the source data in D00100 is copied to D00200 through D00209.

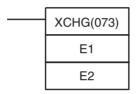


# 3-7-10 DATA EXCHANGE: XCHG(073)

**Purpose** 

Exchanges the contents of the two specified words.

**Ladder Symbol** 



E1: First exchange word

E2: Second exchange word

**Variations** 

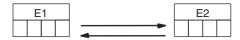
Variations	Executed Each Cycle for ON Condition	XCHG(073)
	Executed Once for Upward Differentiation	@XCHG(073)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	E1	E2
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A448 to A959	
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048	3 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to I	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

XCHG(073) exchanges the contents of E1 and E2.

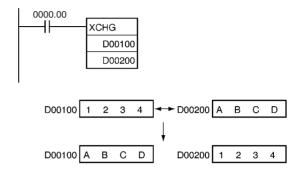


**Flags** 

There are no flags affected by this instruction.

**Example** 

When CIO 0000.00 is ON in the following example, the content of D00100 is exchanged with the content of D00200.

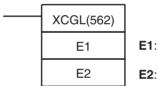


# 3-7-11 DOUBLE DATA EXCHANGE: XCGL(562)

#### **Purpose**

Exchanges the contents of a pair of consecutive words with another pair of consecutive words.

#### **Ladder Symbol**



E1: First exchange word

E2: Second exchange word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	XCGL(562)
	Executed Once for Upward Differentiation	@XCGL(562)
	<b>Executed Once for Downward Differentiation</b>	Not supported

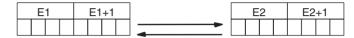
## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

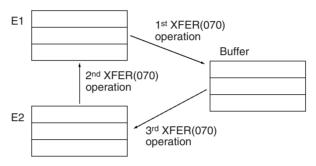
Area	E1	E2
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A448 to A958	
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Registers		

Area	E1	E2
Index Registers	IR0 to IR15	
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047, IR0 to -2048	3 to +2047, IR15
	DR0 to DR15, IR0 to DR0 to	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-() IR0 to , -() IR15	

XCHG(073) exchanges the contents of E1+1 and E1 with the contents of E2+1 and E2.



To exchange 3 or more words, use XFER(070) to transfer the words to a third set of words (a buffer) as shown in the following diagram.

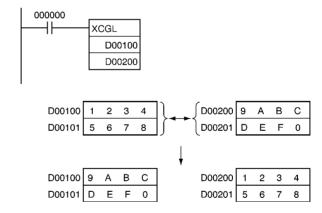


#### **Flags**

There are no flags affected by this instruction.

#### Example

When CIO 000000 is ON in the following example, the contents of D00100 and D00101 are exchanged with the contents of D00200 and D00201.

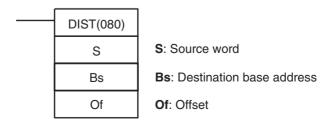


## 3-7-12 SINGLE WORD DISTRIBUTE: DIST(080)

## **Purpose**

Transfers the source word to a destination word calculated by adding an offset value to the base address.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	DIST(080)
	Executed Once for Upward Differentiation	@DIST(080)
	Executed Once for Downward Differentiation	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

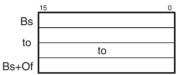
## **Operands**

#### **Bs: Destination Base Address**

Specifies the destination base address. The offset is added to this address to calculate the destination word.

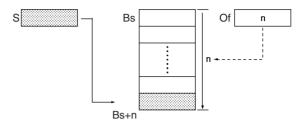
#### Of: Offset

This value is added to the base address to calculate the destination word. The offset can be any value from 0000 to FFFF (0 to 65,535 decimal), but Bs and Bs+Of must be in the same data area.



Area	S	Bs	Of
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959	A448 to A959	A000 to A959
Timer Area	T0000 to T0255		·
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767	,	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF (binary)		#0000 to #FFFF (binary) or &0 to &65535
Data Resisters	DR0 to DR15		DR0 to DR15
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+	+(++)	
,–(– –)IR0 to , –(– –)IR15			

DIST(080) copies S to the destination word calculated by adding Of to Bs. The same DIST(080) instruction can be used to distribute the source word to various words in the data area by changing the value of Of.



#### **Flags**

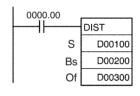
Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON if the source data is 0000.	
		OFF in all other cases.	
Negative Flag	N	ON if the leftmost bit of the source data is 1.	
		OFF in all other cases.	

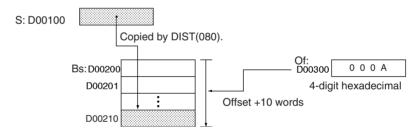
#### **Precautions**

Be sure that the offset does not exceed the end of the data area, i.e., Bs and Bs+Of are in the same data area.

#### **Example**

When CIO 0000.00 is ON in the following example, the contents of D00100 will be copied to D00210 (D00200 + 10) if the contents of D00300 is 10 (000A hexadecimal). The contents of D00100 can be copied to other words by changing the offset in D00300.



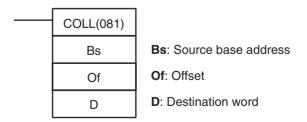


## 3-7-13 DATA COLLECT: COLL(081)

#### **Purpose**

Transfers the source word (calculated by adding an offset value to the base address) to the destination word.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	COLL(081)
	Executed Once for Upward Differentiation @COLL(0)	
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

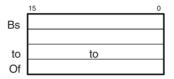
#### **Operands**

#### **Bs: Source Base Address**

Specifies the source base address. The offset is added to this address to calculate the source word.

#### Of: Offset

This value is added to the base address to calculate the source word. The offset can be any value from 0000 to FFFF (0 to 65,535 decimal), but Bs and Bs+Of must be in the same data area.

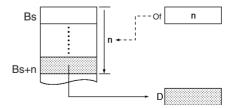


## **Operand Specifications**

Area	Bs	Of	D
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants		#0000 to #FFFF (binary) or &0 to &65535	
Data Resisters		DR0 to DR15	
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		15
	,IR0+(++) to ,IR15+(++)		
,-()IR0 to , -()IR15			

## **Description**

COLL(081) copies the source word (calculated by adding Of to Bs) to the destination word. The same COLL(081) instruction can be used to collect data from various source words in the data area by changing the value of Of.



#### **Flags**

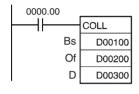
Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the source data is 0000.
		OFF in all other cases.
Negative Flag	N	ON if the leftmost bit of the source data is 1.
		OFF in all other cases.

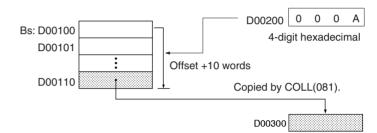
**Precautions** 

Be sure that the offset does not exceed the end of the data area, i.e., Bs and Bs+Of are in the same data area.

Example

When CIO 0000.00 is ON in the following example, the contents of D00110 (D00100  $\pm$  10) will be copied to D00300 if the content of D00200 is 10 (000A hexadecimal). The contents of other words can be copied to D00300 by changing the offset in D00200.



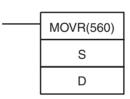


## 3-7-14 MOVE TO REGISTER: MOVR(560)

**Purpose** 

Sets the PLC memory address of the specified word, bit, or timer/counter Completion Flag in the specified Index Register. (Use MOVRW(561) to set the PLC memory address of a timer/counter PV in an Index Register.)

**Ladder Symbol** 



- S: Source (desired word or bit)
- D: Destination (Index Register)

**Variations** 

Variations	Executed Each Cycle for ON Condition	MOVR(560)
	Executed Once for Upward Differentiation	@MOVR(560)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

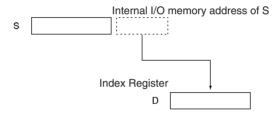
#### **D:** Destination

The destination must be an Index Register (IR0 to IR15).

Area	S	D
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A448 to A959	

Area	S	D
Timer Area	T0000 to T0255 (Completion Flag)	
Counter Area	C0000 to C0255 (Completion Flag)	
DM Area	D00000 to D32767	
Indirect DM addresses in binary		
Indirect DM addresses in BCD		
Constants		
Data Registers		
Index Registers		IR0 to IR15
Indirect addressing using Index Registers		

MOVR(560) finds the PLC memory address (absolute address) of S and writes that address in D (an Index Register).



If a timer or counter is specified in S, MOVR(560) will write the PLC memory address of the timer/counter Completion Flag in D. Use MOVRW(561) to write the PLC memory address of the timer/counter PV in D.

#### **Flags**

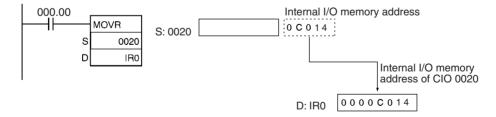
There are no flags affected by this instruction.

#### **Precautions**

MOVR(560) cannot set the PLC memory addresses of timer/counter PVs. Use MOVRW(561) to set the PLC memory addresses of timer/counter PVs. If MOVR(560) is executed for a timer/counter, the PLC memory address of the Completion Flag will be set in the index register.

#### Example

When CIO 0000.00 is ON in the following example, MOVR(560) writes the PLC memory address of CIO 0020 to IR0.

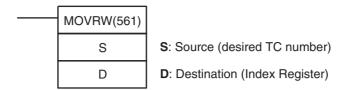


## 3-7-15 MOVE TIMER/COUNTER PV TO REGISTER: MOVRW(561)

#### **Purpose**

Sets the PLC memory address of the specified timer or counter's PV in the specified Index Register. (Use MOVR(560) to set the PLC memory address of a word, bit, or timer/counter Completion Flag in an Index Register.)

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	MOVR(561)
	Executed Once for Upward Differentiation	@MOVR(561)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

#### **D:** Destination

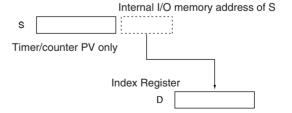
The destination must be an Index Register (IR0 to IR15).

## **Operand Specifications**

Area	S	D
CIO Area		
Work Area		
Holding Bit Area		
Auxiliary Bit Area		
Timer Area	T0000 to T0255 (present value)	
Counter Area	C0000 to C0255 (present value)	
DM Area		
Indirect DM addresses in binary		
Indirect DM addresses in BCD		
Constants		
Data Registers		
Index Registers		IR0 to IR15
Indirect addressing using Index Registers		

#### **Description**

MOVRW(561) finds the PLC memory address for the PV of the timer or counter specified in S and writes that address in D (an Index Register).



MOVRW(561) will set the PLC memory address of the timer or counter's PV in D. Use MOVR(560) to set the PLC memory address of the timer or counter Completion Flag.

**Flags** 

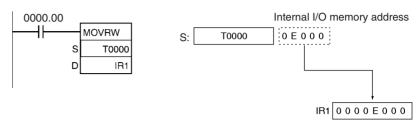
There are no flags affected by this instruction.

**Precautions** 

MOVRW(561) cannot set the PLC memory addresses of data area words, bits, or timer/counter Completion Flags. Use MOVR(560) to set these PLC memory addresses.

**Example** 

When CIO 0000.00 is ON in the following example, MOVRW(561) writes the PLC memory address for the PV of timer T0000 to IR1.



## 3-8 Data Shift Instructions

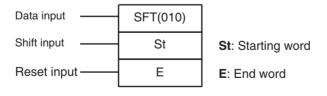
This section describes instructions used to shift data within or between words, but in differing amounts and directions.

Instruction	Mnemonic	Function code	Page
SHIFT REGISTER	SFT	010	225
REVERSIBLE SHIFT REGISTER	SFTR	084	227
ASYNCHRONOUS SHIFT REGISTER	ASFT	017	230
WORD SHIFT	WSFT	016	232
ARITHMETIC SHIFT LEFT	ASL	025	233
DOUBLE SHIFT LEFT	ASLL	570	235
ARITHMETIC SHIFT RIGHT	ASR	026	236
DOUBLE SHIFT RIGHT	ASRL	571	238
ROTATE LEFT	ROL	027	239
DOUBLE ROTATE LEFT	ROLL	572	241
ROTATE LEFT WITHOUT CARRY	RLNC	574	245
DOUBLE ROTATE LEFT WITH- OUT CARRY	RLNL	576	247
ROTATE RIGHT	ROR	028	242
DOUBLE ROTATE RIGHT	RORL	573	244
ROTATE RIGHT WITHOUT CARRY	RRNC	575	248
DOUBLE ROTATE RIGHT WITHOUT CARRY	RRNL	577	250
ONE DIGIT SHIFT LEFT	SLD	074	251
ONE DIGIT SHIFT RIGHT	SRD	075	253
SHIFT N-BITS LEFT	NASL	580	254
DOUBLE SHIFT N-BITS LEFT	NSLL	582	256
SHIFT N-BITS RIGHT	NASR	581	259
DOUBLE SHIFT N-BITS RIGHT	NSRL	583	261

# 3-8-1 SHIFT REGISTER: SFT(010)

**Purpose** Operates a shift register.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	SFT(010)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

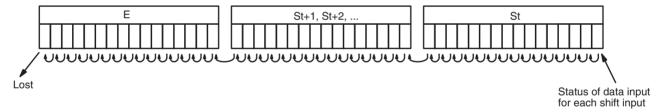
Note St and E must be in the same data area.

#### **Operand Specifications**

Area	St	E
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A448 to A959	
Timer Area		
Counter Area		
DM Area		
Indirect DM addresses in binary		
Indirect DM addresses in BCD		
Constants		
Data Resisters		
Index Registers		
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -204	8 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to	DR15, IR15

## **Description**

When the execution condition on the shift input changes from OFF to ON, all the data from St to E is shifted to the left by one bit (from the rightmost bit to the leftmost bit), and the ON/OFF status of the data input is placed in the rightmost bit.



#### **Flags**

Name	Label	Operation
Error Flag		ON if the indirect IR address for St and E is not in the CIO, AR, or WR data areas.
		OFF in all other cases.

#### **Precautions**

The bit data shifted out of the shift register is discarded.

When the reset input turns ON, all bits in the shift register from the rightmost designated word (St) to the leftmost designated word (E) will be reset (i.e., set to 0). The reset input takes priority over other inputs.

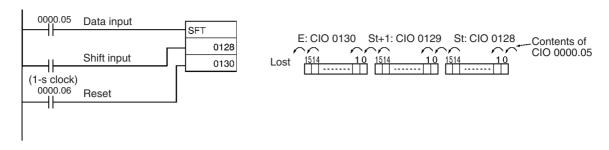
St must be less than or equal to E, but even when St is set to greater than E an error will not occur and one word of data in St will be shifted.

When St and E are designated indirectly using index registers and the actual addresses in I/O memory are not within memory areas for data, an error will occur and the Error Flag will turn ON.

#### **Examples**

#### **Shift Register Exceeding 16 Bits**

The following example shows a 48-bit shift register using words CIO 0128 to CIO 0130. A 1-s clock pulse is used so that the contents of CIO 0000.05 is input and shifted into a 3-word register between CIO 0128.00 and CIO 0130.15 every second.

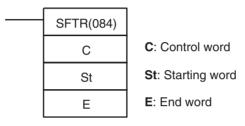


## 3-8-2 REVERSIBLE SHIFT REGISTER: SFTR(084)

## **Purpose**

Creates a shift register that shifts data to either the right or the left.

**Ladder Symbol** 



#### **Variations**

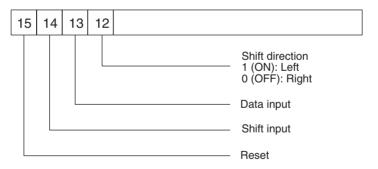
Variations	Executed Each Cycle for ON Condition	SFTR(084)
	Executed Once for Upward Differentiation	@SFTR(084)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks	ì
OK	OK	OK	OK	ı

## **Operands**

#### C: Control Word

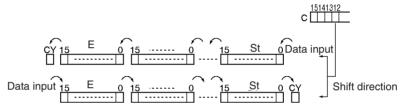


Note St and E must be in the same data area.

Area	С	St	E
CIO Area	CIO 0000 to CIO 6	143	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959 A448 to A959		
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	

Area	С	St	E
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		15
,IR0+(++) to ,IR15+(++)			
,-()IR0 to $,-()IR15$			

When the execution condition of the shift input bit (bit 14 of C) changes to ON, all the data from St to E is moved in the designated shift direction (designated by bit 12 of C) by 1 bit, and the ON/OFF status of the data input is placed in the rightmost or leftmost bit. The bit data shifted out of the shift register is placed in the Carry Flag (CY).



#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON when St is greater than E.	
		OFF in all other cases.	
Carry Flag	CY	ON when 1 is shifted into it.	
		OFF when 0 is shifted into it.	
		OFF when reset is set to 1.	

#### **Precautions**

The above shift operations are applicable when the reset bit (bit 15 of C) is set to OFF.

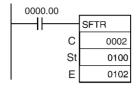
When reset (bit 15 of C) turns ON, all bits in the shift register, from St to E will be reset (i.e., set to 0).

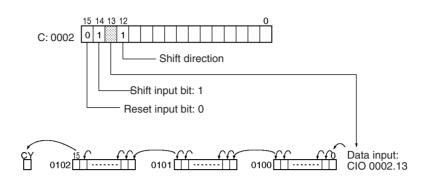
When St is greater than E, an error will be generated and the Error Flag will turn ON.

#### **Examples**

#### **Shifting Data**

If shift input CIO 0002.14 goes ON when CIO 0000.00 is ON, and the reset bit CIO 0002.15 is OFF, words CIO 0100 through CIO 0102 will shift one bit in the direction designated by CIO 0002.12 (e.g., 1: Left) and the contents of input bit CIO 0002.13 will be input into the rightmost bit, CIO 0100.00. The contents of CIO 0102.15 will be shifted to the Carry Flag (CY).





#### **Resetting Data**

If CIO 0002.14 is ON when CIO 0000.00 is ON, and the reset bit, CIO 0002.15, is ON, words CIO 0100 through CIO 0102 and the Carry Flag will be reset to OFF.

#### **Controlling Data**

#### **Resetting Data**

All bits from St to E and the Carry Flag are set to 0 and no other data can be received when the reset input bit (bit 15 of C) is ON.



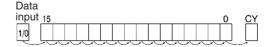
#### Shifting Data Left (from Rightmost to Leftmost Bit)

When the shift input bit (bit 14 of C) is ON, the contents of the input bit (bit 13 of C) is input to bit 00 of the starting word, and each bit thereafter is shifted one bit to the left. The status of bit 15 of the end word is shifted to the Carry Flag.



#### Shifting Data Right (from Leftmost to Rightmost Bit

When the shift input bit (bit 14 of C) is ON, the contents of the input bit (bit 13 of C) is input to bit 15 on the end word, and each bit thereafter is shifted one bit to the right. The status of bit 00 of the starting word is shifted to the Carry Flag.

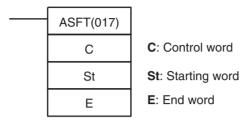


# 3-8-3 ASYNCHRONOUS SHIFT REGISTER: ASFT(017)

#### **Purpose**

Shifts all non-zero word data within the specified word range either towards St or toward E, replacing 0000 hex word data.

#### **Ladder Symbol**



## **Variations**

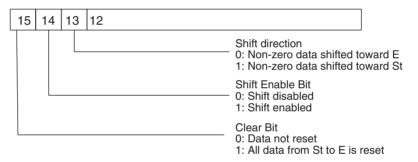
Variations	Executed Each Cycle for ON Condition	ASFT(017)
	Executed Once for Upward Differentiation	@ASFT(017)
	Executed Once for Downward Differentiation	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

## **C: Control Word**

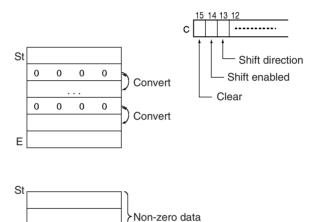


Note St and E must be in the same data area.

Area	С	St	E
CIO Area	CIO 0000 to CIO 6	143	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959	A448 to A959	
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Resisters	DR0 to DR15		

Area	С	St	E
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
,-()IR0 to , -()IR15			

When the Shift Enable Bit (bit 14 of C) is ON, all of the words with non-zero content within the range of words between St and E will be shifted one word in the direction determined by the Shift Direction Bit (bit 13 of C) whenever the word in the shift direction contains all zeros. If ASFT(017) is repeated sufficient times, all all-zero words will be replaced by non-zero words. This will result in all the data between St and E being divided into zero and non-zero data.



Flags

Name	Label	Operation
Error Flag	ER	ON when St is greater than E.
		OFF in all other cases.

Zero data

0

0 0 0

Ε

#### **Precautions**

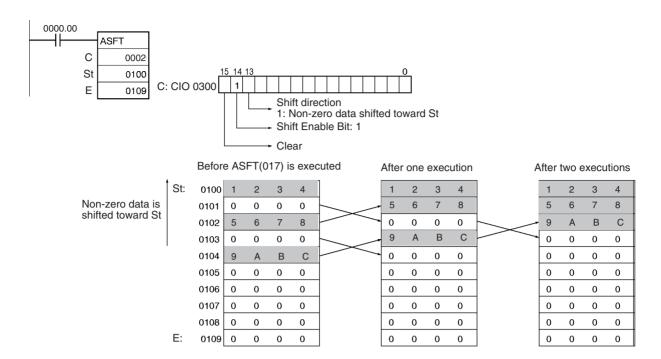
When the Clear Bit (bit 15 of C) goes ON, all bits in the shift register, from St to E, will be reset (i.e., set to 0). The Clear Bit has priority over the Shift Enable Bit (bit 14 of C).

When St is greater than E, an error will be generated and the Error Flag will turn ON.

#### **Examples**

#### **Shifting Data:**

If the Shift Enable Bit, CIO 0002.14, goes ON when CIO 0000.00 is ON, all words with non-zero data content from CIO 0100 through CIO 0109 will be shifted in the direction designated by the Shift Direction Bit, CIO 0002.13 (e.g., 1: shifted toward St) if the word to the left of the non-zero data is all zeros.

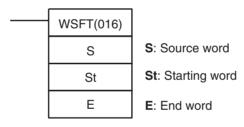


## 3-8-4 WORD SHIFT: WSFT(016)

#### **Purpose**

Shifts data between St and E in word units.

## **Ladder Symbol**



### **Variations**

Variations	Executed Each Cycle for ON Condition	WSFT(016)
	<b>Executed Once for Upward Differentiation</b>	@WSFT(016)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

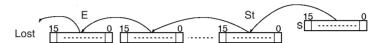
Note St and E must be in the same data area.

Area	S	St	E
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959	A448 to A959	
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		

Area	S	St	E
Indirect DM addresses in BCD	*D00000 to *D3276	37	
Constants	#0000 to #FFFF (binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15			

#### **Description**

WSFT(016) shifts data from St to E in word units and the data from the source word S is placed into St. The contents of E is lost.



#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON when St is greater than E.	
		OFF in all other cases.	

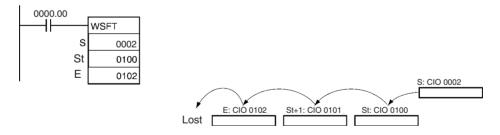
#### **Precautions**

When St is greater than E, an error will be generated and the Error Flag will turn ON.

Note When large amounts of data are shifted, the instruction execution time is quite long. Be sure that the power is not cut while WSFT(016) is being executed, causing the shift operation to stop halfway through.

#### **Examples**

When CIO 0000.00 is ON, data from CIO 0100 through CIO 0102 will be shifted one word toward E. The contents of CIO 0002 will be stored in CIO 0100 and the contents of CIO 0102 will be lost.



#### **ARITHMETIC SHIFT LEFT: ASL(025)** 3-8-5

#### **Purpose**

Shifts the contents of Wd one bit to the left.

**Ladder Symbol** 



### **Variations**

Variations	Executed Each Cycle for ON Condition	ASL(025)
	<b>Executed Once for Upward Differentiation</b>	@ASL(025)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

# **Description**

ASL(025) shifts the contents of Wd one bit to the left (from rightmost bit to leftmost bit). "0" is placed in the rightmost bit and the data from the leftmost bit is shifted into the Carry Flag (CY).



# **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the shift result is 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.	
		OFF in all other cases.	

### **Precautions**

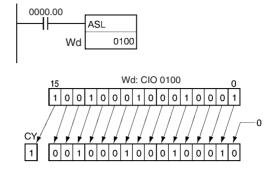
When ASL(025) is executed, the Error Flag will turn OFF.

If the contents of Wd is 0000 as the result of the shift, the Equals Flag will turn  $\,$  ON.

If the contents of the leftmost bit in Wd is 1 as the result of the shift, the Negative Flag will turn ON.

# **Examples**

When CIO 0000.00 is ON, CIO 0100 will be shifted one bit to the left. "0" will be placed in CIO 0100.00 and the contents of CIO 0100.15 will be shifted to the Carry Flag (CY).



# 3-8-6 DOUBLE SHIFT LEFT: ASLL(570)

**Purpose** 

Shifts the contents of Wd and Wd +1 one bit to the left.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	ASLL(570)
	Executed Once for Upward Differentiation	@ASLL(570)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

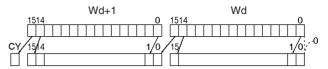
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

### **Description**

ASLL(570) shifts the contents of Wd and Wd +1 one bit to the left (from rightmost bit to leftmost bit). "0" is placed in the rightmost bit of Wd and the contents of the leftmost bit in Wd +1 is shifted into the Carry Flag (CY).



#### **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the shift result is 0000 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.	
		OFF in all other cases.	

#### **Precautions**

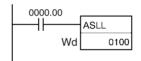
When ASLL(570) is executed, the Error Flag will turn OFF.

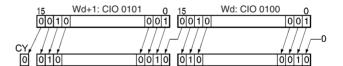
If the contents of Wd and Wd +1 is 0000 0000 as the result of the shift, the Equals Flag will turn ON.

If the contents of the leftmost bit in Wd +1 is 1 as the result of the shift, the Negative Flag will turn ON.

# **Examples**

When CIO 0000.00 is ON, word CIO 0100 and CIO 0101 will shift one bit to the left. "0" is placed into CIO 0100.00 and the contents of CIO 0100.15 will be shifted to the Carry Flag (CY).



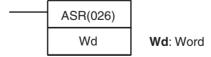


# 3-8-7 ARITHMETIC SHIFT RIGHT: ASR(026)

#### **Purpose**

Shifts the contents of Wd one bit to the right.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ASR(026)
	Executed Once for Upward Differentiation	@ASR(026)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

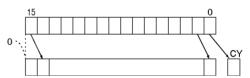
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

# **Description**

ASR(026) shifts the contents of Wd one bit to the right (from leftmost bit to rightmost bit). "0" will be placed in the leftmost bit and the contents of the rightmost bit will be shifted into the Carry Flag (CY).



# Flags

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	OFF

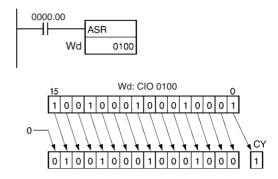
# **Precautions**

When ASR(026) is executed, the Error Flag and the Negative Flag will turn OFF.

If the contents of Wd is 0000 as the result of the shift, the Equals Flag will turn  $\mathsf{ON}.$ 

#### **Examples**

When CIO 0000.00 is ON, word CIO 0100 will shift one bit to the right. "0" will be placed in CIO 0100.15 and the contents of CIO 0100.00 will be shifted to the Carry Flag (CY).

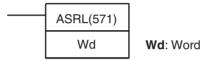


# 3-8-8 DOUBLE SHIFT RIGHT: ASRL(571)

**Purpose** 

Shifts the contents of Wd and Wd +1 one bit to the right.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	ASRL(571)
	Executed Once for Upward Differentiation	@ASRL(571)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

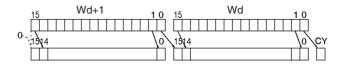
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,–(– –)IR0 to , –(– –)IR15

# **Description**

ASRL(571) shifts the contents of Wd and Wd +1 one bit to the right (from leftmost bit to rightmost bit). "0" will be placed in the leftmost bit of Wd +1 and the contents of the rightmost bit of Wd will be shifted into the Carry Flag (CY).



#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	OFF

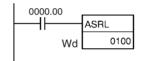
**Precautions** 

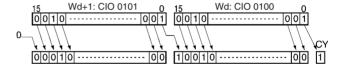
When ASRL (571) is executed, the Error Flag and the Negative Flag will turn OFF.

If the contents of Wd and Wd +1 is 0000 0000 as the result of the shift, the Equals Flag will turn ON.

**Examples** 

When CIO 0000.00 is ON, word CIO 0100 and CIO 0101 will shift one bit to the right. "0" will be placed into CIO 0101.15 and the contents of CIO 0100.00 will be shifted to the Carry Flag (CY).



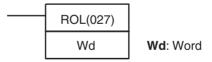


# 3-8-9 ROTATE LEFT: ROL(027)

**Purpose** 

Shifts all Wd bits one bit to the left including the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	ROL(027)
	Executed Once for Upward Differentiation	@ROL(027)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255

Area	Wd
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing using Index Registers	,IR0 to ,IR15  -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15  DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15

#### **Description**

ROL(027) shifts all bits of Wd including the Carry Flag (CY) to the left (from rightmost bit to leftmost bit).



#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

#### **Precautions**

When ROL(027) is executed, the Error Flag will turn OFF.

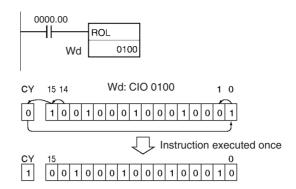
If the contents of Wd is 0000 as the result of the shift, the Equals Flag will turn ON.

If the contents of the leftmost bit in Wd is 1 as the result of the shift, the Negative Flag will turn ON.

**Examples** 

**Note** It is possible to set the Carry Flag contents to 1 or 0 immediately before executing this instruction, by using the Set Carry (STC(040)) or Clear Carry (CLC(041)) instructions.

When CIO 0000.00 is ON, word CIO 0100 and the Carry Flag (CY) will shift one bit to the left. The contents of CIO 0100.15 will be shifted to the Carry Flag (CY) and the Carry Flag contents will be shifted to CIO 0100.00.

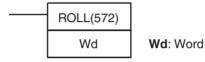


# 3-8-10 DOUBLE ROTATE LEFT: ROLL(572)

**Purpose** 

Shifts all Wd and Wd +1 bits one bit to the left including the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	ROLL(572)
	<b>Executed Once for Upward Differentiation</b>	@ROLL(572)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

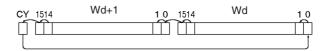
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

**Description** 

ROLL(572) shifts all bits of Wd and Wd +1 including the Carry Flag (CY) to the left (from rightmost bit to leftmost bit).



#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

#### **Precautions**

When ROLL(572) is executed, the Error Flag will turn OFF.

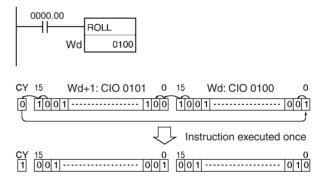
If the contents of Wd and Wd +1 is 0000 0000 as the result of the shift, the Equals Flag will turn ON.

If the contents of the leftmost bit in Wd + 1 is 1 as the result of the shift, the Negative Flag will turn ON.

Note It is possible to set the Carry Flag contents to 1 or 0 immediately before executing this instruction, by using the Set Carry (STC(040)) or Clear Carry (CLC(041)) instructions.

### **Examples**

When CIO 0000.00 is ON, word CIO 0100, CIO 0101 and the Carry Flag (CY) will shift one bit to the left. The contents of CIO 0101.15 will be shifted to the Carry Flag (CY) and the Carry Flag contents will be shifted to CIO 0100.00.

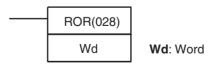


#### **ROTATE RIGHT: ROR(028)** 3-8-11

**Purpose** 

Shifts all Wd bits one bit to the right including the Carry Flag (CY).

**Ladder Symbol** 



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ROR(028)
	<b>Executed Once for Upward Differentiation</b>	@ROR(028)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

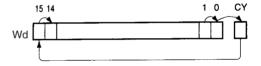
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing using Index Registers	,IR0 to ,IR15  -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15  DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15

# **Description**

ROR(028) shifts all bits of Wd including the Carry Flag (CY) to the right (from leftmost bit to rightmost bit).



# **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

#### **Precautions**

When ROR(028) is executed, the Error Flag will turn OFF.

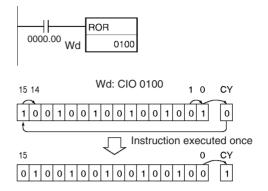
If the contents of Wd is 0000 as the result of the shift, the Equals Flag will turn  $\mathsf{ON}.$ 

If the contents of the leftmost bit in Wd is 1 as the result of the shift, the Negative Flag will turn ON.

**Note** It is possible to set the Carry Flag contents to 1 or 0 immediately before executing this instruction, by using the Set Carry (STC(040)) or Clear Carry (CLC(041)) instructions.

# **Examples**

When CIO 0000.00 is ON, word CIO 0100 and the Carry Flag (CY) will shift one bit to the right. The contents of CIO 0100.00 will be shifted to the Carry Flag (CY) and the Carry Flag contents will be shifted to CIO 0100.15.



# 3-8-12 DOUBLE ROTATE RIGHT: RORL(573)

**Purpose** 

Shifts all Wd and Wd +1 bits one bit to the right including the Carry Flag (CY).

**Ladder Symbol** 



Variations

Variations	Executed Each Cycle for ON Condition	RORL(573)
	Executed Once for Upward Differentiation	@RORL(573)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

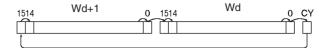
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

### **Description**

RORL(573) shifts all bits of Wd and Wd +1 including the Carry Flag (CY) to the right (from leftmost bit to rightmost bit).



#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

#### **Precautions**

When RORL(573) is executed, the Error Flag will turn OFF.

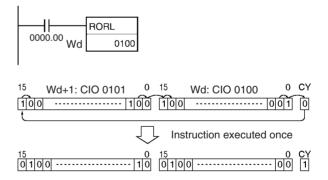
If the contents of Wd and Wd +1 is 0000 0000 as the result of the shift, the Equals Flag will turn ON.

If the contents of the leftmost bit in Wd + 1 is 1 as the result of the shift, the Negative Flag will turn ON.

Note It is possible to set the Carry Flag contents to 1 or 0 immediately before executing this instruction, by using the Set Carry (STC(040)) or Clear Carry (CLC(041)) instructions.

#### **Examples**

When CIO 0000.00 is ON, word CIO 0100, CIO 0101 and the Carry Flag (CY) will shift one bit to the right. The contents of CIO 0100.00 will be shifted to the Carry Flag (CY) and the Carry Flag contents will be shifted to CIO 0101.15.

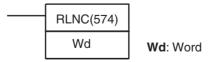


# 3-8-13 ROTATE LEFT WITHOUT CARRY: RLNC(574)

**Purpose** 

Shifts all Wd bits one bit to the left not including the Carry Flag (CY).

**Ladder Symbol** 



#### **Variations**

Variations	Executed Each Cycle for ON Condition	RLNC(574)
	Executed Once for Upward Differentiation	@RLNC(574)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

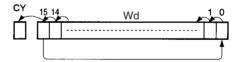
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

# **Description**

RLNC(574) shifts all bits of Wd to the left (from rightmost bit to leftmost bit). The contents of the leftmost bit of Wd shifts to the rightmost bit and to the Carry Flag (CY).



#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

#### **Precautions**

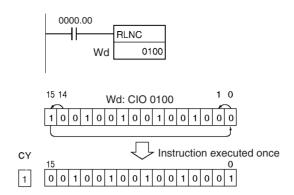
When RLNC(574) is executed, the Error Flag will turn OFF.

If the contents of Wd is 0000 as the result of the shift, the Equals Flag will turn  $\mathsf{ON}.$ 

If the contents of the leftmost bit in Wd is 1 as the result of the shift, the Negative Flag will turn ON.

#### **Examples**

When CIO 0000.00 is ON, word CIO 0100 will shift one bit to the left (excluding the Carry Flag (CY)). The contents of CIO 0100.15 will be shifted to CIO 0100.00.

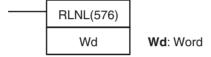


# 3-8-14 DOUBLE ROTATE LEFT WITHOUT CARRY: RLNL(576)

**Purpose** 

Shifts all Wd and Wd +1 bits one bit to the left not including the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	RLNL(576)
	Executed Once for Upward Differentiation	@RLNL(576)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

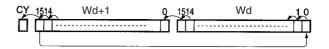
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

# **Description**

RLNL(576) shifts all bits of Wd and Wd +1 to the left (from rightmost bit to leftmost bit). The contents of the leftmost bit of Wd +1 is shifted to the rightmost bit of Wd, and to the Carry Flag (CY).



#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

**Precautions** 

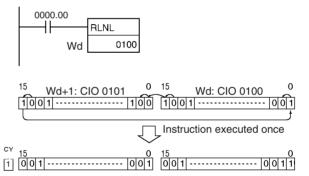
When RLNL(576) is executed, the Error Flag will turn OFF.

If the contents of Wd and Wd +1 is 0000 0000 as the result of the shift, the Equals Flag will turn ON.

If the contents of the leftmost bit in Wd + 1 is 1 as the result of the shift, the Negative Flag will turn ON.

**Examples** 

When CIO 0000.00 is ON, word CIO 0100 and CIO 0101 will shift one bit to the left (excluding the Carry Flag (CY)). The contents of CIO 0101.15 will be shifted to CIO 0100.00.

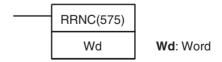


# 3-8-15 ROTATE RIGHT WITHOUT CARRY: RRNC(575)

**Purpose** 

Shifts all Wd bits one bit to the right not including the Carry Flag (CY). The contents of the rightmost bit of Wd shifts to the leftmost bit and to the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	RRNC(575)
	Executed Once for Upward Differentiation	@RRNC(575)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

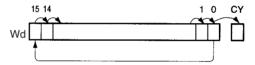
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,–(– –)IR0 to , –(– –)IR15

# **Description**

RRNC(575) shifts all bits of Wd to the right (from leftmost bit to rightmost bit) not including the Carry Flag (CY).



# Flags

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

#### **Precautions**

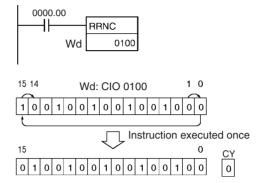
When RRNC(575) is executed, the Error Flag will turn OFF.

If the contents of Wd is 0000 as the result of the shift, the Equals Flag will turn  ${\sf ON}.$ 

If the contents of the leftmost bit in Wd is 1 as the result of the shift, the Negative Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON, word CIO 0100 will shift one bit to the right (excluding the Carry Flag (CY)). The contents of CIO 0100.00 will be shifted to CIO 0100.15.

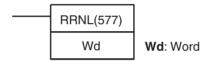


# 3-8-16 DOUBLE ROTATE RIGHT WITHOUT CARRY: RRNL(577)

#### **Purpose**

Shifts all Wd and Wd +1 bits one bit to the right not including the Carry Flag (CY). The contents of the rightmost bit of Wd is shifted to the leftmost bit of Wd +1, and to the Carry Flag (CY).

# **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	RRNL(577)
	Executed Once for Upward Differentiation	@RRNL(577)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
ОК	OK	OK	OK

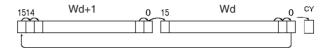
#### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	

Area	Wd
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

#### Description

RRNL(577) shifts all bits of Wd and Wd +1 to the right (from leftmost bit to rightmost bit) not including the Carry Flag (CY).



### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the shift result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as the result of the shift.
		OFF in all other cases.

#### **Precautions**

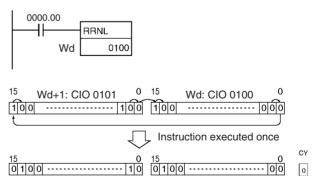
When RRNL(577) is executed, the Error Flag will turn OFF.

If the contents of Wd and Wd +1 is 0000 0000 as the result of the shift, the Equals Flag will turn ON.

If the contents of the leftmost bit in Wd + 1 is 1 as the result of the shift, the Negative Flag will turn ON.

#### **Examples**

When CIO 0000.00 is ON, words CIO 0100 and CIO 0101 will shift one bit to the right, (excluding the Carry Flag (CY)). The contents of CIO 0100.00 will be shifted to CIO 0101.15.



# 3-8-17 ONE DIGIT SHIFT LEFT: SLD(074)

**Purpose** 

Shifts data by one digit (4 bits) to the left.

**Ladder Symbol** 



#### **Variations**

Variations	Executed Each Cycle for ON Condition	SLD(074)
	Executed Once for Upward Differentiation	@SLD(074)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Note St and E must be in the same data area.

### **Operand Specifications**

Area	St	Е
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A448 to A959	
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -204	8 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

### **Description**

SLD(074) shifts data between St and E by one digit (4 bits) to the left. "0" is placed in the rightmost digit (bits 3 to 0 of St), and the content of the leftmost digit (bits 15 to 12 of E) is lost.



### **Flags**

Name	Label	Operation
Error Flag	ER	ON when St is greater than E.
		OFF in all other cases.

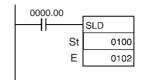
#### **Precautions**

When St is greater than E, an error will be generated and the Error Flag will turn ON.

Note When large amounts of data are shifted, the instruction execution time is quite long. Be sure that the power is not cut while SLD(074) is being executed, causing the shift operation to stop halfway through.

#### **Examples**

When CIO 0000.00 is ON, words CIO 0100 through CIO 0102 will shift by one digit (4 bits) to the left. A zero will be placed in bits 0 to 3 of word CIO 0100 and the contents of bits 12 to 15 of CIO 0102 will be lost.



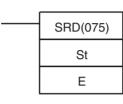


# 3-8-18 ONE DIGIT SHIFT RIGHT: SRD(075)

**Purpose** 

Shifts data by one digit (4 bits) to the right.

**Ladder Symbol** 



St: Starting word

E: End word

**Variations** 

Variations	Executed Each Cycle for ON Condition	SRD(075)
	Executed Once for Upward Differentiation @SRD(075)	
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

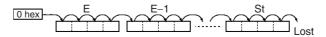
Note St and E must be in the same data area.

# **Operand Specifications**

Area	St	E
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A448 to A959	
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Resisters		
Index Registers		
Indirect addressing	,IR0 or ,IR1	
using Index Registers	–2048 to +2047 ,IR0 or –2048	to +2047 ,IR1
	,IR0+(++) or ,IR1+(++)	
	, -()IR0 or, -()IR1	

### **Description**

SRD(075) shifts data between St and E by one digit (4 bits) to the right. "0" is placed in the leftmost digit (bits 15 to 12 of E), and the content of the rightmost digit (bits 3 to 0 of St) is lost.



# **Flags**

Name	Label	Operation	
Error Flag	ER	ON when St is greater than E.	
		OFF in all other cases.	

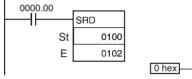
#### **Precautions**

When St is greater than E, an error will be generated and the Error Flag will turn ON.

Note When large amounts of data are shifted, the instruction execution time is quite long. Always take care that the power is not cut while SRD(075) is being executed, causing the shift operation to stop halfway through.

### **Examples**

When CIO 0000.00 is ON, words CIO 0100 through CIO 0102 will shift by one digit (4 bits) to the right. A zero will be placed in bits 12 to 15 of CIO 0102 and the contents of bits 0 to 3 of word CIO 0100 will be lost.



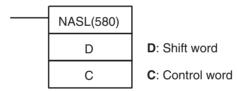


# 3-8-19 SHIFT N-BITS LEFT: NASL(580)

#### **Purpose**

Shifts the specified 16 bits of word data to the left by the specified number of bits.

# **Ladder Symbol**



#### **Variations**

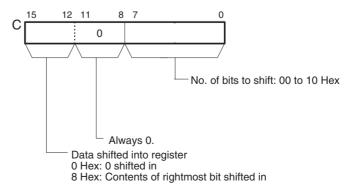
Variations	Executed Each Cycle for ON Condition	NASL(580)
	<b>Executed Once for Upward Differentiation</b>	@NASL(580)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

#### C: Control Word

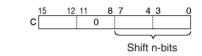


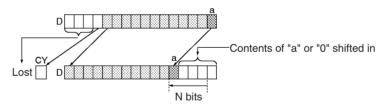
# **Operand Specifications**

Area	D	С	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A448 to A959	A000 to A959	
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	Specified values only		
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
,–(− –)IR0 to , –(− –)IR15			

# **Description**

NASL(580) shifts D (the shift word) by the specified number of binary bits (specified in C) to the left (from the rightmost bit to the leftmost bit). Either zeros or the value of the rightmost bit will be placed into the specified number of bits of the shift word starting from the rightmost bit.





#### **Flags**

Name	Label	Operation
Error Flag	ER	ON when the control word C (the number of bits to shift) is not within range.
		OFF in all other cases.
Equals Flag	=	ON when the shift result is 0.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as a result of the shift.
		OFF in all other cases.

# **Precautions**

For any bits which are shifted outside the specified word, the contents of the last bit is shifted to the Carry Flag (CY), and all other data is lost.

When the number of bits to shift (specified in C) is "0," the data will not be shifted. The appropriate flags will turn ON and OFF, however, according to data in the specified word.

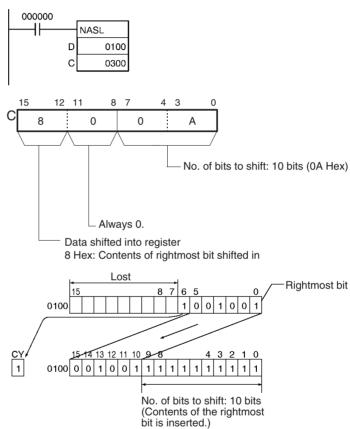
When the contents of the control word C is out of range, an error will be generated and the Error Flag will turn ON.

If as a result of the shift the contents of D is 0000 hex, the Equals Flag will turn ON.

If as a result of the shift the contents of the leftmost bit of D is 1, the Negative Flag will turn ON.

**Examples** 

When CIO 000000 is ON, The contents of CIO 0100 is shifted 10 bits to the left (from the rightmost bit to the leftmost bit). The number of bits to shift is specified in bits 0 to 7 of word CIO 0300 (control data). The contents of bit 0 of CIO 0100 is copied into bits from which data was shifted and the contents of the rightmost bit which was shifted out of range is shifted into the Carry Flag (CY). All other data is lost.

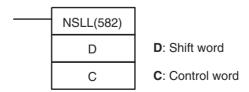


# 3-8-20 DOUBLE SHIFT N-BITS LEFT: NSLL(582)

**Purpose** 

Shifts the specified 32 bits of word data to the left by the specified number of bits.

**Ladder Symbol** 



#### **Variations**

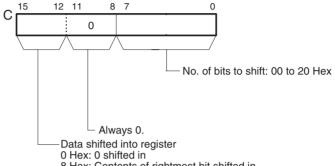
Variations	Executed Each Cycle for ON Condition	NSLL(582)
	<b>Executed Once for Upward Differentiation</b>	@ NSLL(582)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

# **C: Control Word**



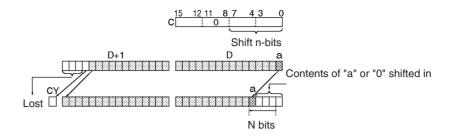
8 Hex: Contents of rightmost bit shifted in

# **Operand Specifications**

Area	D	С	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254	W000 to W255	
Auxiliary Bit Area	A448 to A958	A000 to A959	
Timer Area	T0000 to T0254	T0000 to T0255	
Counter Area	C0000 to C0254	C0000 to C0255	
DM Area	D00000 to D32766	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	Specified values only		
Data Registers		DR0 to DR15	
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

NSLL(582) shifts D and D+1 (the shift words) by the specified number of binary bits (specified in C) to the left (from the rightmost bit to the leftmost bit). Either zeros or the value of the rightmost bit will be placed into the specified number of bits of the shift word starting from the rightmost bit.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON when the control word C (the number of bits to shift) is not within range.
		OFF in all other cases.
Equals Flag	=	ON when the shift result is 0.
		OFF in all other cases.
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit is 1 as a result of the shift.
		OFF in all other cases.

#### **Precautions**

For any bits which are shifted outside the specified word, the contents of the last bit is shifted to the Carry Flag (CY), and all other data is lost.

When the number of bits to shift (specified in C) is "0," the data will not be shifted. The appropriate flags will turn ON and OFF, however, according to data in the specified word.

When the contents of the control word C are out of range, an error will be generated and the Error Flag will turn ON.

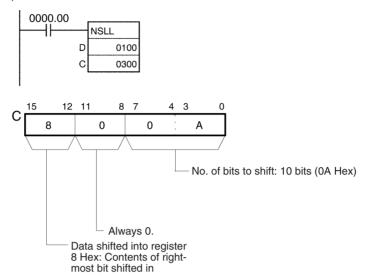
If as a result of the shift the contents of D is 0000, the Equals Flag will turn ON.

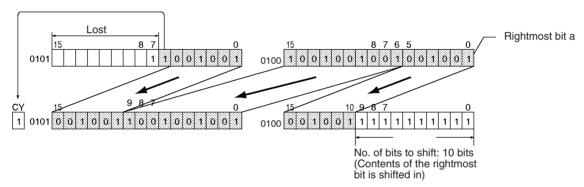
If as a result of the shift the contents of the leftmost bit of D, D +1 is 1, the Negative Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON, CIO 0100 and CIO 0101 will be shifted to the left (from the rightmost bit to the leftmost bit) by 10 bits. The number of bits to shift is specified in bits 0 to 7 of word CIO 0300 (control data). The contents of bit 0 of CIO 0100 is copied into bits from which data was shifted and the contents

of the rightmost bit which was shifted out of range is shifted into the Carry Flag (CY). All other data is lost.



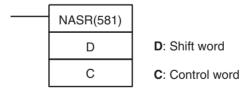


# 3-8-21 SHIFT N-BITS RIGHT: NASR(581)

**Purpose** 

Shifts the specified 16 bits of word data to the right by the specified number of bits.

**Ladder Symbol** 



**Variations** 

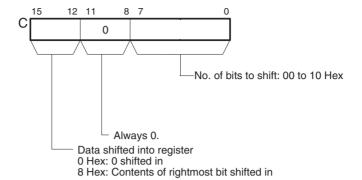
Variations	<b>Executed Each Cycle for ON Condition</b>	NASR(581)
	<b>Executed Once for Upward Differentiation</b>	@NASR(581)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

# C: Control Word

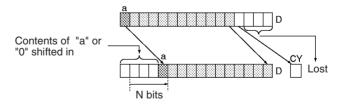


# **Operand Specifications**

Area	D	С	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A448 to A959	A000 to A959	
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants		Specified values only	
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15	9 to 19047 ID15	
	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
,-()IR0 to , -()IR15			

# **Description**

NASR(581) shifts D (the shift word) by the specified number of binary bits (specified in C) to the right (from the rightmost bit to the leftmost bit). Either zeros or the value of the rightmost bit will be placed into the specified number of bits of the shift word starting from the rightmost bit.



# **Flags**

Name	Label	Operation
Error Flag	ER	ON when the control word C (the number of bits to shift) is not within range.
		OFF in all other cases.
Equals Flag	=	ON when the shift result is 0.
		OFF in all other cases.

Name	Label	Operation	
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit is 1 as a result of the shift.	
		OFF in all other cases.	

#### **Precautions**

For any bits which are shifted outside the specified word, the contents of the last bit is shifted to the Carry Flag (CY), and all other data is discarded.

When the number of bits to shift (specified in C) is "0," the data will not be shifted. The appropriate flags will turn ON and OFF, however, according to data in the specified word.

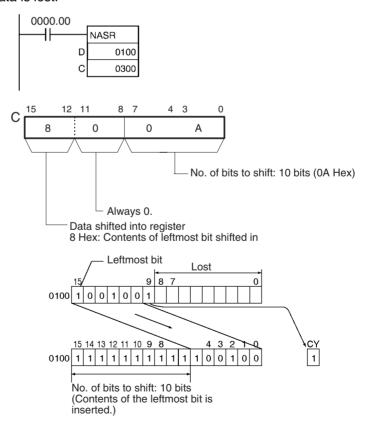
When the contents of the control word C are out of range, an error will be generated and the Error Flag will turn ON.

If as a result of the shift the contents of D is 0000 hex, the Equals Flag will turn ON.

If as a result of the shift the contents of the leftmost bit of D is 1, the Negative Flag will turn ON.

# **Examples**

When CIO 0000.00 is ON, CIO 0100 will be shifted 10 bits to the right (from the leftmost bit to the rightmost bit). The number of bits to shift is specified in bits 0 to 7 of word CIO 0300. The contents of bit 15 of CIO 0100 is copied into the bits from which data was shifted and the contents of the leftmost bit of data which was shifted out of range, is shifted into the Carry Flag (CY). All other data is lost.

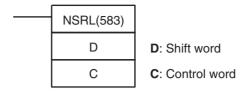


# 3-8-22 DOUBLE SHIFT N-BITS RIGHT: NSRL(583)

### **Purpose**

Shifts the specified 32 bits of word data to the right by the specified number of bits.

# **Ladder Symbol**



#### **Variations**

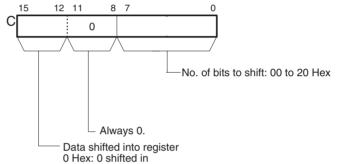
Variations	s Executed Each Cycle for ON Condition	
	Executed Once for Upward Differentiation	@NSRL(583)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

#### C: Control Word



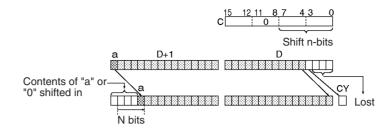
8 Hex: Contents of rightmost bit shifted in

# **Operand Specifications**

Area	D	С	
CIO Area	CIO 0000 to CIO 6142	CIO 0000 to CIO 6143	
Work Area	W000 to W254	W000 to W255	
Auxiliary Bit Area	A448 to A958	A000 to A959	
Timer Area	T0000 to T0254	T0000 to T0255	
Counter Area	C0000 to C0254	C0000 to C0255	
DM Area	D00000 to D32766	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants		Specified values only	
Data Registers		DR0 to DR15	
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15,IR0 to IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

NSRL(583) shifts D and D+1 (the shift words) by the specified number of binary bits (specified in C) to the right (from the leftmost bit to the rightmost bit). Either zeros or the value of the rightmost bit will be placed into the specified number of bits of the shift word starting from the rightmost bit.



#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON when the control word C (the number of bits to shift) is not within range.	
		OFF in all other cases.	
Equals Flag	=	ON when the shift result is 0.	
		OFF in all other cases.	
Carry Flag	CY	ON when 1 is shifted into the Carry Flag (CY).	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit is 1 as a result of the shift.	
		OFF in all other cases.	

#### **Precautions**

For any bits which are shifted outside the specified word, the contents of the last bit is shifted to the Carry Flag (CY), and all other data is lost.

When the number of bits to shift (specified in C) is "0," the data will not be shifted. The appropriate flags will turn ON or OFF, however, according to data in the specified word.

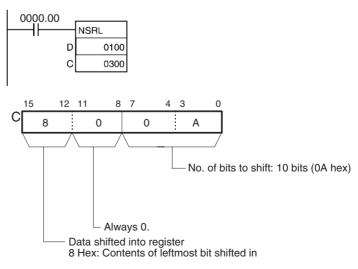
When the contents of the control word C are out of range, an error will be generated and the Error Flag will turn ON.

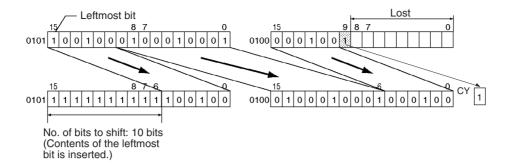
If as a result of the shift the contents of D +1 is 00000000 hex, the Equals Flag will turn ON.

If as a result of the shift the contents of the leftmost bit of D + 1 is 1, the Negative Flag will turn ON.

**Examples** 

When CIO 0000.00 is ON, CIO 0100 and CIO 0101 will be shifted 10 bits to the right (from the leftmost bit to the rightmost bit). The number of bits to shift is specified in bits 0 to 7 of word CIO 0300 (control data). The contents of bit 15 of CIO will be copied into the bits from which data was shifted and the contents of the leftmost bit of data which was shifted out of range will be shifted into the Carry Flag (CY). All other data is lost.





# 3-9 Increment/Decrement Instructions

This section describes instructions used to increment and decrement binary or BCD values.

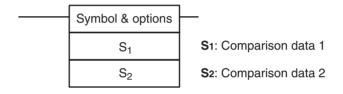
Instruction	Mnemonic	Function code	Page
INCREMENT BINARY	++	590	265
DOUBLE INCREMENT BINARY	++L	591	267
DECREMENT BINARY		592	269
DOUBLE DECREMENT BINARY	L	593	271
INCREMENT BCD	++B	594	273
DOUBLE INCREMENT BCD	++BL	595	275
DECREMENT BCD	B	596	277
DOUBLE DECREMENT BCD	BL	597	279

# 3-9-1 INCREMENT BINARY: ++(590)

**Purpose** 

Increments the 4-digit hexadecimal content of the specified word by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	++(590)
	Executed Once for Upward Differentiation	@++(590)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Wd	
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A448 to A959	
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

### **Description**

The ++(590) instruction adds 1 to the binary content of Wd. The specified word will be incremented by 1 every cycle as long as the execution condition of ++(590) is ON. When the up-differentiated variation of this instruction (@++(590)) is used, the specified word is incremented only when the execution condition has gone from OFF to ON.



The Equals Flag will be turned ON if the result is 0000, and the Negative Flag will be turned ON when bit 15 of Wd is ON in the result.

Both the Equals Flag and the Carry Flag will be turned ON when the content of Wd changes from FFFF to 0000.

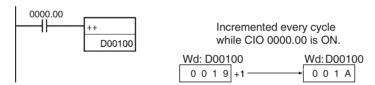
#### **Flags**

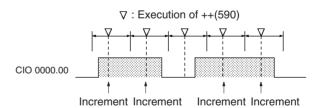
Name	Label	Operation
Error Flag	ER	OFF
Equals	=	ON if the content of Wd is 0000 after execution.
Flag		OFF in all other cases.
Carry Flag	CY	ON if the content of Wd changes from FFFF to 0000 during execution.
		OFF in all other cases.
Negative	N	ON if bit 15 of Wd is ON after execution.
Flag		OFF in all other cases.

#### **Examples**

### Operation of ++(590)

In the following example, the content of D00100 will be incremented by 1 every cycle as long as CIO 0000.00 is ON.

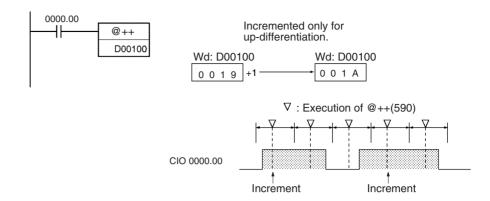




#### Operation of @++(590)

The up-differentiated variation is used in the following example, so the content of D00100 will be incremented by 1 only when CIO 0000.00 has gone from OFF to ON.

# 266

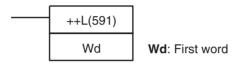


# 3-9-2 DOUBLE INCREMENT BINARY: ++L(591)

**Purpose** 

Increments the 8-digit hexadecimal content of the specified words by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	++L(591)
	Executed Once for Upward Differentiation	@++L(591)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Wd	
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A448 to A958	
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Resisters		
Index Registers	IR0 or IR15	
Indirect addressing using Index Registers	,IR0 to ,IR15	
	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

#### **Description**

The ++L(591) instruction adds 1 to the 8-digit hexadecimal content of Wd+1 and Wd. The content of the specified words will be incremented by 1 every cycle as long as the execution condition of ++L(591) is ON. When the up-dif-

ferentiated variation of this instruction (@++L(591)) is used, the content of the specified words is incremented only when the execution condition has gone from OFF to ON.



The Equals Flag will be turned ON if the result is 0000 0000, and the Negative Flag will be turned ON if bit 15 of Wd+1 is ON in the result.

Both the Equals Flag and the Carry Flag will be turned ON when the content of Wd and Wd+1 changes from FFFF FFFF to 0000 0000.

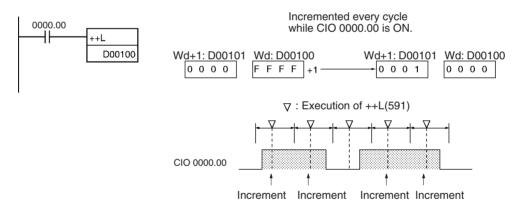
#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the result is 0000 0000 after execution.
		OFF in all other cases.
Carry Flag	CY	ON if the content of Wd and Wd+1 changes from FFFF FFFF to 0000 0000 during execution.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of Wd+1 is ON after execution.
		OFF in all other cases.

#### **Examples**

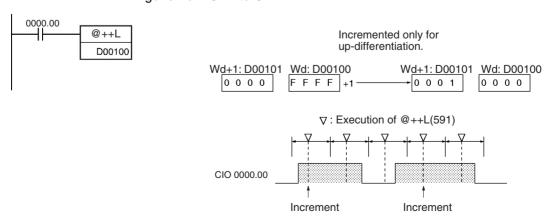
# Operation of ++L(591)

In the following example, the 8-digit hexadecimal content of D00101 and D00100 will be incremented by 1 every cycle as long as CIO 0000.00 is ON.



#### Operation of @++L(591)

The up-differentiated variation is used in the following example, so the content of D00101 and D00100 will be incremented by 1 only when CIO 0000.00 has gone from OFF to ON.

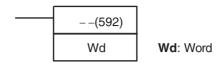


# 3-9-3 DECREMENT BINARY: -- (592)

**Purpose** 

Decrements the 4-digit hexadecimal content of the specified word by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	(592)
	Executed Once for Upward Differentiation	@(592)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

### **Description**

The --(592) instruction subtracts 1 from the binary content of Wd. The specified word will be decremented by 1 every cycle as long as the execution condition of --(592) is ON. When the up-differentiated variation of this instruction (@--(592)) is used, the specified word is decremented only when the execution condition has gone from OFF to ON.



The Equals Flag will be turned ON if the result is 0000, and the Negative Flag will be turned ON if bit 15 of Wd is ON in the result.

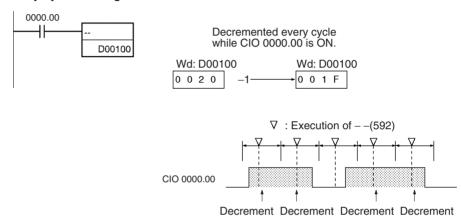
Both the Carry Flag and the Negative Flag will be turned ON when the content of Wd changes from 0000 to FFFF.

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the content of Wd is 0000 after execution.
		OFF in all other cases.
Carry Flag	CY	ON if the content of Wd changes from 0000 to FFFF during execution.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of Wd is ON after execution.
		OFF in all other cases.

## **Examples**

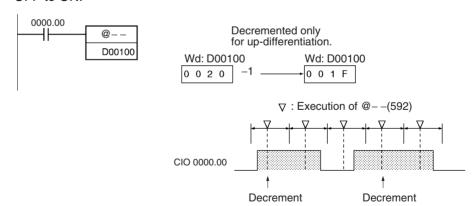
# Operation of -- (592)

In the following example, the content of D00100 will be decremented by 1 every cycle as long as CIO 0000.00 is ON.



## Operation of @--(592)

The up-differentiated variation is used in the following example, so the content of D00100 will be decremented by 1 only when CIO 0000.00 has gone from OFF to ON.

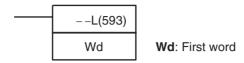


# 3-9-4 DOUBLE DECREMENT BINARY: --L(593)

**Purpose** 

Decrements the 8-digit hexadecimal content of the specified words by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	L(593)
	Executed Once for Upward Differentiation	@L(593)
	Executed Once for Downward Differentiation	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	IR0 or IR15
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

## **Description**

The --L(593) instruction subtracts 1 from the 8-digit hexadecimal content of Wd+1 and Wd. The content of the specified words will be decremented by 1 every cycle as long as the execution condition of --L(593) is ON. When the up-differentiated variation of this instruction (@--L(593)) is used, the content of the specified words is decremented only when the execution condition has gone from OFF to ON.



The Equals Flag will be turned ON if the result is 0000 0000, and the Negative Flag will be turned ON if bit 15 of Wd+1 is ON in the result.

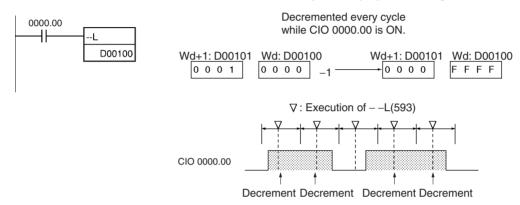
Both the Carry Flag and the Negative Flag will be turned ON when the content changes from 0000 0000 to FFFF FFFF.

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the result is 0000 0000 after execution.
		OFF in all other cases.
Carry Flag	CY	ON if the content of Wd and Wd+1 changes from 0000 0000 to FFFF FFFF during execution.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of Wd+1 is ON after execution.
		OFF in all other cases.

## **Examples**

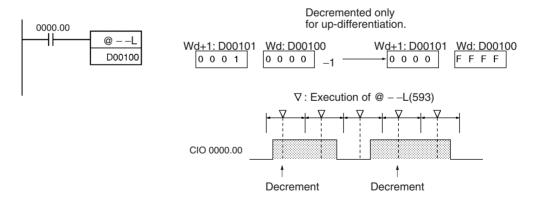
## Operation of -- L(593)

In the following example, the 8-digit hexadecimal content of D00101 and D00100 will be decremented by 1 every cycle as long as CIO 0000.00 is ON.



#### Operation of @--L(593)

The up-differentiated variation is used in the following example, so the content of D00101 and D00100 will be decremented by 1 only when CIO 0000.00 has gone from OFF to ON.



# 3-9-5 INCREMENT BCD: ++B(594)

**Purpose** 

Increments the 4-digit BCD content of the specified word by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	++B(594)
	<b>Executed Once for Upward Differentiation</b>	@++B(594)
	Executed Once for Downward Differentiation	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in BCD	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

## **Description**

The ++B(594) instruction adds 1 to the BCD content of Wd. The specified word will be incremented by 1 every cycle as long as the execution condition of ++B(594) is ON. When the up-differentiated variation of this instruction (@++B(594)) is used, the specified word is incremented only when the execution condition has gone from OFF to ON.



The Equals Flag will be turned ON if the result is 0000.

Both the Equals Flag and the Carry Flag will be turned ON when the content of Wd changes from 9999 to 0000.

Name	Label	Operation
Error Flag	ER	ON if the content of Wd is not BCD.
		OFF in all other cases.
Equals Flag	=	ON if the content of Wd is 0000 after execution.
		OFF in all other cases.
Carry Flag	CY	ON if the content of Wd changes from 9999 to 0000 during execution.  OFF in all other cases.

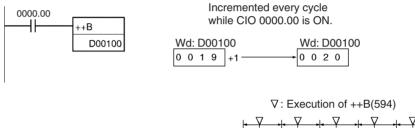
#### **Precautions**

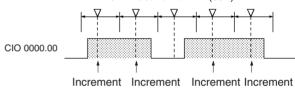
The content of Wd must be BCD. If it is not BCD, an error will occur and the Error Flag will be turned ON.

#### **Examples**

## Operation of ++B(594)

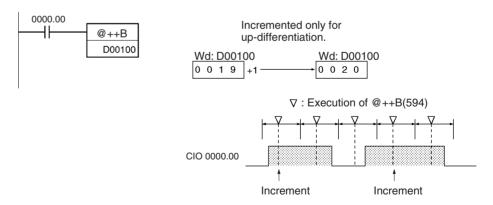
In the following example, the BCD content of D00100 will be incremented by 1 every cycle as long as CIO 0000.00 is ON.





### Operation of @++B(594)

The up-differentiated variation is used in the following example, so the content of D00100 will be incremented by 1 only when CIO 0000.00 has gone from OFF to ON.

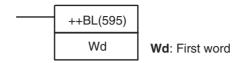


# 3-9-6 DOUBLE INCREMENT BCD: ++BL(595)

**Purpose** 

Increments the 8-digit BCD content of the specified words by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	++BL(595)
	<b>Executed Once for Upward Differentiation</b>	@++BL(595)
	Executed Once for Downward Differentiation	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in BCD	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

## **Description**

The ++BL(595) instruction adds 1 to the 8-digit BCD content of Wd+1 and Wd. The content of the specified words will be incremented by 1 every cycle as long as the execution condition of ++BL(595) is ON. When the up-differentiated variation of this instruction (@++BL(595)) is used, the content of the specified words is incremented only when the execution condition has gone from OFF to ON.



The Equals Flag will be turned ON if the result is 0000 0000.

Both the Equals Flag and the Carry Flag will be turned ON when the content of Wd and Wd+1 changes from 9999 9999 to 0000 0000.

Name	Label	Operation
Error Flag	ER	ON if the content of Wd+1 and Wd is not BCD.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000 0000 after execution.
		OFF in all other cases.
Carry Flag	CY	ON if the content of Wd and Wd+1 changes from 9999 9999 to 0000 0000 during execution.
		OFF in all other cases.

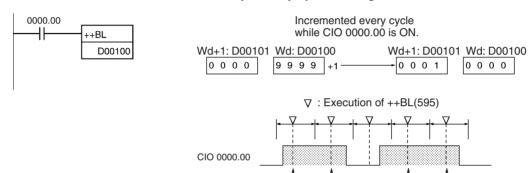
#### **Precautions**

The content of Wd+1 and Wd must be BCD. If it is not BCD, an error will occur and the Error Flag will be turned ON.

#### **Examples**

#### Operation of ++BL(595)

In the following example, the 8-digit BCD content of D00101 and D00100 will be incremented by 1 every cycle as long as CIO 0000.00 is ON.

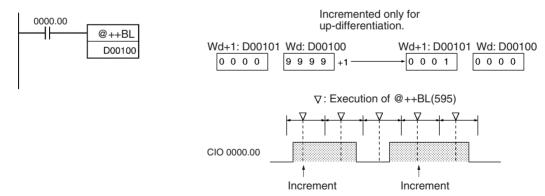


#### Operation of @++BL(595)

The up-differentiated variation is used in the following example, so the BCD content of D00101 and D00100 will be incremented by 1 only when CIO 0000.00 has gone from OFF to ON.

Increment Increment

Increment Increment



# 3-9-7 DECREMENT BCD: --B(596)

**Purpose** 

Decrements the 4-digit BCD content of the specified word by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	B(596)
	Executed Once for Upward Differentiation	@B(596)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

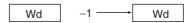
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in BCD	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

### **Description**

The --B(596) instruction subtracts 1 from the BCD content of Wd. The specified word will be decremented by 1 every cycle as long as the execution condition of --B(596) is ON. When the up-differentiated variation of this instruction (@--B(596)) is used, the specified word is decremented only when the execution condition has gone from OFF to ON.



The Equals Flag will be turned ON if the result is 0000 and the Carry Flag will be turned ON when the content of Wd changes from 0000 to 9999.

Name	Label	Operation	
Error Flag	ER	ON if the content of Wd is not BCD.	
		OFF in all other cases.	
Equals Flag	=	ON if the content of Wd is 0000 after execution.	
		OFF in all other cases.	
Carry Flag	CY	ON if the content of Wd changes from 0000 to 9999 during execution.	
		OFF in all other cases.	

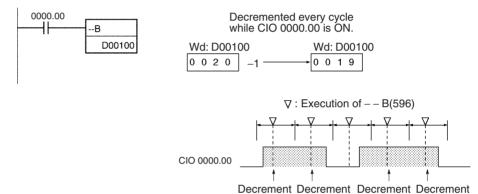
**Precautions** 

The content of Wd must be BCD. If it is not BCD, an error will occur and the Error Flag will be turned ON.

### **Examples**

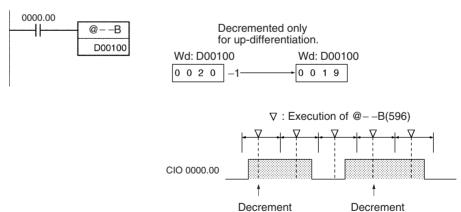
#### Operation of -B(596)

In the following example, the BCD content of D00100 will be decremented by 1 every cycle as long as CIO 0000.00 is ON.



## Operation of @--B(596)

The up-differentiated variation is used in the following example, so the BCD content of D00100 will be decremented by 1 only when CIO 0000.00 has gone from OFF to ON.

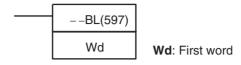


# 3-9-8 DOUBLE DECREMENT BCD: --BL(597)

**Purpose** 

Decrements the 8-digit BCD content of the specified words by 1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	BL(597)
	Executed Once for Upward Differentiation	@BL(597)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in BCD	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

### **Description**

The - -BL(597) instruction subtracts 1 from the 8-digit BCD content of Wd+1 and Wd. The content of the specified words will be decremented by 1 every cycle as long as the execution condition of - -BL(597) is ON. When the updifferentiated variation of this instruction (@- -BL(597)) is used, the content of the specified words is decremented only when the execution condition has gone from OFF to ON.

Wd+1	Wd	<b>-1</b> <del></del>	Wd+1	Wd

The Equals Flag will be turned ON if the result is 0000 0000 and the Carry Flag will be turned ON when the content of Wd and Wd+1 changes from 0000 0000 to 9999 9999.

Name	Label	Operation
Error Flag	ER	ON if the content of Wd+1 and Wd is not BCD.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000 0000 after execution.
		OFF in all other cases.
Carry Flag	CY	ON if the content of Wd and Wd+1 changes from 0000 0000 to 9999 9999 during execution.
		OFF in all other cases.

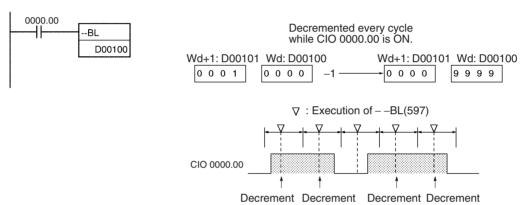
#### **Precautions**

The content of Wd+1 and Wd must be BCD. If it is not BCD, an error will occur and the Error Flag will be turned ON.

#### **Examples**

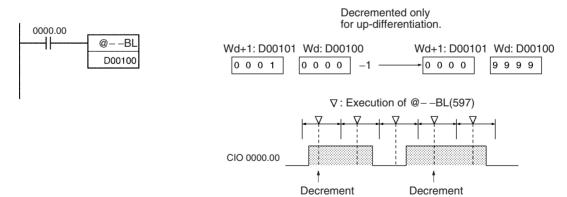
### Operation of -- BL(597)

In the following example, the 8-digit BCD content of D00101 and D00100 will be decremented by 1 every cycle as long as CIO 0000.00 is ON.



## Operation of @--BL(597)

The up-differentiated variation is used in the following example, so the BCD content of D00101 and D00100 will be decremented by 1 only when CIO 0000.00 has gone from OFF to ON.



# 3-10 Symbol Math Instructions

This section describes the Symbol Math Instructions, which perform arithmetic operations on BCD or binary data.

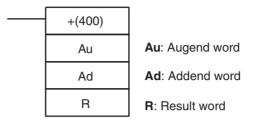
Instruction	Mnemonic	Function code	Page
SIGNED BINARY ADD WITH- OUT CARRY	+	400	282
DOUBLE SIGNED BINARY ADD WITHOUT CARRY	+L	401	283
SIGNED BINARY ADD WITH CARRY	+C	402	285
DOUBLE SIGNED BINARY ADD WITH CARRY	+CL	403	287
BCD ADD WITHOUT CARRY	+B	404	289
DOUBLE BCD ADD WITHOUT CARRY	+BL	405	290
BCD ADD WITH CARRY	+BC	406	292
DOUBLE BCD ADD WITH CARRY	+BCL	407	293
SIGNED BINARY SUBTRACT WITHOUT CARRY	_	410	295
DOUBLE SIGNED BINARY SUBTRACT WITHOUT CARRY	-L	411	296
SIGNED BINARY SUBTRACT WITH CARRY	_C	412	300
DOUBLE SIGNED BINARY SUBTRACT WITH CARRY	-CL	413	302
BCD SUBTRACT WITHOUT CARRY	-В	414	304
DOUBLE BCD SUBTRACT WITHOUT CARRY	–BL	415	306
BCD SUBTRACT WITH CARRY	–ВС	416	309
DOUBLE BCD SUBTRACT WITH CARRY	-BCL	417	310
SIGNED BINARY MULTIPLY	*	420	312
DOUBLE SIGNED BINARY MULTIPLY	*L	421	314
UNSIGNED BINARY MULTI- PLY	*U	422	315
DOUBLE UNSIGNED BINARY MULTIPLY	*UL	423	317
BCD MULTIPLY	*B	424	318
DOUBLE BCD MULTIPLY	*BL	425	320
SIGNED BINARY DIVIDE	/	430	321
DOUBLE SIGNED BINARY DIVIDE	/L	431	323
UNSIGNED BINARY DIVIDE	/U	432	324
DOUBLE UNSIGNED BINARY DIVIDE	/UL	433	326
BCD DIVIDE	/В	434	328
DOUBLE BCD DIVIDE	/BL	435	329

# 3-10-1 SIGNED BINARY ADD WITHOUT CARRY: +(400)

**Purpose** 

Adds 4-digit (single-word) hexadecimal data and/or constants.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	+(400)
	<b>Executed Once for Upward Differentiation</b>	@+(400)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Au	Ad	R
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	7	
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

**Description** 

+(400) adds the binary values in Au and Ad and outputs the result to R.

		Au	(Signed binary)
	+	Ad	(Signed binary)
CY will turn ON when there		Гр	(Signed binary)
is a carry.	CT	n	(Signed binary)

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when the addition results in a carry.	
		OFF in all other cases.	
Overflow Flag	OF	ON when the result of adding two positive numbers is in the range 8000 to FFFF hex.	
		OFF in all other cases.	
Underflow Flag	UF	ON when the result of adding two negative numbers is the range 0000 to 7FFF hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the result is 1.	
		OFF in all other cases.	

### **Precautions**

When +(400) is executed, the Error Flag will turn OFF.

If as a result of the addition, the content of R is 0000 hex, the Equals Flag will turn ON.

If the addition results in a carry, the Carry Flag will turn ON.

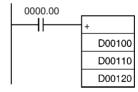
If the result of adding two positive numbers is negative (in the range 8000 to FFFF hex), the Overflow Flag will turn ON.

If the result of adding two negative numbers is positive (in the range 0000 to 7FFF hex), the Underflow Flag will turn ON.

If as a result of the addition, the content of the leftmost bit of R is 1, the Negative Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON in the following example, D00100 and D00110 will be added as 4-digit signed binary values and the result will be output to D00120.

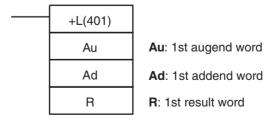


# 3-10-2 DOUBLE SIGNED BINARY ADD WITHOUT CARRY: +L(401)

#### **Purpose**

Adds 8-digit (double-word) hexadecimal data and/or constants.

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	+L(401)
	Executed Once for Upward Differentiation	@+L(401)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Au	Ad	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	37	
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers	IR0 or IR15		
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

# **Description**

+L(401) adds the binary values in Au and Au+1 and Ad and Ad+1 and outputs the result to R and R+1.

	Au+1		Au	(Signed binary)
	+	Ad+1	Ad	(Signed binary)
CY will turn ON when there is a carry.	СҮ	R+1	R	(Signed binary)

# Flags

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when the addition results in a carry.	
		OFF in all other cases.	
Overflow Flag	OF	ON when the result of adding two positive numbers is in the range 8000 0000 to FFFF FFFF hex.	
		OFF in all other cases.	
Underflow Flag	UF	ON when the result of adding two negative numbers is in the range 0000 0000 to 7FFF FFFF hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the result is 1.	
		OFF in all other cases.	

## **Precautions**

When +L(401) is executed, the Error Flag will turn OFF.

If as a result of the addition, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If the addition results in a carry, the Carry Flag will turn ON.

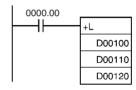
If the result of adding two positive numbers is negative (in the range 8000 0000 to FFFF FFFF hex), the Overflow Flag will turn ON.

If the result of adding two negative numbers is positive (in the range 0000 0000 to 7FFF FFFF hex), the Underflow Flag will turn ON.

If as a result of the addition, the content of the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

#### **Examples**

When CIO 0000.00 is ON, D00100 and D00110 and D00111 and D00110 will be added as 8-digit signed binary values and the result will be output to D00120 and D00121.

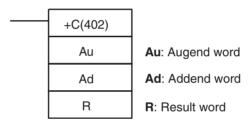


# 3-10-3 SIGNED BINARY ADD WITH CARRY: +C(402)

## **Purpose**

Adds 4-digit (single-word) hexadecimal data and/or constants with the Carry Flag (CY).

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	+C(402)
	Executed Once for Upward Differentiation	@+C(402)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

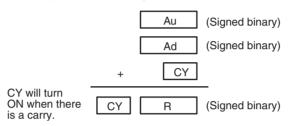
#### **Operand Specifications**

Area	Au	Ad	R	
CIO Area	CIO 0000 to CIO 61	CIO 0000 to CIO 6143		
Work Area	W000 to W255	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959	
Timer Area	T0000 to T0255			
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767			
Indirect DM addresses in binary	@ D00000 to @ D3	2767		
Indirect DM addresses in BCD *D00000 to *D32767				

Area	Au	Ad	R
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
DR0 to DR15, IR0 to DR0 to ,IR0+(++) to ,IR15+(++)		to DR0 to DR15, IR	15
		-(++)	
	,-()IR0 to , -(	-)IR15	

#### **Description**

+C(402) adds the binary values in Au, Ad, and CY and outputs the result to R.



## **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the addition result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the addition results in a carry.
		OFF in all other cases.
Overflow Flag	OF	ON when the result of adding two positive numbers and CY is in the range 8000 to FFFF hex.
		OFF in all other cases.
Underflow Flag	UF	ON when the result of adding two negative numbers and CY is in the range 0000 to 7FFF hex.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of the result is 1.
		OFF in all other cases.

#### **Precautions**

When +C(402) is executed, the Error Flag will turn OFF.

If as a result of the addition, the content of R is 0000 hex, the Equals Flag will turn ON.

If the addition results in a carry, the Carry Flag will turn ON.

If the result of adding two positive numbers and CY is negative (in the range 8000 to FFFF hex), the Overflow Flag will turn ON.

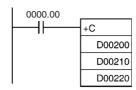
If the result of adding two negative numbers and CY is positive (in the range 0000 to 7FFF hex), the Underflow Flag will turn ON.

If as a result of the addition, the content of the leftmost bit of R is 1, the Negative Flag will turn ON.

Note To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

#### **Examples**

When CIO 0000.00 is ON, D00200, D00210, and CY will be added as 4-digit signed binary values and the result will be output to D00220.

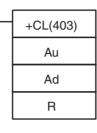


# 3-10-4 DOUBLE SIGNED BINARY ADD WITH CARRY: +CL(403)

**Purpose** 

Adds 8-digit (double-word) hexadecimal data and/or constants with the Carry Flag (CY).

**Ladder Symbol** 



Au: 1st augend word
Ad: 1st addend word
R: 1st result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	+CL(403)
	Executed Once for Upward Differentiation	@+CL(403)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

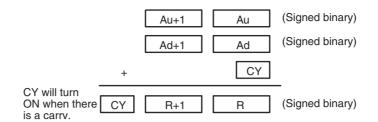
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Au	Ad	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FF	FF FFFF	
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

+CL(403) adds the binary values in Au and Au+1, Ad and Ad+1, and CY and outputs the result to R and R+1.



Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when the addition results in a carry.	
		OFF in all other cases.	
Overflow Flag	OF	ON when the result of adding two positive numbers and CY is in the range 8000 0000 to FFFF FFFF hex.	
		OFF in all other cases.	
Underflow Flag	UF	ON when the result of adding two negative numbers and CY is in the range 0000 0000 to 7FFF FFFF hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the result is 1.	
		OFF in all other cases.	

#### **Precautions**

When +CL(403) is executed, the Error Flag will turn OFF.

If as a result of the addition, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If the addition results in a carry, the Carry Flag will turn ON.

If the result of adding two positive numbers and CY is negative (in the range 8000 0000 to FFFF FFFF hex), the Overflow Flag will turn ON.

If the result of adding two negative numbers and CY is positive (in the range 0000 0000 to 7FFF FFFF hex), the Underflow Flag will turn ON.

If as a result of the addition, the content of the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

Note To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

### **Examples**

When CIO 0000.00 is ON, D00201, D00200, D00211, D00210, and CY will be added as 8-digit signed binary values, and the result will be output to D00221 and D00220.

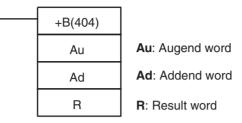
```
0000.00
+CL
D00200
D00210
D00220
```

# **3-10-5 BCD ADD WITHOUT CARRY: +B(404)**

# **Purpose**

Adds 4-digit (single-word) BCD data and/or constants.

**Ladder Symbol** 



# **Variations**

Variations	Executed Each Cycle for ON Condition	+B(404)
	<b>Executed Once for Upward Differentiation</b>	@+B(404)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Au	Ad	R
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #9999		
	(BCD)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

+B(404) adds the BCD values in Au and Ad and outputs the result to R.

	[	Au	(BCD)
+	[	Ad	(BCD)
CY will turn ON when there CY is a carry.	][	R	BCD)

Name	Label	Operation
Error Flag	ER	ON when Au is not BCD.
		ON when Ad is not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the addition results in a carry.
		OFF in all other cases.

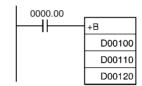
**Precautions** 

If Au or Ad is not BCD, an error is generated and the Error Flag will turn ON. If as a result of the addition, the content of R is 0000 hex, the Equals Flag will turn ON.

If an addition results in a carry, the Carry Flag will turn ON.

**Examples** 

When CIO 0000.00 is ON in the following example, D00100 and D00110 will be added as 4-digit BCD values, and the result will be output to D00120.

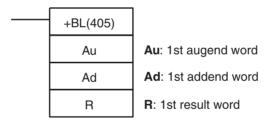


# 3-10-6 DOUBLE BCD ADD WITHOUT CARRY: +BL(405)

**Purpose** 

Adds 8-digit (double-word) BCD data and/or constants.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	+BL(405)
	Executed Once for Upward Differentiation	@+BL(405)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

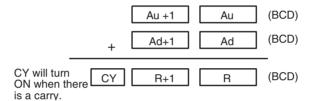
### **Operand Specifications**

Area	Au	Ad	R	
CIO Area	CIO 0000 to CIO 6	142		
Work Area	W000 to W254			
Auxiliary Bit Area	A000 to A958	A000 to A958 A448 to A958		
Timer Area	T0000 to T0254			
Counter Area	C0000 to C0254			
DM Area	D00000 to D32766			

Area	Au	Ad	R
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	7	
Constants	#0000 0000 to #9999 9999		
	(BCD)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR	0 to -2048 to +2047	7 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

### **Description**

+BL(405) adds the BCD values in Au and Au+1 and Ad and Ad+1 and outputs the result to R, R+1.



## **Flags**

Name	Label	Operation
Error Flag	ER	ON when Au, Au +1 is not BCD.
		ON when Ad, Ad +1 is not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the addition results in a carry.
		OFF in all other cases.

#### **Precautions**

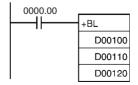
If Au, Au +1 or Ad, Ad +1 are not BCD, an error is generated and the Error Flag will turn ON.

If as a result of the addition, the content of R, R +1 is 0000 0000 hex, the Equals Flag will turn ON.

If an addition results in a carry, the Carry Flag will turn ON.

## **Examples**

When CIO 0000.00 is ON in the following example, D00101 and D00110 and D00111 and D00110 will be added as 8-digit BCD values, and the result will be output to D00121 and D00120.

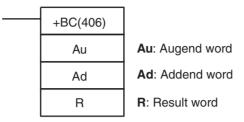


# 3-10-7 BCD ADD WITH CARRY: +BC(406)

### **Purpose**

Adds 4-digit (single-word) BCD data and/or constants with the Carry Flag (CY).

### **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	+BC(406)
	Executed Once for Upward Differentiation	@+BC(406)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

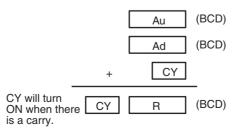
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Au	Ad	R
CIO Area	CIO 0000 to CIO 6	143	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	7	
Constants	#0000 to #9999		
	(BCD)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

## **Description**

+BC(406) adds BCD values in Au, Ad, and CY and outputs the result to R.



Name	Label	Operation
Error Flag	ER	ON when Au is not BCD.
		ON when Ad is not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the addition results in a carry.
		OFF in all other cases.

#### **Precautions**

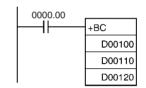
If Au or Ad is not BCD, an error is generated and the Error Flag will turn ON. If as a result of the addition, the content of R is 0000 hex, the Equals Flag will turn ON.

If an addition results in a carry, the Carry Flag will turn ON.

**Note** To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

### **Examples**

When CIO 0000.00 is ON in the following example, D00100, D00110, and CY will be added as 4-digit BCD values, and the result will be output to D00120.

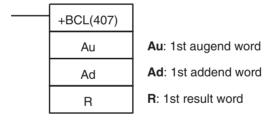


# 3-10-8 DOUBLE BCD ADD WITH CARRY: +BCL(407)

#### **Purpose**

Adds 8-digit (double-word) BCD data and/or constants with the Carry Flag (CY).

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	+BCL(407)
	Executed Once for Upward Differentiation	@+BCL(407)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

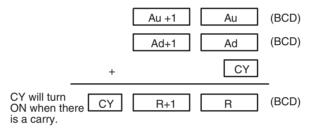
### **Operand Specifications**

Area	Au	Ad	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		

Area	Au	Ad	R
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D3276	37	
Constants	#0000 0000 to #99	99 9999	
	(BCD)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

#### **Description**

+BCL(407) adds the BCD values in Au and Au+1, Ad and Ad+1, and CY and outputs the result to R, R+1.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON when Au, Au +1 is not BCD.
		ON when Ad, Ad +1 is not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the addition results in a carry.
		OFF in all other cases.

#### **Precautions**

If Au, Au +1 or Ad, Ad +1 are not BCD, an error is generated and the Error Flag will turn ON.

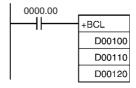
If as a result of the addition, the content of R, R +1 is 0000 0000 hex, the Equals Flag will turn ON.

If an addition results in a carry, the Carry Flag will turn ON.

Note To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

### **Examples**

When CIO 0000.00 is ON in the following example, D00101, D00100, D00111, D00110, and CY will be added as 8-digit BCD values, and the result will be output to D00121 and D00120.

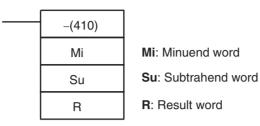


# 3-10-9 SIGNED BINARY SUBTRACT WITHOUT CARRY: -(410)

# **Purpose**

Subtracts 4-digit (single-word) hexadecimal data and/or constants.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	-(410)
	<b>Executed Once for Upward Differentiation</b>	@-(410)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 6	43	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	7	
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

-(410) subtracts the binary values in Su from Mi and outputs the result to R. When the result is negative, it is output to R as a 2's complement. (Refer to 3-10-10 DOUBLE SIGNED BINARY SUBTRACT WITHOUT CARRY: -L(411) for an example of handling 2's complements.)

	Mi	(Signed binary)
_	Su	(Signed binary)
CY will turn ON CY when there is a borrow.	R	— (Signed binary)

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when the subtraction results in a borrow.	
		OFF in all other cases.	
Overflow Flag	OF	ON when the result of subtracting a negative number from a positive number is in the range 8000 to FFFF hex.	
		OFF in all other cases.	
Underflow Flag	UF	ON when the result of subtracting a positive number from a negative number is in the range 0000 to 7FFF hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the result is 1.	
		OFF in all other cases.	

#### **Precautions**

When –(410) is executed, the Error Flag will turn OFF.

If as a result of the subtraction, the content of R is 0000 hex, the Equals Flag will turn ON.

If the subtraction results in a borrow, the Carry Flag will turn ON.

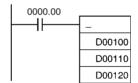
If the result of subtracting a negative number from a positive number is negative (in the range 8000 to FFFF hex), the Overflow Flag will turn ON.

If the result of subtracting a positive number from a negative number is positive (in the range 0000 to 7FFF hex), the Underflow Flag will turn ON.

If as a result of the subtraction, the content of the leftmost bit of R is 1, the Negative Flag will turn ON.

#### **Examples**

When CIO 0000.00 is ON in the following example, D00110 will be subtracted from D00100 as 4-digit signed binary values and the result will be output to D00120.

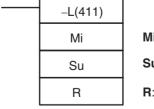


# 3-10-10 DOUBLE SIGNED BINARY SUBTRACT WITHOUT CARRY: -L(411)

## **Purpose**

Subtracts 8-digit (double-word) hexadecimal data and/or constants.

### **Ladder Symbol**



Mi: 1st minuend word

Su: 1st subtrahend word

R: 1st result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	-L(411)
	Executed Once for Upward Differentiation	@-L(411)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Mi	Su	R	
CIO Area	CIO 0000 to CIO 6142			
Work Area	W000 to W254	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958	
Timer Area	T0000 to T0254			
Counter Area	C0000 to C0254			
DM Area	D00000 to D32766			
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D3276	<del>3</del> 7		
Constants	#0000 0000 to #FF	FF FFFF		
	(binary)			
Data Resisters				
Index Registers	IR0 or IR15			
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -()IR15			

# **Description**

-L(411) subtracts the binary values in Su and Su+1 from Mi and Mi+1 and outputs the result to R, R+1. When the result is negative, it is output to R and R+1 as a 2's complement.

		Mi+1	Mi	Signed binary)
	_	Su+1	Su	(Signed binary)
CY will turn ON when there s a borrow.	CY	R+1	R	 ] (Signed binary)

## **Flags**

Name	Label	Operation		
Error Flag	ER	OFF		
Equals Flag	=	ON when the result is 0000 0000.		
		OFF in all other cases.		
Carry Flag	CY	ON when the subtraction results in a borrow.		
		OFF in all other cases.		
Overflow Flag	OF	ON when the result of subtracting a negative number from a positive number is in the range 8000 0000 to FFFF FFFF hex.		
		OFF in all other cases.		
Underflow Flag	UF	ON when the result of subtracting a positive number from a negative number is in the range 0000 0000 to 7FFF FFFF hex.		
		OFF in all other cases.		
Negative Flag	N	ON when the leftmost bit of the result is 1.		
		OFF in all other cases.		

#### **Precautions**

When -L(411) is executed, the Error Flag will turn OFF.

If as a result of the subtraction, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If the subtraction results in a borrow, the Carry Flag will turn ON.

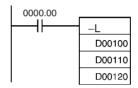
If the result of subtracting a negative number from a positive number is negative (in the range 8000 0000 to FFFF FFFF hex), the Overflow Flag will turn ON.

If the result of subtracting a positive number from a negative number is positive (in the range 0000 0000 to 7FFF FFFF hex), the Underflow Flag will turn ON.

If as a result of the subtraction, the content of the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

# **Examples**

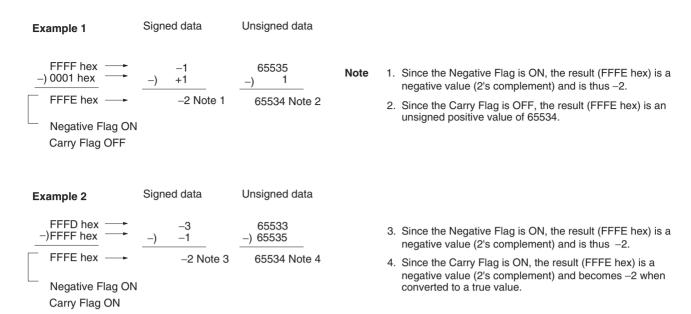
When CIO 0000.00 is ON in the following example, D00111 and D00110 will be subtracted from D00101 and D00100 as 8-digit signed binary values and the result will be output to D00121 and D00120.



If the result of a subtraction is a negative number (Mi<Su for –(410) or Mi+1, Mi <Su+1, Su for –L(411)), the result is output as the 2's complement and the Carry Flag (CY) will turn ON to indicate that the result of the subtraction is negative. To convert the 2's complement to the true number, an instruction which subtracts the result from 0000 or 0000 0000 is necessary using the Carry Flag (CY) as an execution condition.

#### Note 2's Complement

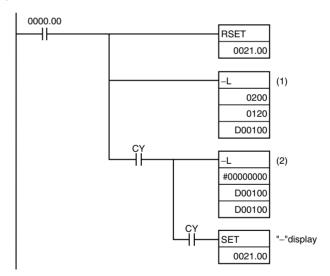
A 2's complement is the value obtained by subtracting each binary digit from 1 and adding one to the result. For example, the 2's complement for the binary number 1101 is calculated as follows: 1111 (F hexadecimal) – 1101 (D hexadecimal) + 1 (1 hexadecimal) = 0011 (3 hexadecimal). The 2's complement for 3039 (hexadecimal) is calculated as follows: FFFF (hexadecimal) – 3039 (hexadecimal) + 0001 (hexadecimal) = CFC7 (hexadecimal). Therefore, in case of 4-digit hexadecimal value, the 2's complement can be calculated as follows: FFFF (hexadecimal) – a (hexadecimal) + 0001 (hexadecimal) = b (hexadecimal). To obtain the true number "a" from the 2's complement b (hexadecimal): a (hexadecimal) = 10000 (hexadecimal) – b (hexadecimal). For example, to obtain the true number "a" from the 2's complement CFC7 (hexadecimal): 10000 (hexadecimal) – CFC7 = 3039.



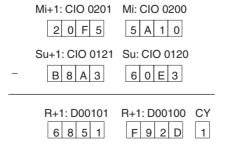
#### **Program Example**

## 20F55A10 - B8A360E3 = -97AE06D3.

In this example, the eight-digit binary value in CIO 0121 and CIO 0120 is subtracted from the value in CIO 0201 and CIO 0200, and the result is output in eight-digit binary to D00101 and D00100. If the result is negative, the instruction at (2) will be executed, and the actual result will then be output to D00101 and D00100.



# Subtraction at 1



The Carry Flag (CY) is ON, so the result is subtracted from 0000 0000 to obtain the actual number.

#### Subtraction at 2

	0 0 0 0	0 0 0 0	
_	Su+1: D00101 6 8 5 1	Su: D00100 F 9 2 D	
	D. 1. D00101	D. 1: D00100	<u></u>

R+1: D00101 R+1: D00100 CY
9 7 A E 0 6 D 3 1

### **Final Subtraction Result**

Mi+1: CIO 0201 Mi: CIO 0200

2 0 F 5 5 A 1 0

Su+1: D00101 Su: D00100

R+1: D00101 R+1: D00100 CY

R+1: D00101 R+1: D00100 CY
9 7 A E 0 6 D 3 1

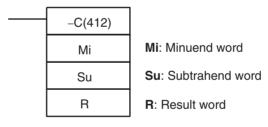
The Carry Flag (CY) is turned ON, so the actual number is -97AE06D3. Because the content of D00101 and D00100 is negative, CY is used to turn ON CIO 0021.00 to indicate this.

# 3-10-11 SIGNED BINARY SUBTRACT WITH CARRY: -C(412)

**Purpose** 

Subtracts 4-digit (single-word) hexadecimal data and/or constants with the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	-C(412)
	<b>Executed Once for Upward Differentiation</b>	@-C(412)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959 A448 to A959		
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		

Area	Mi	Su	R
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,–(– –)IR0 to , –(– –)IR15		

### **Description**

-C(412) subtracts the binary values in Su and CY from Mi, and outputs the result to R. When the result is negative, it is output to R as a 2's complement. (Refer to 3-10-12 DOUBLE SIGNED BINARY SUBTRACT WITH CARRY: – CL(413) for an example of handling 2's complements.)

		Mi	(Signed binary)
		Su	(Signed binary)
	-	CY	
CY will turn ON when there is a borrow.	СУ	R	— (Signed binary)

# **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the subtraction result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the subtraction results in a borrow.
		OFF in all other cases.
Overflow Flag	OF	ON when the result of subtracting a negative number and CY from a positive number is in the range 8000 to FFFF hex.  OFF in all other cases.
Underflow Flag	UF	ON when the result of subtracting a positive number and CY from a negative number is in the range 0000 to 7FFF hex.  OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of the result is 1.
		OFF in all other cases.

### **Precautions**

When -C(412) is executed, the Error Flag will turn OFF.

If as a result of the subtraction, the content of R is 0000 hex, the Equals Flag will turn ON.

If the subtraction results in a borrow, the Carry Flag will turn ON.

If the result of subtracting a negative number and CY from a positive number is negative (in the range 8000 to FFFF hex), the Overflow Flag will turn ON.

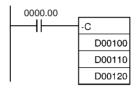
If the result of subtracting a positive number and CY from a negative number is positive (in the range 0000 to 7FFF hex), the Underflow Flag will turn ON.

If as a result of the subtraction, the content of the leftmost bit of R is 1, the Negative Flag will turn ON.

**Note** To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

## **Examples**

When CIO 0000.00 is ON in the following example, D00110 and CY will be subtracted from D00100 as 4-digit signed binary values and the result will be output to D00120.

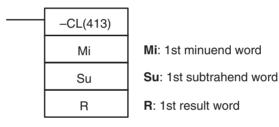


# 3-10-12 DOUBLE SIGNED BINARY SUBTRACT WITH CARRY: -CL(413)

### **Purpose**

Subtracts 8-digit (double-word) hexadecimal data and/or constants with the Carry Flag (CY).

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	-CL(413)
	Executed Once for Upward Differentiation	@-CL(413)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	57	
Constants	#0000 0000 to #FF	FF FFFF	
	(binary)		
Data Resisters			

Area	Mi	Su	R
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15		

#### Description

-CL(413) subtracts the binary values in Su and Su+1 and CY from Mi and Mi+1, and outputs the result to R, R+1. When the result is negative, it is output to R, R+1 as a 2's complement.

		Mi+1	Mi	(Signed binary)
		Su+1	Su	(Signed binary)
	_		CY	
CY will turn ON when there is a borrow	CY	R+1	R	(Signed binary)

## **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when the subtraction results in a borrow.	
		OFF in all other cases.	
Overflow Flag	OF	ON when the result of subtracting a negative number and CY from a positive number is in the range 8000 0000 to FFFF FFFF hex.	
		OFF in all other cases.	
Underflow Flag	UF	ON when the result of subtracting a positive number and CY from a negative number is in the range 0000 0000 to 7FFF FFFF hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the result is 1.	
		OFF in all other cases.	

### **Precautions**

When -CL(413) is executed, the Error Flag will turn OFF.

If as a result of the subtraction, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If the subtraction results in a borrow, the Carry Flag will turn ON.

If the result of subtracting a negative number and CY from a positive number is negative (in the range 8000 0000 to FFFF FFFF hex), the Overflow Flag will turn ON.

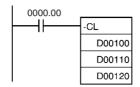
If the result of subtracting a positive number and CY from a negative number is positive (in the range 0000 0000 to 7FFF FFFF hex), the Underflow Flag will turn ON.

If as a result of the subtraction, the content of the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

**Note** To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

### **Examples**

When CIO 0000.00 is ON in the following example, D00111, D00110 and CY will be subtracted from D00101 and D00100 as 8-digit signed binary values, and the result will be output to D00121 and D00120.



If the result of the subtraction is a negative number (Mi<Su for -C(412) or Mi+1, Mi <Su+1, Su for -CL(413)), the result is output as a 2's complement. The Carry Flag (CY) will turn ON. To convert the 2's complement to the true number, a program which subtracts the result from 0000 or 0000 0000 is necessary, using the Carry Flag (CY) as the execution condition. The Carry Flag turning ON thus indicates that the result of the subtraction is negative.

#### Note 2's Complement

A 2's complement is the value obtained by subtracting each binary digit from 1 and adding one to the result.

**Example:** The 2's complement for the binary number 1101 is as follows:

1111 (F hex) - 1101 (D hex) + 1 (1 hex) = 0011 (3 hex).

**Example:** The 2's complement for the 4-digit hexadecimal number 3039 is as follows:

FFFF hex -3039 hex +0001 hex = CFC7 hex.

Accordingly, the 2's complement for the 4-digit hexadecimal number "a" is as follows:

FFFF hex - a hex + 0001 hex = b hex.

And to obtain the true number "a" hex from the 2's complement "b" hex:

a hex = 10000 hex - b hex.

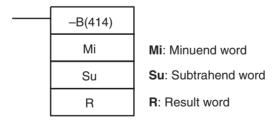
**Example:** To obtain the true number from the 2's complement CFC7 hex: 10000 hex – CFC7 hex = 3039 hex.

# 3-10-13 BCD SUBTRACT WITHOUT CARRY: -B(414)

### **Purpose**

Subtracts 4-digit (single-word) BCD data and/or constants.

#### **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	-B(414)
	Executed Once for Upward Differentiation	@-B(414)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 61	43	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	2767	
Indirect DM addresses in BCD	*D00000 to *D3276	7	
Constants	#0000 to #9999		
	(BCD)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	)IR15	

## **Description**

-B(414) subtracts the BCD values in Su from Mi and outputs the result to R. If the result of the subtraction is negative, the result is output to R as a 10's complement. (Refer to 3-10-14 DOUBLE BCD SUBTRACT WITHOUT CARRY: – BL(415) for an example of handling 10's complements.)

		Mi	(BCD)
	_	Su	(BCD)
CY will turn ON when there is a horrow	CY	R	(BCD)

### **Flags**

Name	Label	Operation
Error Flag	ER	ON when Mi is not BCD.
		ON when Su is not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the subtraction results in a borrow.
		OFF in all other cases.

#### **Precautions**

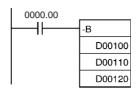
If Mi and/or Su are not BCD, an error is generated and the Error Flag will turn ON.

If as a result of the subtraction, the content of R is 0000 hex, the Equals Flag will turn ON.

If a subtraction results in a borrow, the Carry Flag will turn ON.

#### **Examples**

When CIO 0000.00 is ON in the following example, D00110 is subtracted from D00100 as 4-digit BCD values, and the result will be output to D00120.



# 3-10-14 DOUBLE BCD SUBTRACT WITHOUT CARRY: -BL(415)

**Purpose** 

Subtracts 8-digit (double-word) BCD data and/or constants.

**Ladder Symbol** 

-BL(415)
Mi
Su
R

Mi: 1st minuend word

Su: 1st subtrahend word

R: 1st result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	-BL(415)
	Executed Once for Upward Differentiation	@-BL(415)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

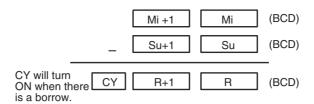
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 6	142	
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	37	
Constants	#0000 0000 to #999	99 9999	
	(BCD)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

### **Description**

-BL(415) subtracts the BCD values in Su and Su+1 from Mi and Mi+1 and outputs the result to R, R+1. If the result is negative, it is output to R, R+1 as a 10's complement.



Name	Label	Operation
Error Flag	ER	ON when Mi and/or Mi +1 are not BCD.
		ON when Su and/or Su +1 are not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0000 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the subtraction results in a borrow.
		OFF in all other cases.

#### **Precautions**

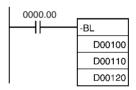
If Mi, Mi +1 and/or Su, Su +1 are not BCD, an error is generated and the Error Flag will turn ON.

If as a result of the subtraction, the content of R, R +1 is 0000 0000 hex, the Equals Flag will turn ON.

If a subtraction results in a borrow, the Carry Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON in the following example, D00111 and D00110 will be subtracted from D00101 and D00100 as 8-digit BCD values, and the result will be output to D00121 and D00120.



If the result of the subtraction is a negative number (Mi<Su for -B(414) or Mi+1, Mi <Su+1, Su for -BL(415)), the result is output as a 10's complement. The Carry Flag (CY) will turn ON. To convert the 10's complement to the true number, a program which subtracts the result from 0 is necessary, using the Carry Flag (CY) as the execution condition. The Carry Flag turning ON thus indicates that the result of the subtraction is negative.

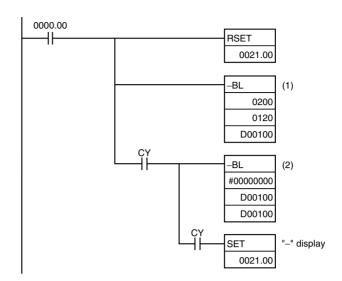
#### Note 10's Complement

A 10's complement is the value obtained by subtracting each digit from 9 and adding one to the result. For example, the 10's complement for 7556 is calculated as follows: 9999-7556+1=2444. For a four digit number, the 10's complement of A is 9999-A+1=B. To obtain the true number from the 10's complement B: A=10000-B. For example, to obtain the true number from the 10's complement 2444: 10000-2444=7556.

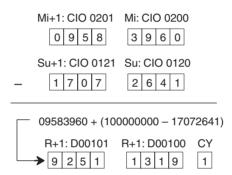
#### **Program Example**

9.583.960 - 17.072.641 = -7.488.681.

In this example, the eight-digit BCD content of CIO 0121 and CIO 0120 is subtracted from the content of CIO 0201 and CIO 0200, and the result is output in eight-digit BCD to D00101 and D00100. The result is negative, so the instruction at (2) will be executed, and the true number will then be output to D00101 and D00100.

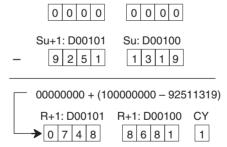


### **Subtraction at 1**

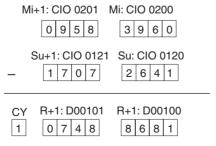


The Carry Flag (CY) is ON, so the result is subtracted from 0000 0000.

#### Subtraction at 2



## **Final Subtraction Result**



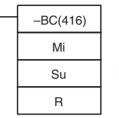
The Carry Flag (CY) will be turned ON, so the actual number is -7,488,681. Because the content of D00101 and D00100 is negative, CY is used to turn ON CIO 0021.00 to indicate this.

# 3-10-15 BCD SUBTRACT WITH CARRY: -BC(416)

### **Purpose**

Subtracts 4-digit (single-word) BCD data and/or constants with the Carry Flag (CY).

### **Ladder Symbol**



Mi: Minuend word

Su: Subtrahend word

R: Result word

## **Variations**

Variations	Executed Each Cycle for ON Condition	-BC(416)
	Executed Once for Upward Differentiation	@-BC(416)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

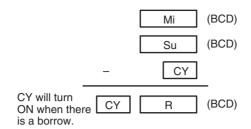
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 61	143	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	7	
Constants	#0000 to #9999		
	(BCD)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	)IR15	

### **Description**

-BC(416) subtracts BCD values in Su and CY from Mi and outputs the result to R. If the result is negative, it is output to R as a 10's complement. (Refer to 3-10-16 DOUBLE BCD SUBTRACT WITH CARRY: -BCL(417) for an example of handling 10's complements.)



Name	Label	Operation
Error Flag	ER	ON when Mi is not BCD.
		ON when Su is not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0000.
		OFF in all other cases.
Carry Flag	CY	ON when the subtraction results in a borrow.
		OFF in all other cases.

**Precautions** 

If Mi and/or Su are not BCD, an error is generated and the Error Flag will turn ON.

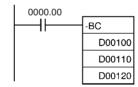
If as a result of the subtraction, the content of R is 0000 hex, the Equals Flag will turn ON.

If a subtraction results in a borrow, the Carry Flag will turn ON.

Note To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

**Examples** 

When CIO 0000.00 is ON in the following example, D00110 and CY will be subtracted from D00100 as 4-digit BCD values, and the result will be output to D00120.

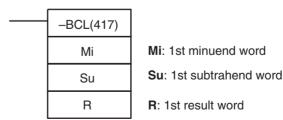


# 3-10-16 DOUBLE BCD SUBTRACT WITH CARRY: -BCL(417)

**Purpose** 

Subtracts 8-digit (double-word) BCD data and/or constants with the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	-BCL(417)
	Executed Once for Upward Differentiation	@-BCL(417)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #99	99 9999	
	(BCD)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	dex Registers		7 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15		15
,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -()IR15		

## **Description**

-BCL(417)subtracts the BCD values in Su, Su+1, and CY from Mi and Mi+1 and outputs the result to R, R+1. If the result is negative, it is output to R, R+1 as a 10's complement.

	Mi +1	Mi	(BCD)
	Su+1	Su	(BCD)
		CY	
CY will turn ON when there CY is a borrow.	R+1	R	(BCD)

## **Flags**

Name	Label	Operation	
Error Flag	ER	ON when Mi and/or Mi +1 are not BCD.	
		ON when Su and/or Su +1 are not BCD.	
		OFF in all other cases.	
Equals Flag	=	ON when the result is 0000 0000.	
		OFF in all other cases.	
Carry Flag	CY	ON when the subtraction results in a borrow.	
		OFF in all other cases.	

### **Precautions**

If Mi, Mi +1 and/or Su, Su +1 are not BCD, an error is generated and the Error Flag will turn ON.

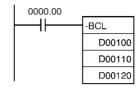
If as a result of the subtraction, the content of R, R  $\pm$ 1 is 0000 0000 hex, the Equals Flag will turn ON.

If an subtraction results in a borrow, the Carry Flag will turn ON.

**Note** To clear the Carry Flag (CY), execute the Clear Carry (CLC(041)) instruction.

#### **Examples**

When CIO 0000.00 is ON in the following example, D00111, D00110, and CY will be subtracted from D00101 and D00100 as 8-digit BCD values, and the result will be output to D00121 and D00120.



If the result of the subtraction is a negative number (Mi<Su for -BC(416) or Mi+1, Mi <Su+1, Su for -BCL(417)), the result is output as a 10's complement. The Carry Flag (CY) will turn ON. To convert the 10's complement to the true number, a program which subtracts the result from 0 is necessary, using the Carry Flag (CY) as the execution condition. The Carry Flag turning ON thus indicates that the result of the subtraction is negative.

### Note 10's Complement

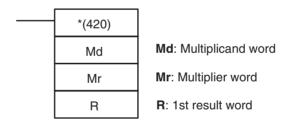
A 10's complement is the value obtained by subtracting each digit from 9 and adding one to the result. For example, the 10's complement for 7556 is calculated as follows: 9999 - 7556 + 1 = 2444. For a four digit number, the 10's complement of A is 9999 - A + 1 = B. To obtain the true number from the 10's complement B: A = 10000 - B. For example, to obtain the true number from the 10's complement 2444: 10000 - 2444 = 7556.

# 3-10-17 SIGNED BINARY MULTIPLY: \*(420)

#### **Purpose**

Multiplies 4-digit signed hexadecimal data and/or constants.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	*(420)
	Executed Once for Upward Differentiation	@*(420)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	Md	Mr	R
CIO Area	CIO 0000 to CIO 6		CIO 0000 to CIO 6142
Work Area	W000 to W255		W000 to W254
Auxiliary Bit Area	A000 to A959		A448 to A958

Area	Md	Mr	R
Timer Area	T0000 to T0255		T0000 to T0254
Counter Area	C0000 to C0255		C0000 to C0254
DM Area	D00000 to D32767		D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
DR0 to DR15, IR0 to DR0 to DR15, IR15		15	
	,IR0+(++) to ,IR15+(++)		
	,-()IR0  to ,-()IR15		

## **Description**

\*(420) multiplies the signed binary values in Md and Mr and outputs the result to R, R+1.



## **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 0000.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the result is 1.	
		OFF in all other cases.	

### **Precautions**

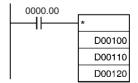
When \*(420) is executed, the Error Flag will turn OFF.

If as a result of the multiplication, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the multiplication, the content of the leftmost bit of R+1 and R is 1, the Negative Flag will turn ON.

## **Examples**

When CIO 0000.00 is ON in the following example, D00100 and D00110 will be multiplied as 4-digit signed hexadecimal values and the result will be output to D00120.



# 3-10-18 DOUBLE SIGNED BINARY MULTIPLY: \*L(421)

**Purpose** 

Multiplies 8-digit signed hexadecimal data and/or constants.

**Ladder Symbol** 

\*L(421)

Md

Mr

R

Md: 1st multiplicand word

Mr: 1st multiplier word

R: 1st result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	*L(421)
	<b>Executed Once for Upward Differentiation</b>	@*L(421)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

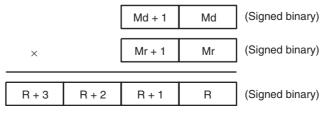
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Md	Mr	R
CIO Area	CIO 0000 to CIO 6142		CIO 0000 to CIO 6140
Work Area	W000 to W254	W000 to W254	
Auxiliary Bit Area	A000 to A958		A448 to A956
Timer Area	T0000 to T0254		T0000 to T0252
Counter Area	C0000 to C0254		C0000 to C0252
DM Area	D00000 to D32766	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FF	FF FFFF	
	(binary)	(binary)	
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to $,-()IR15$		

## **Description**

\*L(421) multiplies the signed binary values in Md and Md+1 and in Mr and Mr+1 and outputs the result to R, R+1, R+2, and R+3.



Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0 (all 16 bits).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of the result is 1.
		OFF in all other cases.

#### **Precautions**

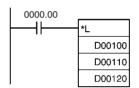
When \*L(421) is executed, the Error Flag will turn OFF.

If as a result of the multiplication, the content of R, R+1, R+2, R+3 is 0000 0000 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the multiplication, the content of the leftmost bit of R+3 is 1, the Negative Flag will turn ON.

## **Examples**

When CIO 0000.00 is ON in the following example, D00101, D00100, D00111, and D00110 will be multiplied as 8-digit signed hexadecimal values and the result will be output to D00123, D00122, D00121, and D00120.

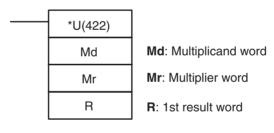


# 3-10-19 UNSIGNED BINARY MULTIPLY: \*U(422)

## **Purpose**

Multiplies 4-digit unsigned hexadecimal data and/or constants.

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	*U(422)
	Executed Once for Upward Differentiation	@*U(422)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	Md	Mr	R
CIO Area	CIO 0000 to CIO 6	CIO 0000 to CIO 6143	
Work Area	W000 to W255	W000 to W255	
Auxiliary Bit Area	A000 to A959	A000 to A959	
Timer Area	T0000 to T0255	T0000 to T0255	
Counter Area	C0000 to C0255		C0000 to C0254

Area	Md	Mr	R
DM Area	D00000 to D32767		D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D3276	37	
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

## **Description**

\*U(420) multiplies the unsigned binary values in Md and Mr and outputs the result to R, R+1.



## **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0000 0000.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of the result is 1.
		OFF in all other cases.

### **Precautions**

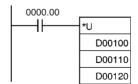
When \*U(422) is executed, the Error Flag will turn OFF.

If as a result of the multiplication, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the multiplication, the content of the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON in the following example, D00100 and D00110 will be multiplied as 4-digit unsigned binary values and the result will be output to D00121 and D00120.



# 3-10-20 DOUBLE UNSIGNED BINARY MULTIPLY: \*UL(423)

**Purpose** 

Multiplies 8-digit unsigned hexadecimal data and/or constants.

**Ladder Symbol** 

\*UL(423)

Md

Mr

R

Md: 1st multiplicand word

Mr: 1st multiplier word

R: 1st result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	*UL(423)
	Executed Once for Upward Differentiation	@*UL(423)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Md	Mr	R
CIO Area	CIO 0000 to CIO 6142		CIO 0000 to CIO 6140
Work Area	W000 to W254		W000 to W252
Auxiliary Bit Area	A000 to A958		A448 to A956
Timer Area	T0000 to T0254		T0000 to T0252
Counter Area	C0000 to C0254		C0000 to C0252
DM Area	D00000 to D32766		D00000 to D32764
Indirect DM addresses in binary	@ D00000 to @ D	32767	·
Indirect DM addresses in BCD	*D00000 to *D3276	67	
Constants	#0000 0000 to #FFFF FFFF (binary)		
Data Resisters			- '
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15		•

## **Description**

\*UL(423) multiplies the unsigned binary values in Md and Md+1 and in Mr and Mr+1 and outputs the result to R, R+1, R+2, and R+3.

_				
(Unsigned binary)	Md	Md + 1		
- <b>1</b>				
(Unsigned binary)	Mr	Mr + 1		×
<u>.</u>				
(Unsigned binary)	R	R + 1	R + 2	R + 3

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0 (all 16 bits).
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of the result is 1.
		OFF in all other cases.

#### **Precautions**

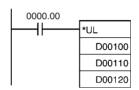
When \*UL(423) is executed, the Error Flag will turn OFF.

If as a result of the multiplication, the content of R, R+1, R+2, R+3 is 0000 0000 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the multiplication, the content of the leftmost bit of R+3 is 1, the Negative Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON in the following example, D00101, D00100, D00111, and D00110 will be multiplied as 8-digit unsigned binary values and the result will be output to D00123, D00122, D00121, and D00120.

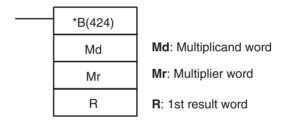


# 3-10-21 BCD MULTIPLY: \*B(424)

## **Purpose**

Multiplies 4-digit (single-word) BCD data and/or constants.

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	*B(424)
	Executed Once for Upward Differentiation	@*B(424)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	Md	Mr	R
CIO Area	CIO 0000 to CIO 6	CIO 0000 to CIO 6143	
Work Area	W000 to W255	W000 to W255	
Auxiliary Bit Area	A000 to A959	A000 to A959	
Timer Area	T0000 to T0255	T0000 to T0255	
Counter Area	C0000 to C0255		C0000 to C0254

Area	Md	Mr	R
DM Area	D00000 to D32767		D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D3276	57	
Constants	#0000 to #9999		
	(BCD)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

## **Description**

 $^{\star}$ B(424) multiplies the BCD content of Md and Mr and outputs the result to R, R+1.



## **Flags**

Name	Label	Operation	
Error Flag	ER	ON when Md is not BCD.	
		ON when Mr is not BCD.	
		OFF in all other cases.	
Equals Flag	=	ON when the result is 0000 0000.	
		OFF in all other cases.	

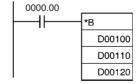
### **Precautions**

If Md and/or Mr are not BCD, an error will be generated and the Error Flag will turn ON.

If as a result of the multiplication, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON in the following example, D00100 and D00110 will be multiplied as 4-digit BCD values and the result will be output to D00121 and D00120.

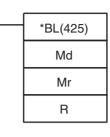


# 3-10-22 DOUBLE BCD MULTIPLY: \*BL(425)

**Purpose** 

Multiplies 8-digit (double-word) BCD data and/or constants.

**Ladder Symbol** 



Md: 1st multiplicand word

Mr: 1st multiplier word

R: 1st result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	*BL(425)
	Executed Once for Upward Differentiation	@*BL(425)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Md	Mr	R
CIO Area	CIO 0000 to CIO 6142		CIO 0000 to CIO 6140
Work Area	W000 to W254		W000 to W252
Auxiliary Bit Area	A000 to A958		A448 to A956
Timer Area	T0000 to T0254		T0000 to T0252
Counter Area	C0000 to C0254		C0000 to C0252
DM Area	D00000 to D32766		D00000 to D32764
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #9999 9999 (BCD)		
Data Resisters			
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15  -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15  DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15		

## **Description**

\*BL(425) multiplies BCD values in Md and Md+1 and in Mr and Mr+1 and outputs the result to R, R+1, R+2, and R+3.



Name	Label	Operation
Error Flag	ER	ON when Md and/or Md+1 are not BCD.
		ON when Mr and/or Mr +1 are not BCD.
		OFF in all other cases.
Equals Flag	=	ON when the result is 0 (all 16 bits).
		OFF in all other cases.

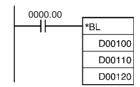
**Precautions** 

If Md, Md+1 and/or Mr, Mr+1 are not BCD, an error will be generated and the Error Flag will turn ON.

If as a result of the multiplication, the content of R, R+1, R+2, R+3 is 0000 0000 0000 0000 hex, the Equals Flag will turn ON.

**Examples** 

When CIO 0000.00 is ON in the following example, D00101, D00100, D00111, and D00110 will be multiplied as 8-digit BCD values and the result will be output to D00123, D00122, D00121 and D00120.

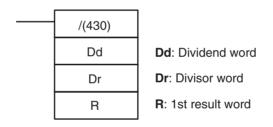


# 3-10-23 SIGNED BINARY DIVIDE: /(430)

**Purpose** 

Divides 4-digit (single-word) signed hexadecimal data and/or constants.

### **Ladder Symbol**



**Variations** 

Variations	Executed Each Cycle for ON Condition	/(430)
	Executed Once for Upward Differentiation	@/(430)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

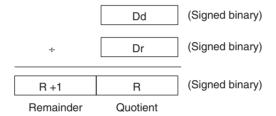
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	Dd	Dr	R
CIO Area	CIO 0000 to CIO 6	143	CIO 0000 to CIO 6142
Work Area	W000 to W255	W000 to W255	
Auxiliary Bit Area	A000 to A959	A000 to A959	
Timer Area	T0000 to T0255	T0000 to T0255	
Counter Area	C0000 to C0255	C0000 to C0255	
DM Area	D00000 to D32767		D00000 to D32766

Area	Dd	Dr	R
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF	#0001 to #FFFF	
	(binary)	(binary)	
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15-	+(++)	
	,–(– –)IR0 to , –(– –)IR15		

### **Description**

/(430) divides the signed binary (16 bit) values in Dd by those in Dr and outputs the result to R, R+1. The quotient is placed in R and the remainder in R+1.



## **Flags**

Name	Label	Operation	
Error Flag	ER	ON when Dr is 0000.	
		OFF in all other cases.	
Equals Flag	=	ON when as a result of the division, R is 0000.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the R is 1.	
		OFF in all other cases.	

### **Precautions**

Dividing 8000 hex by FFFF hex will produce an inconsistent result.

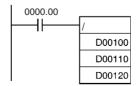
When the content of Dr is 0000 hex, an error will be generated and the Error Flag will turn ON.

If as a result of the division, the content of R is 0000 hex, the Equals Flag will turn ON.

If as a result of the division, the content of the leftmost bit of R is 1, the Negative Flag will turn ON.

#### **Examples**

When CIO 0000.00 is ON in the following example, D00100 will be divided by D00110 as 4-digit signed binary values and the quotient will be output to D00120 and the remainder to D00121.



# 3-10-24 DOUBLE SIGNED BINARY DIVIDE: /L(431)

**Purpose** 

Divides 8-digit (double-word) signed hexadecimal data and/or constants.

**Ladder Symbol** 

/L(431)

Dd

Dr

R

Dd: 1st dividend word

Dr: 1st divisor word

R: 1st result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	/L(431)
	<b>Executed Once for Upward Differentiation</b>	@/L(431)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

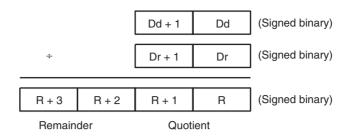
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Dd	Dr	R
CIO Area	CIO 0000 to CIO 6142		CIO 0000 to CIO 6140
Work Area	W000 to W254		W000 to W252
Auxiliary Bit Area	A000 to A958		A448 to A956
Timer Area	T0000 to T0254		T0000 to T0252
Counter Area	C0000 to C0254		C0000 to C0252
DM Area	D00000 to D32766		D00000 to D32764
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #0000 0001 to #FFFF FFFF		
	(binary)	(binary)	
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	–)IR15	

### Description

/L(431) divides the signed binary values in Dd and Dd+1 by those in Dr and Dr+1 and outputs the result to R, R+1, R+2, and R+3. The quotient is output to R and R+1 and the remainder is output to R+2 and R+3.



Name	Label	Operation	
Error Flag	ER	ON when Dr and Dr+1 is 0000 0000.	
		OFF in all other cases.	
Equals Flag	=	ON when as a result of the division, R+1, R is 0000 0000.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the R+1 is 1.	
		OFF in all other cases.	

#### **Precautions**

Dividing 8000 0000 hex by FFFF FFFF hex will produce an inconsistent result.

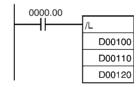
When the content of Dr+1 and Dr is 0000 0000, the Error Flag will turn ON.

If as a result of the division, the content of R+1, R is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the division, the content of the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

#### **Examples**

When CIO 0000.00 is ON in the following example, D00101 and D00100 are divided by D00111 and D00110 as 8-digit signed hexadecimal values and the quotient will be output to D00121 and D00120 and the remainder to D00123 and D00122.

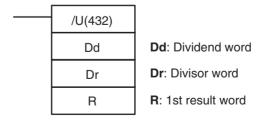


# 3-10-25 UNSIGNED BINARY DIVIDE: /U(432)

## **Purpose**

Divides 4-digit (single-word) unsigned hexadecimal data and/or constants.

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	/U(432)
	Executed Once for Upward Differentiation	@/U(432)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Dd	Dr	R	
CIO Area	CIO 0000 to CIO 6143		CIO 0000 to CIO 6142	
Work Area	W000 to W255		W000 to W254	
Auxiliary Bit Area	A000 to A959		A448 to A958	
Timer Area	T0000 to T0255		T0000 to T0254	
Counter Area	C0000 to C0255		C0000 to C0254	
DM Area	D00000 to D32767	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants	#0000 to #FFFF #0001 to #FFFF			
	(binary) (binary)			
Data Resisters	DR0 to DR15			
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, I		15	
	,IR0+(++) to ,IR15+(++)			
	,–(– –)IR0 to , –(– –)IR15			

### **Description**

/U(432) divides the unsigned binary values in Dd by those in Dr and outputs the quotient to R and the remainder to R+1.

	Dd	(Unsigned binary)
÷	Dr	(Unsigned binary)
R +1	R	 Unsigned binary)
Remainder	Quotient	

## **Flags**

Name	Label	Operation	
Error Flag	ER	ON when Dr is 0000.	
		OFF in all other cases.	
Equals Flag	=	ON when as a result of the division, R is 0000 hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of the R is 1.	
		OFF in all other cases.	

#### **Precautions**

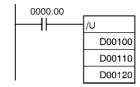
When the content of Dr is 0000 hex, the Error Flag will turn ON.

If as a result of the division, the content of R is 0000 hex, the Equals Flag will turn  $\mathsf{ON}.$ 

If as a result of the division, the content of the leftmost bit of R is 1, the Negative Flag will turn ON.

## **Examples**

When CIO 0000.00 is ON in the following example, D00100 will be divided by D00110 as 4-digit unsigned binary values and the quotient will be output to D00120 and the remainder will be output to D00121.

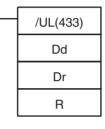


# 3-10-26 DOUBLE UNSIGNED BINARY DIVIDE: /UL(433)

**Purpose** 

Divides 8-digit (double-word) unsigned hexadecimal data and/or constants.

**Ladder Symbol** 



Dd: 1st dividend word

Dr: 1st divisor word

R: 1st result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	/UL(433)
	Executed Once for Upward Differentiation	@/UL(433)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

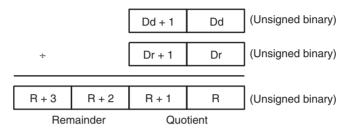
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	Dd	Dr	R
CIO Area	CIO 0000 to CIO 6142		CIO 0000 to CIO 6140
Work Area	W000 to W254		W000 to W252
Auxiliary Bit Area	A000 to A958		A448 to A956
Timer Area	T0000 to T0254		T0000 to T0252
Counter Area	C0000 to C0254		C0000 to C0252
DM Area	D00000 to D32766		D00000 to D32764
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF	#0000 0001 to #FFFF FFFF	
	(binary)	(binary)	
Data Resisters			

Area	Dd	Dr	R
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+	-(++)	
	,IR0+(++) to ,IR15+ ,-()IR0 to , -(	-)IR15	

#### Description

/UL(433) divides the unsigned binary values in Dd and Dd+1 by those in Dr and Dr+1 and outputs the quotient to R, R+1 and the remainder to R+2, and R+3.



### **Flags**

Name	Label	Operation
Error Flag	ER	ON when Dr and Dr+1 is 0000 0000 hex.
		OFF in all other cases.
Equals Flag	=	ON when as a result of the division R+1, R is 0000 0000 hex.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of the R+1 is 1.
		OFF in all other cases.

#### **Precautions**

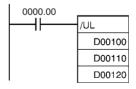
When the content of Dr, Dr+1 is 0000 0000 hex, the Error Flag will turn ON.

If as a result of the division, the content of R, R+1, is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the division, the content of the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

### **Examples**

When CIO 0000.00 is ON in the following example, D00100 and D00101 will be divided by D00111 and D00110 as 8-digit unsigned hexadecimal values and the quotient will be output to D00121 and D00120 and the remainder to D00123 and D00122.

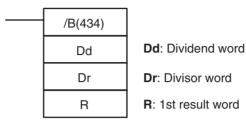


# 3-10-27 BCD DIVIDE: /B(434)

## **Purpose**

Divides 4-digit (single-word) BCD data and/or constants.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	/B(434)
	Executed Once for Upward Differentiation	@/B(434)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

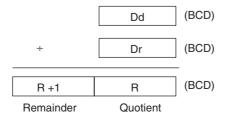
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Dd	Dr	R
CIO Area	CIO 0000 to CIO 6143		CIO 0000 to CIO 6142
Work Area	W000 to W255		W000 to W254
Auxiliary Bit Area	A000 to A959		A448 to A958
Timer Area	T0000 to T0255		T0000 to T0254
Counter Area	C0000 to C0255		C0000 to C0254
DM Area	D00000 to D32767 D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #9999	#0001 to #9999	
	(BCD)	(BCD)	
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(-	–)IR15	

# **Description**

/B(434) divides the BCD content of Dd by that of Dr and outputs the quotient to R and the remainder to R+1.



Name	Label	Operation
Error Flag	ER	ON when Dd is not BCD.
		ON when Dr is not BCD.
		ON when Dr is 0000.
		OFF in all other cases.
Equals Flag	=	ON when R is 0000 hex.
		OFF in all other cases.

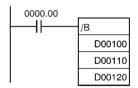
**Precautions** 

If Dd or Dr is not BCD or if Dr is 0000, an error will be generated and the Error Flag will turn ON.

If as a result of the division, the content of R is 0000 hex, the Equals Flag will turn ON.

**Examples** 

When CIO 0000.00 is ON in the following example, D00100 will be divided by D00110 as 4-digit BCD values and the quotient will be output to D00120 and the remainder to D00121.

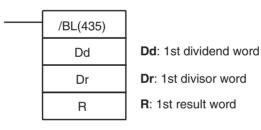


# 3-10-28 DOUBLE BCD DIVIDE: /BL(435)

**Purpose** 

Divides 8-digit (double-word) BCD data and/or constants.

**Ladder Symbol** 



**Variations** 

Variations	<b>Executed Each Cycle for ON Condition</b>	/BL(435)
	<b>Executed Once for Upward Differentiation</b>	@/BL(435)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

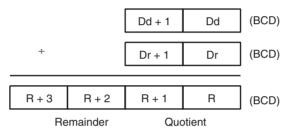
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	Dd	Dr	R
CIO Area	CIO 0000 to CIO 6	142	CIO 0000 to CIO 6140
Work Area	W000 to W254	W000 to W254	
Auxiliary Bit Area	A000 to A958	A000 to A958	
Timer Area	T0000 to T0254	T0000 to T0254	
Counter Area	C0000 to C0254	C0000 to C0254	

Area	Dd	Dr	R
DM Area	D00000 to D32766		D00000 to D32764
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #9999 9999	#0000 0001 to #9999 9999	
	(BCD)	(BCD)	
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
,-()IR0 to , -()IR15			

## **Description**

/BL(435) divides BCD values in Dd and Dd+1 by those in Dr and Dr+1 and outputs the quotient to R, R+1 and the remainder to R+2, R+3.



## **Flags**

Name	Label	Operation
Error Flag	ER	ON when Dd, Dd+1 is not BCD.
		ON when Dr, Dr +1 is not BCD.
		ON when the content of Dr+1 and Dr is 0000 0000 hex.
		OFF in all other cases.
Equals Flag	=	ON when as the result of a division R+1 and R is 0000 0000.
		OFF in all other cases.

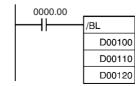
#### **Precautions**

If Dd, Dd+1 and/or Dr, Dr+1 are not BCD or the content of Dr, Dr+1 is 0000 0000 hex, an error will be generated and the Error Flag will turn ON.

If as a result of the division, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

## **Examples**

When CIO 0000.00 is ON in the following example, D00101 and D00100 will be divided by D00111 and D00110 as 8-digit BCD values and the quotient will be output to D00121 and D00120 and the remainder to D00123 and D00122.



# 3-11 Conversion Instructions

This section describes instructions used for data conversion.

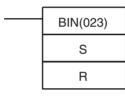
Instruction	Mnemonic	Function code	Page
BCD-TO-BINARY	BIN	023	331
DOUBLE BCD-TO-DOUBLE BINARY	BINL	058	333
BINARY-TO-BCD	BCD	024	334
DOUBLE BINARY-TO-DOU- BLE BCD	BCDL	059	336
2'S COMPLEMENT	NEG	160	338
DOUBLE 2'S COMPLEMENT	NEGL	161	339
ASCII CONVERT	ASC	086	341
ASCII TO HEX	HEX	162	345
16-BIT TO 32-BIT SIGNED BINARY	SIGN	600	349

# 3-11-1 BCD-TO-BINARY: BIN(023)

**Purpose** 

Converts BCD data to binary data.

**Ladder Symbol** 



S: Source word

R: Result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	BIN(023)
	Executed Once for Upward Differentiation	@BIN(023)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	S	R	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959	A448 to A959	
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Resisters	DR0 to DR15		

Area	S	R
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

### **Description**

BIN(023) converts the BCD data in S to binary data and writes the result to R.



### **Flags**

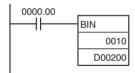
Name	Label	Operation
Error Flag	ER	ON if the content of S is not BCD.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000.
		OFF in all other cases.
Negative Flag	N	OFF

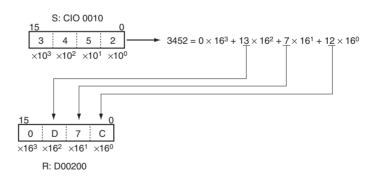
## **Example**

The following diagram shows an example BCD-to-binary conversion.

$$S \xrightarrow{15 \ 12 \ 11 \ 8 \ 7 \ 4 \ 3 \ 0} \xrightarrow{R} R \xrightarrow{15 \ 12 \ 11 \ 8 \ 7 \ 4 \ 3 \ 0} \times 10^{3} \times 10^{2} \times 10^{1} \times 10^{0} \xrightarrow{\times 16^{3} \times 16^{2} \times 16^{1} \times 16^{0}}$$

When CIO 0000.00 is ON in the following example, the 4-digit BCD value in CIO 0010 is converted to hexadecimal and stored in D00200.



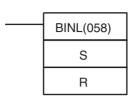


# 3-11-2 DOUBLE BCD-TO-DOUBLE BINARY: BINL(058)

## **Purpose**

Converts 8-digit BCD data to 8-digit hexadecimal (32-bit binary) data.

**Ladder Symbol** 



S: First source word

R: First result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	BINL(058)
	Executed Once for Upward Differentiation	@BINL(058)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958	A448 to A958	
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -204	18 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

BINL(058) converts the 8-digit BCD data in S and S+1 to 8-digit hexadecimal (32-bit binary) data and writes the result to R and R+1.

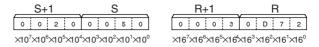
S+1	S		R+1	R
(BCD)	(BCD)	<b></b> [	(BIN)	(BIN)

# **Flags**

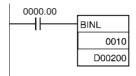
Name	Label	Operation
Error Flag	ER	ON if the content of S+1, S is not BCD.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000 0000 hex.
		OFF in all other cases.
Negative Flag	N	OFF

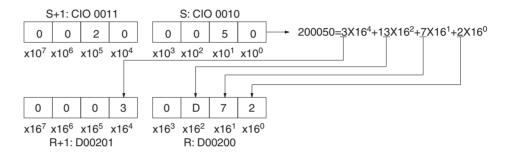
## **Examples**

The following diagram shows an example of 8-digit BCD-to-binary conversion.



When CIO 0000.00 is ON in the following example, the 8-digit BCD value in CIO 0010 and CIO 0011 is converted to hexadecimal and stored in D00200 and D00201.



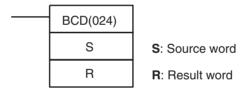


# 3-11-3 BINARY-TO-BCD: BCD(024)

### **Purpose**

Converts a word of binary data to a word of BCD data.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	BCD(024)
	Executed Once for Upward Differentiation	@BCD(024)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operands**

#### S: Source Word

S must be between 0000 and 270F hexadecimal (0000 and 9999 BCD).

Area	S	R
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A000 to A959	A448 to A959
Timer Area	T0000 to T0255	•
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	

Area	S	R
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 DR0 to DR15, IR0 to DR0 to ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15	,

### **Description**

BCD(024) converts the binary data in S to BCD data and writes the result to R.



### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the content of S is not between 0000 to 270F hex (0 to 9999 decimal).  OFF in all other cases.
Equals Flag	=	ON if the result is 0000. OFF in all other cases.

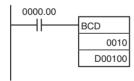
### **Precautions**

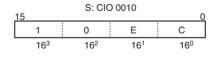
The content of S must be between 0000 to 270F hex (0000 to 9999 decimal).

## Example

The following diagram shows an example BCD-to-binary conversion.

When CIO 0000.00 is ON in the following example, the 4-digit hexadecimal value in CIO 0010 is converted to BCD and stored in D00100.



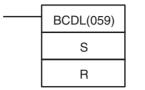


# 3-11-4 DOUBLE BINARY-TO-DOUBLE BCD: BCDL(059)

### **Purpose**

Converts 8-digit hexadecimal (32-bit binary) data to 8-digit BCD data.

## **Ladder Symbol**



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	BCDL(059)
	<b>Executed Once for Upward Differentiation</b>	@BCDL(059)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

#### S: First Source Word

The content of S+1 and S must be between 0000 0000 and 05F5 E0FF hexadecimal (0000 0000 and 9999 9999 BCD).

Note S and S+1, as well as D and D+1 must be in the same data area.

### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048	8 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

### **Description**

BCDL(059) converts the 8-digit hexadecimal (32-bit binary) data in S and S+1 to 8-digit BCD data and writes the result to R and R+1.



# Flags

Name	Label	Operation
Error Flag	ER	ON if the content of S and S+1 is not between 0000 0000 to 05F5 E0FF hexadecimal (0000 0000 to 9999 9999 decimal).
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000 0000.
		OFF in all other cases.

**Precautions** 

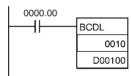
The content of S+1 and S must be between 0000 0000 to 05F5 E0FF hex (0000 0000 to 9999 9999 decimal).

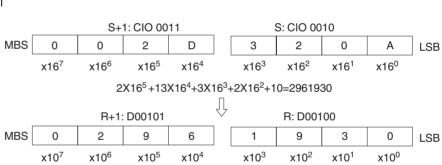
**Examples** 

The following diagram shows an example of 8-digit BCD-to-binary conversion.



When CIO 0000.00 is ON in the following example, the hexadecimal value in CIO 0011 and CIO 0010 is converted to a BCD value and stored in D00101 and D00100.



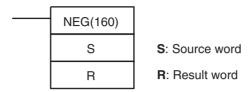


# 3-11-5 2'S COMPLEMENT: NEG(160)

**Purpose** 

Calculates the 2's complement of a word of hexadecimal data.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	NEG(160)
	Executed Once for Upward Differentiation	@NEG(160)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6143	
Work Area	W000 to W255	
Auxiliary Bit Area	A000 to A959	A448 to A959
Timer Area	T0000 to T0255	
Counter Area	C0000 to C0255	
DM Area	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 to #FFFF	
	(binary)	
Data Resisters	DR0 to DR15	
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

## **Description**

NEG(160) calculates the 2's complement of S and writes the result to R. The 2's complement calculation basically reverses the status of the bits in S and adds 1.

2's complement (Complement + 1) 
$$\overline{(S)}$$
  $\longrightarrow$  (R)

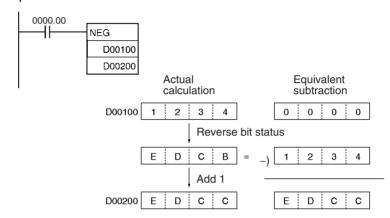
**Note** This operation (reversing the status of the bits and adding 1) is equivalent to subtracting the content of S from 0000.

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the result is 0000.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of the result is ON.
		OFF in all other cases.

Note The result for 8000 hex will be 8000 hex.

### Example

When CIO 0000.00 is ON in the following example, NEG(160) calculates the 2's complement of the content of D00100 and writes the result to D00200.

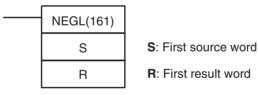


# 3-11-6 DOUBLE 2'S COMPLEMENT: NEGL(161)

### **Purpose**

Calculates the 2's complement of two words of hexadecimal data.

## **Ladder Symbol**



Variations

Variations	Executed Each Cycle for ON Condition	NEGL(161)
	Executed Once for Upward Differentiation	@NEGL(161)
	<b>Executed Once for Downward Differentiation</b>	Not supported

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	

Area	S	R
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF	
	(binary)	
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

Note S and S+1 as well as R and R+1 must be in the same data area

### **Description**

NEGL(161) calculates the 2's complement of S+1 and S and writes the result to R+1 and R. The 2's complement calculation basically reverses the status of the bits in S+1 and S and adds 1.

**Note** This operation (reversing the status of the bits and adding 1) is equivalent to subtracting the content of S+1 and S from 0000 0000.

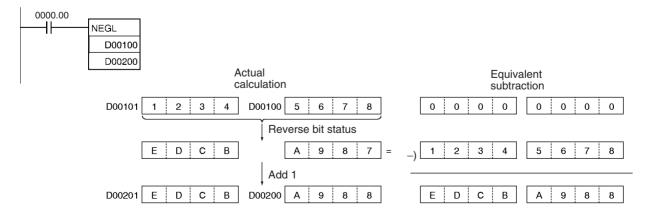
### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if the result is 0000 0000.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of R+1 is ON.
		OFF in all other cases.

**Note** The result for 8000 0000 hex will be 8000 0000 hex.

### Example

When CIO 0000.00 is ON in the following example, NEGL(161) calculates the 2's complement of the content of D00101 and D00100 and writes the result to D00201 and D00200.

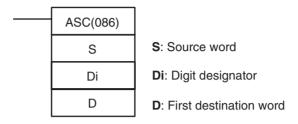


## 3-11-7 ASCII CONVERT: ASC(086)

## **Purpose**

Converts 4-bit hexadecimal digits in the source word into their 8-bit ASCII equivalents. This instruction can be used only in the Coordinator Module.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ASC(086)
	<b>Executed Once for Upward Differentiation</b>	@ASC(086)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks	
OK	OK	OK	OK	

## **Operands**

#### S: Source Word

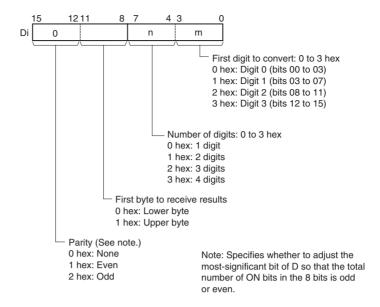
Up to four digits in the source word can be converted. The digits are numbered 0 to 3, right to left.

	15 12	211	8 7	7 4	3 (	)
S	Digit 3	Digit 2	2	Digit 1	Digit 0	1

All data starting from the first digit to be converted is taken as hexadecimal data and converted to ASCII. Digit 0 follows digit 3.

## Di: Digit Designator

The digit designator specifies various parameters for the conversion, as shown in the following diagram.



	15 8	7 0
D	Upper byte	Lower byte
D+1	Upper byte	Lower byte
D+2	Upper byte	Lower byte

ASCII characters are stored from the first byte receive the results in order to higher bytes and higher words.

Note: D and D+2 must be in the same area.

#### D: First destination word

The converted ASCII data is written to the destination word(s) beginning with the specified byte in D. Three destination words (D to D+3) will be required if 4 digits are being converted and the leftmost byte is selected as the first byte in D. The destination words must be in the same data area.

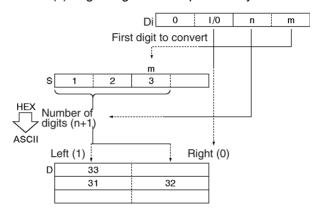
Any bytes in the destination word(s) that are not overwritten with ASCII data will be left unchanged.

Area	S	Di	D	
CIO Area	CIO 0000 to CIO 6	143		
Work Area	W000 to W255			
Auxiliary Bit Area	A000 to A959		A448 to A959	
Timer Area	T0000 to T0255			
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767			
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants		Specified values only		
Data Resisters	DR0 to DR15			

Area	S	Di	D		
Index Registers					
Indirect addressing	,IR0 to ,IR15				
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15				
	DR0 to DR15, IR0	to DR0 to DR15, IR1	15		
	,IR0+(++) to ,IR15+(++)				
	,-()IR0 to , -(	-)IR15			

#### Description

ASC(086) treats the contents of S as 4 hexadecimal digits, converts the designated digit(s) of S into their 8-bit ASCII equivalents, and writes this data into the destination word(s) beginning with the specified byte in D.



## **Parity**

It is possible to specify the parity of the ASCII data for use in error control during data transmissions. The leftmost bit of each ASCII character will be automatically adjusted for even, odd, or no parity.

When no parity (0) is designated, the leftmost bit will always be zero. When even parity (1) is designated, the leftmost bit will be adjusted so that the total number of ON bits is even. When odd parity (2) is designated, the leftmost bit of each ASCII character will be adjusted so that there is an odd number of ON bits. The status of the parity bit does not affect the meaning of the ASCII code.

#### Examples of even parity:

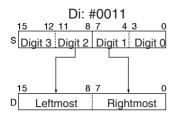
When adjusted for even parity, ASCII "31" (00110001) will be "B1" (10110001: parity bit turned ON to create an even number of ON bits); ASCII "36" (00110110) will be "36" (00110110: parity bit remains OFF because the number of ON bits is already even).

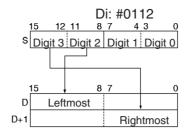
#### Examples of odd parity:

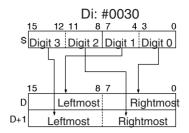
When adjusted for odd parity, ASCII "36" (00110110) will be "B6" (10110110: parity bit turned ON to create an odd number of ON bits); ASCII "46" (01000110) will be "46" (01000110: parity bit remains OFF because the number of ON bits is already odd).

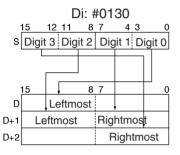
#### **Examples of Di**

When two or more digits are being converted, ASC(086) will read the bytes in S from right to left and will wrap around to the rightmost byte if necessary. The following diagram shows some example values for Di and the conversions that they produce.







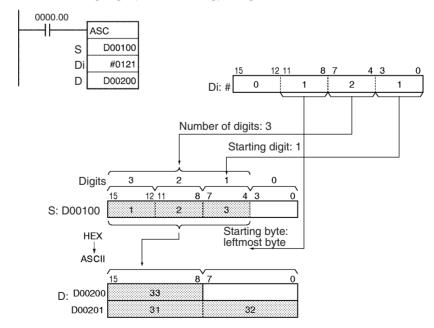


**Flags** 

Name	Label	Operation
Error Flag	ER	ON if the content of Di is not within the specified ranges.
		OFF in all other cases.

#### **Example**

When CIO 0000.00 is ON in the following example, ASC(086) converts three hexadecimal digits in D00100 (beginning with digit 1) into their ASCII equivalents and writes this data to D00200 and D00201 beginning with the leftmost byte in D00200. In this case, a digit designator of #0121 specifies no parity, the starting byte (when writing) = leftmost byte, the number of digits to read = 3, and the starting digit (when reading) = digit 1.



## **ASCII Conversion Example**

	Contents of digit being converted				Co	nver	ted (c	utpu	t) dat	а			
Value	Value		status	•	Code	(MS	B)		Bit s	tatus	;	(	LSB)
0	0	0	0	0	30 hex	*	0	1	1	0	0	0	0
1	0	0	0	1	31 hex	*	0	1	1	0	0	0	1
2	0	0	1	0	32 hex	*	0	1	1	0	0	1	0
3	0	0	1	1	33 hex	*	0	1	1	0	0	1	1
4	0	1	0	0	34 hex	*	0	1	1	0	1	0	0
5	0	1	0	1	35 hex	*	0	1	1	0	1	0	1
6	0	1	1	0	36 hex	*	0	1	1	0	1	1	0
7	0	1	1	1	37 hex	*	0	1	1	0	1	1	1
8	1	0	0	0	38 hex	*	0	1	1	1	0	0	0
9	1	0	0	1	39 hex	*	0	1	1	1	0	0	1
Α	1	0	1	0	41 hex	*	1	0	0	0	0	0	1
В	1	0	1	1	42 hex	*	1	0	0	0	0	1	0
С	1	1	0	0	43 hex	*	1	0	0	0	0	1	1
D	1	1	0	1	44 hex	*	1	0	0	0	1	0	0
Е	1	1	1	0	45 hex	*	1	0	0	0	1	0	1
F	1	1	1	1	46 hex	*	1	0	0	0	1	1	0

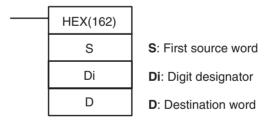
<sup>\*:</sup> Parity bit: Depends on parity designation.

# 3-11-8 ASCII TO HEX: HEX(162)

## **Purpose**

Converts up to 4 bytes of ASCII data in the source word to their hexadecimal equivalents and writes these digits in the specified destination word. This instruction can be used only in the Coordinator Module.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	HEX(162)
	Executed Once for Upward Differentiation	@HEX(162)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

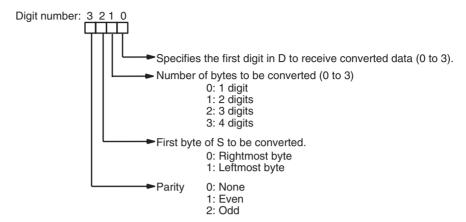
## **Operands**

#### S: First Source Word

The contents of the source words are treated as ASCII data. Up to three source words can be used. (Three source words will be required if 4 bytes are being converted and the leftmost byte is selected as the first byte in S.) The source words must be in the same data area.

## Di: Digit Designator

The digit designator specifies various parameters for the conversion, as shown in the following diagram.



#### D: Destination word

The converted hexadecimal digits are written into D from right to left, beginning with the specified first digit. Any digits in the destination word that are not overwritten with the converted data will be left unchanged.

#### **Operand Specifications**

Area	S	Di	D		
CIO Area	CIO 0000 to CIO 6143				
Work Area	W000 to W255	W000 to W255			
Auxiliary Bit Area	A000 to A959		A448 to A959		
Timer Area	T0000 to T0255		<u> </u>		
Counter Area	C0000 to C0255				
DM Area	D00000 to D32767	,			
Indirect DM addresses in binary	@ D00000 to @ D32767				
Indirect DM addresses in BCD	*D00000 to *D32767				
Constants		Specified values only			
Data Resisters		DR0 to DR15			
Index Registers					
Indirect addressing	ng ,IR0 to ,IR15				
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15				
	DR0 to DR15, IR0 to DR0 to DR15, IR15				
	,IR0+(++) to ,IR15+(++)				
	,-()IR0 to , -()IR15				

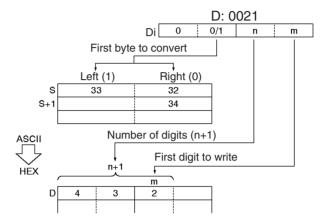
## **Description**

HEX(162) treats the contents of the source word(s) as ASCII data representing hexadecimal digits (0 to 9 and A to F), converts the specified number of bytes to hexadecimal, and writes the hexadecimal data to the destination word beginning at the specified digit.

An error will occur if the source words contain data which is not an ASCII equivalent of hexadecimal digits. The following table shows hexadecimal digits and their ASCII equivalents (excluding parity bits).

Hexadecimal digits (4 bits)	ASCII equivalent (2 hexadecimal digits)
0 to 9	30 to 39
A to F	41 to 46

The following diagram shows the basic operation of HEX(162) with Di=0021.



## **Parity**

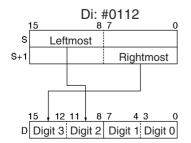
It is possible to specify the parity of the ASCII data for use in error control during data transmissions. The leftmost bit in each byte is the parity bit. With no parity the parity bit should always be zero, with even parity the status of the parity bit should result in an even number of ON bits, and with odd parity the status of the parity bit should result in an odd number of ON bits.

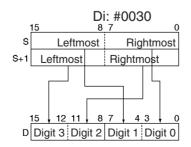
The following table shows the operation of HEX(162) for each parity setting.

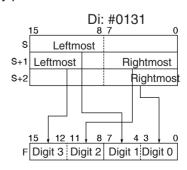
Parity setting (leftmost digit of Di)	Operation of HEX(162)
No parity (0)	HEX(162) will be executed only when the parity bit in each byte is 0. An error will occur if a parity bit is non-zero.
Even parity (1)	HEX(162) will be executed only when there is an even number of ON bits in each byte. An error will occur if a byte has an odd number of ON bits.
Odd parity (2)	HEX(162) will be executed only when there is an odd number of ON bits in each byte. An error will occur if a byte has an even number of ON bits.

## **Examples of Di**

When two or more bytes are being converted, HEX(162) will write the converted digits to the destination word from right to left and will wrap around to the rightmost digit if necessary. The following diagram shows some example values for Di and the conversions that they produce.







## **Flags**

Name	Label	Operation
Error Flag	ER	ON if there is a parity error in the ASCII data.
		ON if the ASCII data in the source words is not equivalent to hexadecimal digits
		ON if the content of Di is not within the specified ranges.
		OFF in all other cases.

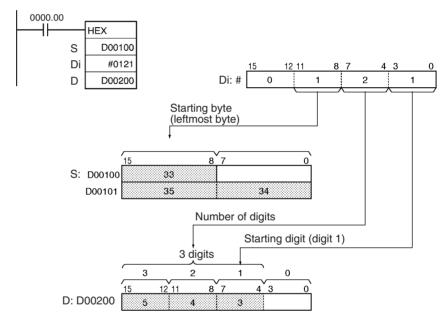
#### **Precautions**

An error will occur and the Error Flag will be turned ON if there is a parity error in the ASCII data, the ASCII data in the source words is not equivalent to hexadecimal digits, or the content of Di is not within the specified ranges.

## **Examples**

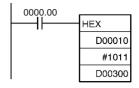
When CIO 0000.00 is ON in the following example, HEX(162) converts the ASCII data in D00100 and D00101 according to the settings of the digit designator. (Di=#0121 specifies no parity, the starting byte (when reading) = leftmost byte, the number of bytes to read = 3, and the starting digit (when writing) = digit 1.)

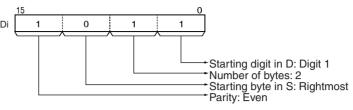
HEX(162) converts three bytes of ASCII data (3 characters) beginning with the leftmost byte of D00100 into their hexadecimal equivalents and writes this data to D00200 beginning with digit 1.

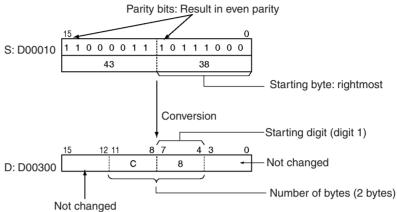


When CIO 0000.00 is ON in the following example, HEX(162) converts the ASCII data in D00010 beginning with the rightmost byte and writes the hexadecimal equivalents in D00300 beginning with digit 1.

The digit designator setting of #1011 specifies even parity, the starting byte (when reading) = rightmost byte, the number of bytes to read = 2, and the starting digit (when writing) = digit 1.)





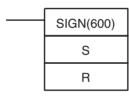


## 3-11-9 16-BIT TO 32-BIT SIGNED BINARY: SIGN(600)

**Purpose** 

Expands a 16-bit signed binary value to its 32-bit equivalent.

**Ladder Symbol** 



S: Source word

R: First result word

**Variations** 

Variations	Executed Each Cycle for ON Condition	SIGN(600)
	<b>Executed Once for Upward Differentiation</b>	@SIGN(600)
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	S	R
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6142
Work Area	W000 to W255	W000 to W254
Auxiliary Bit Area	A000 to A959	A448 to A958
Timer Area	T0000 to T0255	T0000 to T0254
Counter Area	C0000 to C0255	C0000 to C0254
DM Area	D00000 to D32767	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	

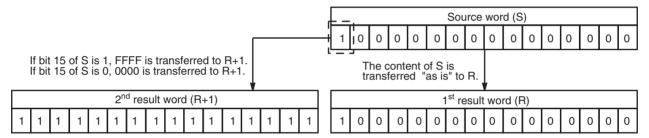
Area	S	R	
Constants	#0000 to #FFFF		
	(binary)		
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15		

**Note** R and R+1 must be in the same data area.

## **Description**

SIGN(600) converts the 16-bit signed binary number in S to its 32-bit signed binary equivalent and writes the result in R+1 and R.

The conversion is accomplished by copying the content of S to R and writing FFFF to R+1 if bit 15 of S is 1 or writing 0000 to R+1 if bit 15 of S is 0.

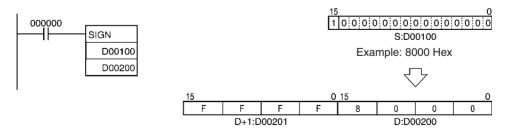


## **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON if the result is 0000 0000.	
		OFF in all other cases.	
Negative Flag	N	ON if bit 15 of R+1 is ON.	
		OFF in all other cases.	

## **Example**

When CIO 000000 is ON in the following example, SIGN(600) converts the 16-bit signed binary content of D00100 (#8000 = -32,768 decimal) to its 32-bit equivalent (#FFFF 8000 = -32,768 decimal) and writes that result to D00201 and D00200.



# 3-12 Logic Instructions

Logic Instructions

This section describes instructions which perform logic operations on word data.

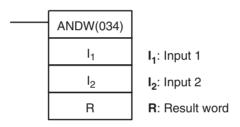
Instruction	Mnemonic	Function code	Page
LOGICAL AND	ANDW	034	351
DOUBLE LOGICAL AND	ANDL	610	353
LOGICAL OR	ORW	035	354
DOUBLE LOGICAL OR	ORWL	611	356
EXCLUSIVE OR	XORW	036	358
DOUBLE EXCLUSIVE OR	XORL	612	360
EXCLUSIVE NOR	XNRW	037	362
DOUBLE EXCLUSIVE NOR	XNRL	613	363
COMPLEMENT	COM	029	365
DOUBLE COMPLEMENT	COML	614	366

# 3-12-1 LOGICAL AND: ANDW(034)

**Purpose** 

Takes the logical AND of corresponding bits in single words of word data and/ or constants.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	ANDW(034)
	Executed Once for Upward Differentiation	@ANDW(034)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	I <sub>1</sub>	l <sub>2</sub>	R	
CIO Area	CIO 0000 to CIO 6	143		
Work Area	W000 to W255			
Auxiliary Bit Area	A000 to A959		A448 to A959	
Timer Area	T0000 to T0255			
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D3276	37		
Constants	#0000 to #FFFF			
	(binary)			

Area	l <sub>1</sub>	l <sub>2</sub>	R	
Data Resisters	DR0 to DR15			
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -(	-)IR15		

## **Description**

ANDW(034) takes the logical AND of data specified in  $\rm I_1$  and  $\rm I_2$  and outputs the result to R.

- The logical AND is taken of corresponding bits in I<sub>1</sub> and I<sub>2</sub> in succession.
- When the contents of corresponding bits in both I<sub>1</sub> and I<sub>2</sub> are 1, a 1 will be output to the corresponding bit in R. When one or more bits is 0, a 0 will be output to the corresponding bit in R.

 $I_1, I_2 \rightarrow R$ 

I <sub>1</sub>	l <sub>2</sub>	R
1	1	1
1	0	0
0	1	0
0	0	0

#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0000 hex.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of R is 1.
		OFF in all other cases.

#### **Precautions**

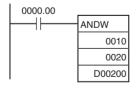
When ANDW(034) is executed, the Error Flag will turn OFF.

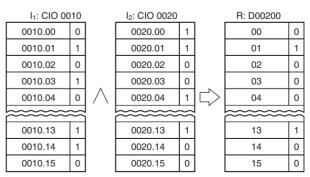
If as a result of the AND, the content of R is 0000 hex, the Equals Flag will turn ON.

If as a result of the AND, the leftmost bit of R is 1, the Negative Flag will turn  $\ensuremath{\mathsf{ON}}$ 

#### **Examples**

When the execution condition CIO 0000.00 is ON, the logical AND will be taken of corresponding bits in CIO 0010 and CIO 0020, and the results will be output to corresponding bits in D00200.





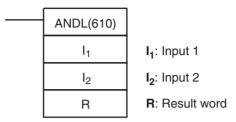
Note: The vertical arrow indicates logical AND.

# 3-12-2 DOUBLE LOGICAL AND: ANDL(610)

## **Purpose**

Takes the logical AND of corresponding bits in double words of word data and/ or constants.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	ANDL(610)
	Executed Once for Upward Differentiation	@ANDL(610)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	I <sub>1</sub>	l <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D327	66	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #I	FFFF FFFF	
	(binary)		
Data Resisters			•
Index Registers			
Indirect addressing using	,IR0 to ,IR15		
Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(-	– –)IR15	

## **Description**

ANDL(610) takes the logical AND of data specified in  $I_1$ ,  $I_1+1$  and  $I_2$ ,  $I_2+1$  and outputs the result to R, R+1.

## $(I_{1,}\,I_{1}{+}1),\,(I_{2,}\,I_{2}{+}1)\rightarrow (R,\,R{+}1)$

I <sub>1,</sub> I <sub>1</sub> +1	l <sub>2,</sub> l <sub>2</sub> +1	R, R+1
1	1	1
1	0	0
0	1	0
0	0	0

## **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 0000 hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of R+1 is 1.	
		OFF in all other cases.	

#### **Precautions**

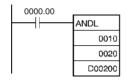
When ANDL(610) is executed, the Error Flag will turn OFF.

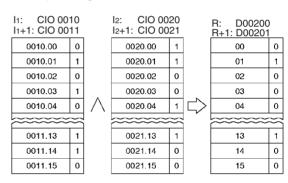
If as a result of the AND, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the AND, the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

## **Examples**

When the execution condition CIO 0000.00 is ON, the logical AND will be taken of corresponding bits in CIO 0011, CIO 0010 and CIO 0021, CIO 0020 and the results will be output to corresponding bits in D00201 and D00200.





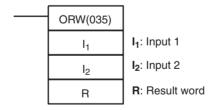
Note: The vertical arrow indicates logical AND.

# 3-12-3 LOGICAL OR: ORW(035)

## **Purpose**

Takes the logical OR of corresponding bits in single words of word data and/or constants.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ORW(035)
	Executed Once for Upward Differentiation	@ORW(035)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	I <sub>1</sub>	l <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6143		
Work Area		W000 to W255	
Auxiliary Bit Area	A000 t	o A959	A448 to A959
Timer Area		T0000 to T0255	
Counter Area		C0000 to C0255	
DM Area		D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767		67
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF		
	(bin	ary)	
Data Resisters		DR0 to DR15	
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,–(	()IR0 to , -()IR	15

## **Description**

ORW(035) takes the logical OR of data specified in  $\rm I_1$  and  $\rm I_2$  and outputs the result to R.

- ullet The logical OR is taken of corresponding bits in  $I_1$  and  $I_2$  in succession.
- When either one of the corresponding bits in I<sub>1</sub> and I<sub>2</sub> is 1, a 1 will be output to the corresponding bit in R. When both of them are 0, a 0 will be output to the corresponding bit in R.

 $I_1 + I_2 \rightarrow R$ 

l <sub>1</sub>	l <sub>2</sub>	R
1	1	1
1	0	1
0	1	1
0	0	0

## **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0000 hex.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of R is 1.
		OFF in all other cases.

## **Precautions**

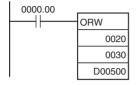
When ORW(035) is executed, the Error Flag will turn OFF.

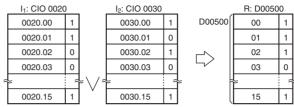
If as a result of the OR, the content of R is 0000 hex, the Equals Flag will turn ON.

If as a result of the OR, the leftmost bit of R is 1, the Negative Flag will turn ON.

## **Examples**

When the execution condition CIO 0000.00 is ON, the logical OR will be taken of corresponding bits in CIO 0020 and CIO 0030, and the results will be output to corresponding bits in D00500.





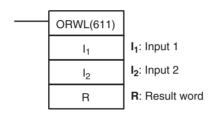
Note: The vertical arrow indicates logical OR.

# 3-12-4 DOUBLE LOGICAL OR: ORWL(611)

## **Purpose**

Takes the logical OR of corresponding bits in double words of word data and/ or constants.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ORWL(611)
	Executed Once for Upward Differentiation	@ORWL(611)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	I <sub>1</sub>	l <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6	142	
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D3276	<b>3</b> 7	
Constants	#0000 0000 to #FF	FF FFFF	
	(binary)		
Data Resisters			

Area	I <sub>1</sub>	l <sub>2</sub>	R
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR	10 to -2048 to +2047	7 ,IR15
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

## **Description**

ORWL(611) takes the logical OR of data specified in  $I_1$ ,  $I_1+1$  and  $I_2$ ,  $I_2+1$  as double-word data and outputs the result to R, R+1.

When any of the corresponding bits in I<sub>1</sub>, I<sub>1+1</sub>, I<sub>2</sub>, and I<sub>2+1</sub> are 1, a 1 will be output to the corresponding bit in R, R+1. When both of them are 0, a 0 will be output to the corresponding bit in R, R+1.

 $(I_1, I_1+1) + (I_2, I_2+1) \rightarrow (R, R+1)$ 

l <sub>1,</sub> l <sub>1</sub> +1	l <sub>2,</sub> l <sub>2</sub> +1	R, R+1
1	1	1
1	0	1
0	1	1
0	0	0

## **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 0000 hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of R is 1.	
		OFF in all other cases.	

## **Precautions**

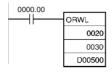
When ORWL(611) is executed, the Error Flag will turn OFF.

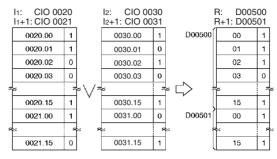
If as a result of the OR, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the OR, the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

## **Examples**

When the execution condition CIO 0000.00 is ON, the logical OR will be taken of corresponding bits in CIO 0021, CIO 0020 and CIO 0031, CIO 0030 and the results will be output to corresponding bits in D00501 and D00500.





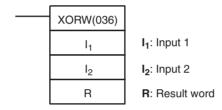
Note: The vertical arrow indicates logical OR.

# 3-12-5 **EXCLUSIVE OR: XORW(036)**

## **Purpose**

Takes the logical exclusive OR of corresponding bits in single words of word data and/or constants.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	XORW(036)
	Executed Once for Upward Differentiation	@XORW(036)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	I <sub>1</sub>	l <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6	143	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D3276	37	
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		

Area	l <sub>1</sub>	l <sub>2</sub>	R
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

## **Description**

XORW(036) takes the logical exclusive OR of data specified in  $\rm I_1$  and  $\rm I_2$  and outputs the result to R.

- The logical exclusive OR is taken of corresponding bits in I<sub>1</sub> and I<sub>2</sub> in succession.
- When the contents of corresponding bits of I<sub>1</sub> and I<sub>2</sub> are different, a 1 will be output to the corresponding bit of R and when they are the same, 0 will be output to the corresponding bit in R.

 $I_1, \overline{I_2} + \overline{I_1}, I_2 \rightarrow R$ 

-,, -		
l <sub>1</sub>	l <sub>2</sub>	R
1	1	0
1	0	1
0	1	1
0	0	0

## **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0000.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of R is 1.
		OFF in all other cases.

#### **Precautions**

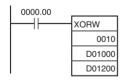
When XORW(036) is executed, the Error Flag will turn OFF.

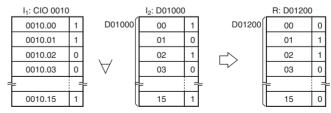
If as a result of the OR, the content of R is 0000 hex, the Equals Flag will turn ON.

If as a result of the OR, the leftmost bit of R is 1, the Negative Flag will turn ON.

## **Examples**

When the execution condition CIO 0000.00 is ON, the logical exclusive OR will be taken of corresponding bits in CIO 0010 and D01000, and the results will be output to corresponding bits in D01200.





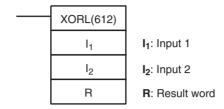
Note: The symbol indicates logical exclusive OR.

# 3-12-6 DOUBLE EXCLUSIVE OR: XORL(612)

## **Purpose**

Takes the logical exclusive OR of corresponding bits in double words of word data and/or constants.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	XORL(612)
	Executed Once for Upward Differentiation	@XORL(612)
	Executed Once for Downward Differentiation	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	I <sub>1</sub>	l <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766	3	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
DR0 to DR15, IR0 to DR0 to DR15, IR15			15
,IR0+(++) to ,IR15+(++)			
	,-()IR0  to ,-()IR15		

## **Description**

XORL(612) takes the logical exclusive OR of data specified in  $I_1$ ,  $I_1+1$  and  $I_2$ ,  $I_2+1$  as double-word data and outputs the result to R, R+1.

When the contents of any of the corresponding bits in I<sub>1</sub>, I<sub>1</sub>+1, I<sub>2</sub>, and I<sub>2</sub>+1 are different, a 1 will be output to the corresponding bit it R, R+1. When both of them are the same, a 0 will be output to the corresponding bit in R, R+1.

 $(I_1, I_1+1), (\overline{I_2, I_2+1}) + \overline{(I_1, I_1+1)}, (I_2, I_2+1) \rightarrow (R, R+1)$ 

I <sub>1,</sub> I <sub>1</sub> +1	l <sub>2,</sub> l <sub>2</sub> +1	R, R+1
1	1	0
1	0	1
0	1	1
0	0	0

## **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0000 0000 hex.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of R is 1.
		OFF in all other cases.

#### **Precautions**

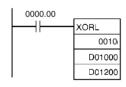
When XORL(612) is executed, the Error Flag will turn OFF.

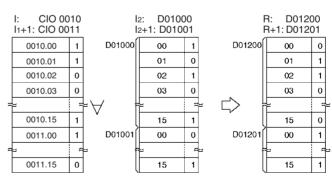
If as a result of the exclusive OR, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the exclusive OR, the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

## **Examples**

When the execution condition CIO 0000.00 is ON, the logical exclusive OR will be taken of corresponding bits in CIO 0011, CIO 0010 and D01001, D01000 and the results will be output to corresponding bits in D01201 and D01200.





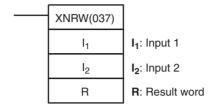
Note: The symbol indicates logical exclusive OR.

# 3-12-7 EXCLUSIVE NOR: XNRW(037)

## **Purpose**

Takes the logical exclusive NOR of corresponding single words of word data and/or constants.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	XNRW(037)
	Executed Once for Upward Differentiation	@XNRW(037)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	I <sub>1</sub>	l <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF		
	(binary)		
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

XNRW(037) takes the logical exclusive NOR of data specified in  $\rm I_1$  and  $\rm I_2$  and outputs the result to R.

 The logical exclusive NOR is taken of corresponding bits in I<sub>1</sub> and I<sub>2</sub> in succession.

 When the contents of corresponding bits of I<sub>1</sub> and I<sub>2</sub> are different, a 0 will be output to the corresponding bit of R and when they are the same, 1 will be output to the corresponding bit in R.

 $I_1, I_2 + \overline{I_1}, \overline{I_2} \rightarrow R$ 

-,, -		
I <sub>1</sub>	l <sub>2</sub>	R
1	1	1
1	0	0
0	1	0
0	0	1

#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0000 hex.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of R is 1.
		OFF in all other cases.

#### **Precautions**

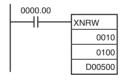
When XNRW(037) is executed, the Error Flag will turn OFF.

If as a result of the NOR, the content of R is 0000 hex, the Equals Flag will turn ON.

If as a result of the NOR, the leftmost bit of R is 1, the Negative Flag will turn ON.

## **Examples**

When the execution condition CIO 0000.00 is ON, the logical exclusive NOR will be taken of corresponding bits in CIO 0010 and CIO 0100, and the results will be output to corresponding bits in D00500.





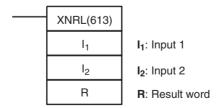
Note: The symbol indicates logical exclusive NOR.

# 3-12-8 DOUBLE EXCLUSIVE NOR: XNRL(613)

#### **Purpose**

Takes the logical exclusive NOR of corresponding bits in double words of word data and/or constants.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	XNRL(613)
	Executed Once for Upward Differentiation	@XNRL(613)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	l <sub>1</sub>	l <sub>2</sub>	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 toW254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FF	FF FFFF	
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing ,IR0 to ,IR15			
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
,–(– –)IR0 to , –(– –)IR15			

## **Description**

XNRL(613) takes the logical exclusive NOR of data specified in  $I_1$ ,  $I_1+1$  and  $I_2$ ,  $I_2+1$  and outputs the result to R, R+1.

• When the contents of any of the corresponding bits in I<sub>1</sub>, I<sub>1</sub>+1, I<sub>2</sub>, and I<sub>2</sub>+1 are different, a 0 will be output to the corresponding bit in R, R+1. When both of them are the same, a 1 will be output to the corresponding bit in R, R+1.

 $(I_1,I_1+1),(I_2,I_2+1)+\overline{(I_1,I_1+1)},\overline{(I_2,I_2+1)}\to (R,R+1)$ 

I <sub>1,</sub> I <sub>1</sub> +1	l <sub>2,</sub> l <sub>2</sub> +1	R, R+1
1	1	1
1	0	0
0	1	0
0	0	1

#### **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 0000 hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of R+1 is 1.	
		OFF in all other cases.	

#### **Precautions**

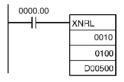
When XNRL(613) is executed, the Error Flag will turn OFF.

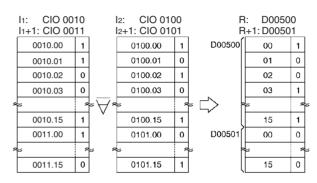
If as a result of the exclusive NOR, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of the exclusive NOR, the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

#### **Examples**

When the execution condition CIO 0000.00 is ON, the logical exclusive NOR will be taken of corresponding bits in CIO 0011, CIO 0010, and CIO 0101, CIO 0100 and the results will be output to corresponding bits in D00501 and D00500.





Note: The symbol indicates logical exclusive NOR.

# 3-12-9 COMPLEMENT: COM(029)

**Purpose** 

Turns OFF all ON bits and turns ON all OFF bits in Wd.

**Ladder Symbol** 



## **Variations**

Variations	<b>Executed Each Cycle for ON Condition</b>	COM(029)
	<b>Executed Once for Upward Differentiation</b>	@COM(029)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

Area	Wd
CIO Area	CIO 0000 to CIO 6143
Work Area	W000 to W255
Auxiliary Bit Area	A448 to A959
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
DM Area	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	DR0 to DR15

Section 3-12 Logic Instructions

Area	Wd
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to $,-()IR15$

**Description** 

COM(029) reverses the status of every bit in the specified word.

 $\overline{\text{Wd}} \rightarrow \text{Wd}$ : 1  $\rightarrow$  0 and 0  $\rightarrow$  1

Note When using the COM instruction, be aware that the status of each bit will change each cycle in which the execution condition is ON.

**Flags** 

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON when the result is 0000 hex.	
		OFF in all other cases.	
Negative Flag	N	ON when the leftmost bit of R is 1.	
		OFF in all other cases.	

**Precautions** 

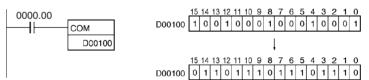
When COM(029) is executed, the Error Flag will turn OFF.

If as a result of COM, the content of R is 0000 hex, the Equals Flag will turn ON.

If as a result of COM, the leftmost bit of R is 1, the Negative Flag will turn ON.

**Examples** 

When CIO 0000.00 is ON in the following example, the status of each bit in D00100 will be reversed.



# 3-12-10 DOUBLE COMPLEMENT: COML(614)

**Purpose** 

Turns OFF all ON bits and turns ON all OFF bits in Wd and Wd+1.

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	COML(614)
	Executed Once for Upward Differentiation @ COML(61	
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Wd
CIO Area	CIO 0000 to CIO 6142
Work Area	W000 to W254
Auxiliary Bit Area	A448 to A958
Timer Area	T0000 to T0254
Counter Area	C0000 to C0254
DM Area	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767
Indirect DM addresses in BCD	*D00000 to *D32767
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

## **Description**

COML(614) reverses the status of every bit in Wd and Wd+1.  $\overline{(Wd+1, Wd)} \rightarrow (Wd+1, Wd)$ 

**Note** When using the COML instruction, be aware that the status of each bit will change each cycle in which the execution condition is ON.

#### **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON when the result is 0000 0000 hex.
		OFF in all other cases.
Negative Flag	N	ON when the leftmost bit of R+1 is 1.
		OFF in all other cases.

## **Precautions**

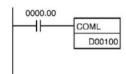
When COML(614) is executed, the Error Flag will turn OFF.

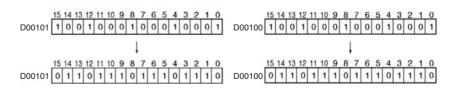
If as a result of COML, the content of R, R+1 is 0000 0000 hex, the Equals Flag will turn ON.

If as a result of COML, the leftmost bit of R+1 is 1, the Negative Flag will turn ON.

## **Examples**

When CIO 0000.00 is ON in the following example, the status of each bit in D00100 and D00101 will be reversed.





Special Math Instructions Section 3-13

# 3-13 Special Math Instructions

This section describes instructions used for special math calculations.

Instruction	Mnemonic	Function code	Page
ARITHMETIC PROCESS	APR	069	368
BIT COUNTER	BCNT	067	375
VIRTUAL AXIS	AXIS	981	376

# 3-13-1 ARITHMETIC PROCESS: APR(069)

## **Purpose**

Calculates the linear extrapolation of the source data (16-bit or 32-bit binary). The linear extrapolation function allows any relationship between X and Y to be approximated with line segments.

The high-speed counter PV can be used directly as input data.

With the Motion Control Modules, the linear extrapolation data table can be transferred to the high-speed buffer so the linear extrapolation calculations can be processed at high speed.

## **Ladder Symbol**



- T: First word of linear extrapolation data table
- S: Source data
- R: Result word

## **Variations**

Variations	Executed Each Cycle for ON Condition	APR(069)
	Executed Once for Upward Differentiation	@APR(069)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

Operand	Value	Data range
Т	Data area address	(See note.)
S	16-bit unsigned binary data	0000 to 65,535
	16-bit signed binary data	-32,768 to 32,767
	32-bit signed binary data	-2,147,483,648 to 2,147,483,647
R	32-bit unsigned binary data	00000000 to 4,294,967,295
	16-bit signed binary data	-32,768 to 32,767
	32-bit signed binary data	-2,147,483,648 to 2,147,483,647

**Note** T is the first word of the range containing the linear extrapolation data table (binary).

Area	Т	S	R
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959

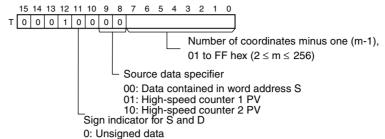
Area	Т	S	R
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	Specified values or	nly	
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

# Operand Description (Table Words)

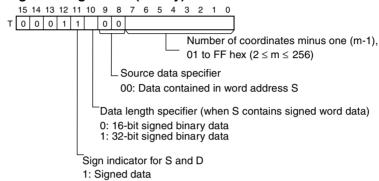
The following diagrams show the structure of the linear extrapolation data table for the various data formats.

Special Math Instructions Section 3-13

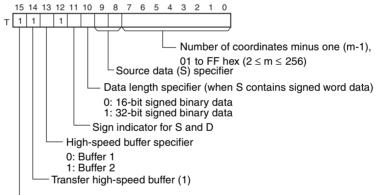
## **Unsigned Integer Data (Binary)**



## **Signed Integer Data (Binary)**

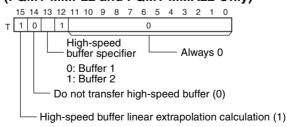


# High-speed Buffer Transfer of Extrapolation Table (FQM1-MMP22 and FQM1-MMA22 Only)



High-speed buffer linear extrapolation calculation

# High-speed Buffer Linear Extrapolation Calculation (FQM1-MMP22 and FQM1-MMA22 Only)

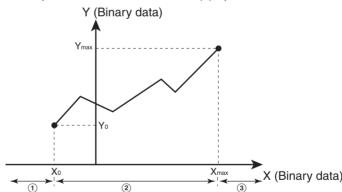


Unsigned integer data	16-k	oit signed binary d	ata 3	32-bit signed binary data
T+1 Xm (Max. X value)	T+1	X0	T+1	X0 (rightmost 16 bits)
T+2 Y0 (rightmost 16 bits)	T+2	Y0	T+2	X0 (leftmost 16 bits)
T+3 Y0 (leftmost 16 bits)	T+3	X1	T+3	Y0 (rightmost 16 bits)
T+4 X1 (16 bits)	T+4	Y1	T+4	Y0 (leftmost 16 bits)
T+5 Y1 (rightmost 16 bits)	T+5	X2	T+5	X1 (rightmost 16 bits)
T+6 Y1 (leftmost 16 bits)	T+6	Y2	T+6	X1 (rightmost 16 bits)
to to		to	T+7	Y1 (rightmost 16 bits)
T+ (3m+1) Xm (Max. X value)	T+ (2n+1)	Xn		Y0 (leftmost 16 bits)
T+ (3m+2) Ym (rightmost 16 bits)	T+ (2n+2)	Yn	to	to
T+ (3m+3) Ym (rightmost 16 bits)	to	to	T+ (4n+1)	Xn (rightmost 16_bits)
	T+ (2 <b>†0</b> +1)	Xm	1	Xn (leftmost 16 bits)
	T+ (2m+2)	Ym	T+ (4n+3)	Yn (rightmost 16 bits)
			T+ (4n+4)	Yn (leftmost 16 bits)
			to	to
			T+ (4m+1)	Xm (rightmost 16_bits)
			T+ (4m+2)	Xm (leftmost 16 bits)
				Ym (rightmost 16_bits)
				Ym (leftmost 16 bits)

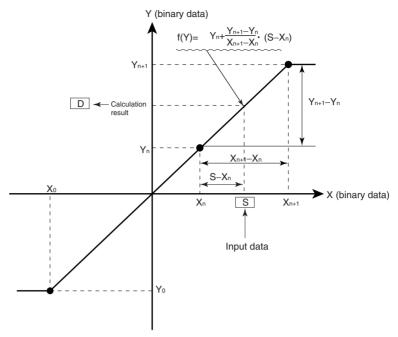
**Note** The X coordinates must be in ascending order:  $X_1 < X_2 < ... < X_m$ . Input all values of  $(X_n, Y_n)$  as binary data, regardless of the data format specified in control word T.

# Description of the Linear Extrapolation Function

APR(069) processes the input data specified in S with the following equation and the line-segment data  $(X_n, Y_n)$  specified in the table beginning at T+1. The result is output to the destination word(s) specified with D.



- For S < X<sub>0</sub>
   Converted value = Y<sub>0</sub>
- $\begin{array}{ll} \text{2.} & \text{For } X_0 \leq S \leq X_{max}, \text{ if } X_n < S < X_{n+1} \\ & \text{Converted value} = Y_n + [\{Y_n + 1 Y_n\}/\{X_n + 1 X_n\}] \times [\textit{Input data } S X_n\} \\ \end{array}$



3. X<sub>max</sub> < S Converted value = Y<sub>max</sub>

Up to 256 endpoints can be stored in the line-segment data table beginning at T+1. The following 3 kinds of I/O data can be used:

- 16-bit unsigned binary input data/32-bit unsigned binary output data
- 16-bit signed binary I/O data
- 32-bit signed binary I/O data

**Flags** 

Name	Label	Operation
Error Flag	ER	ON if the X coordinates in the table starting at T are not in ascending order $(X_1 \le X_2 \le \le X_m)$ .
		ON if bits 9 and 8 of T are not 00, 01 or 10.
		ON if there is an error in the linear extrapolation data table starting at T.
		ON if the linear extrapolation calculation's source data is not within the defined graph.
		ON if APR(069) is being used in a Coordinator Module and the source data is set to high-speed counter data.
		ON if APR(069) is being used in a Coordinator Module and high-speed buffer linear extrapolation is selected.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of D is ON.
		OFF in all other cases.

 An error will occur and the ER Flag will be turned ON if the X coordinates are not in ascending order (X<sub>1</sub> < X<sub>2</sub> < ... < X<sub>m</sub>). • The Equals Flag will be turned ON if the calculation result in D or D and D+1 is 0, as shown in the following table.)

Data format	Content of D (or
Unsigned 16-bit data	0000 0000 hex
Signed 16-bit data	0000 hex
Signed 32-bit data	0000 0000 hex

• The N Flag will be turned ON if the most significant bit of the calculation result (D or D and D+1) is 1.

#### **Examples**

## **Linear Extrapolation Using 16-bit Unsigned Binary Data**

APR(069) processes the input data specified in S based on the control data in T and the line-segment data specified in the table beginning at T+1. The result is output to D.

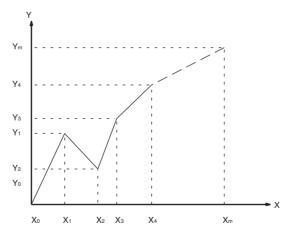
The following table shows the control data in T.

Bit	Setting name	Setting
15	High-speed buffer calculation specifier	0: Normal 1: High-speed buffer
14	Linear approximation data table to high-speed buffer transfer	0: Do not transfer 1: Transfer
13	High-speed buffer specifier (See note.)	0: Buffer 1 1: Buffer 2
12		1
08 to 11		0000
00 to 07	m-1 (m is the number of coordinates.)	

Note Bit 13 determines the processing of source data S.

When bit 13 is 0, the source data in S is used as the input data.

When bit 13 is 1, the source data is subtracted from the maximum X value and that result  $(X_m-S)$  is used as the input data. Use this method when the extrapolation data table is based on the Y-axis instead of the X-axis.

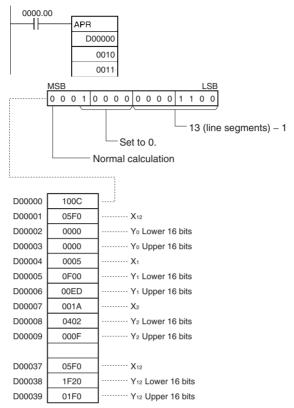


Word	Coordinate
T+1	Xm (max. X value)
T+2	Y <sub>0</sub> (rightmost 16 bits)
T+3	Y <sub>0</sub> (leftmost 16 bits)
T+4	X <sub>1</sub>
T+5	Y <sub>1</sub> (rightmost 16 bits)
T+6	Y <sub>1</sub> (leftmost 16 bits)
$\downarrow$	↓
T+(3m+1)	X <sub>m</sub>
T+(3m+2)	Y <sub>m</sub> (rightmost 16 bits)
T+(3m+3)	Y <sub>m</sub> (leftmost 16 bits)

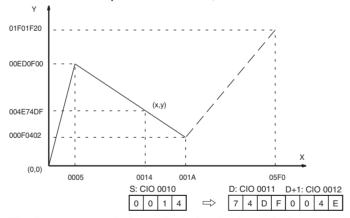
- $Y_n = f(X_n), Y_0 = f(X_0)$
- Be sure that  $X_{n-1} < X_n$  in all cases.
- Input all values of (X<sub>n</sub>, Y<sub>n</sub>) as binary data.

This example shows how to construct a linear extrapolation with 12 coordinates. The block of data is continuous, as it must be, from D00000 to D0039 (T to T +  $(3 \times 12 + 3)$ ). The input data is taken from CIO 0010, and the result is output to CIO 0011 and CIO 0011.

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In this case, the source word, CIO 0010, contains 0014, and f(0014) = 004E74DF is output to D and D+1, CIO 0011 and CIO 0011.



The linear-extrapolation calculation is shown below.

$$Y = 00ED0F00 + \frac{000F0402 - 00ED0F00}{001A - 0005} \times (0014 - 0005)$$

$$= 00ED0F00 - (A92CF \times 000F)$$

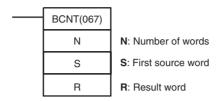
$$= 004E74DF \qquad Values are all hexadecimal (Hex).$$

# 3-13-2 BIT COUNTER: BCNT(067)

## **Purpose**

Counts the total number of ON bits in the specified word(s).

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	BCNT(067)
	Executed Once for Upward Differentiation	@BCNT(067)
	Executed Once for Downward Differentiation	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

## N: Number of words

The number of words must be 0001 to FFFF (1 to 65,535 words).

#### S: First source word

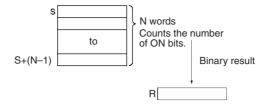
S and S+(N-1) must be in the same data area.

## **Operand Specifications**

Area	N	S	R
CIO Area	CIO 0000 to CIO 6	143	
Work Area	W000 to W255		
Auxiliary Bit Area	A000 to A959		A448 to A959
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0001 to #FFFF (binary) or &1 to &65,535		
Data Resisters	DR0 to DR15		DR0 to DR15
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to ,-()IR15		

## **Description**

BCNT(067) counts the total number of bits that are ON in all words between S and S+(N-1) and places the result in R.



## **Flags**

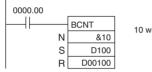
Name	Label	Operation
Error Flag	ER	ON if N is 0000.
		ON if result exceeds FFFF.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000.
		OFF in all other cases.

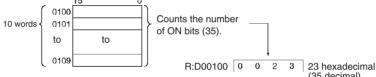
#### **Precautions**

An error will occur if N=0000 or the result exceeds FFFF.

#### **Example**

When CIO 0000.00 is ON in the following example, BCNT(067) counts the total number of ON bits in the 10 words from CIO 0100 through CIO 0109 and writes the result to D00100.





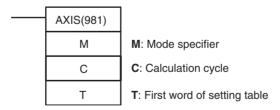
## 3-13-3 VIRTUAL AXIS: AXIS(981)

#### **Purpose**

Generates a virtual pulse output with trapezoidal acceleration/deceleration.

The operands for AXIS(981) are a target position specified in pulses or as an absolute position, and a target speed specified in pulses/s (Hz). While the input condition is ON, AXIS(981) internally generates the specified number of pulses and integrates (counts) the number of pulses (area) in the trapezoid.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	AXIS(981)
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

#### M: Mode specifier

#0000: Relative mode #0001: Absolute mode

#### C: Calculation cycle

#0000: 2 ms calculation cycle #0001: 1 ms calculation cycle #0002: 0.5 ms calculation cycle

#0003: 3 ms calculation cycle (Can be selected in unit version 3.2 or later.) #0004: 4 ms calculation cycle (Can be selected in unit version 3.2 or later.)

#### T: First Word of Setting Table

Address		Name	Description	Setting range	Set/ monitored
T T+1		Internal pulse count (8-digit hexadecimal)	The present value of internal pulse counter is stored here.	Relative mode: 0000 0000 to FFFF FFFF Absolute mode: 8000 0000 to 7FFF FFFF	Monitored (Read)
T+2	Bit 15	Virtual pulse output status	Indicates whether or not the virtual pulse output has started.	OFF: Pulse output stopped ON: Pulse being output	
	Bit 08		Indicates the direction of virtual pulse currently being output.	OFF: CW ON: CCW	
	Bit 07		Indicates whether or not the virtual pulse output is being counted internally.	OFF: Pulse being counted ON: Target position reached (Counting stopped)	
	Bit 01		Indicates whether the virtual pulse output is accelerating or decelerating. The status of bit 01 can be logically ANDed with bit 00 to determine the status. For example, if bit 00 = 1 and bit 01 = 0, the virtual pulse output is accelerating.	OFF: Accelerating or constant speed ON: Decelerating Note: This function is supported only in CPU Units with unit version 3.2 or later.	
	Bit 00		Indicates whether or not the virtual pulse output is accelerating/decelerating.	OFF: Constant speed ON: Accelerating/decelerating	
T+3 to	T+4	Present speed (8-digit hexadecimal)	The frequency of the virtual pulse output is stored here.	0000 0000 to 000F 4240 hex (0 to 1 MHz in 1-Hz units)	
T+5 to T+6		Target position (8-digit hexadecimal)	Set the number of virtual output pulses here.	Relative mode: 0000 0000 to FFFF FFFF Absolute mode: 8000 0000 to 7FFF FFFF	Set (Read/ Write)
T+7 to T+8		Target frequency (8-digit hexadecimal)	Set the target frequency of virtual pulses here.	0000 0001 to 000F 4240 hex (1 to 1 MHz in 1-Hz units)	
T+9 to T+10		Starting frequency (8-digit hexadecimal)	Set the starting frequency of virtual pulses here.	0000 0000 to 000F 4240 hex (0 to 1 MHz in 1-Hz units)	
T+11		Acceleration rate (4-digit hexadecimal)	Set the acceleration rate of virtual pulses here.	0001 to 270F (1 to 9,999 Hz, in 1-Hz units)	
T+12		Deceleration rate (4-digit hexadecimal)	Set the deceleration rate of virtual pulses here.	0001 to 270F (1 to 9,999 Hz, in 1-Hz units)	
T+13	to T+26	Work area	Used by the system.		

#### **Description**

Use the AXIS instruction with an input condition that is ON for one cycle.
 AXIS cannot be used as a differentiated instruction (the @ prefix is not supported).

Special Math Instructions Section 3-13

 AXIS is executed at the rising edge of the input condition. If the input remains ON, the virtual pulse output continues until the target position is reached. Once the target position is reached, the virtual pulse output is stopped. If the input condition goes OFF during the virtual pulse output, the output stops at that point.

- The AXIS instruction's mode specifier operand (M) specifies whether the virtual pulse output operates in relative or absolute mode.
  - In relative mode, the internal pulse counter initializes the internal pulse count to 0 when AXIS is executed and starts incrementing from 0.
  - In absolute mode, the internal pulse counter retains the internal pulse count when AXIS is executed and starts incrementing or decrementing from that existing pulse count.
- The internal pulse counts are refreshed every cycle at the interval specified in the calculation cycle (4 ms, 3 ms, 2 ms, 1 ms, or 0.5 ms) with a constant execution cycle. If the specified calculation cycle time does not match the execution cycle time, the time difference between the cycles can cause an error in the count. If highly accurate pulse counts are required, use the constant cycle time function and match the execution cycle time and calculation cycle time. (Set the constant cycle time in the System Setup's Cycle Time Tab Page.)
- When AXIS is being used, the virtual axis operates in the following manner.
  - a) AXIS starts the internal pulse count at the starting frequency and increases the frequency each calculation cycle by the frequency increment set in the acceleration rate.
  - b) When the target frequency is reached, incrementing the frequency stops and the pulse count continues at a constant frequency.
  - c) The point to start decreasing the frequency (the deceleration point) is determined from the deceleration rate and the remaining number of travel pulses, which is calculated from the preset target position. When the deceleration point is reached, AXIS decreases the frequency each calculation cycle by the frequency increment set in the deceleration rate. The internal pulse count stops when the target position is reached.
- When trapezoidal control cannot be performed with the specified target position, target frequency, and acceleration/deceleration, AXIS will automatically compensate as follows:

The acceleration and deceleration rates will be set to the same rate (symmetrical trapezoidal control).

OR

When one-half of the specified target pulses have been output, AXIS will start decelerating at the specified acceleration rate (symmetrical triangular control).

**Note** When the AXIS instruction's input condition goes OFF, the contents of setting table words T+2 to T+4 will be initialized to 0.

#### **Operand Specifications**

Area	M	С	T
CIO Area			CIO 0000 to CIO 6117
Work Area			W000 to W229
Auxiliary Bit Area			A000 to A933

Area	М	С	Т
Timer Area			T0000 to T0229
Counter Area			C0000 to C0229
DM Area			D00000 to D32741
Indirect DM addresses in binary			@ D00000 to @ D32767
Indirect DM addresses in BCD			*D00000 to *D32767
Constants	Specified values only		
Data Resisters			
Index Registers			
Indirect addressing			,IR0 or ,IR1
using Index Registers			-2048 to +2047 ,IR0 or -2048 to +2047 ,IR1
			,IR0+(++) or ,IR1+(++)
			, –(– –)IR0 or, –(– –)IR1

#### Flags

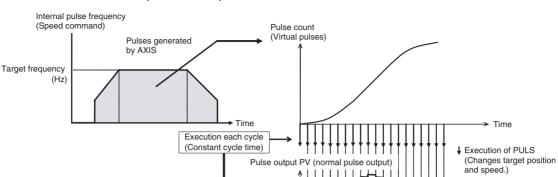
Name	Label	Operation
Error Flag	ER	ON if the settings for the target frequency, starting frequency, and acceleration/deceleration rate are inconsistent.
		ON if the setting table starting at T contains one of the following invalid settings when the instruction is executed:
		Target frequency < Deceleration rate
		• Target frequency > 1,000,000 or Target frequency = 0
		• Starting frequency > 1,000,000
		Target frequency < Starting frequency
		<ul> <li>Acceleration rate &gt; 9,999 or Acceleration rate = 0</li> </ul>
		• Deceleration rate > 9,999 or Deceleration rate = 0
		Target position (travel amount in relative mode) = 0
		Target position (target position in absolute mode) =     Present position
		OFF in all other cases.

#### Example

#### Positioning or Speed Control on a Virtual Axis

The internal pulse count can be treated as a virtual axis position in order to perform electronic cam operation on that virtual axis position with simple linear approximation.

First, the AXIS instruction is executed to generate an internal pulse count. The internal pulse count is read at every cycle, that pulse count is processed with basic arithmetic operations or the APR instruction, and the result is used as a target position or target speed in the PULS(886) instruction. The PULS(886)



PULS (Electronic Cam Mode) is executed in the program to change target position and speed.

instruction (in electronic cam control) is executed immediately after the target position or speed is calculated.

Simple locus control can be performed by executing electronic cam control simultaneously on virtual axes for both pulse outputs 1 and 2.

Target position

→ Time

## 3-14 Floating-point Math Instructions

Instruction	Mnemonic	Function code	Page
FLOATING TO 16-BIT	FIX	450	386
FLOATING TO 32-BIT	FIXL	451	388
16-BIT TO FLOATING	FLT	452	389
32-BIT TO FLOATING	FLTL	453	390
FLOATING-POINT ADD	+F	454	392
FLOATING-POINT SUB- TRACT	_F	455	394
FLOATING-POINT MULTI- PLY	*F	456	396
FLOATING-POINT DIVIDE	/F	457	397
DEGREES TO RADIANS	RAD	458	400
RADIANS-TO-DEGREES	DEG	459	401
SINE	SIN	460	403
COSINE	cos	461	404
TANGENT	TAN	462	406
ARC SINE	ASIN	463	408
ARC COSINE	ACOS	464	410
ARC TANGENT	ATAN	465	412
SQUARE ROOT	SQRT	466	413
EXPONENT	EXP	467	415
LOGARITHM	LOG	468	417
EXPONENTIAL POWER	PWR	840	419

The following floating-point comparison instructions are supported in addition to the instructions listed above.

Instruction	Mnemonic	Function code	Page
Single-precision Floating- point Symbol Comparison Instructions	LD, AND, OR + =F, <>F, <f, <="F,">F, or &gt;=F</f,>	329 to 334	421

#### **Data Format**

Floating-point data expresses real numbers using a sign, exponent, and mantissa. When data is expressed in floating-point format, the following formula applies.

Real number =  $(-1)^{s} 2^{e-127}$  (1.f)

s: Sign

e: Exponent

f: Mantissa

The floating-point data format conforms to the IEEE754 standards. Data is expressed in 32 bits, as follows:

Sign	Exponer	nt		Mantissa	
S	е			f	
31	30	23	22		0

Data	No. of bits	Contents
s: sign	1	0: positive; 1: negative
e: exponent	8	The exponent (e) value ranges from 0 to 255. The actual exponent is the value remaining after 127 is subtracted from e, resulting in a range of – 127 to 128. "e=0" and "e=255" express special numbers.
f: mantissa	23	The mantissa portion of binary floating-point data fits the formal 2.0 > 1.f ≥1.0.

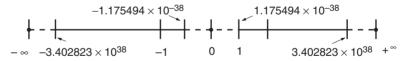
#### **Number of Digits**

The number of effective digits for floating-point data is 24 bits for binary (approximately seven digits decimal).

#### Floating-point Data

The following data can be expressed by floating-point data:

- **-**~
- $-3.402823 \times 10^{38} \le \text{value} \le -1.175494 \times 10^{-38}$
- 0
- $1.175494 \times 10^{-38} \le \text{value} \le 3.402823 \times 10^{38}$
- +∞
- Not a number (NaN)



#### **Special Numbers**

The formats for NaN,  $\pm \infty$ , and 0 are as follows:

NaN\*:  $e = 255, f \neq 0$ + $\infty$ : e = 255, f = 0, s = 0- $\infty$ : e = 255, f = 0, s = 10: e = 0

\*NaN (not a number) is not a valid floating-point number. Executing floating-point calculation instructions will not result in NaN.

# Writing Floating-point Data

When floating-point is specified for the data format in the I/O memory edit display in the CX-Programmer, standard decimal numbers input in the display are automatically converted to the floating-point format shown above (IEEE754-format) and written to I/O Memory. Data written in the IEEE754-format is automatically converted to standard decimal format when monitored on the display.



It is not necessary for the user to be aware of the IEEE754 data format when reading and writing floating-point data. It is only necessary to remember that floating point values occupy two words each.

### Numbers Expressed as Floating-point Values

The following types of floating-point numbers can be used.

Mantissa (f)	Exponent (e)			
	0	Not 0 and not all 1's	All 1's (255)	
0	0	Normalized number	Infinity	
Not 0	Non-normalized number		NaN	

Note A non-normalized number is one whose absolute value is too small to be expressed as a normalized number. Non-normalized numbers have fewer significant digits. If the result of calculations is a non-normalized number (including intermediate results), the number of significant digits will be reduced.

#### **Normalized Numbers**

Normalized numbers express real numbers. The sign bit will be 0 for a positive number and 1 for a negative number.

The exponent (e) will be expressed from 1 to 254, and the real exponent will be 127 less, i.e., -126 to 127.

The mantissa (f) will be expressed from 0 to  $2^{23} - 1$ , and it is assume that, in the real mantissa, bit  $2^{23}$  is 1 and the binary point follows immediately after it.

Normalized numbers are expressed as follows:

$$(-1)^{(\text{sign s})} \times 2^{(\text{exponent e})-127} \times (1 + \text{mantissa} \times 2^{-23})$$

#### **Example**

Sign:

Exponent: 128 - 127 = 1

 $1 + (2^{22} + 2^{21}) \times 2^{-23} = 1 + (2^{-1} + 2^{-2}) = 1 + 0.75 = 1.75$ Mantissa:

 $-1.75 \times 2^1 = -3.5$ Value:

#### Non-normalized Numbers

Non-normalized numbers express real numbers with very small absolute values. The sign bit will be 0 for a positive number and 1 for a negative number.

The exponent (e) will be 0, and the real exponent will be -126.

The mantissa (f) will be expressed from 1 to  $2^{23} - 1$ , and it is assume that. in the real mantissa, bit  $2^{23}$  is 0 and the binary point follows immediately after it.

Non-normalized numbers are expressed as follows:

$$(-1)^{(\text{sign s})} \times 2^{-126} \times (\text{mantissa x } 2^{-23})$$

#### **Example**

Sign:

Exponent:

 $0 + (2^{22} + 2^{21}) \times 2^{-23} = 0 + (2^{-1} + 2^{-2}) = 0 + 0.75 = 0.75$  $0.75 \times 2^{-126}$ Mantissa:

Value:

**Zero** Values of +0.0 and -0.0 can be expressed by setting the sign to 0 for positive

or 1 for negative. The exponent and mantissa will both be 0. Both +0.0 and -0.0 are equivalent to 0.0. Refer to *Floating-point Arithmetic Results*, below,

for differences produced by the sign of 0.0.

Infinity Values of  $+\infty$  and  $-\infty$  can be expressed by setting the sign to 0 for positive or 1

for negative. The exponent will be 255  $(2^8 - 1)$  and the mantissa will be 0.

NaN (not a number) is produced when the result of calculations, such as 0.0/

 $0.0, \infty/\infty$ , or  $\infty-\infty$ , does not correspond to a number or infinity. The exponent

will be  $255 (2^8 - 1)$  and the mantissa will be not 0.

Note There are no specifications for the sign of NaN or the value of the mantissa

field (other than to be not 0).

#### Floating-point Arithmetic Results

**Rounding Results** 

The following methods will be used to round results when the number of digits in the accurate result of floating-point arithmetic exceeds the significant digits of internal processing expressions.

If the result is close to one of two internal floating-point expressions, the closer expression will be used. If the result is midway between two internal floating-point expressions, the result will be rounded so that the last digit of the mantissa is 0.

Overflows, Underflows, and Illegal Calculations

Overflows will be output as either positive or negative infinity, depending on the sign of the result. Underflows will be output as either positive or negative zero, depending on the sign of the result.

Illegal calculations will result in NaN. Illegal calculations include adding infinity to a number with the opposite sign, subtracting infinity from a number with the same sign, multiplying zero and infinity, dividing zero by zero, or dividing infinity by infinity.

The value of the result may not be correct if an overflow occurs when converting a floating-point number to an integer.

Precautions in Handling Special Values

The following precautions apply to handling zero, infinity, and NaN.

- The sum of positive zero and negative zero is positive zero.
- The difference between zeros of the same sign is positive zero.
- If any operand is a NaN, the results will be a NaN.
- Positive zero and negative zero are treated as equivalent in comparisons.
- Comparison or equivalency tests on one or more NaN will always be true for != and always be false for all other instructions.

#### Floating-point Calculation Results

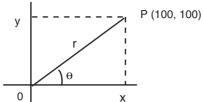
When the absolute value of the result is greater than the maximum value that can be expressed for floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm \infty$ . If the result is positive, it will be output as  $+\infty$ ; if negative, then  $-\infty$ .

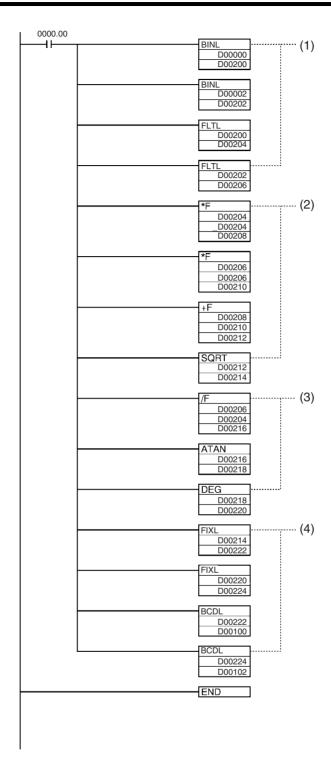
The Equals Flag will only turn ON when both the exponent (e) and the mantissa (f) are zero after a calculation. A calculation result will also be output as zero when the absolute value of the result is less than the minimum value that can be expressed for floating-point data. In that case the Underflow Flag will turn ON.

Example

In this program example, the X-axis and Y-axis coordinates (x, y) are provided by 8-digit BCD content of D00000, D00001 and D00002, D00003. The dis-

tance (r) from the origin and the angle ( $\theta$ , in degrees) are found and output to D00100, D00101 and D00102, D00103. In the result, everything to the right of the decimal point is truncated.





#### **Calculations** Example Distance $r = \sqrt{x^2 + y^2}$ Distance $r = \sqrt{100^2 + 100^2} = 141.4214$ Angle $\theta = \tan^{-1} \left( \frac{100}{100} \right) = 45.0$ Angle $\theta = \tan^{-1} \left( \frac{y}{y} \right)$ **DM Contents** D00000 #0100 0141 D00100 (BCD) (BCD) D00002 #0100 0045 D00102 (BCD) (BCD)

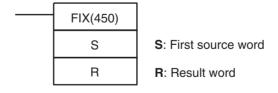
- 1. This section of the program converts the data from BCD to floating-point.
  - a) The data area from D00200 onwards is used as a work area.
  - b) First BINL(058) is used to temporarily convert the BCD data to binary data, and then FLTL(453) is used to convert the binary data to floating-point data.
  - c) The value of x that has been converted to floating-point data is output to D00205 and D00204.
  - d) The value of y that has been converted to floating-point data is output to D00207 and D00206.
- 2. In order to find the distance r, Floating-point Math Instructions are used to calculate the square root of  $x^2+y^2$ . The result is then output to D00215 and D00214 as floating-point data.
- 3. In order to find the angle  $\theta$ , Floating-point Math Instructions are used to calculate  $\tan^{-1}(y/x)$ . ATAN(465) outputs the result in radians, so DEG(459) is used to convert to degrees. The result is then output to D00221 and D00220 as floating-point data.
- 4. The data is converted back from floating-point to BCD.
  - a) First FIXL(451) is used to temporarily convert the floating-point data to binary data, and then BCDL(059) is used to convert the binary data to BCD data.
  - b) The distance r is output to D00101 and D00100 in BCD.
  - c) The angle  $\theta$  is output to D00103 and D00102 in BCD.

### 3-14-1 FLOATING TO 16-BIT: FIX(450)

#### **Purpose**

Converts a 32-bit floating-point value to 16-bit signed binary data and places the result in the specified result word.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	FIX(450)
	<b>Executed Once for Upward Differentiation</b>	@FIX(450)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142	CIO 0000 to CIO 6143	
Work Area	W000 to W254	W000 to W255	
Auxiliary Bit Area	A000 to A958	A448 to A959	
Timer Area	T0000 to T0254	T0000 to T0255	
Counter Area	C0000 to C0254	C0000 to C0255	
DM Area	D00000 to D32766	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#00000000 to #FFFFFFF		
	(binary)		
Data Registers		DR0 to DR15	
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

#### **Description**

FIX(450) converts the integer portion of the 32-bit floating-point number in S+1 and S (IEEE754-format) to 16-bit signed binary data and places the result in



Only the integer portion of the floating-point data is converted, and the fraction portion is truncated. The integer portion of the floating-point data must be within the range of -32,768 to 32,767.

Example conversions:

A floating-point value of 3.5 is converted to 3.

A floating-point value of -3.5 is converted to -3.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the data in S+1 and S is not a number (NaN).	
		ON if the integer portion of S+1 and S is not within the range of –32,768 to 32,767.	
		OFF in all other cases.	
Equals Flag	=	ON if the result is 0000.	
		OFF in all other cases.	
Negative Flag	N	ON if bit 15 of the result is ON.	
		OFF in all other cases.	

#### **Precautions**

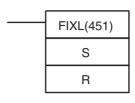
The content of S+1 and S must be floating-point data and the integer portion must be in the range of -32,768 to 32,767.

### 3-14-2 FLOATING TO 32-BIT: FIXL(451)

#### **Purpose**

Converts a 32-bit floating-point value to 32-bit signed binary data and places the result in the specified result words.

#### **Ladder Symbol**



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	FIXL(451)
	Executed Once for Upward Differentiation	@FIXL(451)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958 A448 to A958		
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#00000000 to #FFFFFFF		
	(binary)		
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15		
DR0 to DR15, IR0 to DR0 to DR15, IR15		DR15, IR15	
	,IR0+(++) to ,IR15+(++)		
	,–(– –)IR0 to , –()IR15		

#### **Description**

FIXL(451) converts the integer portion of the 32-bit floating-point number in S+1 and S (IEEE754-format) to 32-bit signed binary data and places the result in R+1 and R.



Only the integer portion of the floating-point data is converted, and the fraction portion is truncated. (The integer portion of the floating-point data must be within the range of -2,147,483,648 to 2,147,483,647.)

Example conversions:

A floating-point value of 2,147,483,640.5 is converted to 2,147,483,640 in 32-bit signed binary.

A floating-point value of -214,748,340.5 is converted to -214,748,340 in 32-bit signed binary.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the data in S+1 and S is not a number (NaN).	
		ON if the integer portion of S+1 and S is not within the range of -2,147,483,648 to 2,147,483,647.	
		OFF in all other cases.	
Equals Flag	=	ON if the result is 0000 0000.	
		OFF in all other cases.	
Negative Flag	N	ON if bit 15 of R+1 is ON after execution.	
		OFF in all other cases.	

#### **Precautions**

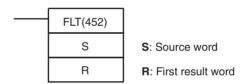
The content of S+1 and S must be floating-point data and the integer portion must be in the range of -2,147,483,648 to 2,147,483,647.

### 3-14-3 16-BIT TO FLOATING: FLT(452)

#### **Purpose**

Converts a 16-bit signed binary value to 32-bit floating-point data and places the result in the specified result words.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	FLT(452)
	Executed Once for Upward Differentiation	@FLT(452)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6142
Work Area	W000 to W255	W000 to W254
Auxiliary Bit Area	A000 to A959	A448 to A958
Timer Area	T0000 to T0255	T0000 to T0254
Counter Area	C0000 to C0255	C0000 to C0254
DM Area	D00000 to D32767	D00000 to D32766
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	

Area	S	R	
Constants	#0000 to #FFFF		
	(binary)		
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to	DR15, IR15	
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

#### **Description**

FLT(452) converts the 16-bit signed binary value in S to 32-bit floating-point data (IEEE754-format) and places the result in R+1 and R. A single 0 is added after the decimal point in the floating-point result.



Only values within the range of -32,768 to 32,767 can be specified for S. To convert signed binary data outside of that range, use FLTL(453).

Example conversions:

A signed binary value of 3 is converted to 3.0.

A signed binary value of -3 is converted to -3.0.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

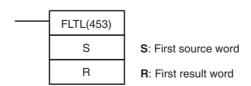
The content of S must contain signed binary data with a (decimal) value in the range of –32,768 to 32,767.

### 3-14-4 32-BIT TO FLOATING: FLTL(453)

#### **Purpose**

Converts a 32-bit signed binary value to 32-bit floating-point data and places the result in the specified result words.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	FLTL(453)
	<b>Executed Once for Upward Differentiation</b>	@FLTL(453)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958	A448 to A958	
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF (binary)		
Data Resisters			
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0  to ,-()IR15		

#### **Description**

FLTL(453) converts the 32-bit signed binary value in S+1 and S to 32-bit floating-point data (IEEE754-format) and places the result in R+1 and R. A single 0 is added after the decimal point in the floating-point result.

S+1	S	Signed binary data (32 bits)
,	ļ	
R+1	R	Floating-point data (32 bits)

Signed binary data within the range of -2,147,483,648 to 2,147,483,647 can be specified for S+1 and S. The floating point value has 24 significant binary digits (bits). The result will not be exact if a number greater than 16,777,215 (the maximum value that can be expressed in 24-bits) is converted by FLTL(453).

#### **Example Conversions:**

A signed binary value of 16,777,215 is converted to 16,777,215.0. A signed binary value of -16,777,215 is converted to -16,777,215.0.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	OFF	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

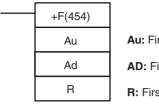
The result will not be exact if a number with an absolute value greater than 16,777,215 (the maximum value that can be expressed in 24-bits) is converted.

### 3-14-5 FLOATING-POINT ADD: +F(454)

#### **Purpose**

Adds two 32-bit floating-point numbers and places the result in the specified result words.

#### **Ladder Symbol**



Au: First augend word

AD: First addend word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	+F(454)
	Executed Once for Upward Differentiation	@+F(454)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

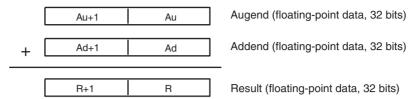
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	Au	Ad	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FF	FF FFFF	
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,–(– –)IR0 to , –(– –)IR15		

#### **Description**

+F(454) adds the 32-bit floating-point number in Ad+1 and Ad to the 32-bit floating-point number in Au+1 and Au and places the result in R+1 and R. (The floating point data must be in IEEE754 format.)



If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of augend and addend data will produce the results shown in the following table.

	Augend					
Addend	0	0 Numeral +∞ -∞				
0	0	Numeral	+∞	-∞		
Numeral	Numeral	See note 1.	+∞			
+∞	+∞	+∞	+∞	See note 2.		
-∞	-∞	-∞	See note 2.			
NaN		•	•		See note 2.	

#### Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The Error Flag will be turned ON and the instruction will not be executed.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the augend or addend data is not recognized as floating-point data.	
		ON if the augend or addend data is not a number (NaN).	
		ON if +∞ and -∞ are added.	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

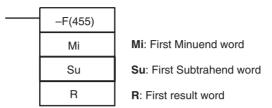
The augend (Au+1 and Au) and Addend (Ad+1 and Ad) data must be in IEEE754 floating-point data format.

### 3-14-6 FLOATING-POINT SUBTRACT: -F(455)

#### **Purpose**

Subtracts one 32-bit floating-point number from another and places the result in the specified result words.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	-F(455)
	<b>Executed Once for Upward Differentiation</b>	@-F(455)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

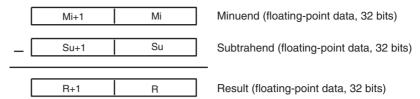
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Mi	Su	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FF	FF FFFF	
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers   -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

#### **Description**

-F(455) subtracts the 32-bit floating-point number in Su+1 and Su from the 32-bit floating-point number in Mi+1 and Mi and places the result in R+1 and R. (The floating point data must be in IEEE754 format.)



If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of minuend and subtrahend data will produce the results shown in the following table.

	Minuend				
Subtrahend	0	0 Numeral +∞ -∞			
0	0	Numeral	+∞	-∞	
Numeral	Numeral	See note 1.	+∞	-∞	
+∞	-∞	-∞	See note 2.	-∞	
-∞	+∞	+∞	+∞	See note 2.	
NaN					See note 2.

#### Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The Error Flag will be turned ON and the instruction will not be executed.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the minuend or subtrahend data is not recognized as floating-point data.	
		ON if the minuend or subtrahend is not a number (NaN).	
		ON if +∞ is subtracted from +∞.	
		ON if $-\infty$ is subtracted from $-\infty$ .	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

The Minuend (Mi+1 and Mi) and Subtrahend (Su+1 and Su) data must be in IEEE754 floating-point data format.

### 3-14-7 FLOATING-POINT MULTIPLY: \*F(456)

#### **Purpose**

Multiplies two 32-bit floating-point numbers and places the result in the specified result words.

#### **Ladder Symbol**



Md: First Multiplicand wordMr: First Multiplier word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	*F(456)
	<b>Executed Once for Upward Differentiation</b>	@*F(456)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Md	Mr	R	
CIO Area	CIO 0000 to CIO 6142			
Work Area	W000 to W254			
Auxiliary Bit Area	A000 to A958		A448 to A958	
Timer Area	T0000 to T0254			
Counter Area	C0000 to C0254			
DM Area	D00000 to D32766			
Indirect DM addresses in binary	@ D00000 to @ D3	2767		
Indirect DM addresses in BCD	*D00000 to *D3276	7		
Constants	#0000 0000 to #FFI	F FFFF		
	(binary)			
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR	48 to +2047 ,IR0 to -2048 to +2047 ,IR15		
DR0 to DR15, IR0 to DR0 to DR15, IR15				
	,IR0+(++) to ,IR15+(++)			
,-()IR0  to ,-()IR15				

#### **Description**

\*F(456) multiplies the 32-bit floating-point number in Md+1 and Md by the 32-bit floating-point number in Mr+1 and Mr and places the result in R+1 and R. (The floating point data must be in IEEE754 format.)

	Md+1 Md		Multiplicand (floating-point data, 32 bits)
×	Mr+1	Mr	Multiplier (floating-point data, 32 bits)
	R+1	R	Result (floating-point data, 32 bits)

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of multiplicand and multiplier data will produce the results shown in the following table.

	Multiplicand				
Multiplier	0	Numeral	+∞	-8	NaN
0	0	0	See note 2.	See note 2.	
Numeral	0	See note 1.	+/∞	+/-∞	
+∞	See note 2.	+/∞	+∞		
-∞	See note 2.	+/∞		+∞	
NaN					See note 2.

Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The Error Flag will be turned ON and the instruction will not be executed.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the multiplicand or multiplier data is not recognized as floating-point data.	
		ON if the multiplicand or multiplier is not a number (NaN).	
		ON if +∞ and 0 are multiplied.	
		ON if -∞ and 0 are multiplied.	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

**Precautions** 

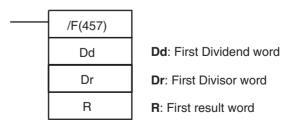
The Multiplicand (Md+1 and Md) and Multiplier (Mr+1 and Mr) data must be in IEEE754 floating-point data format.

### 3-14-8 FLOATING-POINT DIVIDE: /F(457)

**Purpose** 

Divides one 32-bit floating-point number by another and places the result in the specified result words.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	/F(457)
	Executed Once for Upward Differentiation	@/F(457)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	Dd	Dr	R	
CIO Area	CIO 0000 to CIO 6142			
Work Area	W000 to W254			
Auxiliary Bit Area	A000 to A958		A448 to A958	
Timer Area	T0000 to T0254			
Counter Area	C0000 to C0254			
DM Area	D00000 to D32766			
Indirect DM addresses in binary	@ D00000 to @ D3	32767		
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants	#0000 0000 to #FF	FF FFFF		
	(binary)			
Data Resisters			•	
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
,–(– –)IR0 to , –(– –)IR15				

#### **Description**

/F(457) divides the 32-bit floating-point number in Dd+1 and Dd by the 32-bit floating-point number in Dr+1 and Dr and places the result in R+1 and R. (The floating point data must be in IEEE754 format.)

	Dd+1	Dd	Dividend (floating-point data, 32 bits)
÷	Dr+1	Dr	Divisor (floating-point data, 32 bits)
		,	_
	R+1	R	Result (floating-point data, 32 bits)

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of dividend and divisor data will produce the results shown in the following table.

	Dividend				
Divisor	0	Numeral	+∞	-∞	NaN
0	See note 3.	+/∞	+∞	-∞	
Numeral	0	See note 1.	+/∞	+/-∞	
+∞	0	See note 2.	See note 3.	See note 3.	
	0	See note 2.	See note 3.	See note 3.	
NaN					See note 3.

#### Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The results will be zero for underflows.
- 3. The Error Flag will be turned ON and the instruction will not be executed.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the dividend or divisor data is not recognized as floating-point data.	
		ON if the dividend or divisor is not a number (NaN).	
		ON if the dividend and divisor are both 0.	
		ON if the dividend and divisor are both $+\infty$ or $-\infty$ .	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

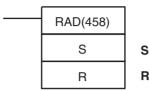
The Dividend (Dd+1 and Dd) and Divisor (Dr+1 and Dr) data must be in IEEE754 floating-point data format.

### 3-14-9 DEGREES TO RADIANS: RAD(458)

#### **Purpose**

Converts a 32-bit floating-point number from degrees to radians and places the result in the specified result words.

#### **Ladder Symbol**



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	RAD(458)
	Executed Once for Upward Differentiation	@RAD(458)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

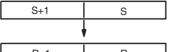
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958	A448 to A958	
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

#### **Description**

RAD(458) converts the 32-bit floating-point number in S+1 and S from degrees to radians and places the result in R and R+1. (The floating point source data must be in IEEE754 format.)



Source (degrees, 32-bit floating-point data)

Result (radians, 32-bit floating-point data)

Degrees are converted to radians by means of the following formula:

Degrees  $\times \pi/180 = \text{radians}$ 

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

#### **Precautions**

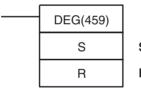
The source data in S+1 and S must be in IEEE754 floating-point data format.

### 3-14-10 RADIANS TO DEGREES: DEG(459)

#### **Purpose**

Converts a 32-bit floating-point number from radians to degrees and places the result in the specified result words.

#### **Ladder Symbol**



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	DEG(459)
	<b>Executed Once for Upward Differentiation</b>	@DEG(459)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

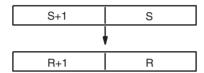
#### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	

Area	S	R	
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

#### **Description**

DEG(459) converts the 32-bit floating-point number in S+1 and S from radians to degrees and places the result in R+1 and R. (The floating point source data must be in IEEE754 format.)



Source (radians, 32-bit floating-point data)

Result (degrees, 32-bit floating-point data)

Radians are converted to degrees by means of the following formula:

Radians  $\times$  180/ $\pi$  = degrees

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the source data is not recognized as floating-point data.	
		ON if the source data is not a number (NaN).	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

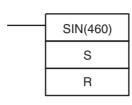
The source data in S+1 and S must be in IEEE754 floating-point data format.

### 3-14-11 SINE: SIN(460)

#### **Purpose**

Calculates the sine of a 32-bit floating-point number (in radians) and places the result in the specified result words.

#### **Ladder Symbol**



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	SIN(460)
	<b>Executed Once for Upward Differentiation</b>	@SIN(460)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF (binary)	
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	Registers –2048 to +2047 ,IR0 to –2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

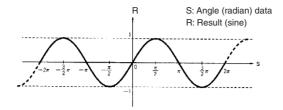
#### Description

SIN(460) calculates the sine of the angle (in radians) expressed as a 32-bit floating-point value in S+1 and S and places the result in R+1 and R. (The floating point source data must be in IEEE754 format.)



Specify the desired angle (-65,535 to 65,535) in radians in S+1 and S. If the angle is outside of the range -65,535 to 65,535, an error will occur and the instruction will not be executed. For information on converting from degrees to radians, see 3-14-19 DEGREES-TO-RADIANS: RAD(458).

The following diagram shows the relationship between the angle and result.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not a number (NaN).
		ON if the absolute value of the source data exceeds 65,535.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	OFF
Underflow Flag	UF	OFF
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

**Precautions** 

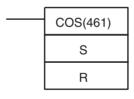
The source data in S+1 and S must be in IEEE754 floating-point data format.

### 3-14-12 COSINE: COS(461)

**Purpose** 

Calculates the cosine of a 32-bit floating-point number (in radians) and places the result in the specified result words.

**Ladder Symbol** 



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	COS(461)
	Executed Once for Upward Differentiation	@COS(461)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

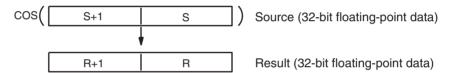
#### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	

Area	S	R	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,–(– –)IR0 to , –(– –)IR15		

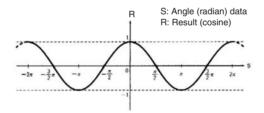
#### **Description**

COS(461) calculates the cosine of the angle (in radians) expressed as a 32-bit floating-point value in S+1 and S and places the result in R+1 and R. (The floating point source data must be in IEEE754 format.)



Specify the desired angle (-65,535 to 65,535) in radians in S+1 and S. If the angle is outside of the range -65,535 to 65,535, an error will occur and the instruction will not be executed. For information on converting from degrees to radians, see 3-14-9 DEGREES TO RADIANS: RAD(458).

The following diagram shows the relationship between the angle and result.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not a number (NaN).
		ON if the absolute value of the source data is not between 0 to 65,535.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	OFF
Underflow Flag	UF	OFF
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

#### **Precautions**

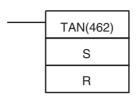
The source data in S+1 and S must be in IEEE754 floating-point data format.

### 3-14-13 TANGENT: TAN(462)

#### **Purpose**

Calculates the tangent of a 32-bit floating-point number (in radians) and places the result in the specified result words.

#### **Ladder Symbol**



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	TAN(462)
	Executed Once for Upward Differentiation	@TAN(462)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

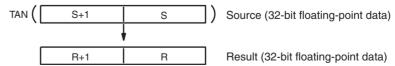
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF	
	(binary)	
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
DR0 to DR15, IR0 to DR0 to DR15, IR15		DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

#### **Description**

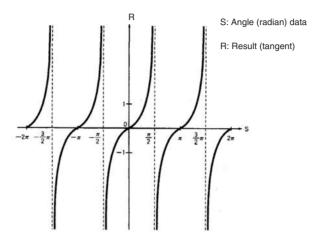
TAN(462) calculates the tangent of the angle (in radians) expressed as a 32-bit floating-point value in S+1 and S and places the result in R+1 and R. (The floating point source data must be in IEEE754 format.)



Specify the desired angle (-65,535 to 65,535) in radians in S+1 and S. If the angle is outside of the range -65,535 to 65,535, an error will occur and the instruction will not be executed. For information on converting from degrees to radians, see 3-14-9 DEGREES TO RADIANS: RAD(458).

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

The following diagram shows the relationship between the angle and result.



### Flags

Name	Label	Operation
Error Flag	ER	ON if the source data is not a number (NaN).
		ON if the absolute value of the source data is not between 0 to 65,535.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.
Underflow Flag	UF	OFF
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

#### **Precautions**

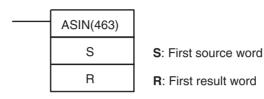
The source data in S+1 and S must be in IEEE754 floating-point data format.

### 3-14-14 ARC SINE: ASIN(463)

#### **Purpose**

Calculates the arc sine of a 32-bit floating-point number and places the result in the specified result words. (The arc sine function is the inverse of the sine function; it returns the angle that produces a given sine value between –1 and 1.)

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ASIN(463)
	Executed Once for Upward Differentiation	@ ASIN(463)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958	A448 to A958	
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

#### **Description**

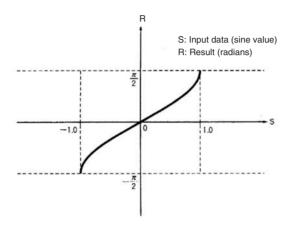
ASIN(463) computes the angle (in radians) for a sine value expressed as a 32-bit floating-point number in S+1 and S and places the result in R+1 and R. (The floating point source data must be in IEEE754 format.)



The source data must be between -1.0 and 1.0. If the absolute value of the source data exceeds 1.0, an error will occur and the instruction will not be executed.

The result is output to words R+1 and R as an angle (in radians) within the range of  $-\pi/2$  to  $\pi/2$ .

The following diagram shows the relationship between the input data and result.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		ON if the absolute value of the source data exceeds 1.0.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	OFF
Underflow Flag	UF	OFF
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

#### **Precautions**

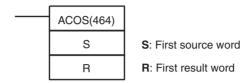
The source data in S+1 and S must be in IEEE754 floating-point data format.

### 3-14-15 ARC COSINE: ACOS(464)

#### **Purpose**

Calculates the arc cosine of a 32-bit floating-point number and places the result in the specified result words. (The arc cosine function is the inverse of the cosine function; it returns the angle that produces a given cosine value between -1 and 1.)

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ACOS(464)
	Executed Once for Upward Differentiation	@ACOS(464)
	Executed Once for Downward Differentiation	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF (binary)	
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	ex Registers   -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

#### **Description**

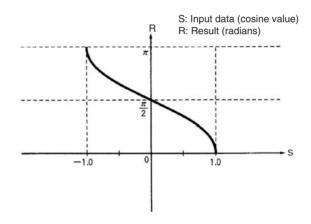
ACOS(464) computes the angle (in radians) for a cosine value expressed as a 32-bit floating-point number in S+1 and S and places the result in R+1 and R. (The floating point source data must be in IEEE754 format.)



The source data must be between -1.0 and 1.0. If the absolute value of the source data exceeds 1.0, an error will occur and the instruction will not be executed

The result is output to words R+1 and R as an angle (in radians) within the range of 0 to  $\pi$ .

The following diagram shows the relationship between the input data and result.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		ON if the absolute value of the source data exceeds 1.0.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	OFF
Underflow Flag	UF	OFF
Negative Flag	N	OFF

#### **Precautions**

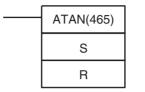
The source data in S+1 and S must be in IEEE754 floating-point data format.

### 3-14-16 ARC TANGENT: ATAN(465)

#### **Purpose**

Calculates the arc tangent of a 32-bit floating-point number and places the result in the specified result words. (The arc tangent function is the inverse of the tangent function; it returns the angle that produces a given tangent value.)

#### **Ladder Symbol**



S: First source word

R: First result word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	ATAN(465)
	Executed Once for Upward Differentiation	@ ATAN(465)
	Executed Once for Downward Differentiation	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operand Specifications**

Area	S	R
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	A448 to A958
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF	
	(binary)	
Data Resisters		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

#### **Description**

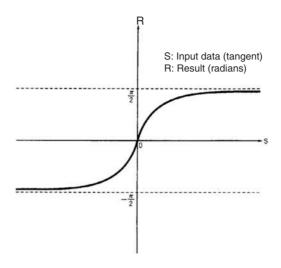
ATAN(465) computes the angle (in radians) for a tangent value expressed as a 32-bit floating-point number in S+1 and S and places the result in R+1 and R

(The floating point source data must be in IEEE754 format.)



The result is output to words R+1 and R as an angle (in radians) within the range of  $-\pi/2$  to  $\pi/2$ .

The following diagram shows the relationship between the input data and result.



# **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the source data is not recognized as floating-point data.	
		ON if the source data is not a number (NaN).	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	OFF	
Underflow Flag	UF	OFF	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

# **Precautions**

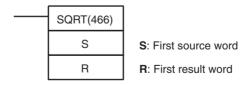
The source data in S+1 and S must be in IEEE754 floating-point data format.

# 3-14-17 SQUARE ROOT: SQRT(466)

# **Purpose**

Calculates the square root of a 32-bit floating-point number and places the result in the specified result words.

# **Ladder Symbol**



# **Variations**

Variations	Executed Each Cycle for ON Condition	SQRT(466)
	<b>Executed Once for Upward Differentiation</b>	@SQRT(466)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

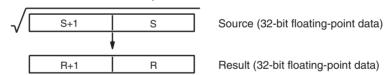
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958	A448 to A958	
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF (binary)		
Data Resisters			
Index Registers			
Indirect addressing using Index Registers	,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15		

# **Description**

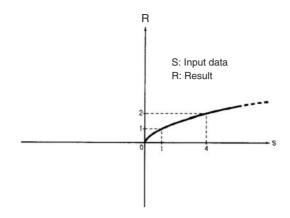
SQRT(466) calculates the square root of the 32-bit floating-point number in S+1 and S and places the result in R+1 and R. (The floating point source data must be in IEEE754 format.)



The source data must be positive; if it is negative, an error will occur and the instruction will not be executed.

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $+\infty$ .

The following diagram shows the relationship between the input data and result.



# Flags

Name	Label	Operation	
Error Flag	ER	ON if the source data is not recognized as floating-point data.	
		ON if the source data is negative.	
		ON if the source data is not a number (NaN).	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	OFF	
Negative Flag	N	OFF	

## **Precautions**

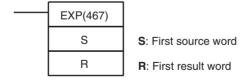
The source data in S+1 and S must be in IEEE754 floating-point data format.

# 3-14-18 EXPONENT: EXP(467)

# **Purpose**

Calculates the natural (base e) exponential of a 32-bit floating-point number and places the result in the specified result words.

# **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	EXP(467)
	Executed Once for Upward Differentiation	@EXP(467)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

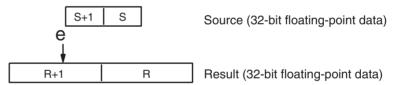
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958	A448 to A958	
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

EXP(467) calculates the natural (base e) exponential of the 32-bit floating-point number in S+1 and S and places the result in R+1 and R. In other words, EXP(467) calculates  $e^{x}$  (x = source) and places the result in R+1 and R.

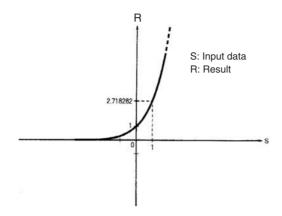


If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $+\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

**Note** The constant e is 2.718282.

The following diagram shows the relationship between the input data and result.



# Flags

Name	Label	Operation	
Error Flag	ER	ON if the source data is not recognized as floating-point data.	
		ON if the source data is not a number (NaN).	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.	
Negative Flag	N	OFF	

## **Precautions**

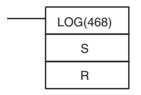
The source data in S+1 and S must be in IEEE754 floating-point data format.

# 3-14-19 LOGARITHM: LOG(468)

# **Purpose**

Calculates the natural (base e) logarithm of a 32-bit floating-point number and places the result in the specified result words.

# **Ladder Symbol**



S: First source word

R: First result word

## **Variations**

Variations	Executed Each Cycle for ON Condition	LOG(468)
	<b>Executed Once for Upward Differentiation</b>	@LOG(468)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	R	
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958	A448 to A958	
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

LOG(468) calculates the natural (base e) logarithm of the 32-bit floating-point number in S+1 and S and places the result in R+1 and R.

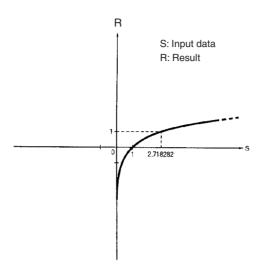


The source data must be positive; if it is negative, an error will occur and the instruction will not be executed.

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

## Note The constant e is 2.718282.

The following diagram shows the relationship between the input data and result.



# Flags

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is negative.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.
Underflow Flag	UF	OFF
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

## **Precautions**

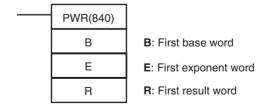
The source data in S+1 and S must be in IEEE754 floating-point data format.

# 3-14-20 EXPONENTIAL POWER: PWR(840)

# **Purpose**

Raises a 32-bit floating-point number to the power of another 32-bit floating-point number.

# **Ladder Symbol**



# **Variations**

Variations	Executed Each Cycle for ON Condition PWR(84	
	<b>Executed Once for Upward Differentiation</b>	@PWR(840)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

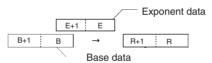
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	В	E	R
CIO Area	CIO 0000 to CIO 6142		
Work Area	W000 to W254		
Auxiliary Bit Area	A000 to A958		A448 to A958
Timer Area	T0000 to T0254		
Counter Area	C0000 to C0254		
DM Area	D00000 to D32766		
Indirect DM addresses in binary	@ D00000 to @ D3	32767	
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 0000 to #FFFF FFFF		
	(binary)		
Data Resisters			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

PWR(840) raises the 32-bit floating-point number in B+1 and B to the power of the 32-bit floating-point number in E+1 and E. In other words, PWR(840) calculates  $X^Y$  (X = B+1 and B; Y = E+1 and E).



For example, when the base words (B+1 and B) contain 3.1 and the exponent words (E+1 and E) contain 3, the result is  $3.1^3$  or 29.791.

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON.

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON.

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if the base (B+1 and B) or exponent (E+1 and E) is not recognized as floating-point data.
		ON if the base (B+1 and B) or exponent (E+1 and E) is not a number (NaN).
		ON if the base (B+1 and B) is 0 and the exponent (E+1 and E) is less than 0. (Division by 0)
		ON if the base (B+1 and B) is negative and the exponent (E+1 and E) is non-integer. (Root of a negative number)
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.

Name	Label	Operation	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a 32-bit floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a 32-bit floating-point value.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

# **Precautions**

The base (B+1 and B) and the exponent (E+1 and E) must be in IEEE754 floating-point data format.

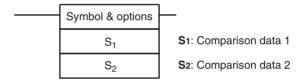
# 3-14-21 Single-precision Floating-point Comparison Instructions

# **Purpose**

These input comparison instructions compare two single-precision floating point values (32-bit IEEE754 constants and/or the contents of specified words) and create an ON execution condition when the comparison condition is true.

**Note** Refer to 3-6-1 *Input Comparison Instructions (300 to 328)* for details on the signed and unsigned binary input comparison instructions.

# **Ladder Symbol**



## **Variations**

Variations	Creates ON Each Cycle Comparison is True	Input compari-
		son instruction

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	S <sub>1</sub>	S <sub>2</sub>
CIO Area	CIO 0000 to CIO 6142	
Work Area	W000 to W254	
Auxiliary Bit Area	A000 to A958	
Timer Area	T0000 to T0254	
Counter Area	C0000 to C0254	
DM Area	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 0000 to #FFFF FFFF (	binary)
Data Resisters		

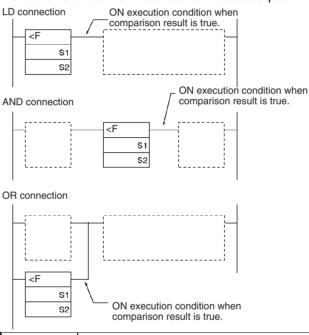
Area	S <sub>1</sub>	S <sub>2</sub>	
Index Registers	IR0 or IR15		
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

The input comparison instruction compares the data specified in  $S_1$  and  $S_2$  as single-precision floating point values (32-bit IEEE754 data) and creates an ON execution condition when the comparison condition is true. When the data is stored in words,  $S_1$  and  $S_2$  specify the first of two words containing the 32-bit data. It is also possible to input the floating-point data as an 8-digit hexadecimal constant in  $S_1$  and  $S_2$ .

## **Inputting the Instructions**

The input comparison instructions are treated just like the LD, AND, and OR instructions to control the execution of subsequent instructions.



Input type	Operation	
LD	The instruction can be connected directly to the left bus bar.	
AND	The instruction cannot be connected directly to the left bus bar.	
OR	The instruction can be connected directly to the left bus bar.	

## **Options**

With the three input types and six symbols, there are 18 different possible combinations.

	Symbol	Option (data format)
=	(Equal)	F: Single-precision floating-point data
<>	(Not equal)	
<	(Less than)	
<=	(Less than or equal)	
>	(Greater than)	
>=	(Greater than or equal)	

# **Summary of Input Comparison Instructions**

The following table shows the function codes, mnemonics, names, and functions of the 18 single-precision floating-point input comparison instructions. (C1=S<sub>1</sub>+1, S<sub>1</sub> and C2=S<sub>2</sub>+1, S<sub>2</sub>.)

Code	Mnemonic	Name	Function					
329	LD=F	LOAD FLOATING EQUAL						
	AND=F	AND FLOATING EQUAL	C1 = C2					
	OR=F	OR FLOATING EQUAL						
330	LD<>F	LOAD FLOATING NOT EQUAL	True if					
	AND<>F	AND FLOATING NOT EQUAL	C1 ≠ C2					
	OR<>F	OR FLOATING NOT EQUAL						
331	LD <f< td=""><td>LOAD FLOATING LESS THAN</td><td>True if</td></f<>	LOAD FLOATING LESS THAN	True if					
	AND <f< td=""><td colspan="7">AND FLOATING LESS THAN</td></f<>	AND FLOATING LESS THAN						
	OR <f< td=""><td>OR FLOATING LESS THAN</td><td></td></f<>	OR FLOATING LESS THAN						
332	LD<=F	LOAD FLOATING LESS THAN OR EQUAL	True if					
	AND<=F	AND FLOATING LESS THAN OR EQUAL	C1 ≤ C2					
	OR<=F	OR FLOATING LESS THAN OR EQUAL						
333	LD>F	LOAD FLOATING GREATER THAN	True if					
	AND>F	AND FLOATING GREATER THAN	C1 > C2					
	OR>F	OR FLOATING GREATER THAN	1					
325	LD>=F	LOAD FLOATING GREATER THAN OR EQUAL	True if					
	AND>=F	AND FLOATING GREATER THAN OR EQUAL	C1 ≥ C2					
	OR>=F	OR FLOATING GREATER THAN OR EQUAL						

# Flags

Name	Label	Operation
Error Flag	ER	ON if $S_1+1$ , $S_1$ or $S_2+1$ , $S_2$ is not a valid floating-point number (NaN).
		ON if $S_1+1$ , $S_1$ or $S_2+1$ , $S_2$ is $+\infty$ .
		ON if $S_1+1$ , $S_1$ or $S_2+1$ , $S_2$ is $-\infty$ .
		OFF in all other cases.
Greater Than	>	ON if $S_1+1$ , $S_1 > S_2+1$ , $S_2$ .
Flag		OFF in all other cases.
Greater Than or	>=	ON if $S_1+1$ , $S_1 \ge S_2+1$ , $S_2$ .
Equal Flag		OFF in all other cases.
Equal Flag	=	ON if $S_1+1$ , $S_1 = S_2+1$ , $S_2$ .
		OFF in all other cases.
Not Equal Flag	=	ON if $S_1+1$ , $S_1 \neq S_2+1$ , $S_2$ .
		OFF in all other cases.
Less Than Flag	<	ON if $S_1+1$ , $S_1 < S_2+1$ , $S_2$ .
		OFF in all other cases.
Less Than or	<=	ON if $S_1+1$ , $S_1 \le S_2+1$ , $S_2$ .
Equal Flag		OFF in all other cases.
Negative Flag	N	Unchanged

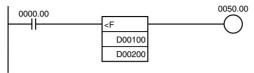
## **Precautions**

Input comparison instructions cannot be used as right-hand instructions, i.e., another instruction must be used between them and the right bus bar.

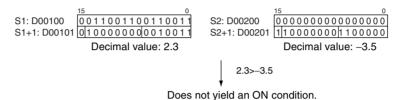
# **Example**

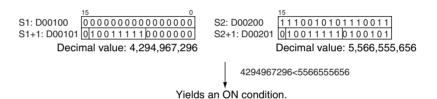
# AND FLOATING LESS THAN: AND<F(331)

When CIO 0000.00 is ON in the following example, the floating point data in D00101, D00100 is compared to the floating point data in D00201, D00200. If the content of D00101, D00100 is less than that of D00201, D00200, execution proceeds to the next line and CIO 0050.00 is turned ON. If the content of D00101, D00100 is not less than that of D00201, D00200, execution does not proceed to the next instruction line.



FLOATING LESS THAN Comparison (<F)





# 3-15 Double-precision Floating-point Instructions

The Double-precision Floating-point Instructions convert data and perform floating-point arithmetic operations on double-precision floating-point data. The FQM1 Units support the following instructions.

Instruction	Mnemonic	Function code	Page
DOUBLE FLOATING TO 16-BIT	FIXD	841	430
DOUBLE FLOATING TO 32-BIT	FIXLD	842	432
16-BIT TO DOUBLE FLOATING	DBL	843	433
32-BIT TO DOUBLE FLOATING	DBLL	844	434
DOUBLE FLOATING-POINT ADD	+D	845	436
DOUBLE FLOATING-POINT SUBTRACT	–D	846	437
DOUBLE FLOATING-POINT MULTIPLY	*D	847	439
DOUBLE FLOATING-POINT DIVIDE	/D	848	441
DOUBLE DEGREES TO RADIANS	RADD	849	443
DOUBLE RADIANS TO DEGREES	DEGD	850	444
DOUBLE SINE	SIND	851	446
DOUBLE COSINE	COSD	852	447
DOUBLE TANGENT	TAND	853	449
DOUBLE ARC SINE	ASIND	854	450
DOUBLE ARC COSINE	ACOSD	855	452
DOUBLE ARC TANGENT	ATAND	856	454
DOUBLE SQUARE ROOT	SQRTD	857	456
DOUBLE EXPONENT	EXPD	858	457
DOUBLE LOGARITHM	LOGD	859	459
DOUBLE EXPONENTIAL POWER	PWRD	860	461
Double-precision Floating-point Symbol Comparison Instructions	LD, AND, OR + =D, <>D, <d, <="D,&lt;br">&gt;D, or &gt;=D</d,>	335 to 340	462

### **Data Format**

Floating-point data expresses real numbers using a sign, exponent, and mantissa. When data is expressed in floating-point format, the following formula applies.

Real number =  $(-1)^{s} 2^{e-1,023}$  (1.f)

s: Sign

e: Exponent

f: Mantissa

The floating-point data format conforms to the IEEE754 standards. Data is expressed in 32 bits, as follows:

Sign	Exponen	nt	Mantissa	
s	е		f	
63	62	52 51		0

Data	No. of bits	Contents							
s: sign	1	0: positive; 1: negative							
e: exponent	11	The exponent (e) value ranges from 0 to 2,047. The actual exponent is the value remaining after 1,023 is subtracted from e, resulting in a range of –1,023 to 1,024. "e=0" and "e=2,047" express special numbers.							
f: mantissa	52	The mantissa portion of binary floating-point data fits the format 2.0 > 1.f ≥1.0.							

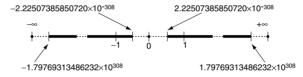
## **Number of Digits**

The number of effective digits for floating-point data is 53 bits for binary (approximately 15 digits decimal).

## **Floating-point Data**

The following data can be expressed by floating-point data:

- -∞
- $-1.79769313486232 \times 10^{308} \le \text{value} \le -2.22507385850720 \times 10^{-308}$
- 0
- $2.22507385850720 \times 10^{-308} \le \text{value} \le 1.79769313486232 \times 10^{30}$
- +∞
- Not a number (NaN)



## **Special Numbers**

The formats for NaN,  $\pm \infty$ , and 0 are as follows:

NaN\*: e = 1,024 and  $f \neq 0$   $+\infty$ : e = 1,024, f = 0, and s = 0  $-\infty$ : e = 1,024, f = 0, and s = 10: e = 0 and f = 0

\*NaN (not a number) is not a valid floating-point number. Executing Double-precision Floating-point instructions will not result in NaN.

# Writing Floating-point Data

When double-precision floating-point is specified for the data format in the I/O memory edit display in the CX-Programmer, standard decimal numbers input in the display are automatically converted to the double-precision floating-point format shown above (IEEE754-format) and written to I/O Memory. Data written in the IEEE754-format is automatically converted to standard decimal format when monitored on the display.

s e		f									
6362 5	251 48	47	3231	16	15 C						
<u> </u>		!	i								
n+3	3	n+2	1	n+1	n						

It is not necessary for the user to be aware of the IEEE754 data format when reading and writing double-precision floating-point data. It is only necessary to remember that double-precision floating point values occupy four words each.

# **Numbers Expressed as Floating-point Values**

The following types of floating-point numbers can be used.

Mantissa (f)	Exponent (e)									
	0	Not 0 and not all 1's (1,024)	All 1's (1,024)							
0	0	Normalized number	Infinity							
Not 0	Non-normalized number		NaN							

Note A non-normalized number is one whose absolute value is too small to be expressed as a normalized number. Non-normalized numbers have fewer significant digits. If the result of calculations is a non-normalized number (including intermediate results), the number of significant digits will be reduced.

### **Normalized Numbers**

Normalized numbers express real numbers. The sign bit will be 0 for a positive number and 1 for a negative number.

The exponent (e) will be expressed from 1 to 2,046, and the real exponent will be 1,023 less, i.e., -1,022 to 1,023.

The mantissa (f) will be expressed from 0 to  $(2^{52} - 1)$ , and it is assumed that, in the real mantissa, bit 252 is 1 and the decimal point follows immediately after it.

Normalized numbers are expressed as follows:

$$(-1)^{(\text{sign s})}$$
 x 2<sup>(exponent e)-1,023</sup> x (1 + mantissa x 2<sup>-52</sup>)

# Example

	32																															0
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	1	1	0	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
6	33	62										52	51																			33

Sign:

Exponent:

1,024 - 1,023 = 1  $1 + (2^{51} + 2^{50}) \times 2^{-52} = 1 + (2^{-1} + 2^{-2}) = 1 + (0.75) = 1.75$ Mantissa:

 $-1.75 \times 2^1 = -3.5$ Value:

### Non-normalized numbers

Non-normalized numbers express real numbers with very small absolute values. The sign bit will be 0 for a positive number and 1 for a negative number.

The exponent (e) will be 0, and the real exponent will be -1,022.

The mantissa (f) will be expressed from 1 to  $(2^{52} - 1)$ , and it is assumed that, in the real mantissa, bit 2<sup>52</sup> is 0 and the decimal point follows immediately after it.

Non-normalized numbers are expressed as follows:

$$(-1)^{(\text{sign s})} \times 2^{-1,022} \times (\text{mantissa} \times 2^{-52})$$

## Example

Sign:

Exponent:

 $0 + (2^{51} + 2^{50}) \times 2^{-52} = 0 + (2^{-1} + 2^{-2}) = 0 + (0.75) = 0.75$  $-0.75 \times 2^{-1,022} = 1.668805 \times 10^{-308}$ Mantissa:

Value:

Zero

Values of +0.0 and -0.0 can be expressed by setting the sign to 0 for positive or 1 for negative. The exponent and mantissa will both be 0. Both +0.0 and - 0.0 are equivalent to 0.0. Refer to *Floating-point Arithmetic Results*, below, for differences produced by the sign of 0.0.

Infinity

Values of  $+\infty$  and  $-\infty$  can be expressed by setting the sign to 0 for positive or 1 for negative. The exponent will be 2,047 ( $2^{11} - 1$ ) and the mantissa will be 0.

NaN

NaN (not a number) is produced when the result of calculations, such as 0.0/0.0,  $\infty/\infty$ , or  $\infty-\infty$ , does not correspond to a number or infinity. The exponent will be 255 ( $2^8-1$ ) and the mantissa will be not 0.

**Note** There are no specifications for the sign of NaN or the value of the mantissa field (other than to be not 0).

# Floating-point Arithmetic Results

## **Rounding Results**

The following methods will be used to round results when the number of digits in the accurate result of floating-point arithmetic exceeds the significant digits of internal processing expressions.

If the result is close to one of two internal floating-point expressions, the closer expression will be used. If the result is midway between two internal floating-point expressions, the result will be rounded so that the last digit of the mantissa is 0.

# Overflows, Underflows, and Illegal Calculations

Overflows will be output as either positive or negative infinity, depending on the sign of the result. Underflows will be output as either positive or negative zero, depending on the sign of the result.

Illegal calculations will result in NaN. Illegal calculations include adding infinity to a number with the opposite sign, subtracting infinity from a number with the opposite sign, multiplying zero and infinity, dividing zero by zero, or dividing infinity by infinity.

The value of the result may not be correct if an overflow occurs when converting a floating-point number to an integer.

# Precautions in Handling Special Values

The following precautions apply to handling zero, infinity, and NaN.

- The sum of positive zero and negative zero is positive zero.
- The difference between zeros of the same sign is positive zero.
- If any operand is a NaN, the results will be a NaN.
- Positive zero and negative zero are treated as equivalent in comparisons.
- Comparison or equivalency tests on one or more NaN will always be true for != and always be false for all other instructions.

# **Double-precision Floating-point Calculation Results**

When the absolute value of the result is greater than the maximum value that can be expressed for floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm \infty$ . If the result is positive, it will be output as  $+\infty$ ; if negative, then  $-\infty$ .

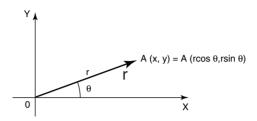
The Equals Flag will only turn ON when both the exponent (e) and the mantissa (f) are zero after a calculation. A calculation result will also be output as zero when the absolute value of the result is less than the minimum value that can be expressed for floating-point data. In that case the Underflow Flag will turn ON.

# **Comparing Single-precision and Double-precision Calculations**

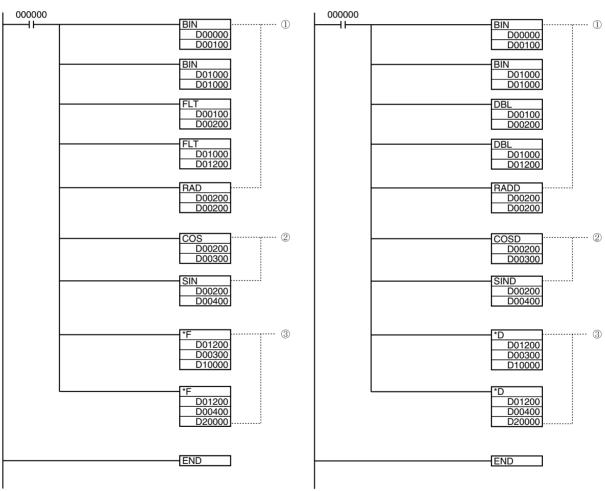
This example shows the differences in between single-precision and double-precision calculations when the following vector expressed in polar coordinates is converted to rectangular coordinates A (x,y).

$$r = re^{j} \left(\frac{\pi}{360}\right) \theta$$

In this example, the 4-digit BCD angle ( $\theta$ , in degrees) is read from D00000 and the 4-digit BCD distance (r) is read from D01000.



 Ladder Program for the Single-precision Calculation • Ladder Program for the Double-precision Calculation



- 1. This program section converts the BCD data to single-precision floating-point data (32 bits, IEEE754-format).
  - a) The BIN(023) instructions convert the BCD data to binary and the FLT(452) instructions convert the binary data to single-precision floating-point data.
  - b) The floating-point data for the angle  $\theta$  is output to D00200 and D00201.
  - c) RAD(458) converts the angle data in D00200 and D00201 to radians.
  - d) The floating-point data for the radius r is output to D01200 and D01201.
- 2. This program section calculates the sin  $\theta$  and the cos  $\theta$  as single-precision floating-point values.
  - a) The value for  $\cos \theta$  is output to D00300 and D00301.
  - b) The value for  $\sin \theta$  is output to D00400 and D00401.
- 3. This program section calculates x ( $r \times \cos \theta$ ) and y ( $r \times \sin \theta$ ).
  - a) The value for x (r  $\times$  cos  $\theta$ ) is output to D10000 and D10001.
  - b) The value for y (r  $\times$  sin  $\theta$ ) is output to D20000 and D20001.

Coordinate	Floating-point number	Real number
х	4116 59CF	3.4202015399933
У	405A E492	9.3969259262085

1.	This program s	section	converts	the BC	CD da	ıta to
	double-precisio	n floa	ting-point	data	(64	bits,
	IEEE754-forma	ıt).				

- a) The BIN(023) instructions convert the BCD data to binary and the DBL(843) instructions convert the binary data to double-precision floating-point data.
- b) The floating-point data for the angle  $\theta$  is output to words D00200 to D00203.
- c) RADD(849) converts the angle data in words D00200 to D00203 to radians.
- d) The floating-point data for the radius r is output to words D01200 to D01203.
- 2. This program section calculates the sin  $\theta$  and the cos  $\theta$  as double-precision floating-point values.
  - a) The value for  $\cos \theta$  is output to words D00300 to D00303.
  - b) The value for  $\sin \theta$  is output to words D00400 and D00403.
- 3. This program section calculates x ( $r \times \cos \theta$ ) and y ( $r \times \sin \theta$ ).
  - a) The value for x (r  $\times$  cos  $\theta$ ) is output to words D10000 to D10003.
  - b) The value for y (r  $\times$  sin  $\theta$ ) is output to D20000 and D20003.

Coordinate	Floating-point number	Real number
х	4022 CB39 E973 5C32	3.4202014332567
У	400B 5C92 91AC 8EF1	9.3969262078591

## Comparison of the Calculation Results

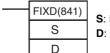
When the real-number results are compared, it is clear that the double-precision calculation yields a more accurate result.

# 3-15-1 DOUBLE FLOATING TO 16-BIT: FIXD(841)

## **Purpose**

Converts a double-precision (64-bit) floating-point value to 16-bit signed binary data and places the result in the specified result word.

# **Ladder Symbol**



- S: First source word
- D: Destination word

## **Variations**

Variations	Executed Each Cycle for ON Condition	FIXD(841)
	Executed Once for Upward Differentiation	@FIXD(841)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

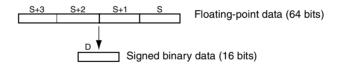
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6140	CIO 0000 to CIO 6143
Work Area	W000 to W252	W000 to W255
Auxiliary Bit Area	A000 to A956	A448 to A959
Timer Area	T0000 to T0252	T0000 to T0255
Counter Area	C0000 to C0252	C0000 to C0255
DM Area	D00000 to D32764	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Registers		DR0 to DR15
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
,-()IR0 to , -()IR15		

# **Description**

FIXD(841) converts the integer portion of the double-precision (64-bit) floating-point number in words S to S+3 (IEEE754-format) to 16-bit signed binary data and places the result in D.



Only the integer portion of the floating-point data is converted, and the fraction portion is truncated. The integer portion of the floating-point data must be within the range of -32,768 to 32,767.

Example conversions:

A floating-point value of 3.5 is converted to 3.

A floating-point value of -3.5 is converted to -3.

# **Flags**

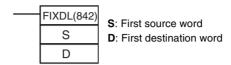
Name	Label	Operation
Error Flag	ER	ON if the source data (S to S+3) is not a number (NaN).
		ON if the integer portion of the source data (S to S+3) is not within the range of -32,768 to 32,767.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of the result is ON.
		OFF in all other cases.

# 3-15-2 DOUBLE FLOATING TO 32-BIT: FIXLD(842)

## **Purpose**

Converts a double-precision (64-bit) floating-point value to 32-bit signed binary data and places the result in the specified result words.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	FIXLD(842)
	Executed Once for Upward Differentiation	@FIXLD(842)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

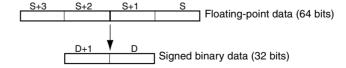
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6140	CIO 0000 to CIO 6142	
Work Area	W000 to W252	W000 to W254	
Auxiliary Bit Area	A000 to A956	A448 to A958	
Timer Area	T0000 to T0252	T0000 to T0254	
Counter Area	C0000 to C0252	C0000 to C0254	
DM Area	D00000 to D32764	D00000 to D32766	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers		8 to +2047 ,IR15	
		DR15, IR15	
	,IR0+(++) to ,IR15+(++)		
,-()IR0  to ,-()IR15			

## **Description**

FIXLD(842) converts the integer portion of the double-precision (64-bit) floating-point number in words S to S+3 (IEEE754-format) to 32-bit signed binary data and places the result in D+1 and D.



Only the integer portion of the floating-point data is converted, and the fraction portion is truncated. (The integer portion of the floating-point data must be within the range of -2.147,483,648 to 2.147,483,647.)

Example conversions:

A floating-point value of 2,147,483,640.5 is converted to 2,147,483,640 in 32-bit signed binary.

A floating-point value of -2,147,483,640.5 is converted to -2,147,483,640 in 32-bit signed binary.

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if the data in words S to S+3 is not a number (NaN).
		ON if the integer portion of words S to S+3 is not within the range of -2,147,483,648 to 2,147,483,647.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000 0000.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 of D+1 is ON after execution.
		OFF in all other cases.

## **Precautions**

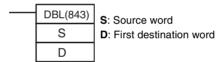
The content of words S to S+3 must be floating-point data and the integer portion must be in the range of -2,147,483,648 to 2,147,483,647.

# 3-15-3 16-BIT TO DOUBLE FLOATING: DBL(843)

## **Purpose**

Converts a 16-bit signed binary value to double-precision (64-bit) floating-point data and places the result in the specified destination words.

# **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	DBL(843)
	<b>Executed Once for Upward Differentiation</b> @ DBL(843)	
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

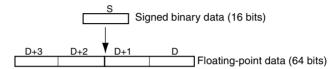
# **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6140
Work Area	W000 to W255	W000 to W252
Auxiliary Bit Area	A000 to A959	A448 to A956
Timer Area	T0000 to T0255	T0000 to T0252
Counter Area	C0000 to C0255	C0000 to C0252
DM Area	D00000 to D32767	D00000 to D32764
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants	#0000 to #FFFF	
	(binary)	

Area	S	D	
Data Registers	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

DBL(843) converts the 16-bit signed binary value in S to double-precision (64-bit) floating-point data (IEEE754-format) and places the result in words D to D+3. A single 0 is added after the decimal point in the floating-point result.



Only values within the range of -32,768 to 32,767 can be specified for S. To convert signed binary data outside of that range, use DBLL(844).

Example conversions:

A signed binary value of 3 is converted to 3.0.

A signed binary value of -3 is converted to -3.0.

# **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if both the exponent and mantissa of the result are 0. OFF in all other cases.
Negative Flag	N	ON if the result is negative. OFF in all other cases.

## **Precautions**

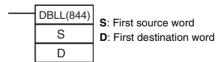
The content of S must contain signed binary data with a (decimal) value in the range of –32,768 to 32,767.

# 3-15-4 32-BIT TO DOUBLE FLOATING: DBLL(844)

### **Purpose**

Converts a 32-bit signed binary value to double-precision (64-bit) floating-point data and places the result in the specified destination words.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	DBLL(844)
	Executed Once for Upward Differentiation	@DBLL(844)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

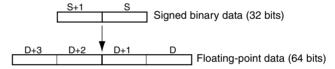
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6142	CIO 0000 to CIO 6140	
Work Area	W000 to W254	W000 to W252	
Auxiliary Bit Area	A000 to A958	A448 to A956	
Timer Area	T0000 to T0254	T0000 to T0252	
Counter Area	C0000 to C0254	C0000 to C0252	
DM Area	D00000 to D32766	D00000 to D32764	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#00000000 to #FFFFFFF		
	(binary)		
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

DBLL(844) converts the 32-bit signed binary value in S+1 and S to double-precision (64-bit) floating-point data (IEEE754-format) and places the result in words D to D+3. A single 0 is added after the decimal point in the floating-point result.



Signed binary data within the range of -2,147,483,648 to 2,147,483,647 can be specified for S+1 and S. The floating point value has 24 significant binary digits (bits). The result will not be exact if a number greater than 16,777,215 (the maximum value that can be expressed in 24-bits) is converted by DBLL(844).

## **Example Conversions:**

A signed binary value of 16,777,215 is converted to 16,777,215.0. A signed binary value of -16,777,215 is converted to -15,777,215.0.

# **Flags**

Name	Label	Operation
Error Flag	ER	OFF
Equals Flag	=	ON if both the exponent and mantissa of the result are 0. OFF in all other cases.
Negative Flag	N	ON if the result is negative. OFF in all other cases.

## **Precautions**

The result will not be exact if a number with an absolute value greater than 16,777,215 (the maximum value that can be expressed in 24-bits) is converted.

# 3-15-5 DOUBLE FLOATING-POINT ADD: +D(845)

# **Purpose**

Adds two double-precision (64-bit) floating-point numbers and places the result in the specified destination words.

## **Ladder Symbol**



Au: First augend wordAd: First addend wordD: First destination word

## **Variations**

Variations	Executed Each Cycle for ON Condition	+D(845)
	Executed Once for Upward Differentiation	@+D(845)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	Au	Ad	D	
CIO Area	CIO 0000 to CIO 6	140	•	
Work Area	W000 to W252			
Auxiliary Bit Area	A000 to A956		A448 to A956	
Timer Area	T0000 to T0252			
Counter Area	C0000 to C0252			
DM Area	D00000 to D32764			
Indirect DM addresses in binary	@ D00000 to @ D3	32767		
Indirect DM addresses in BCD	*D00000 to *D3276	57		
Constants				
Data Registers				
Index Registers				
Indirect addressing	sing ,IR0 to ,IR15			
using Index Registers	ng Index Registers -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -(	-)IR15		

# **Description**

+D(845) adds the double-precision (64-bit) floating-point number in words Ad to Ad+3 the double-precision (64-bit) floating-point number in words Au to Au+3 and places the result in words D to D+3. (The floating point data must be in IEEE754 format.)



If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of augend and addend data will produce the results shown in the following table.

	Augend				
Addend	0	Numeral	+∞		NaN
0	0	Numeral	+∞	-∞	
Numeral	Numeral	See note 1.	+∞	-8	
+∞	+∞	+∞	+∞	See note 2.	
			See note 2.		
NaN					See note 2.

### Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The Error Flag will be turned ON and the instruction will not be executed.

## **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the augend or addend data is not recognized as floating-point data.	
		ON if the augend or addend data is not a number (NaN).	
		ON if +∞ is to -∞.	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision floating-point value.	
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision floating-point value.	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

## **Precautions**

The augend (Au to Au+3) and Addend (Ad to Ad+3) data must be in IEEE754 floating-point data format.

# 3-15-6 DOUBLE FLOATING-POINT SUBTRACT: -D(846)

## **Purpose**

Subtracts one double-precision (64-bit) floating-point number from another and places the result in the specified destination words.

## **Ladder Symbol**

-D(846)
Mi
Su
D

Mi: First Minuend word Su: First Subtrahend word

D: First destination word

## **Variations**

Variations	Executed Each Cycle for ON Condition	-D(846)
	Executed Once for Upward Differentiation	@-D(846)
	Executed Once for Downward Differentiation	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Mi	Su	D
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956		A448 to A956
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## Description

-D(846) subtracts the double-precision (64-bit) floating-point number in words Su to Su+3 from the double-precision (64-bit) floating-point number in Mi to Mi+3 and places the result in words D to D+3. (The floating point data must be in IEEE754 format.)

	S1+3	S1+2	S1+1	S1	Minuend (floating-point data, 64-bits)
					I will delia (lloatilig-politi data, 04-bits)
	S2+3	S2+2	S2+1	S2	
-					Subtrahend (floating-point data, 64-bits)
	D+3	D+2	D+1	D	_
					Result (floating-point data, 64-bits)

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of minuend and subtrahend data will produce the results shown in the following table.

	Minuend					
Subtrahend	0	Numeral	+∞	-∞	NaN	
0	0	Numeral	+∞	-∞		
Numeral	Numeral	See note 1.	+∞			
+∞			See note 2.			
-∞	+∞	+∞	+∞	See note 2.		
NaN					See note 2.	

### Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The Error Flag will be turned ON and the instruction will not be executed.

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if the minuend or subtrahend data is not recognized as floating-point data.
		ON if the minuend or subtrahend is not a number (NaN).
		ON if +∞ is subtracted from +∞.
		ON if $-\infty$ is subtracted from $-\infty$ .
		OFF in all other cases.
Equals Flag = ON if		ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision floating-point value.
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision floating-point value.
Negative Flag N ON if the re		ON if the result is negative.
		OFF in all other cases.

## **Precautions**

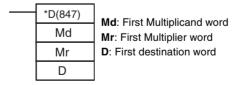
The Minuend (Mi to Mi+3) and Subtrahend (Su to Su+3) data must be in IEEE754 floating-point data format.

# 3-15-7 DOUBLE FLOATING-POINT MULTIPLY: \*D(847)

## **Purpose**

Multiplies two double-precision (64-bit) floating-point numbers and places the result in the specified result words.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	*D(847)
	<b>Executed Once for Upward Differentiation</b>	@*D(847)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

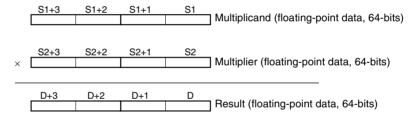
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	Md	Mr	D		
CIO Area	CIO 0000 to CIO 6140				
Work Area	W000 to W252				
Auxiliary Bit Area	A000 to A956		A448 to A956		
Timer Area	T0000 to T0252				
Counter Area	C0000 to C0252				
DM Area	D00000 to D32764				
Indirect DM addresses in binary	@ D00000 to @ D32767				
Indirect DM addresses in BCD	*D00000 to *D32767				
Constants					
Data Registers					
Index Registers					
Indirect addressing	,IR0 to ,IR15				
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15				
	DR0 to DR15, IR0 to DR0 to DR15, IR15				
	,IR0+(++) to ,IR15+(++)				
	,-()IR0 to , -(	)IR15			

## **Description**

\*D(847) multiplies the double-precision (64-bit) floating-point number in words Md to Md+3 by the double-precision (64-bit) floating-point number in words Mr to Mr+3 and places the result in words D to D+3. (The floating point data must be in IEEE754 format.)



If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of multiplicand and multiplier data will produce the results shown in the following table.

	Multiplicand					
Multiplier	0	Numeral	+∞	-∞	NaN	
0	0	0	See note 2.	See note 2.		
Numeral	0	See note 1.	+/-∞	+/-∞		
+∞	See note 2.	+/∞	+∞			
	See note 2	+/∞		+∞		
NaN					See note 2.	

Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The Error Flag will be turned ON and the instruction will not be executed.

# Flags

Name	Label	Operation
Error Flag	ER	ON if the multiplicand or multiplier data is not recognized as floating-point data.
		ON if the multiplicand or multiplier is not a number (NaN).
		ON if +∞ and 0 are multiplied.
		ON if -∞ and 0 are multiplied.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision floating-point value.
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision floating-point value.
Negative Flag N ON if the result is negative		ON if the result is negative.
		OFF in all other cases.

**Precautions** 

The Multiplicand (Md to Md+3) and Multiplier (Mr to Mr+3) data must be in IEEE754 floating-point data format.

# 3-15-8 DOUBLE FLOATING-POINT DIVIDE: /D(848)

## **Purpose**

Divides one double-precision (64-bit) floating-point number by another and places the result in the specified destination words.

# **Ladder Symbol**



**Dd**: First Dividend word **Dr**: First Divisor word **D**: First destination word

# **Variations**

Variations	Executed Each Cycle for ON Condition	/D(848)
	<b>Executed Once for Upward Differentiation</b>	@/D(848)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

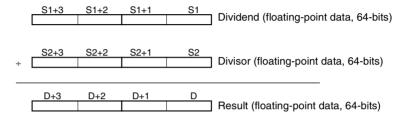
## **Operand Specifications**

Area	Dd	Dr	D		
CIO Area	CIO 0000 to CIO 6	140			
Work Area	W000 to W252				
Auxiliary Bit Area	A000 to A956		A448 to A956		
Timer Area	T0000 to T0252				
Counter Area	C0000 to C0252				
DM Area	D00000 to D32764				
Indirect DM addresses in binary	@ D00000 to @ D3	32767			
Indirect DM addresses in BCD	*D00000 to *D3276	57			
Constants					

Area	Dd	Dr	D		
Data Registers					
Index Registers					
Indirect addressing	,IR0 to ,IR15				
using Index Registers   -2048 to +2047 ,IR0 to -2048 to +204		0 to -2048 to +2047	7 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15				
	,IR0+(++) to ,IR15+(++)				
	,-()IR0 to , -(	-)IR15			

## **Description**

/D(848) divides the double-precision (64-bit) floating-point number in words Dd to Dd+3 by the double-precision (64-bit) floating-point number in words Dr to Dr+3 and places the result in words D to D+3. (The floating point data must be in IEEE754 format.)



If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

The various combinations of dividend and divisor data will produce the results shown in the following table.

	Dividend				
Divisor	0	Numeral	+∞	-∞	NaN
0	See note 3.	+/-∞	+∞	-∞	
Numeral	0	See note 1.	+/∞	+/-∞	
+∞	0	See note 2.	See note 3.	See note 3.	
-∞	0	See note 2.	See note 3.	See note 3.	
NaN					See note 3.

## Note

- 1. The results could be zero (including underflows), a numeral,  $+\infty$ , or  $-\infty$ .
- 2. The results will be zero for underflows.
- 3. The Error Flag will be turned ON and the instruction will not be executed.

## **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the dividend or divisor data is not recognized as floating-point data.	
		ON if the dividend or divisor is not a number (NaN).	
		ON if the dividend and divisor are both 0.	
		ON if the dividend and divisor are both $+\infty$ or $-\infty$ .	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision floating-point value.	

Name	Label	Operation
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision floating-point value.
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

## **Precautions**

The Dividend (Dd to Dd+3) and Divisor (Dr to Dr+3) data must be in IEEE754 floating-point data format.

# 3-15-9 DOUBLE DEGREES TO RADIANS: RADD(849)

## **Purpose**

Converts a double-precision (64-bit) floating-point number from degrees to radians and places the result in the specified result words.

# **Ladder Symbol**



- S: First source word
- D: First destination word

## **Variations**

Variations	Executed Each Cycle for ON Condition	RADD(849)
	Executed Once for Upward Differentiation	@RADD(849)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

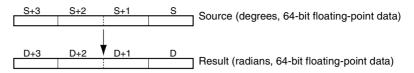
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956 A448 to A956		
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

RADD(849) converts the double-precision (64-bit) floating-point number in words S to S+3 from degrees to radians and places the result in words D to D+3. (The floating point source data must be in IEEE754 format.)



Degrees are converted to radians by means of the following formula:

Degrees  $\times \pi/180$  = radians

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

## **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision floating-point value.
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision floating-point value.
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

## **Precautions**

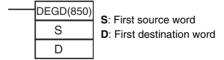
The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-10 DOUBLE RADIANS TO DEGREES: DEGD(850)

# **Purpose**

Converts a double-precision (64-bit) floating-point number from radians to degrees and places the result in the specified result words.

## **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	DEGD(850)
	Executed Once for Upward Differentiation	@DEGD(850)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

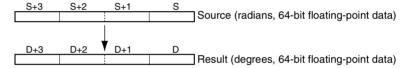
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956	A448 to A956	
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

DEGD(850) converts the double-precision (64-bit) floating-point number in words S to S+3 from radians to degrees and places the result in words D to D+3. (The floating point source data must be in IEEE754 format.)



Radians are converted to degrees by means of the following formula:

Radians  $\times$  180/ $\pi$  = degrees

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

## **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision floating-point value.
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision floating-point value.
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

## **Precautions**

The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-11 DOUBLE SINE: SIND(851)

# **Purpose**

Calculates the sine of a double-precision (64-bit) floating-point number (in radians) and places the result in the specified destination words.

## **Ladder Symbol**



- S: First source word
- D: First destination word

## **Variations**

Variations	Executed Each Cycle for ON Condition	SIND(851)
	Executed Once for Upward Differentiation	@SIND(851)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6140	
Work Area	W000 to W252	
Auxiliary Bit Area	A000 to A956	A448 to A956
Timer Area	T0000 to T0252	
Counter Area	C0000 to C0252	
DM Area	D00000 to D32764	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Registers		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

## **Description**

SIND(851) calculates the sine of the angle (in radians) expressed as a double-precision (64-bit) floating-point value in words S to S+3 and places the result in words D to D+3.

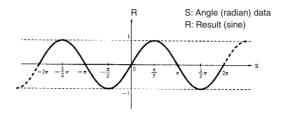
(The floating point source data must be in IEEE754 format.)

SIN(	S+3 S+2	S+1 S	) →	D+3 D+2	D+1 D

Specify the desired angle (-65,535) to 65,535 in radians in words S to S+3. If the angle is outside of the range -65,535 to 65,535, an error will occur and the instruction will not be executed. For information on converting between

degrees and radians, see 3-15-9 DOUBLE DEGREES TO RADIANS: RADD(849) or 3-15-10 DOUBLE RADIANS TO DEGREES: DEGD(850).

The following diagram shows the relationship between the angle and result.



## **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not a number (NaN). ON if the absolute value of the source data exceeds 65,535. OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0. OFF in all other cases.
Overflow Flag	OF	Unchanged
Underflow Flag	UF	Unchanged
Negative Flag	N	ON if the result is negative. OFF in all other cases.

## **Precautions**

The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-12 DOUBLE COSINE: COSD(852)

## **Purpose**

Calculates the cosine of a double-precision (64-bit) floating-point number (in radians) and places the result in the specified destination words.

## **Ladder Symbol**



- S: First source word
- D: First destination word

# **Variations**

Variations	<b>Executed Each Cycle for ON Condition</b>	COSD(852)
	<b>Executed Once for Upward Differentiation</b>	@COSD(852)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6140	
Work Area	W000 to W252	
Auxiliary Bit Area	A000 to A956	A448 to A956
Timer Area	T0000 to T0252	
Counter Area	C0000 to C0252	
DM Area	D00000 to D32764	

Area	S	D
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Registers		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048	3 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to	DR15, IR15
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

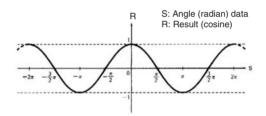
## **Description**

COSD(852) calculates the cosine of the angle (in radians) expressed as a double-precision (64-bit) floating-point value in words S to S+3 and places the result in words D to D+3.

(The floating point source data must be in IEEE754 format.)

Specify the desired angle (-65,535 to 65,535) in radians in words S to S+3. If the angle is outside of the range -65,535 to 65,535, an error will occur and the instruction will not be executed. For information on converting between degrees and radians, see 3-15-9 DOUBLE DEGREES TO RADIANS: RADD(849) or 3-15-10 DOUBLE RADIANS TO DEGREES: DEGD(850).

The following diagram shows the relationship between the angle and result.



## **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not a number (NaN).
		ON if the absolute value of the source data exceeds 65,535.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	Unchanged
Underflow Flag	UF	Unchanged
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

# **Precautions**

The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-13 DOUBLE TANGENT: TAND(853)

### **Purpose**

Calculates the tangent of a double-precision (64-bit) floating-point number (in radians) and places the result in the specified destination words.

### **Ladder Symbol**

TAND(853)	S: First source word
S	<b>D</b> : First destination word
D	

#### **Variations**

Variations	Executed Each Cycle for ON Condition	TAND(853)
	Executed Once for Upward Differentiation	@TAND(853)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956	A448 to A956	
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)		
,-()IR0 to , -()IR15			

### Description

TAND(853) calculates the tangent of the angle (in radians) expressed as a double-precision (64-bit) floating-point value in words S to S+3 and places the result in words D to D+3.

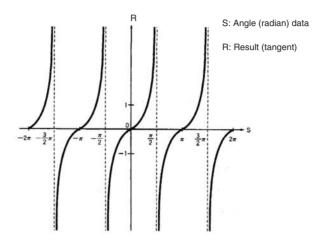
(The floating point source data must be in IEEE754 format.)

TAN( S+3 S+2	S+1 S ) →	D+3 D+2	D+1 D
--------------	-----------	---------	-------

Specify the desired angle (-65,535 to 65,535) in radians in words S to S+3. If the angle is outside of the range -65,535 to 65,535, an error will occur and the instruction will not be executed. For information on converting between degrees and radians, see 3-15-9 DOUBLE DEGREES TO RADIANS: RADD(849) or 3-15-10 DOUBLE RADIANS TO DEGREES: DEGD(850).

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

The following diagram shows the relationship between the angle and result.



# **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the source data is not a number (NaN).	
		ON if the absolute value of the source data exceeds 65,535.	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.	
		OFF in all other cases.	
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision (64-bit) floating-point value.	
Underflow Flag	UF	Unchanged	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-14 DOUBLE ARC SINE: ASIND(854)

### **Purpose**

Calculates the arc sine of a double-precision (64-bit) floating-point number and places the result in the specified destination words. (The arc sine function is the inverse of the sine function; it returns the angle that produces a given sine value between -1 and 1.)

### **Ladder Symbol**



- S: First source word
- D: First destination word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	ASIND(854)
	Executed Once for Upward Differentiation	@ASIND(854)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956	A448 to A956	
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,–(– –)IR0 to , –(– –)IR15		

### Description

ASIND(854) computes the angle (in radians) for a sine value expressed as a double-precision (64-bit) floating-point number in words S to S+3 and places the result in words D to D+3.

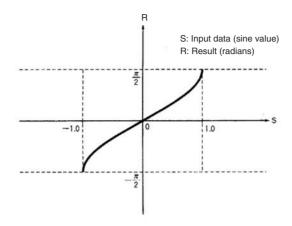
(The floating point source data must be in IEEE754 format.)

$$SIN^{-1}($$
  $S+3$   $S+2$   $S+1$   $S$   $)  $\rightarrow$   $D+3$   $D+2$   $D+1$   $D$$ 

The source data must be between -1.0 and 1.0. If the absolute value of the source data exceeds 1.0, an error will occur and the instruction will not be executed.

The result is output to words D to D+3 as an angle (in radians) within the range of  $-\pi/2$  to  $\pi/2$ .

The following diagram shows the relationship between the input data and result.



### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the source data is not recognized as floating-point data.	
		ON if the source data is not a number (NaN).	
		ON if the absolute value of the source data exceeds 1.0.	
		OFF in all other cases.	
Equals Flag	=	ON if both the exponent and mantissa of the result are 0	
		OFF in all other cases.	
Overflow Flag	OF	Unchanged	
Underflow Flag	UF	Unchanged	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

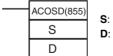
The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-15 DOUBLE ARC COSINE: ACOSD(855)

### **Purpose**

Calculates the arc cosine of a double-precision (64-bit) floating-point number and places the result in the specified result words. (The arc cosine function is the inverse of the cosine function; it returns the angle that produces a given cosine value between -1 and 1.)

#### **Ladder Symbol**



- S: First source word
- D: First destination word

### **Variations**

Variations	Executed Each Cycle for ON Condition	ACOSD(855)
	Executed Once for Upward Differentiation	@ACOSD(855)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6140	
Work Area	W000 to W252	
Auxiliary Bit Area	A000 to A956	A448 to A956
Timer Area	T0000 to T0252	
Counter Area	C0000 to C0252	
DM Area	D00000 to D32764	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Registers		
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,-()IR0 to , -()IR15	

### **Description**

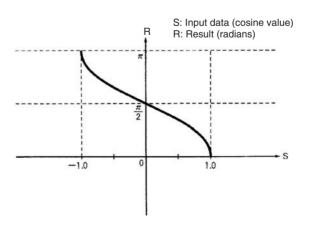
ACOSD(855) computes the angle (in radians) for a cosine value expressed as a double-precision (64-bit) floating-point number in words S to S+3 and places the result in words D to D+3.

(The floating point source data must be in IEEE754 format.)

The source data must be between -1.0 and 1.0. If the absolute value of the source data exceeds 1.0, an error will occur and the instruction will not be executed.

The result is output to words D to D+3 as an angle (in radians) within the range of 0 to  $\pi$ .

The following diagram shows the relationship between the input data and result.



# **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		ON if the absolute value of the source data exceeds 1.0.
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	Unchanged
Underflow Flag	UF	Unchanged
Negative Flag	N	Unchanged

#### **Precautions**

The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-16 DOUBLE ARC TANGENT: ATAND(856)

### **Purpose**

Calculates the arc tangent of a double-precision (64-bit) floating-point number and places the result in the specified result words. (The arc tangent function is the inverse of the tangent function; it returns the angle that produces a given tangent value.)

# **Ladder Symbol**



- S: First source word
- D: First destination word

## **Variations**

Variations	Executed Each Cycle for ON Condition	ATAND(856)
	Executed Once for Upward Differentiation	@ ATAND(856)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6140	
Work Area	W000 to W252	
Auxiliary Bit Area	A000 to A956	A448 to A956
Timer Area	T0000 to T0252	
Counter Area	C0000 to C0252	
DM Area	D00000 to D32764	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Registers		

Area	S	D
Index Registers		
Indirect addressing	,IR0 to ,IR15	
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
	DR0 to DR15, IR0 to DR0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++)	
	,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15	

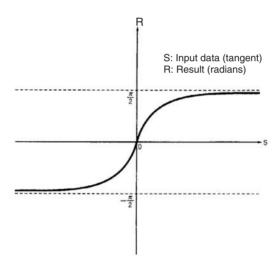
### **Description**

ATAND(856) computes the angle (in radians) for a tangent value expressed as a double-precision (64-bit) floating-point number in words S to S+3 and places the result in D to D+3.

(The floating point source data must be in IEEE754 format.)

The result is output to words D to D+3 as an angle (in radians) within the range of  $-\pi/2$  to  $\pi/2$ .

The following diagram shows the relationship between the input data and result.



### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	Unchanged
Underflow Flag	UF	Unchanged
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

# **Precautions**

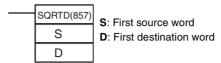
The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-17 DOUBLE SQUARE ROOT: SQRTD(857)

### **Purpose**

Calculates the square root of a double-precision (64-bit) floating-point number and places the result in the specified result words.

### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	SQRTD(857)
	Executed Once for Upward Differentiation	@SQRTD(857)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956	A448 to A956	
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	rect addressing ,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

### **Description**

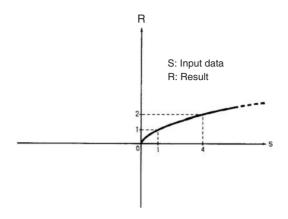
SQRTD(857) calculates the square root of the double-precision (64-bit) floating-point number in words S to S+3 and places the result in words D to D+3. (The floating point source data must be in IEEE754 format.)



The source data must be positive; if it is negative, an error will occur and the instruction will not be executed.

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

The following diagram shows the relationship between the input data and result.



### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is negative.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision (64-bit) floating-point value.
Underflow Flag	UF	Unchanged
Negative Flag	N	Unchanged

### **Precautions**

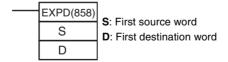
The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-18 DOUBLE EXPONENT: EXPD(858)

# **Purpose**

Calculates the natural (base e) exponential of a double-precision (64-bit) floating-point number and places the result in the specified result words.

# **Ladder Symbol**



### **Variations**

Variations	<b>Executed Each Cycle for ON Condition</b>	EXPD(858)
	<b>Executed Once for Upward Differentiation</b>	@EXPD(858)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	S	D	
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956	A448 to A956	
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
,-()IR0 to , -()IR15			

### **Description**

EXPD(858) calculates the natural (base e) exponential of the double-precision (64-bit) floating-point number in words S to S+3 and places the result in words D to D+3. In other words, EXP(467) calculates  $e^x$  (x = source) and places the result in words D to D+3.

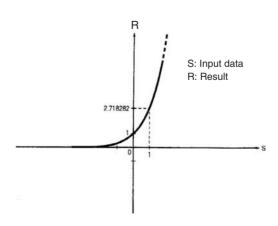


If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON and the result will be output as 0.

Note The constant e is 2.718282.

The following diagram shows the relationship between the input data and result.



# Flags

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision (64-bit) floating-point value.
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision (64-bit) floating-point value.
Negative Flag	N	Unchanged

### **Precautions**

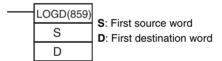
The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-19 DOUBLE LOGARITHM: LOGD(859)

### **Purpose**

Calculates the natural (base e) logarithm of a double-precision (64-bit) floating-point number and places the result in the specified destination words.

# **Ladder Symbol**



# **Variations**

Variations	Executed Each Cycle for ON Condition	LOGD(859)
	<b>Executed Once for Upward Differentiation</b>	@LOGD(859)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks	
OK	OK	OK	OK	

# **Operand Specifications**

Area	S	D
CIO Area	CIO 0000 to CIO 6140	
Work Area	W000 to W252	
Auxiliary Bit Area	A000 to A956	A448 to A956
Timer Area	T0000 to T0252	
Counter Area	C0000 to C0252	
DM Area	D00000 to D32764	
Indirect DM addresses in binary	@ D00000 to @ D32767	
Indirect DM addresses in BCD	*D00000 to *D32767	
Constants		
Data Registers		

Area	S	D	
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15			

### **Description**

LOGD(859) calculates the natural (base e) logarithm of the double-precision (64-bit) floating-point number in words S to S+3 and places the result in words D to D+3.

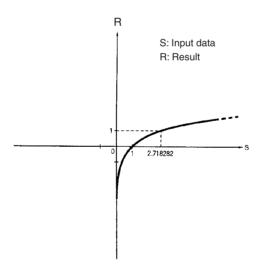
log	S+3	S+2	S+1	S	$\rightarrow$	D+3	D+2	D+1	D

The source data must be positive; if it is negative, an error will occur and the instruction will not be executed.

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON and the result will be output as  $\pm\infty$ .

Note The constant e is 2.718282.

The following diagram shows the relationship between the input data and result.



**Flags** 

Name	Label	Operation
Error Flag	ER	ON if the source data is not recognized as floating-point data.
		ON if the source data is negative.
		ON if the source data is not a number (NaN).
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision (64-bit) floating-point value.

Name	Label	Operation	
Underflow Flag	UF	Unchanged	
Negative Flag	N	ON if the result is negative.	
		OFF in all other cases.	

#### **Precautions**

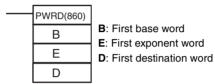
The source data in words S to S+3 must be in IEEE754 floating-point data format.

# 3-15-20 DOUBLE EXPONENTIAL POWER: PWRD(860)

#### **Purpose**

Raises a double-precision (64-bit) floating-point number to the power of another double-precision (64-bit) floating-point number.

# **Ladder Symbol**



### **Variations**

Variations	Executed Each Cycle for ON Condition	PWRD(860)
	Executed Once for Upward Differentiation	@PWRD(860)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operand Specifications**

Area	В	E	D	
CIO Area	CIO 0000 to CIO 6140			
Work Area	W000 to W252			
Auxiliary Bit Area	A000 to A956		A448 to A956	
Timer Area	T0000 to T0252			
Counter Area	C0000 to C0252			
DM Area	D00000 to D32764			
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants				
Data Registers				
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -(	-)IR15		

### **Description**

PWRD(860) raises the double-precision (64-bit) floating-point number in words B to B+3 to the power of the double-precision (64-bit) floating-point number in words E to E+3. In other words, PWR(840) calculates  $X^Y$  (X = content of B to B+3; Y = content of E to E+3).



For example, when the base words (B to B+3) contain 3.1 and the exponent words (E to E+3) contain 3, the result is  $3.1^3$  or 29.791.

If the absolute value of the result is greater than the maximum value that can be expressed as floating-point data, the Overflow Flag will turn ON.

If the absolute value of the result is less than the minimum value that can be expressed as floating-point data, the Underflow Flag will turn ON.

### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the base data (B to B+3) or exponent data (E to E+3) is not recognized as floating-point data.
		ON if the base data (B to B+3) or exponent data (E to E+3) is not a number (NaN).
		ON if the base data (B to B+3) is 0 and the exponent data (E to E+3) is less than 0. (Division by 0)
		ON if the base data (B to B+3) is negative and the exponent data (E to E+3) is non-integer. (Root of a negative number)
		OFF in all other cases.
Equals Flag	=	ON if both the exponent and mantissa of the result are 0.
		OFF in all other cases.
Overflow Flag	OF	ON if the absolute value of the result is too large to be expressed as a double-precision floating-point value.
Underflow Flag	UF	ON if the absolute value of the result is too small to be expressed as a double-precision floating-point value.
Negative Flag	N	ON if the result is negative.
		OFF in all other cases.

### **Precautions**

The base data (B to B+3) and the exponent data (E to E+3) must be in IEEE754 floating-point data format.

# 3-15-21 Double-precision Floating-point Input Instructions

# **Purpose**

These input comparison instructions compare two double-precision floating point values (64-bit IEEE754 format) and create an ON execution condition when the comparison condition is true.

**Note** Refer to 3-6-1 Input Comparison Instructions (300 to 328) for details on the signed and unsigned binary input comparison instructions and 3-14-21 Single-precision Floating-point Comparison Instructions for details on single-precision floating-point input comparison instructions.

### **Ladder Symbol**



#### **Variations**

Variations	 Input compari- son instruction
	oon monaonon

# **Applicable Program Areas**

Block program areas Step program areas		Subroutines	ines Interrupt tasks	
OK	OK	OK	OK	

# **Operand Specifications**

Area	S <sub>1</sub>	S <sub>2</sub>	
CIO Area	CIO 0000 to CIO 6140		
Work Area	W000 to W252		
Auxiliary Bit Area	A000 to A956		
Timer Area	T0000 to T0252		
Counter Area	C0000 to C0252		
DM Area	D00000 to D32764		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Registers			
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to I	DR15, IR15	
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

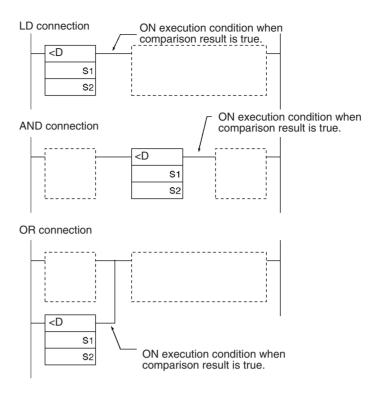
# **Description**

The input comparison instruction compares the data specified in  $S_1$  and  $S_2$  as double-precision floating point values (64-bit IEEE754 data) and creates an ON execution condition when the comparison condition is true. When the data is stored in words,  $S_1$  and  $S_2$  specify the first of four words containing the 64-bit data. The 64-bit floating-point data cannot be input as constants.

### **Inputting the Instructions**

The input comparison instructions are treated just like the LD, AND, and OR instructions to control the execution of subsequent instructions.

Input type	Operation
LD	The instruction can be connected directly to the left bus bar.
AND	The instruction cannot be connected directly to the left bus bar.
OR	The instruction can be connected directly to the left bus bar.



# **Options**

With the three input types and six symbols, there are 18 different possible combinations.

	Symbol	Option (data format)
=	(Equal)	D: Double-precision floating-point data
<>	(Not equal)	
<	(Less than)	
<=	(Less than or equal)	
>	(Greater than)	
>=	(Greater than or equal)	

# **Summary of Input Comparison Instructions**

The following table shows the function codes, mnemonics, names, and functions of the 18 single-precision floating-point input comparison instructions. (C1=S<sub>1</sub>+3, S<sub>1</sub>+2, S<sub>1</sub>+1, S<sub>1</sub> and C2=S<sub>2</sub>+3, S<sub>2</sub>+2, S<sub>2</sub>+1, S<sub>2</sub>.)

Code	Mnemonic	Name	Function
335	LD=D	LOAD DOUBLE FLOATING EQUAL	True if
	AND=D	AND DOUBLE FLOATING EQUAL	C1 = C2
	OR=D	OR DOUBLE FLOATING EQUAL	
336	LD<>D	LOAD DOUBLE FLOATING NOT EQUAL	True if
	AND<>D	AND DOUBLE FLOATING NOT EQUAL	C1 ≠ C2
	OR<>D	OR DOUBLE FLOATING NOT EQUAL	
337	LD <d< td=""><td>LOAD DOUBLE FLOATING LESS THAN</td><td>True if</td></d<>	LOAD DOUBLE FLOATING LESS THAN	True if
	AND <d< td=""><td>AND DOUBLE FLOATING LESS THAN</td><td>C1 &lt; C2</td></d<>	AND DOUBLE FLOATING LESS THAN	C1 < C2
	OR <d< td=""><td>OR DOUBLE FLOATING LESS THAN</td><td></td></d<>	OR DOUBLE FLOATING LESS THAN	
338	LD<=D	LOAD DOUBLE FLOATING LESS THAN OR EQUAL	True if C1 ≤ C2
	AND<=D	AND DOUBLE FLOATING LESS THAN OR EQUAL	
	OR<=D	OR DOUBLE FLOATING LESS THAN OR EQUAL	

Code	Mnemonic	Name	Function
339	LD>D	LOAD DOUBLE FLOATING GREATER THAN	True if
	AND>D	AND DOUBLE FLOATING GREATER THAN	C1 > C2
	OR>D	OR DOUBLE FLOATING GREATER THAN	
340	LD>=D	LOAD DOUBLE FLOATING GREATER THAN OR EQUAL	True if C1 ≥ C2
	AND>=D	AND DOUBLE FLOATING GREATER THAN OR EQUAL	
	OR>=D	OR DOUBLE FLOATING GREATER THAN OR EQUAL	

**Flags** 

In this table, C1 = content of S1 to S1+3 and C2 = content of S2 to S2+3.

Name	Label	Operation
Error Flag	ER	ON if C1 or C2 is not a valid floating-point number (NaN).
		ON if C1 or C2 is +∞.
		ON if C1 or C2 is -∞.
		OFF in all other cases.
Greater Than	>	ON if C1 > C2.
Flag		OFF in all other cases.
Greater Than or	>=	ON if C1 ≥ C2.
Equal Flag		OFF in all other cases.
Equal Flag	=	ON if $C1 = C2$ .
		OFF in all other cases.
Not Equal Flag	=	ON if C1 ≠ C2.
		OFF in all other cases.
Less Than Flag	<	ON if C1 < C2.
		OFF in all other cases.
Less Than or	<=	ON if $C1 \le C2$ .
Equal Flag		OFF in all other cases.
Negative Flag	N	Unchanged

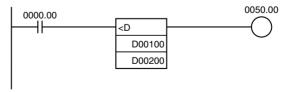
**Precautions** 

Input comparison instructions cannot be used as right-hand instructions, i.e., another instruction must be used between them and the right bus bar.

# **Example**

### AND DOUBLE FLOATING LESS THAN: AND<D(331)

When CIO 0000.00 is ON in the following example, the floating point data in words D00100 to D00103 is compared to the floating point data in words D00200 to D00203. If the content of D00100 to D00103 is less than that of D00200 to D00203, execution proceeds to the next line and CIO 0050.00 is turned ON. If the content of D00100 to D00103 is not less than that of D00200 to D00203, execution does not proceed to the next instruction line.



# DOUBLE FLOATING LESS THAN Comparison (<D)

15	0	15	0	
S1 :D00100 100010110100	0100	S2 :D00100 0111	100100111110	
S1+1:D00101 111001110110	1100	S2+1:D00101 1 0 1 0	100001011000	
S1+2:D00102 1 0 1 0 1 0 1 1 1 1 1	1011	S2+2:D00102 1 1 0 0	110100110101	
S1+3:D00103 0 1 0 0 0 0 0 0 0 0 0	1011	S2+3:D00103 0 0 1 1	111111110111	
Decimal value: 3.45	80	Decima	ıl value: -1.4876	
		34580>14876		
Does not yield an ON condition.				

15	0 15	0			
S1:D00100	S2:D00100 010101000 S2+1:D00101 10101000 S2+2:D00102 010010010 S2+3:D00103 010010010	00101011			
Decimal value: -3.4580E+4	48 Decimal value:	1.4876E+48			
	-3.4580E+48<1.4876E+48				
Yields an ON condition.					

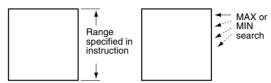
# 3-16 Table Data Processing Instructions

This section describes instructions used to handle table data.

Instruction	Mnemonic	Function code	Page
FIND MAXIMUM	MAX	182	467
FIND MINIMUM	MIN	183	471

#### **Range Instructions**

The range instructions included here act on a specified range of words to find the maximum value (MAX(182)) or minimum value (MIN(183)).

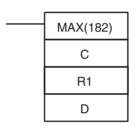


# 3-16-1 FIND MAXIMUM: MAX(182)

**Purpose** 

Finds the maximum value in a range.

**Ladder Symbol** 



C: First control word

R1: First word in range

D: Destination word

**Variations** 

Variations	Executed Each Cycle for ON Condition	MAX(182)
	<b>Executed Once for Upward Differentiation</b>	@MAX(182)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

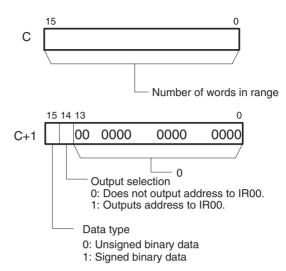
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

### C and C+1: Control words

C specifies the number of words in the range, bit 15 of C+1 indicates whether the data will be treated as signed binary or unsigned binary, and bit 14 of C+1 indicates whether or not to output the memory address of the word that contains the maximum value to IR00.

Note C and C+1 must be in the same data area.

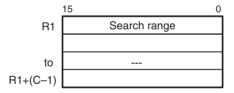


The following table shows the possible values of C+1.

C+1	Data type	Index Register output
0000	Unsigned binary	No
4000	Unsigned binary	Yes
8000	Signed binary	No
C000	Signed binary	Yes

### R1: First word in range

R1 specifies the first word in the search range. The words from R1 to R1+(C-1) are searched for the maximum value. (C is the number of words specified in C.)



Note R1 and R1+(C-1) must be in the same data area.

# **Operand Specifications**

Area	С	R1	D
CIO Area	CIO 0000 to CIO 6142	CIO 0000 to CIO 6	143
Work Area	W000 to W254	W000 to W255	
Auxiliary Bit Area	A000 to A958	A000 to A959	A448 to A959
Timer Area	T0000 to T0254	T0000 to T0255	
Counter Area	C0000 to C0254	C0000 to C0255	
DM Area	D00000 to D32766	D00000 to D32767	
Indirect DM addresses in binary	@ D00000 to @ D327	67	
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	Specified values only		
Data Resisters			DR0 to DR15

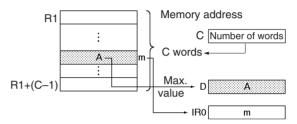
Area	С	R1	D
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to D	R0 to DR15, IR15	
	,IR0+(++) to ,IR15+(++		
,–(− –)IR0 to , –(− –)IR15			

#### Description

MAX(182) searches the range of memory from R1 to R1+C-1 for the maximum value in the range and outputs that maximum value to D.

When bit 14 of C+1 has been set to 1, MAX(182) writes the memory address of the word containing the maximum value to IR00. (If two or more words within the range contain the maximum value, the address of the first word containing the maximum value is written to IR00.)

When bit 15 of C+1 has been set to 1, MAX(182) treats the data within the range as signed binary data.



### **Flags**

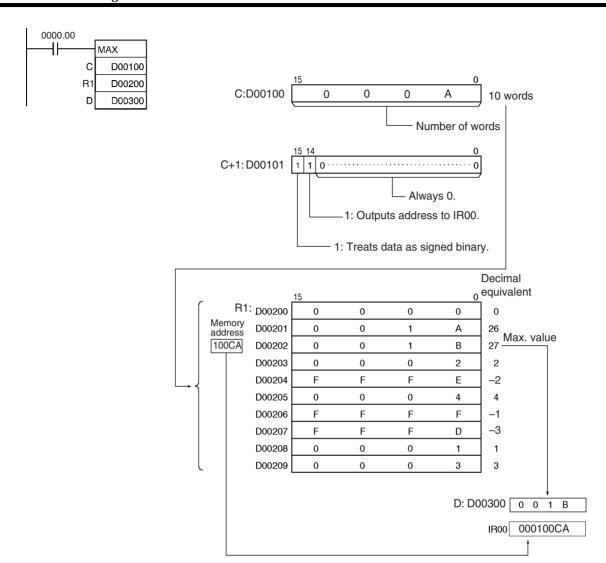
Name	Label	Operation
Error Flag	ER	ON if the content of C is not within the specified range of 0001 through FFFF.
		OFF in all other cases.
Equals Flag	=	ON if the maximum value is 0000.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 is ON in the word containing the maximum value.
		OFF in all other cases.

#### **Precautions**

When bit 15 of C+1 has been set to 1, the data within the range is treated as signed binary data and hexadecimal values 8000 to FFFF are considered negative. Thus, the results of the search will differ depending on the data-type setting.

### **Examples**

When CIO 0000.00 turns ON in the following example, MAX(182) searches the 10-word range beginning at D00200 for the maximum value. The maximum value is written to D00300 and the memory address of the word containing the maximum value is written to IR00.

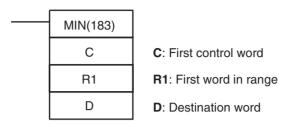


# 3-16-2 FIND MINIMUM: MIN(183)

### **Purpose**

Finds the minimum value in a range.

# **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	MIN(183)
	Executed Once for Upward Differentiation	@MIN(183)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

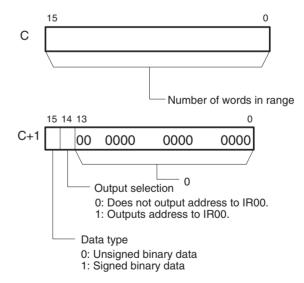
Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

### C and C+1: Control words

C specifies the number of words in the range, bit 15 of C+1 indicates whether the data will be treated as signed binary or unsigned binary, and bit 14 of C+1 indicates whether or not to output the memory address of the word that contains the minimum value to IR00.

Note C and C+1 must be in the same data area.

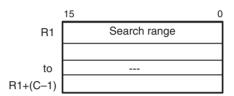


The following table shows the possible values of C+1.

C+1	Data type	Index Register output
0000	Unsigned binary	No
4000	Unsigned binary	Yes
8000	Signed binary	No
C000	Signed binary	Yes

### R1: First word in range

R1 specifies the first word in the search range. The words from R1 to R1+(C-1) are searched for the minimum value. (C is the number of words specified in C.)



Note R1 and R1+C-1 must be in the same data area.

### **Operand Specifications**

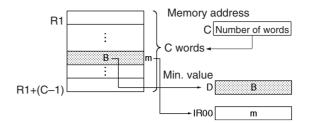
Area	С	R1	D
CIO Area	CIO 0000 to CIO 6142	CIO 0000 to CIO 6143	
Work Area	W000 to W254	W000 to W255	
Auxiliary Bit Area	A000 to A958	A000 to A959	A448 to A959
Timer Area	T0000 to T0254	T0000 to T0255	
Counter Area	C0000 to C0254	C0000 to C0255	
DM Area	D00000 to D00000 to D32767 D32766		,
Indirect DM addresses in binary	@ D0000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	Specified values only		
Data Resisters			DR0 to DR15
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+	+(++)	
	,-()IR0 to , -(	-)IR15	

#### **Description**

MIN(183) searches the range of memory from R1 to R1+C-1 for the minimum value in the range and outputs that minimum value to D.

When bit 14 of C+1 has been set to 1, MIN(183) writes the memory address of the word containing the minimum value to IR00. (If two or more words within the range contain the minimum value, the address of the first word containing the minimum value is written to IR00.)

When bit 15 of C+1 has been set to 1, MIN(183) treats the data within the range as signed binary data.



# Flags

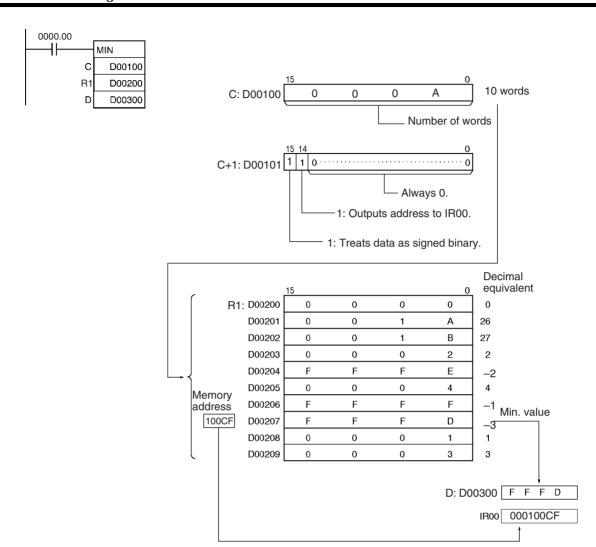
Name	Label	Operation
Error Flag	ER	ON if the content of C is not within the specified range of 0001 through FFFF.
		OFF in all other cases.
Equals Flag	=	ON if the minimum value is 0000.
		OFF in all other cases.
Negative Flag	N	ON if bit 15 is ON in the word containing the minimum value.
		OFF in all other cases.

#### **Precautions**

When bit 15 of C+1 has been set to 1, the data within the range is treated as signed binary data and hexadecimal values 8000 to FFFF are considered negative. Thus, the results of the search will differ depending on the data-type setting.

### **Examples**

When CIO 0000.00 turns ON in the following example, MIN(183) searches the 10-word range beginning at D00200 for the minimum value. The minimum value is written to D00300 and the memory address of the word containing the minimum value is written to IR00.



# 3-17 Data Control Instructions

This section describes instructions used to scale and average data.

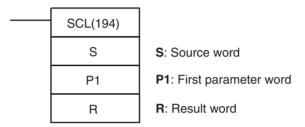
Instruction	Mnemonic	Function code	Page
SCALING	SCL	194	475
SCALING 2	SCL2	486	479
SCALING 3	SCL3	487	483
AVERAGE	AVG	195	486

# 3-17-1 SCALING: SCL(194)

**Purpose** 

Converts unsigned binary data into unsigned BCD data according to the specified linear function.

**Ladder Symbol** 



**Variations** 

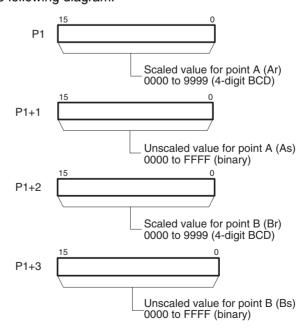
Variations	Executed Each Cycle for ON Condition	SCL(194)
	Executed Once for Upward Differentiation	@SCL(194)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

The contents of the four words starting with the first parameter word (P1) are shown in the following diagram.



Note P1 to P1+3 must be in the same area.

### **Operand Specifications**

Area	S	P1	R
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6140	CIO 0000 to CIO 6143
Work Area	W000 to W255	W000 to W252	W000 to W255
Auxiliary Bit Area	A000 to A959	A000 to A956	A448 to A959
Timer Area	T0000 to T0255	T0000 to T0252	T0000 to T0255
Counter Area	C0000 to C0255	C0000 to C0252	C0000 to C0255
DM Area	D00000 to D32767	D00000 to D32764	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Resisters	DR0 to DR15		DR0 to DR15
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IF	R0 to -2048 to +2047	7 ,IR15
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

### **Description**

SCL(194) is used to convert the unsigned binary data contained in the source word S into unsigned BCD data and place the result in the result word R according to the linear function defined by points (As, Ar) and (Bs, Br). The address of the first word containing the coordinates of points (As, Ar) and (Bs, Br) is specified for the first parameter word P1. These points are defined by 2 values (As and Bs) before scaling and 2 values (Ar and Br) after scaling.

The following equations are used for the conversion.

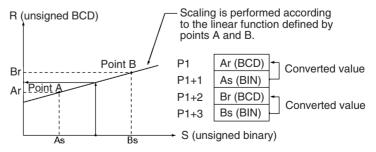
$$R = Br - \frac{(Br - Ar)}{BCD \ conversion \ of \ (Bs - As)} \ \times \ BCD \ conversion \ of \ (Bs - S)$$

The slope of the line is as follows:

$$R = Br - \frac{(Br - Ar)}{BCD \text{ conversion of } (Bs - As)}$$

Points A and B can define a line with either a positive or negative slope. Using a negative slope enables reverse scaling.

The result will be rounded to the nearest integer. If the result is less than 0000, 0000 will be output as the result. If the result is greater than 9999, 9999 will be output.



SCL(194) can be used to scale the results of analog signal conversion values from Motion Control Modules with Analog I/O (FQM1-MMA22) according to

user-defined scale parameters. For example, if a 1 to 5-V input to a Motion Control Module with Analog I/O is input to memory as 0000 to 0FA0 hexadecimal, the value in memory can be scaled to 50 to 200 BCD using SCL(194).

SCL(194) converts unsigned binary to unsigned BCD. To convert a negative value, it will be necessary to first add the maximum negative value in the program before using SCL(194) (see example).

SCL(194) cannot output a negative value to the result word, R. If the result is a negative value, 0000 will be output to R.

#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the contents of P1 (Ar) or P1+2 (Br) is not BCD.
		ON if the contents of P1+1 (As) and P1+3 (Bs) are equal.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000.
		OFF in all other cases.

#### **Precautions**

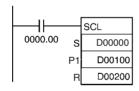
An error will occur and the Error Flag will turn ON if the values for Ar (P1) and Br (P1+2) are not in BCD, or if the values for As (P1+1) and Bs (P1+3) are equal.

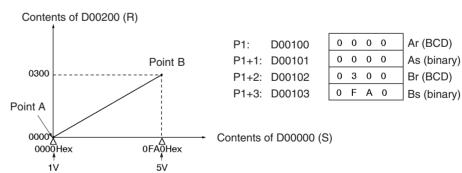
The Equals Flag will turn ON when the contents of the result word R is 0000.

#### **Examples**

In the following example, it is assume that an analog signal from 1 to 5 V is converted and input to D00000 as 0000 to 0FA0 hexadecimal. SCL(194) is used to convert (scale) the value in D00000 to a value between 0000 and 0300 BCD.

When CIO 0000.00 is ON, the contents of D00000 is scaled using the linear function defined by point A (0000, 0000) and point B (0FA0, 0300). The coordinates of these points are contained in D00100 to D00103, and the result is output to D00200.

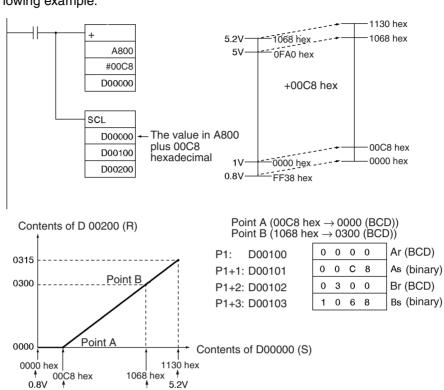




### **Negative Values**

A Motion Control Module actually inputs values from FF38 to 1068 hexadecimal for 0.8 to 5.2 V. SCL(194), however, can handle only unsigned binary values between 0000 and FFFF hexadecimal, making it impossible to use SCL(194) directly to handle signed binary values below 1 V (0000 hexadecimal), i.e., FF38 to FFFF hexadecimal. In an actual application, it is thus necessary to add 00C8 hexadecimal to all values so that FF38 hexadecimal is

Data Control Instructions Section 3-17



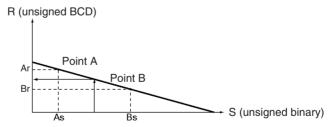
represented as 0000 hexadecimal before using SCL(194), as shown in the following example.

In this example, values from 0000 to 00C8 hexadecimal will be converted to negative values. SCL(194), however, can output only unsigned BCD values from 0000 to 9999, so 0000 BCD will be output whenever the content of D00000 is between 0000 and 00C8 hexadecimal.

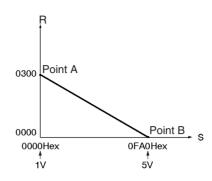
5V

#### **Reverse Scaling**

Reverse scaling can also be used by setting As < Bs and Ar > Br. The following relationship will result.



Reverse scaling can be used, for example, to convert (reverse scale) 1 to 5 V (0000 to 0FA0 hexadecimal) to 0300 to 0000, respectively, as shown in the following diagram.

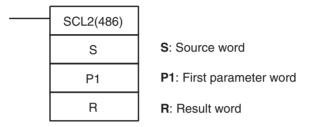


# 3-17-2 SCALING 2: SCL2(486)

**Purpose** 

Converts signed binary data into signed BCD data according to the specified linear function. An offset can be input in defining the linear function.

**Ladder Symbol** 



**Variations** 

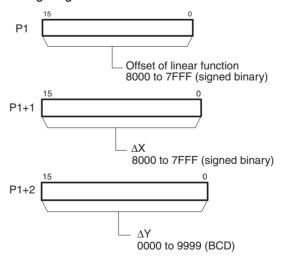
Variations	Executed Each Cycle for ON Condition	SCL2(486)
	Executed Once for Upward Differentiation	@SCL2(486)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

**Operands** 

The contents of the three words starting with the first parameter word (P1) are shown in the following diagram.



Note P1 to P1+2 must be in the same area.

# **Operand Specifications**

Area	S	P1	R
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6141	CIO 0000 to CIO 6143
Work Area	W000 to W255	W000 to W253	W000 to W255
Auxiliary Bit Area	A000 to A959	A000 to A957	A448 to A959
Timer Area	T0000 to T0255	T0000 to T0253	T0000 to T0255
Counter Area	C0000 to C0255	C0000 to C0253	C0000 to C0255
DM Area	D00000 to D32767	D00000 to D32765	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Resisters	DR0 to DR15		DR0 to DR15
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IF	10 to -2048 to +2047	7 ,IR15
	DR0 to DR15, IR0	to DR0 to DR15, IR	15
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

### **Description**

SCL2(486) is used to convert the signed binary data contained in the source word S into signed BCD data (the BCD data contains the absolute value and the Carry Flag shows the sign) and place the result in the result word R according to the linear function defined by the slope ( $\Delta X$ ,  $\Delta Y$ ) and an offset. The address of the first word containing  $\Delta X$ ,  $\Delta Y$ , and the offset is specified for the first parameter word P1. The sign of the result is indicated by the status of the Carry Flag (ON: negative, OFF: positive).

The following equations are used for the conversion.

$$R = \frac{\Delta Y}{BCD \text{ conversion of } \Delta X} \times ((BCD \text{ conversion of S}) - (BCD \text{ conversion of offset})$$

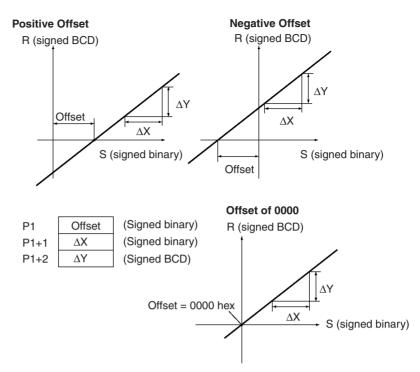
The slope of the line is  $\Delta Y/\Delta X$ .

The offset and slope can be a positive value, 0, or a negative value. Using a negative slope enables reverse scaling.

The result will be rounded to the nearest integer.

The result in R will be the absolute BCD conversion value and the sign will be indicated by the Carry Flag. The result can thus be between -9999 and 9999.

If the result is less than -9999, -9999 will be output as the result. If the result is greater than 9999, 9999 will be output.



SCL2(486) can be used to scale the results of analog signal conversion values from Motion Control Modules with Analog I/O (FQM1-MMA22) according to user-defined scale parameters. For example, if a 1 to 5-V input to a Motion Control Module is input to memory as 0000 to 0FA0 hexadecimal, the value in memory can be scaled to -100 to 200 BCD using SCL2(486).

SCL2(486) converts signed binary to signed BCD. Negative values can thus be handled directly for S. The result of scaling in R and the Carry Flag can also be used to output negative values for the scaling result.

### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the contents of P1+1 ( $\Delta X$ ) is 0000.	
		ON if the contents of P1+2 ( $\Delta Y$ ) is not BCD.	
		OFF in all other cases.	
Equals Flag	=	ON if the result is 0.	
		OFF in all other cases.	
Carry Flag	CY	ON if the result is negative.	
		OFF if the result is zero or positive.	

**Precautions** 

An error will occur and the Error Flag will turn ON if the value for  $\Delta X$  (P1+1) is 0000 or if the value for  $\Delta Y$  (P1+2) is not BCD.

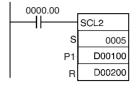
The Equals Flag will turn ON when the contents of the result word R is 0000. The Carry Flag will turn ON if the value placed in the result word is negative.

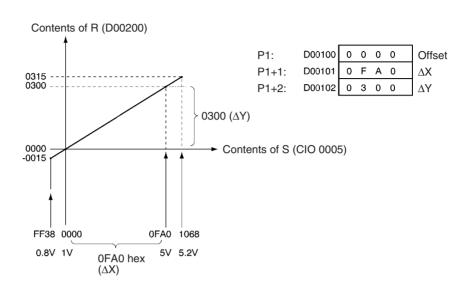
**Examples** 

# Scaling 1 to 5-V Analog Input to 0 to 300

In the following example, it is assumed that an analog signal from 1 to 5 V is converted and input to CIO 0005 as 0000 to 0FA0 hexadecimal. SCL2(486) is used to convert (scale) the value in CIO 0005 to a value between 0000 and 0300 BCD.

When CIO 0000.00 is ON, the contents of CIO 0005 is scaled using the linear function defined by  $\Delta X$  (0FA0),  $\Delta Y$  (0300), and the offset (0). These values are contained in D00100 to D00102, and the result is output to D00200.

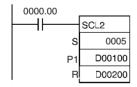


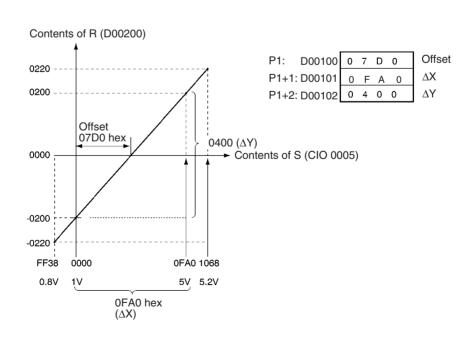


# Scaling 1 to 5-V Analog Input to -200 to 200

In the following example, it is assume that an analog signal from 1 to 5 V is converted and input to CIO 0005 as 0000 to 0FA0 hexadecimal. SCL2(486) is used to convert (scale) the value in CIO 0005 to a value between -0200 and 0200 BCD.

When CIO 0000.00 is ON, the contents of CIO 0005 is scaled using the linear function defined by  $\Delta X$  (0FA0),  $\Delta Y$  (0400), and the offset (07D0). These values are contained in D00100 to D00102, and the result is output to D00200.



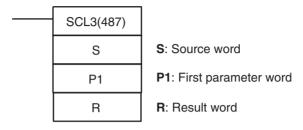


# 3-17-3 SCALING 3: SCL3(487)

### **Purpose**

Converts signed BCD data into signed binary data according to the specified linear function. An offset can be input in defining the linear function.

#### **Ladder Symbol**



# **Variations**

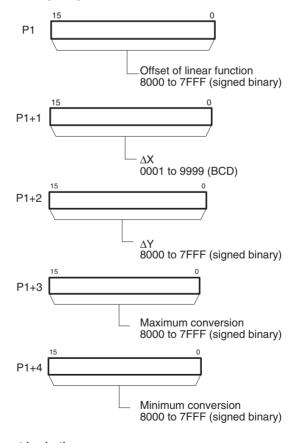
Variations	Executed Each Cycle for ON Condition	SCL3(487)
	Executed Once for Upward Differentiation	@SCL3(487)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

### **Operands**

The contents of the five words starting with the first parameter word (P1) are shown in the following diagram.



Note P1 to P1+4 must be in the same area.

#### **Operand Specifications**

Area	S	P1	R
CIO Area	CIO 0000 to CIO 6143	CIO 0000 to CIO 6139	CIO 0000 to CIO 6143
Work Area	W000 to W255	W000 to W251	W000 to W255
Auxiliary Bit Area	A000 to A959	A000 to A955	A448 to A959
Timer Area	T0000 to T0255	T0000 to T0251	T0000 to T0255
Counter Area	C0000 to C0255	C0000 to C0251	C0000 to C0255
DM Area	D00000 to D32767	D00000 to D32763	D00000 to D32767
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants			
Data Resisters	DR0 to DR15		DR0 to DR15
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IF	10 to -2048 to +2047	7 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -(	-)IR15	

### **Description**

SCL3(487) is used to convert the signed BCD data (the BCD data contains the absolute value and the Carry Flag shows the sign) contained in the source word S into signed binary data and place the result in the result word R according to the linear function defined by the slope ( $\Delta X$ ,  $\Delta Y$ ) and an offset. The maximum and minimum conversion values are also specified. The address of the first word containing  $\Delta X$ ,  $\Delta Y$ , the offset, the maximum conversion, and the minimum conversion is specified for the first parameter word P1.

The sign of the result is indicated by the status of the Carry Flag (ON: negative, OFF: positive). Use STC(040) and CLC(041) to turn the Carry Flag ON and OFF.

The following equations are used for the conversion.

$$R = \frac{\Delta Y}{Binary \ conversion \ of \ \Delta X} \ x \ ((Binary \ conversion \ of \ S) + (Offset))$$

The slope of the line is  $\Delta Y/\Delta X$ .

The offset and slope can be a positive value, 0, or a negative value. Using a negative slope enables reverse scaling.

The result will be rounded to the nearest integer.

The source value in S is treated as an absolute BCD value and the sign is indicated by the Carry Flag. The source value can thus be between -9999 and 9999.

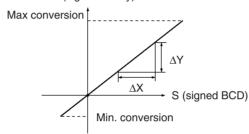
If the result is less than the minimum conversion value, the minimum conversion value will be output as the result. If the result is greater than the maximum conversion value, the maximum conversion value will be output.

# Positive Offset R (signed binary) Max conversion Max conversion Max conversion Min. conversion Offset S (signed BCD) S (signed BCD)

Min. conversion

#### Offset of 0000

R (signed binary)



SCL3(487) is used to convert data using a user-defined scale to signed binary for Analog Output Units. For example, SCL3(487) can convert 0 to 200  $^{\circ}$ C to 0000 to 0FA0 (hex) and output an analog output signal 1 to 5 V from the Analog Output Unit.

#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the contents of S is not BCD.
		ON if the contents of P1+1 ( $\Delta X$ ) is not between 0001 and 9999 BCD.
		OFF in all other cases.
Equals Flag	=	ON if the result is 0000.
		OFF in all other cases.
Negative Flag	N	ON when the MSB of the R (the result) is 1.
		OFF in all other cases.

#### **Precautions**

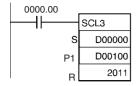
An error will occur and the Error Flag will turn ON if the contents of S is not BCD or if the value for  $\Delta X$  (P1+1) is not between 0001 and 9999 BCD.

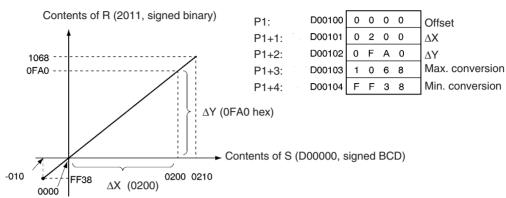
The Equals Flag will turn ON when the contents of the result word R is 0000. The Negative Flag will turn ON if the MSB of the result in R is 1, i.e., if the

result is negative.

#### **Examples**

When a value from 0 to 200 is scaled to an analog signal (1 to 5 V, for example), a signed BCD value of 0000 to 0200 is converted (scaled) to signed binary value of 0000 to 0FA0 for a Motion Control Module. When CIO 0000.00 turns ON in the following example, the contents of D00000 is scaled using the linear function defined by  $\Delta X$  (0200),  $\Delta Y$  (0FA0), and the offset (0). These values are contained in D00100 to D00102. The sign of the BCD value in D00000 is indicated by the Carry Flag. The result is output to CIO 2011.



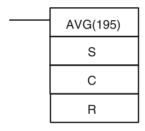


# 3-17-4 AVERAGE: AVG(195)

# **Purpose**

Calculates the average value of an input word for the specified number of cycles.

# **Ladder Symbol**



S: Source word

**C**: Control word (Number of cycles N and sign specification)

R: Result word (average)

R+1: First work area word

# **Variations**

Variations	Executed Each Cycle for ON Condition	AVG(195)
	Executed Once for Upward Differentiation	Not supported.
	Executed Once for Downward Differentiation	Not supported.

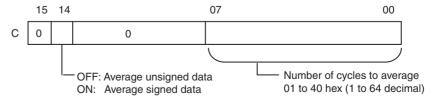
# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	OK	OK

#### **Operands**

# C: Number of Cycles and Sign Specification

The number of cycles N must be between 01 and 40 hexadecimal (1 to 64 cycles). Bit 14 specifies if signed data or unsigned data is used.



# R: Result Word (Average)

# R+1: First Work Area Word (Read-only)

R will contain the average value after the specified number of cycles. R+1 provides information on the averaging process and R+2 to R+N+3 contain the previous values of S as shown in the following diagram.

#### R: Average

R+1: Processing data (read-only)

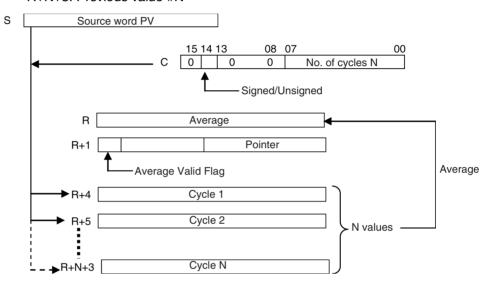
R+2: Processing data (read-only)

R+3: Processing data (read-only)

R+4: Previous value #1

R+5: Previous value #2

R+N+3: Previous value #N



Note R to R+N+3 must be in the same area.

# **Operand Specifications**

Area	S	С	R
CIO Area	CIO 0000 to CIO 6	CIO 000 to CIO 6139	
Work Area	W000 to W255		W000 to W251
Auxiliary Bit Area	A000 to A959		A448 to A955
Timer Area	T0000 to T0255		T0000 to T0251
Counter Area	C0000 to C0255		C0000 to C0251
DM Area	D00000 to D32767		D00000 to D32763
Indirect DM addresses in binary	@ D00000 to @ D32767		•
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	#0000 to #FFFF #0001 to #0040		
	(binary) (binary)		
Data Resisters	DR0 to DR15		

Area	S	С	R	
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -()IR15			

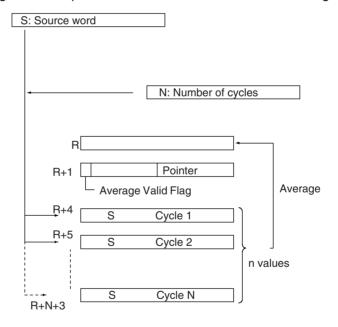
#### **Description**

For the first N–1 cycles when the execution condition is ON, AVG(195) writes the values of S (signed or unsigned binary data) in order to words starting with R+4. The Previous Value Pointer (bits 00 to 07 of R+1) is incremented each time a value is written. Until the Nth value is written, the contents of S will be output unchanged to R and the Average Value Flag (bit 15 of R+1) will remain OFF.

When the Nth value is written to R+N+3, the average of all the values that have been stored will be computed, the average will be output to R as a signed or unsigned binary value, and the Average Value Flag (bit 15 of R+1) will be turned ON. For all further cycles, the value in R will be updated for the most current N values of S. The maximum value of N is 64.

The Previous Value Pointer will be reset to 0 after N-1 values have been written.

The average value output to R will be rounded to the nearest integer.



# **Flags**

Name	Label	Operation
Error Flag	ER	ON if the value of N is 0.
		OFF in all other cases.

#### **Precautions**

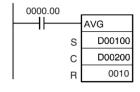
The contents of the First Work Area Word (R+1) is cleared to 0000 each time the execution condition changes from OFF to ON.

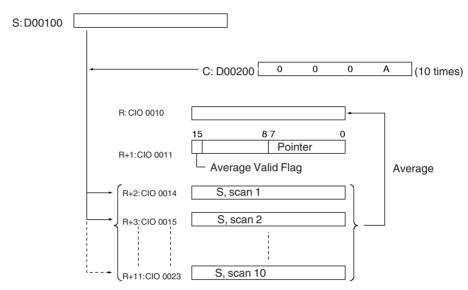
The contents of the First Work Area Word (R+1) will not be cleared to 0000 the first time the program is executed at the start of operation. If AVG(195) is to be executed in the first program scan, clear the First Work Area Word from the program.

If N (Number of Cycles) is 00, an error will occur and the Error Flag will turn ON.

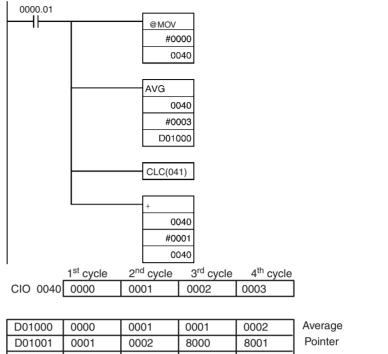
#### **Examples**

When CIO 0000.00 is ON in the following example, the contents of D00100 will be stored one time each scan for the number of scans specified in D00200. The contents will be stored in order in the ten words from CIO 0014 to CIO 0023. The average of the contents of these ten words will be placed in CIO 0010 and then bit 15 of CIO 0011 will be turned ON.





In the following example, the content of CIO 0040 is set to #0000 and then incremented by 1 each cycle. For the first two cycles, AVG(195) stores the content of CIO 0040 to D01004 and D01005. The contents of D01001 will also change (which can be used to confirm that the results of AVG(195) has changed). On the third and later cycles, AVG(195) calculates the average value of the contents of D01004 to D01006 and writes that average value to D01000.



D01000	0000	0001	0001	0002	Average
D01001	0001	0002	8000	8001	Pointer
D01002					
D01003					
D01004	0000	0000	0000	0003	3 previous values of
D01005		0001	0001	0001	CIO 0040
D01006			0002	0002	

# 3-18 Subroutines

This section describes instructions used to control subroutines.

Instruction	Mnemonic	Function code	Page
SUBROUTINE CALL	SBS	091	491
MACRO	MCRO	099	496
SUBROUTINE ENTRY	SBN	092	500
SUBROUTINE RETURN	RET	093	503
JUMP TO SUBROUTINE	JSB	982	503

# 3-18-1 SUBROUTINE CALL: SBS(091)

**Purpose** 

Calls the subroutine with the specified subroutine number and executes that program.

**Ladder Symbol** 



N: Subroutine number

**Variations** 

Variations	Executed Each Cycle for ON Condition	SBS(091)
	<b>Executed Once for Upward Differentiation</b>	@SBS(091)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

**Operands** 

#### N: Subroutine number

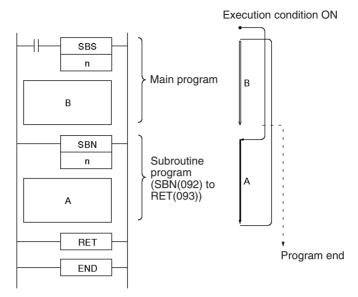
Specifies the subroutine number between 0 and 255 decimal.

# **Operand Specifications**

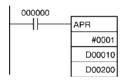
Area	N
CIO Area	
Work Area	
Auxiliary Bit Area	
Timer Area	
Counter Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	0 to 255 (decimal)
Data Resisters	
Index Registers	
Indirect addressing using Index Registers	

Description

SBS(091) calls the subroutine with the specified subroutine number. The subroutine is the program section between SBN(092) and RET(093). When the subroutine is completed, program execution continues with the next instruction after SBS(091).

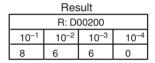


Subroutines can be nested up to 16 levels. Nesting is when another subroutine is called from within a subroutine program, such as shown in the following example, which is nested to 3 levels.

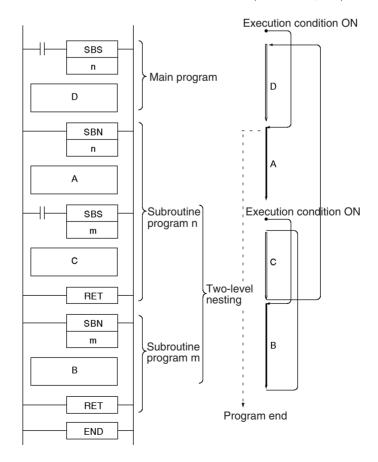


Source data					
S: D00010					
0 10 <sup>1</sup> 10 <sup>0</sup> 10 <sup>-1</sup>					
0 3 0 0					

Set the source	data in	10 <sup>-1</sup>	degrees
(0000 to 0900,	BCD)		Ü



Result data has four significant digits, fifth and higher digits are ignored. (0000 to 9999, BCD)

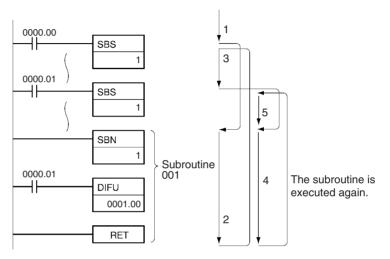


**Note** A subroutine can be called more than once in a program.

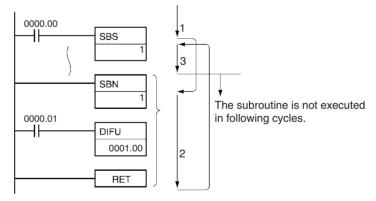
# Subroutines and Differentiation

Observe the following precautions when using differentiated instructions (DIFU(013), DIFU(014), or up/down differentiated instructions) in subroutines.

The operation of differentiated instructions in a subroutine is unpredictable if a subroutine is executed more than once in the same cycle. In the following example, subroutine 001 is executed when CIO 0000.00 is ON and CIO 0001.00 is turned ON by DIFU(013) when CIO 0000.01 has gone from OFF to ON. If CIO 0000.01 is ON in the same cycle, subroutine 001 will be executed again but this time DIFU(013) will turn CIO 0001.00 OFF without checking the status of CIO 0000.01.



In contrast, the output of a differentiated instruction (DIFU(013) or DIFD(014)) would remain ON if the instruction was executed and the output was turned ON but the same subroutine was not called a second time.



In the following example, subroutine 001 is executed if CIO 0000.00 is ON. Output CIO 0001.00 is turned ON by DIFU(013) when CIO 0000.01 has gone from OFF to ON. If CIO 0000.00 is OFF in the following cycle, subroutine 001 will not be executed again and output CIO 0001.00 will remain ON.

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if nesting exceeds 16 levels.
		ON if the specified subroutine number does not exist.
		ON if a subroutine calls itself.
		ON if a subroutine being executed is called.
		ON if the specified subroutine is not defined in the current task.
		OFF in all other cases.

#### **Precautions**

SBS(091) and the corresponding SBN(092) must be programmed in the same task. An error will occur if the corresponding SBN(092) is not in the task.

SBS(091) will be treated as NOP(000) when it is within a program section interlocked by IL(002) and ILC(003).

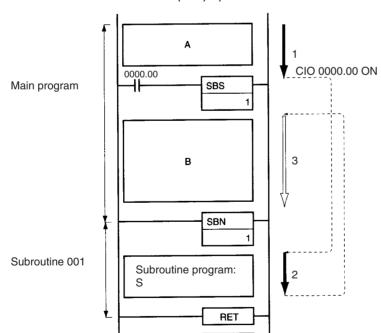
When SBS(091) is executed in the following cases, the subroutine will not actually be called and the Error Flag will be turned ON:

- 1,2,3... 1. The specified subroutine is not defined within the current task.
  - 2. The subroutine is calling itself.
  - 3. Subroutine nesting exceeds 16 levels.
  - 4. The specified subroutine is being executed.

# **Examples**

# **Example 1: Sequential (Non-nested) Subroutines**

When CIO 0000.00 is ON in the following example, subroutine 001 is executed and program execution returns to the next instruction after SBS(091). The remainder of the main program (through the instruction just before SBN(092) 1) is then executed.

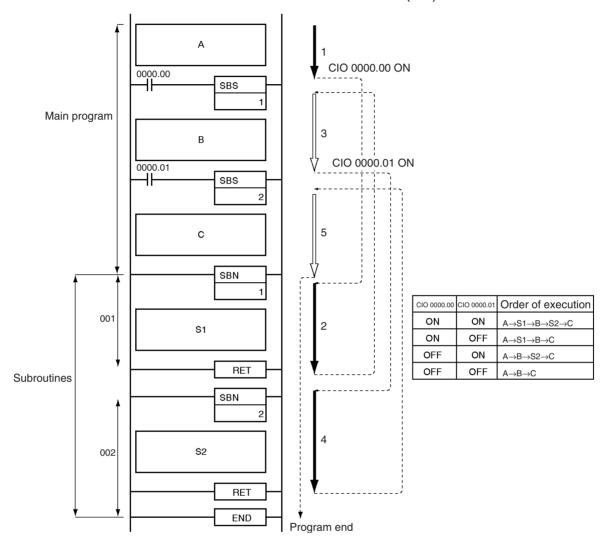


**END** 

CIO 0000.00	Order of execution
ON	$A \rightarrow S \rightarrow B$
OFF	A→B

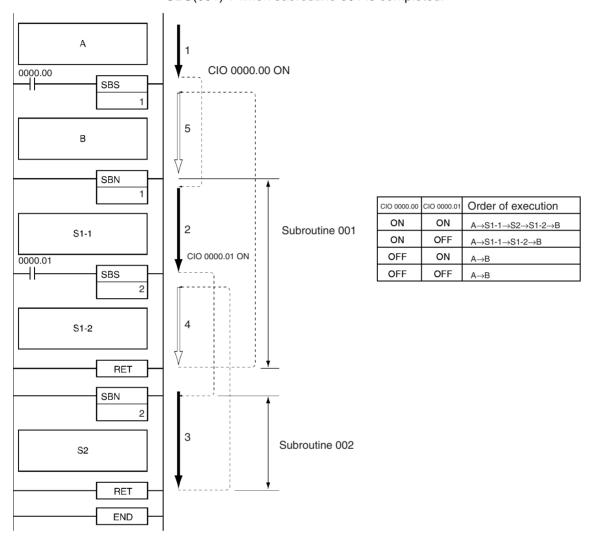
# **Example 2: Sequential (Non-nested) Subroutines**

When CIO 0000.00 is ON in the following example, subroutine 001 is executed and program execution returns to the next instruction after SBS(091) 1. When CIO 0000.01 is ON, subroutine 002 is executed and program execution returns to the next instruction after SBS(091) 2.



# **Example 3: Nested Subroutines**

When CIO 0000.00 is ON in the following example, subroutine 001 is executed. If CIO 0000.01 is ON, subroutine 002 is executed from within subroutine 001 and program execution returns to the next instruction after SBS(091) 2 when subroutine 002 is completed. Execution of subroutine 001 continues and program execution returns to the next instruction after SBS(091) 1 when subroutine 001 is completed.

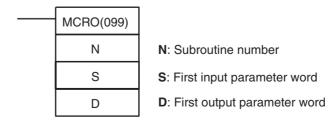


# 3-18-2 MACRO: MCRO(099)

**Purpose** 

Calls the subroutine with the specified subroutine number and executes that program using the input parameters in S to S+4 and the output parameters in D to D+4.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	MCRO(099)
	Executed Once for Upward Differentiation	@MCRO(099)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

#### N: Subroutine number

Specifies the subroutine number between 0 and 255 decimal.

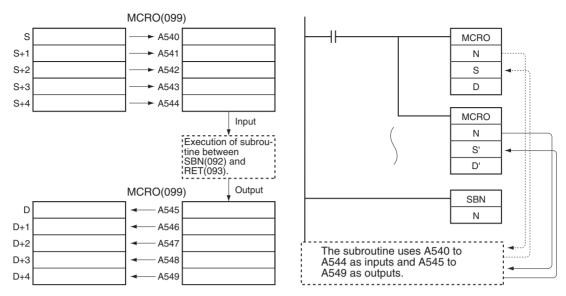
# **Operand Specifications**

Area	N	S	D
CIO Area		CIO 0000 to CIO 6	139
Work Area		W000 to W251	
Auxiliary Bit Area		A000 to A443	A448 to A955
		A448 to A955	
Timer Area		T0000 to T0251	
Counter Area		C0000 to C0251	
DM Area		D00000 to D32763	
Indirect DM addresses in binary		@ D00000 to @ D32767	
Indirect DM addresses in BCD		*D00000 to *D32767	
Constants	0 to 255 (decimal)		
Data Resisters			
Index Registers			
Indirect addressing		,IR0 to ,IR15	
using Index Registers		-2048 to +2047 ,IF +2047 ,IR15	10 to -2048 to
		DR0 to DR15, IR0 IR15	to DR0 to DR15,
		,IR0+(++) to ,IR15+	+(++)
		,-()IR0 to , -(	-)IR15

# **Description**

MCRO(099) calls the subroutine with the specified subroutine number just like SBS(091). Unlike SBS(091), MCRO(099) operands S and D can be used to change bit and word addresses in the subroutine, although the structure of the subroutine is constant.

When MCRO(099) is executed, the contents of S through S+4 are copied to A540 through A544 (macro area inputs) and the specified subroutine is executed. When the subroutine is completed, the contents of A545 through A549 (macro area outputs) are copied to D through D+4 and program execution continues with the next instruction after MCRO(099).



MCRO(099) can be used to consolidate two or more subroutines with the same structure but different input and output addresses into a single subroutine program. When MCRO(099) is executed, the specified input and output data is transferred to the specified subroutine.

#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if nesting exceeds 16 levels.
		ON if the specified subroutine number does not exist.
		ON if a subroutine calls itself.
		ON if a subroutine being executed is called.
		ON if the specified subroutine is not defined in the current task.
		OFF in all other cases.

The following table shows relevant words in the Auxiliary Area.

Name	Address	Operation
Macro area input words	A540 to A544	When MCRO(099) is executed the five words from S to S+4 are copied to A510 to A514. These input words are passed to the subroutine.
Macro area input words	A545 to A549	After the subroutine specified in MCRO(099) has been executed, the output data in these output words and copied to D to D+4.

#### **Precautions**

The five words of input data (words or bits) in A540 to A544 and the five words of output data (words or bits) in A545 to A549 must be used in the subroutine called by MCRO(099). It is not possible to pass more than five words of data.

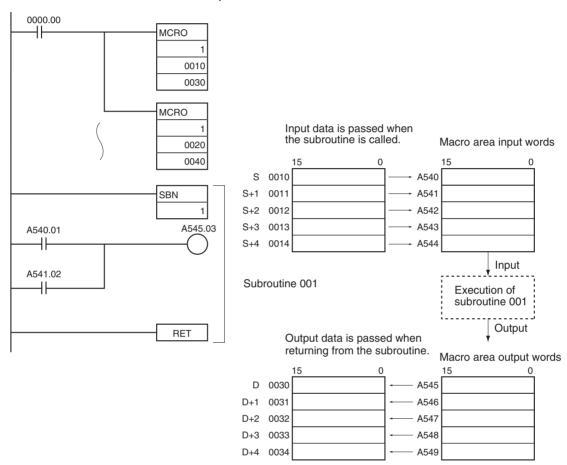
It is possible to nest MCRO(099) instructions, but the data in the macro area input and output words (A540 to A549) must be saved when calling nested subroutine because all MCRO(099) instructions use the same 10 words.

# Example

When CIO 0000.00 is ON in the following example, two MCRO(099) instructions pass different input and output data to subroutine 001.

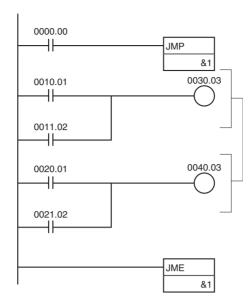
The first MCRO(099) instruction passes the input data in CIO 0010 to CIO 0014 and executes the subroutine. When the subroutine is completed, the output data is stored in CIO 0030 to CIO 0034.

2. The second MCRO(099) instruction passes the input data in CIO 0020 to CIO 0024 and executes the subroutine. When the subroutine is completed, the output data is stored in CIO 0040 to CIO 0044.



The second MCRO(099) instruction operates in the same way, but the input data in CIO 0020 to CIO 0024 is passed to A540 to A544 and the output data in A545 to A549 is passed to CIO 0040 to CIO 0044.

The above programming is equivalent to the following programming.

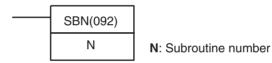


# 3-18-3 SUBROUTINE ENTRY: SBN(092)

#### **Purpose**

Indicates the beginning of the subroutine program with the specified subroutine number. Used in combination with RET(093) to define a subroutine region.

# **Ladder Symbol**



# **Variations**

Variations	Executed Each Cycle for ON Condition	SBN(092)

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	Not allowed	Not allowed	OK

# **Operands**

#### N: Subroutine number

Specifies the subroutine number between 0 and 255 decimal.

# **Operand Specifications**

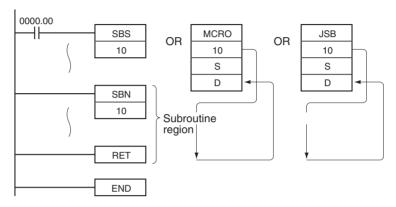
Area	N
CIO Area	
Work Area	
Auxiliary Bit Area	
Timer Area	
Counter Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	0 to 255 (decimal)
Data Resisters	

Area	N
Index Registers	
Indirect addressing using Index Registers	

#### Description

SBN(092) indicates the beginning of the subroutine with the specified subroutine number. The end of the subroutine is indicated by RET(093).

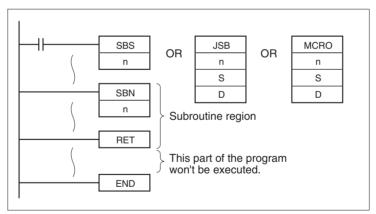
The region of the program beginning at the first SBN(092) instruction is the subroutine region. A subroutine is executed only when it has been called by SBS(091), JSB(982), or MCRO(099).



#### **Precautions**

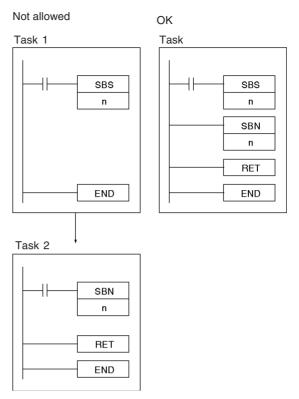
When the subroutine is not being executed, the instructions are treated as NOP(000).

Place the subroutines after the main program and just before the END(001) instruction in the program for each task. If part of the main program is placed after the subroutine region, that program section will be ignored.

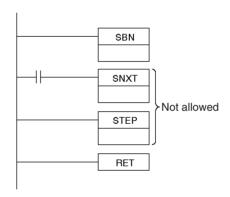


Note Input #0 to #1023 on the CX-Programmer to input the subroutine number, N.

Be sure to place each subroutine in the same program (task) as its corresponding SBS(091), JSB(982), or MCRO(099) instruction. A subroutine in one task cannot be called from another task. It is possible to program a subroutine within an interrupt task.

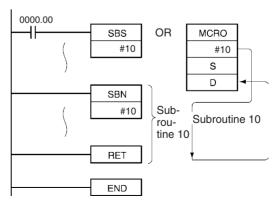


The step instructions, STEP(008) and SNXT(009) cannot be used in subroutines.



Example

When CIO 0000.00 is ON in the following example, subroutine 10 is executed and program execution returns to the next instruction after the SBS(091) or MCRO(099) instruction that called the subroutine.



# 3-18-4 SUBROUTINE RETURN: RET(093)

Purpose Indicates the end of a subroutine program. Used in combination with

SBN(092) to define a subroutine region.

**Ladder Symbol** 

RET(093)

**Variations** 

 Variations
 Executed Each Cycle for ON Condition
 RET(093)

**Applicable Program Areas** 

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	Not allowed	OK	OK

**Description** RET(093) indicates the end of a subroutine and SBN(092) indicates the

beginning of a subroutine. See 3-18-3 SUBROUTINE ENTRY: SBN(092) for

more details on the operation of subroutines.

When program execution reaches RET(093), it is automatically returned to the next instruction after the SBS(091), JSB(982), or MCRO(099) instruction that called the subroutine. When the subroutine has been called by MCRO(099), the output data in A545 through A549 is written to D through

D+4 before program execution is returned.

Precautions When the subroutine is not being executed, the instructions are treated as

NOP(000).

**Example** See *3-18-3 SUBROUTINE ENTRY: SBN(092)* for examples of the operation

of RET(093).

# 3-18-5 JUMP SUBROUTINE: JSB(982)

Purpose Always calls the subroutine with the specified subroutine number regardless

of the ON/OFF status of the execution condition.

The ON/OFF status of the execution condition is stored in the bit between A019.00 and A034.15 that corresponds to the specified subroutine number

(between 0 and 255).

**Ladder Symbol** 

JSB(982)

N N: Subroutine number

S S: First input parameter word

D D: First output parameter word

**Associated Instructions** 

• SUBROUTINE ENTRY: SBN(092)

• SUBROUTINE RETURN: RET(093)

**Variations** 

Variations	Executed Each Cycle	JSB(982)

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

#### N: Subroutine number

Specifies the subroutine number between 0 and 255 decimal.

#### S: First input parameter word

Specifies the first word of the data to be passed to the subroutine.

The memory address of the specified word is set in Index Register IR0.

#### D: First output parameter word

Specifies the first word of the data to be passed out of the subroutine.

The memory address of the specified word is set in Index Register IR0.

#### **Operand Specifications**

Area	N	S	D
CIO Area		CIO 0000 to CIO 6143	
Work Area		W000 to W255	
Auxiliary Bit Area		A000 to A959	A448 to A959
Timer Area		T0000 to T0255	
Counter Area		C0000 to C0255	
DM Area		D00000 to D32767	
Indirect DM addresses in binary		@ D00000 to @ D32767	
Indirect DM addresses in BCD		*D00000 to *D32767	
Constants	0 to 255 (decimal)		
Data Resisters			
Index Registers			
Indirect addressing using Index Registers		,IR2 to ,IR15 -2048 to +2047 ,IR2 to -2048 to +2047 ,IR15 DR0 to DR15, IR2 to DR0 to DR15, IR15 ,IR2+(++) to ,IR15+(++) ,-()IR2 to , -()IR15	

#### **Description**

The specified subroutine is always started, so the JSB(982) instruction's execution condition does not control execution of the instruction. Instead, the execution condition is automatically stored in a corresponding Auxiliary Area bit (A019.00 and A034.15) as the Powerflow Flag. That Powerflow Flag can be used in the subroutine as a switch to perform different processing.

JSB(982) will be executed even when the execution condition is OFF. JSB(982) stores the status of the execution condition in the corresponding bit (A019.00 and A034.15 correspond to subroutine numbers 0 to 255) and calls the specified subroutine. The execution condition (Powerflow Flag stored in A019.00 and A034.15) can be used in the subroutine to control processing.

#### Example 1:

When the execution condition is ON, jogging is performed. When the execution condition is OFF, the axis is stopped or decelerated.

#### Example 2:

When the execution condition goes from OFF to ON, a communications instruction is executed. Even if the execution condition is OFF, the communications instruction will receive the response and communications processing will be monitored until it is completed.

#### **Using Index Registers for General-purpose Subroutines**

With JSB(982), the words containing the input data can be specified and the memory address of the beginning word is automatically stored in IRO so the

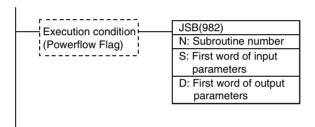
specified subroutine can be used repeatedly. When Index Register IR0 is indirectly addressed in the subroutine, the subroutine accesses the first word containing the desired input data and that input data is read and processed.

The output parameter words can be specified in the same way, and the beginning word for the output data is automatically stored in IR1. Index Register IR1 can be indirectly addressed in the subroutine to write the processing results to the desired words as output data.

Note

- With SBS(091), the subroutine is completely skipped when the execution condition (Powerflow Flag) is OFF. Therefore, if SBS(091) is used to call the subroutine, any processing required when the execution condition is OFF cannot be included in the subroutine. (For example, a subroutine that performs jogging when the execution condition is ON cannot contain processing such as stopping or decelerating an axis required when the execution condition is OFF).
- 2. With SBS(091), there is no function in the subroutine to indicate whether or not the subroutine is being executed for the first time. Therefore, if SBS(091) is used to call the subroutine, it is not possible to divide processing over several cycles in that subroutine.

#### Operation of JSB(982)



**Note** JSB(982) will be executed even when the execution condition (Powerflow Flag) is OFF.

When JSB(982) is executed, it performs the following operations:

**1,2,3...** 1. The subroutine is started and the corresponding Subroutine Powerflow Flag (A019.00 and A034.15) is turned ON.

Address		Corresponding subroutine
Word	Bit	number
A019	00 to 15	SBN000 to SBN015
A020	00 to 15	SBN016 to SBN031
A021	00 to 15	SBN032 to SBN047
to		to
A034	00 to 15	SBN240 to SBN255

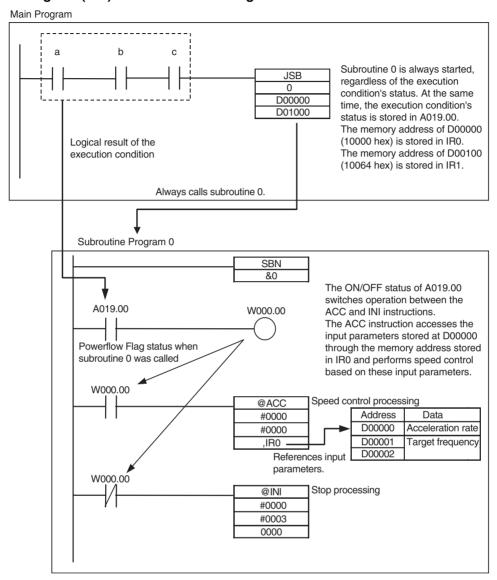
- The memory addresses of the first input parameter word (S) and first output parameter word (D) are stored in Index Registers IRO and IR1, respectively.
- 3. The specified subroutine is executed up to RET(093), the SUBROUTINE RETURN instruction.
- 4. The JSB(982) instruction ends.

**Note** If JSB(982) is placed in a program section between IL(002) and ILC(003), JSB(982) will execute the subroutine even when the program section is interlocked. The contents of the destination subroutine will be interlocked.

# **Flags**

None of the Condition Flags are affected by this instruction.

# Example: Executing JSB(982) with a Powerflow Flag

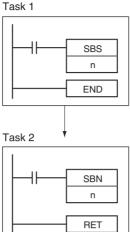


Section 3-18 **Subroutines** 

# **Example Task Structure**

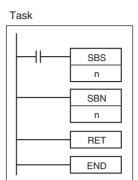
Incorrect

Task 1



END

Correct



# 3-19 Interrupt Control Instructions

This section describes instructions used to control interrupts and interrupt timers.

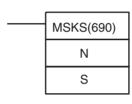
Instruction	Mnemonic	Function code	Page
SET INTERRUPT MASK	MSKS	690	508
READ INTERRUPT MASK	MSKR	692	510
CLEAR INTERRUPT	CLI	691	512
DISABLE INTERRUPTS	DI	693	513
ENABLE INTERRUPTS	El	694	514
INTERVAL TIMER	STIM	980	516

# 3-19-1 SET INTERRUPT MASK: MSKS(690)

#### **Purpose**

Both I/O interrupt tasks and scheduled interrupt tasks are masked (disabled) when the Module enters RUN mode. MSKS(690) can be used to unmask or mask I/O interrupts. MSKS(690) can be used only for FQM1-MMP22 and FQM1-MMA22 Motion Control Modules.

# **Ladder Symbol**



N: Interrupt identifier

S: Interrupt data

#### **Variations**

Variations	Executed Each Cycle for ON Condition	MSKS(690)
	Executed Once for Upward Differentiation	@MSKS(690)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	ОК	OK

# Specifying I/O Interrupt Processing and Mask Processing

Operand	Contents
N	Specify the interrupt input number.
	#0000: Interrupt input 0 #0001: Interrupt input 1 #0002: Interrupt input 2 #0003: Interrupt input 3 #0004: Phase-Z input counter clear interrupt for counter 1 (See note 1.) #0005: Phase-Z input counter clear interrupt for counter 2 (See note 1.)
S	Interrupt mask.  0000 hex: Interrupt enabled  0001 hex: Interrupt masked  0002 hex: Decrementing counter started and interrupts enabled (See note 2.)

# Note

- 1. These settings can be used only in CPU Units with unit version 3.2 or later.
- 2. S cannot be set to #0002 if N has been set to #0004 or #0005.

The relationship between interrupt input numbers and interrupt task numbers is shown in the following table.

Interrupt input number	Interrupt task numbers	
Interrupt input 0	000	CIO 2960.00
Interrupt input 1	001	CIO 2960.01
Interrupt input 2	002	CIO 2960.02
Interrupt input 3	003	CIO 2960.03
Phase-Z input counter clear interrupt for counter 1	004	If the reset method is set to <i>Phase-Z</i> signal + software reset, the task
Phase-Z input counter clear interrupt for counter 2	005	starts when a counter reset is per- formed by the phase-Z signal.

# **Operand Specifications**

Area	N	S
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A000 to A959
Timer Area		T0000 to T0255
Counter Area		C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ 32767
Indirect DM addresses in BCD		*D00000 to *D32767
Constants	Specified values only	#0 to #2
Data Resisters		DR0 to DR15
Index Registers		
Indirect addressing		,IR0 to ,IR15
using Index Registers		-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
		DR0 to DR15, IR0 to DR0 to DR15, IR15
		,IR0+(++) to ,IR15+(++)
		,-()IR0 to , -()IR15

# Flags

Name	Label	Operation
Error Flag	ER	ON if the specified range exceeds an area boundary.
		ON if the specified value exceeds the allowable range.
		ON if N is not within the specified range of 0 to 5 hex.
		ON if S is not within the specified range of 0 to 2 hex.
		OFF in all other cases.
Equals Flag	=	OFF
Negative Flag	N	OFF

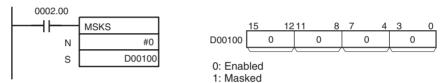
# **System Setup Settings**

Name	Description		Settings
Interrupt	Specify whether built-	00 hex:	Normal (default)
Input Settings	in inputs are to be used as normal inputs	01 hex:	Interruption (up) (interrupt when input turns ON)
	or as interrupt inputs.	02 hex:	Interruption (down) (interrupt when input turns OFF)
		03 hex:	Interruption (both edge) (interrupt when input turns ON or OFF)
Pulse	Specify the counter's	0 hex: Software reset (default setting)	
Input	reset method.	1 hex: Phase-Z signal + software reset	
Setting	An interrupt task can be started only when this value is set to 1 hex.		

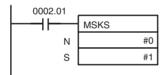
# **Examples**

# **Examples**

When CIO 0002.00 turns ON in the following example, MSKS(690) unmasks (enables) interrupt input 0.



When CIO 0002.01 turns ON in the following example, MSKS(690) disables interrupt input 0.

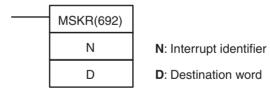


# 3-19-2 READ INTERRUPT MASK: MSKR(692)

# **Purpose**

Reads the current interrupt processing settings that were set with MSKS(690).

# **Ladder Symbol**



# **Variations**

Variations	Executed Each Cycle for ON Condition	MSKR(692)
	Executed Once for Upward Differentiation	@MSKR(692)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Reading Masks**

Operand	Contents
N	Specify the interrupt input number.
	#0000: Interrupt input 0 #0001: Interrupt input 1 #0002: Interrupt input 2 #0003: Interrupt input 3 #0004: Phase-Z input counter clear interrupt for counter 1 (See note.) #0005: Phase-Z input counter clear interrupt for counter 2 (See note.)

Note These settings can be used only in CPU Units with unit version 3.2 or later.

The relationship between interrupt input numbers and interrupt task numbers is shown in the following table.

Interrupt input number	Interrupt task numbers	
Interrupt input 0	000	CIO 2960.00
Interrupt input 1	001	CIO 2960.01
Interrupt input 2	002	CIO 2960.02
Interrupt input 3	003	CIO 2960.03
Phase-Z input counter clear interrupt for counter 1	004	If the reset method is set to <i>Phase-Z</i> signal + software reset, the task
Phase-Z input counter clear interrupt for counter 2	005	starts when a counter reset is per- formed by the phase-Z signal.

# **Operand Specifications**

Area	N	D
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A448 to A959
Timer Area		T0000 to T0255
Counter Area		C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ D32767
Indirect DM addresses in BCD		*D00000 to *D32767
Constants	Specified values only	
Data Resisters		DR0 to DR15
Index Registers		
Indirect addressing		,IR0 to ,IR15
using Index Registers		-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
		DR0 to DR15, IR0 to DR0 to DR15, IR15
		,IR0+(++) to ,IR15+(++)
		,-()IR0 to , -()IR15

# Description

MSKR(692) reads the interrupt input settings specified with MSKS(690). The status (disabled/enabled) of the input interrupt specified with N is output to D.

# **Flags**

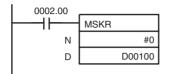
Name	Label	Operation	
Error Flag	ER	ON if N is not within the specified range of 0 to 5.	
		OFF in all other cases.	

# **Precautions**

MSKR(692) can be executed in the main program or in interrupt tasks.

# **Examples**

When CIO 0002.00 turns ON in the following example, MSKR(692) reads the current mask status of Interrupt Input 0 and stores it in D00100.





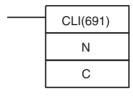
0000: Interrupt enabled 0001: Interrupt masked

# 3-19-3 CLEAR INTERRUPT: CLI(691)

**Purpose** 

Clears or retains recorded interrupt inputs.

**Ladder Symbol** 



N: Interrupt number

C: Control data

**Variations** 

Variations	Executed Each Cycle for ON Condition	CLI(691)
	Executed Once for Upward Differentiation	@CLI(691)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
ОК	OK	OK	OK

# **Operand Specifications**

Operand	Contents
N	Specify the interrupt input number.
	#0000: Interrupt input 0 #0001: Interrupt input 1 #0002: Interrupt input 2 #0003: Interrupt input 3 #0004: Phase-Z input counter clear interrupt for counter 1 (See note.) #0005: Phase-Z input counter clear interrupt for counter 2 (See note.)
С	Control data: Interrupt mask clear specification.
	0000 hex: Recorded interrupt input retained. 0001 hex: Recorded interrupt input cleared.

Note These settings can be used only in CPU Units with unit version 3.2 or later.

Area	N	С
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A000 to A959
Timer Area		T0000 to T0255
Counter Area		C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ D32767

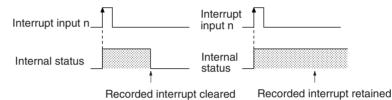
Area	N	С
Indirect DM addresses in BCD		*D00000 to *D32767
Constants	Refer to the previous tabl	e.
Data Resisters		DR0 to DR15
Index Registers		
Indirect addressing using Index Registers		,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
		DR0 to DR15, IR0 to DR0 to DR15, IR15
		,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15

# **Description**

CLI(691) clears or retains the specified recorded input interrupt.

Values #0000 to #0003 correspond to interrupt inputs 0 to 3.

CLI(691) clears a recorded interrupt input when the corresponding bit of C is ON and retains the recorded interrupt input when the corresponding bit is OFF.



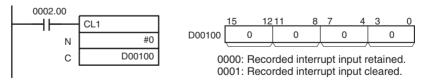
If an interrupt task is being executed and an interrupt input with a different interrupt number is received, that interrupt number is recorded internally. The recorded interrupts are executed later in order of their priority (from the lowest number to the highest). CLI(691) can be used to clear these recorded interrupts before they are executed.

#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if N is not between 0 to 5.
		ON if C is not between 0000 and 0001 hex.
		OFF in all other cases.

# **Examples**

When CIO 0002.00 turns ON in the following example, CLI(691) clears the recorded interrupts for interrupt input 0.



# 3-19-4 DISABLE INTERRUPTS: DI(693)

**Purpose** 

Disables execution of all interrupt tasks.

**Ladder Symbol** 



#### **Variations**

Variations	Executed Each Cycle for ON Condition	DI(693)
	Executed Once for Upward Differentiation	@DI(693)
	Executed Once for Downward Differentiation	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	Not allowed

# **Description**

DI(693) is executed from the main program to temporarily disable all interrupt tasks (input interrupt tasks, interval timer interrupt tasks, pulse output interrupt tasks, and high-speed counter interrupt tasks). All interrupt tasks will be disabled until they are enabled again by execution of EI(694).

#### Note

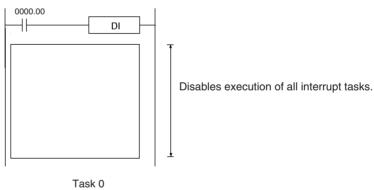
- 1. Use EI(694) to enable interrupts again.
- 2. DI(693) cannot be executed in an interrupt task. Attempting to do so will cause an error and the Error Flag will turn ON.

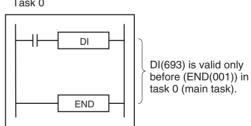
# **Flags**

Name	Label	Operation
Error Flag	ER	ON if DI(693) is executed from an interrupt task.
		OFF in all other cases.

#### **Examples**

When CIO 0000.00 is ON in the following example, DI(693) disables all interrupt tasks.





# 3-19-5 ENABLE INTERRUPTS: EI(694)

**Purpose** 

Enables execution of all interrupt tasks.

**Ladder Symbol** 



#### **Variations**

Variations	Executed Each Cycle for Normally ON Condition	EI(694)
	<b>Executed Once for Upward Differentiation</b>	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	Not allowed

# **Description**

EI(694) is executed from the main program to enable all interrupt tasks (input interrupt tasks, interval timer interrupt tasks, pulse output interrupt tasks, and high-speed counter interrupt tasks) that were disabled by DI(693).

#### Note

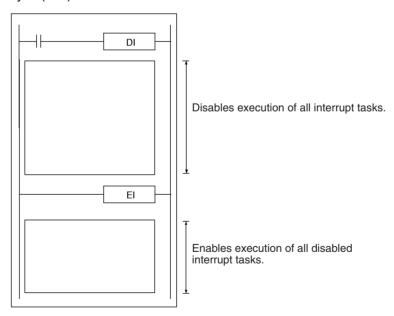
- 1. EI(694) does not require an execution condition.
- 2. EI(694) will not enable interrupt tasks for which MSKS(690) has disabled interrupt inputs, STIM(980) has disabled interval timer interrupts, or CT-BL(882) has disabled target value comparisons.
- 3. EI(694) cannot be executed in an interrupt task. Attempting to do so will cause an error and the Error Flag will turn ON.

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if EI(694) is executed from an interrupt task.
		OFF in all other cases.

#### **Examples**

In the following example, EI(694) enables all interrupt tasks that were disabled by DI(693).



# 3-19-6 INTERVAL TIMER: STIM(980)

# **Purpose**

STIM(980) is used to control the interval timers and pulse outputs with the following functions.

Function	Description
Basic functions	Starting the one-shot interrupt timer, starting the scheduled interrupt timer, reading a timer PV, and stopping an interrupt timer
Pulse output functions (FQM1-MMP22 only)	Starting the one-shot pulse output and starting/stopping the pulse counter timer

# **Ladder Symbol**

STIM(980)
C1
C2
C3

C1: Control data #1

C2: Control data #2

C3: Control data #3

# **Variations**

Variations	Executed Each Cycle for ON Condition	STIM(980)
	Executed Once for Upward Differentiation	@STIM(980)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

#### C1: Control Word 1

The contents of control word #1 are shown below.

Value of C1	Control function
#0000	Start one-shot timer.
#0001	One-shot pulse output 1 (FQM1-MMP22 only)
#0002	One-shot pulse output 2 (FQM1-MMP22 only)
#0003	Start scheduled interrupt timer.
#0006	Read timer PV.
#000A	Stop timer.
#000B	Start or stop pulse counter timer 1 (FQM1-MMP22 only).
#000C	Start or stop pulse counter timer 2 (FQM1-MMP22 only).

# C2 and C3: Control Words 2 and 3

The functions of C2 and C3 depend upon the control function setting in C1.

• C1 = #0000 or #0003 (Start one-shot timer or scheduled interrupt timer.)

Operand	Contents
C2	Timer SV (first word)
C3	Interrupt task number 0000 to 0031 hexadecimal (0 to 49 decimal)

The following table shows the settings for C2 when specifying a word address or constant.

C2	Settings	
Word address	C2: Initial value of decrementing counter 0001 to 270F Hex	
	C2+1: Decrementing time interval in 0.1 ms units 0005 to 0064 Hex (0.5 to 10.0 ms)	
Constant	Decrementing time interval in 0.1 ms units 0005 to 0064 Hex (0.5 to 10.0 ms)	

**Note** a) The total time from the execution of STIM(980) to time-up is: (Content of C2)  $\times$  (Content of C2+1)  $\times$  0.1 ms) = 0.5 to 99,990 ms

- b) If a constant is set for C2, C2 contains the decrementing time interval between 0.5 and 10.0 ms. (The SV is set directly in 0.1 ms units.)
- c) A timer interrupt function (one-shot timer or scheduled interrupt timer) executed with STIM(980) can be used simultaneously with the one-shot pulse output or pulse counter time measurement function.
- C1 = #0001 or #0002 (One-shot pulse output 1 or 2)

Operand	Contents	
C2	ON time setting: 0001 to 270F Hex	
C3	Fime units	
	0000 Hex: 0.1 ms 0001 Hex: 0.01 ms 0002 Hex: 0.1 ms 0003 Hex: 1 ms 0004 Hex: 0.001 ms	

• C1 = #0006 (Read timer PV.)

Operand	Contents	
C2	First word containing PV parameter 1	
C3	Word containing PV parameter 2	

• Contents of PV parameter 1 words

Word	Settings		
C2	Number of times that the decrementing timer value has been decremented (4-digit hexadecimal)		
C2+1 Decrementing time interval (0.1 ms units, 4-digit hexadecima			

• Content of PV parameter 2 word:

Word Settings		Settings
	C3	Elapsed time since last decrement operation (0.1 ms units, 4-digit hexadecimal)

The elapsed time since the interval timer started is:  $((Content of C2) \times (Content of C2+1)) + ((Content of C3) \times 0.1 ms)$ 

• C1 = #000A (Stop timer.)

In this case, set both C2 and C3 to 0000.

• C1 = #000B or #000C (Pulse counter timer 1 or 2)

Operand	Contents	
C2	Start or stop counter.	
	#0000: Start #0001: Stop	
C3	Time units	
	0000 hex: 0.1 ms 0001 hex: 0.01 ms	
	0002 hex: 0.1 ms	
	0003 hex: 1 ms	
	0004 hex: 0.001 ms	

# **Operand Specifications**

Area	C1	C2	C3
CIO Area		CIO 0000 to CIO 6143	
Work Area		W000 to W255	
Auxiliary Bit Area		A000 to A959	
Timer Area		T0000 to T0255	
Counter Area		C0000 to C0255	
DM Area		D00000 to D32767	
Indirect DM addresses in binary		@D00000 to @D32767	
Indirect DM addresses in BCD		*D00000 to *D32767	
Constants	#0 to #C	#0000 to #270F	#0 to #31
Data Resisters			DR0 to DR15
Index Registers			
Indirect addressing		,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
using Index Registers			
		DR0 to DR15, IR0 to DF	R0 to DR15, IR15
		,IR0+(++) to ,IR15+(++)	
		,-()IR0 to , -()IR1	5

# **Description**

STIM(980) is used to control the interval timers and pulse outputs according to the parameters specified in C1 (control data 1), C2 (control data 2), and C3 (control data 3).

**Note** To use STIM(980) to control one-shot pulse outputs, the pulse output operation mode must be set to *1 shot* in advance in the System Setup.

To use STIM(980) for high-precision time measurement, the pulse output operation mode must be set to *Calculation (time measurement)* in advance in the System Setup.

#### Operation

- 1. Starting a One-shot Timer
  - Set C1 to #0000, set C2 to a constant or the word containing the timer SV, and set C3 to the interrupt task number.
- 2. Outputting a One-shot Pulse Output
  - Set C1 to #0001 or #0002, set C2 to the ON time, and set C3 to the interrupt task number.
- 3. Starting a Scheduled Interrupt Timer
  - Set C1 to #0003, set C2 to a constant or the word containing the timer SV, and set C3 to the interrupt task number.

- 4. Reading the Timer PV
  - Set C1 to #0006 and set C2 and C3 to the words that will receive the Timer PV parameters.
- 5. Starting/Stopping Pulse Counter Time Measurement
  Set C1 to #000B or #000C, set C2 to #0000 (start) or #0001 (stop), and set
  C3 to the time units.
- 6. Stopping the Timer (One-shot or Scheduled Interrupt Timer Only) Set C1 to #000A and set C2 and C3 to #0000.

#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if a value that is out of range is specified for an SV. (For example, an error will occur if C1 is set to a value other than 0000, 0001, 0002, 0003, 0006, 000A, 000B, or 000C.)
		ON if the pulse output operation mode set in the System Setup does not match the control mode specified in C1.
Equals Flag	=	
Negative Flag	N	

# **System Setup Settings**

Tab	Name	Setting
Pulse Output Tab	Pulse output opera- tion mode	1 shot

#### **Precautions**

# **Read Timer PV and Stop Timer**

• The Read Timer PV function (C1 = #0006) and Stop Timer function (C1 = #000A) are valid only on a one-shot timer or scheduled interrupt timer started with STIM(980).

The Read Timer and Stop Timer functions cannot be used on the one-shot pulse output or pulse counter time measurement.

#### **One-shot Pulse Outputs**

• When STIM(980) is executed just once to start a one-shot pulse output (C1 = #0001 or #0002), a pulse output with the specified pulse width is started from the corresponding pulse output port.

In general, start the pulse output with either the up-differentiated version of the instruction (@ prefix) or an execution condition that is ON for just one cycle. The later STIM(890) instruction will be ignored if a one-shot pulse output is being generated and another instruction is executed to start a one-shot pulse output.

The Pulse Output Flag (A874.07 or A875.07) will be ON while a one-shot pulse is being output by STIM(890).

• The pulse output operation mode must be set to 1 shot in the System Setup in order to use STIM(980) to control one-shot pulse outputs. If STIM(980) is executed to start a one-shot pulse output from a port that is set for another output mode (such as relative pulse output), the instruction will not be executed and the ER Flag will be turned ON

#### **Pulse Counters**

• When STIM(980) is executed just once to start a counter (C1 = #000B or #000C, and C2 = #0000), the pulse count is started and must be stopped by executing the same instruction with C2 = #0001.

In general, start the pulse counter with either the up-differentiated version of the instruction (@ prefix) or an execution condition that is ON for just one cycle. If another STIM(890) instruction is executed to start the pulse counter while pulses are already being counted, the pulse counter will restart.

• The pulse output operation mode must be set to *Calculation (time measurement)* in the System Setup in order to use STIM(980) to count pulses. If STIM(980) is executed to start a pulse counter at a port that is set for another output mode (such as relative pulse output), the instruction will not be executed and the ER Flag will be turned ON.

# 3-20 High-speed Counter/Pulse Output Instructions

This section describes instructions used to control the high-speed counters and pulse outputs.

Instruction	Mnemonic	Function code	Page
MODE CONTROL	INI	880	521
HIGH-SPEED COUNTER PV READ	PRV	881	527
REGISTER COMPARISON TABLE	CTBL	882	530
SPEED OUTPUT	SPED	885	537
SET PULSES	PULS	886	543
PULSE OUTPUT	PLS2	887	550
ACCELERATION CONTROL	ACC	888	555

# 3-20-1 MODE CONTROL: INI(880)

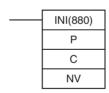
# **Purpose**

INI(880) can be used to execute the following operations:

- To start comparison with the high-speed counter or pulse output counter comparison table
- To stop comparison with the high-speed counter or pulse output counter comparison table
- To change the PV of the high-speed counter
- To change the maximum circular value of the high-speed counter or pulse output counter
- To change the PV of the pulse output
- To stop pulse output
- To stop comparison of the sampling counter
- To change the PV of the sampling counter
- To change the circular value of the sampling counter

This instruction is supported by the FQM1-MMP22 and FQM1-MMA22 Motion Control Modules only.

#### **Ladder Symbol**



P: Port specifier

C: Control data

NV: First word with new PV

#### **Variations**

Variations	Executed Each Cycle for ON Condition	INI(880)
	Executed Once for Upward Differentiation	@INI(880)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

# P: Port Specifier

P specifies the port to which the operation applies.

Р	FQM1-MMP22	FQM1-MMA22
#0001	Counter input port 1	Counter input port 1
#0002	Counter input port 2	Counter input port 2
#0003	Pulse output port 1	Sampling counter
#0004	Pulse output port 2	

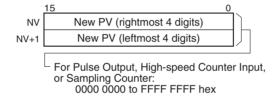
# C: Control Data

The function of INI(880) is determined by the control data, C.

С	INI(880) function
#0000	Start comparison. (Use only in target value comparison mode.)
#0001	Stop comparison. (Use only in target value comparison mode.)
#0002	Change pulse output PV, high-speed counter PV, or sampling counter PV.
#0003	Stop pulse output. (Use only with the FQM1-MMP22.)
#0004	Change pulse output counter circular value, high-speed counter circular value, or sampling counter circular value.

#### **NV: First Word with New PV**

NV and NV+1 contain the new PV when changing the PV (when C = #0002). If the PV is not being changed, this operand is not used and NV should be set to #0000.



# **Operand Specifications**

Area	P C		N	V
			C = #0002 or #0004	C = Other value
CIO Area			CIO 0000 to CIO 6142	CIO 0000 (Cannot be used.)
Work Area			W000 to W254	
Auxiliary Bit Area			A000 to A958	
Timer Area			T0000 to T0254	
Counter Area			C0000 to C0254	
DM Area			D00000 to D32766	
Indirect DM addresses in binary			@ D00000 to @ D32767	
Indirect DM addresses in BCD			*D00000 to *D32767	
Constants	See operand description.	See operand description.		
Data Resisters				

Area	Р	С	N	V
			C = #0002 or #0004	C = Other value
Index Registers				
Indirect addressing			,IR0 to ,IR15	
using Index Registers			-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15	
			,IR0+(++) to ,IR15+(++)	
			,–(– –)IR0 to , –(– –)IR15	

#### Description

INI(880) performs the operation specified in C for the port specified in P. The possible combinations of operations and ports are shown in the following table.

P: Port specifier		C: Control data			
	0000 hex: Start comparison	0001 hex: Stop comparison	0002 hex: Change PV	0003 hex: Stop pulse output	0004 hex: Change circular value
#0001 or #0002: High-speed counter input	OK	OK	ОК	Not allowed.	OK
#0003 or #0004: Pulse output	OK	OK	ОК	ОК	OK
#0003 Sampling counter	Not allowed.	OK	ОК	Not allowed.	OK

#### ■ Starting Comparison (C = 0000 hex)

If C is 0000 hex, INI(880) starts comparison of a high-speed counter's PV or pulse output counter's PV to the comparison table registered with CTBL(882).

**Note** If INI(880) is executed without registering a table, the Error Flag will turn ON and INI(880) will not be executed.

# ■ Stopping Comparison (C = 0001 hex)

If C is 0001 hex, INI(880) stops comparison of a high-speed counter's PV or pulse output counter's PV to the comparison table registered with CTBL(882).

# ■ Changing a PV (C = 0002 hex)

# High-speed Counter Input (P = #0001, #0002, or #0003)

P = #0001 or #0002: Change high-speed counter PV

P = #0003 (FQM1-MMA22): Change sampling counter PV

High-sp	peed counter's counting mode	Control function	PV setting range
Linear mode	Differential inputs, increment/decrement pulses, or pulse + direction inputs	Changes high-speed counter PV. The new value is specified in NV and NV+1.	8000 0000 to 7FFF FFFF hex (-2,147,483,648 to 2,147,483,647)
	mode or sampling operation	<b>Note:</b> An error will occur if the specified port is not set for high-speed counter operation.	0000 0000 to circular set value (hex)

# Pulse Output (P = #0003 or #0004)

High-speed counter's counting mode	Control function	PV setting range
Absolute pulse output linear mode	Changes the pulse output PV. The new value is specified in NV and NV+1.  Note: This instruction can be	8000 0000 to 7FFF FFFF hex (-2,147,483,648 to 2,147,483,647)
Absolute pulse output circular mode	executed only while the pulse output is stopped. An error will occur if it is executed while pulses are being output.	0000 0000 to circular set value (hex)

# ■ Stopping the Pulse Output (P = #0003 or #0004, C = #0003)

This function immediately stops the pulse output from the specified port. If this instruction is executed when pulse output is already stopped, then the pulse amount setting will be cleared. When pulse output is stopped, the Pulse Output Direction Flags (A874.08 and A875.08) will be turned OFF.

# ■ Changing the Counter Circular Value (C = #0004)

#### High-speed Counter Input (P = #0001, #0002, or #0003)

P = #0001 or #0002: Change high-speed counter PV

P = #0003 (FQM1-MMA22): Change sampling counter PV

High-speed counter's counting mode	Control function	PV setting range
Circular mode	Changes the high-speed counter's circular value. The new value is specified in NV and NV+1.	0000 0000 to FFFF FFFF hex (0 to 4,294,967,295)
Sampling counter operation	<b>Note:</b> An error will occur if the specified port is not set for high-speed counter operation.	0000 0000 to FFFF FFFF hex (0 to 4,294,967,295)

#### Pulse Output (P = #0003 or #0004)

Control function	PV setting range
3	0000 0000 to FFFF FFFF hex (0 to 4,294,967,295)

#### **Maximum Circular Value in System Setup**

INI(880) does not change the maximum circular value setting in the System Setup. This instruction changes the counter's register directly, so the counter's circular value is initialized to the System Setup circular value when the power is turned ON. The high-speed counter or pulse output counter circular value can be changed while the counter is counting, so check the status of the counter before changing the circular value. If the circular value is set below the PV, the new circular value won't be effective until the counter has counted all the way to FFFF FFFF and started counting again from 0.

# **Execution Conditions for each Function**

- Starting Comparison between the Target Value Comparison Table and the High-speed Counter PV
  - To start the comparison, execute INI(880) with P set to #0001 or #0002, C set to #0000, and NV set to 0000. Since the comparison operation will continue after INI(880) is executed one time with C = #0000, start the comparison with either the up-differentiated version of the instruction (@ prefix) or an execution condition that is ON for just one cycle.
- 2. Stopping Comparison between the Target Value Comparison Table and the High-speed Counter PV

To stop the comparison, execute INI(880) with P set to #0001 or #0002, C set to #0001, and NV set to 0000.

3. Starting Comparison between the Target Value Comparison Table and the Pulse Output PV

To start the comparison, execute INI(880) with P set to #0003 or #0004, C set to #0000, and NV set to 0000. Since the comparison operation will continue after INI(880) is executed one time with C = #0000, start the comparison with either the up-differentiated version of the instruction (@ prefix) or an execution condition that is ON for just one cycle.

- Note If a target value comparison is executed for the pulse output PV under certain conditions, pulse outputs will stop at completion of the comparison with no mismatch even if the specified pulse width or target position has not been reached. Do not use the target value comparison for pulse output PV under the following conditions:
  - (1) When the pulse output operation mode is either 1 shot or Electronic cam control.
  - (2) When the pulse output operation mode is either *Relative pulse* or *Absolute pulse* for independent-mode positioning.
- 4. Stopping Comparison between the Target Value Comparison Table and the Pulse Output PV

To stop the comparison, execute INI(880) with P set to #0003 or #0004, C set to #0001, and NV set to 0000.

5. Changing the High-speed Counter PV

To change the high-speed counter's PV, execute INI(880) with P set to #0001 or #0002, C set to #0002, and the new PV set in NV and NV+1. If the counter is operating in circular mode, the PV must not be higher than the maximum circular counter value. If the specified PV is higher than the maximum circular counter value, an error will occur and the PV will not be changed.

6. Changing the Pulse Output PV

To change the pulse output PV, execute INI(880) with P set to #0003 or #0004, C set to #0002, and the new PV set in NV and NV+1.

- **Note** a) INI(880) can be executed to change the pulse output PV when the pulse output mode is set to relative pulse output, one-shot pulse output, or pulse counter time measurement. However, these pulse output modes initialize the operation counter to 0 before starting operation, so changing the pulse output PV has no real effect.
  - b) In circular mode, the pulse output PV cannot be changed to a value higher than the maximum circular counter value.
- 7. Stopping the Pulse Output

To stop the pulse output, execute INI(880) with P set to #0003 or #0004, C set to #0003, and NV set to 0000.

- **Note** Set the System Setup's pulse output mode to relative pulse output, absolute pulse output (linear mode), or absolute pulse output (circular mode). An error will occur and INI(880) won't be executed if the pulse output mode is set to one-shot mode or pulse counter time measurement mode.
- 8. Changing the High-speed Counter Circular Value

To change the high-speed counter's circular value, execute INI(880) with P set to #0001 or #0002, C set to #0004, and the new circular value set in NV and NV+1.

- **Note** a) This function does not change the maximum circular value setting in the System Setup; it changes the counter's register directly.
  - b) The circular value can be changed while the counter is counting. Check the status of the counter before changing the circular value.
- 9. Changing the Pulse Output Counter Circular Value

To change the pulse output counter's circular value, execute INI(880) with P set to #0003 or #0004, C set to #0004, and the new circular value set in NV and NV+1.

- **Note** a) This function does not change the maximum circular value setting in the System Setup; it changes the counter's register directly.
  - b) The circular value can be changed while the counter is counting. Check the status of the counter before changing the circular value.
- 10. Stopping (Interrupting) Sampling by the Sampling Counter

To stop sampling, execute INI(880) with P set to #0003, C set to #0001, and NV set to 0000.

11. Changing the Sampling Counter PV

To change the sampling counter's PV, execute INI(880) with P set to #0003, C set to #0002, and the new PV set in NV and NV+1. The PV can not be higher than the maximum circular counter value.

This function can be used to clear or adjust the sampling counter.

12. Changing the Sampling Counter Circular Value

To change the sampling counter's circular value, execute INI(880) with P set to #0003, C set to #0004, and the new circular value set in NV and NV+1.

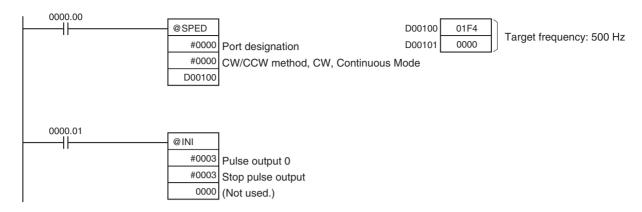
This function can be used to set the sampling period as a circular value.

#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if P is set to a value other than #0001, #0002, #0003, or #0004. (With the FQM1-MMA22, #0004 is not allowed either.)
		ON if the PV in NV and NV+1 exceeds the maximum circular counter value during relative pulse output circular mode or high-speed counter circular mode operation.
		ON if a new PV is specified for a port that is currently outputting pulses.
		ON if INI(880) is executed to stop pulses while the System Setup is set for one-shot pulse output.
		ON if an instruction controlling pulse I/O or a high-speed counter is being executed in the main program, an interrupt occurs, and INI(880) is executed in the interrupt task.
		OFF in all other cases.

#### Example

When CIO 0000.00 goes from OFF to ON in the following example, SPED(885) starts outputting pulses from pulse output 0 in Continuous Mode at 500 Hz. When CIO 0000.01 goes from OFF to ON, INI(880) stops the pulse output.



# 3-20-2 HIGH-SPEED COUNTER PV READ: PRV(881)

# **Purpose**

Use PRV(881) to read the high-speed counter PV, high-speed counter latch value, high-speed counter rate-of-change (counter movements) or frequency, pulse output PV, pulse counter PV (time measurement), or elapsed time of one-shot pulse output.

# **Ladder Symbol**



P: Port specifier

C: Control data

D: First destination word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	PRV(881)
	Executed Once for Upward Differentiation	@PRV(881)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

# P: Port Specifier

P specifies the port to which the operation applies.

Р	Port
#1	High-speed counter 1
#2	High-speed counter 2
#3	Pulse output 1 or Analog input (FQM1-MMA22 only)
#4	Pulse output 2

#### C: Control Data

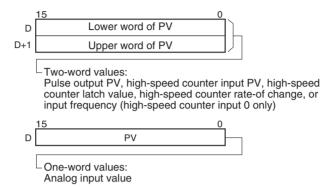
The function of INI(880) is determined by the control data, C.

С	Function
#0	Reads one of the following values:
	High-speed counter PV
	Pulse output PV
	Pulse output counter PV (time measurement)
	Analog input value

С	Function
#1	Reads the high-speed counter rate-of-change or measured frequency.
#2	Reads the high-speed counter latch value.

# **D: First Destination Word**

The PV is output to D or to D and D+1.



# **Operand Specifications**

Area	Р	С	D
CIO Area			CIO 0000 to CIO 6142
Work Area			W000 to W254
Auxiliary Bit Area			A448 to A958
Timer Area			T0000 to T0254
Counter Area			C0000 to C0254
DM Area			D00000 to D32766
Indirect DM addresses in binary			@ D00000 to @ D32767
Indirect DM addresses in BCD			*D00000 to *D32767
Constants	See operand description.	See operand description.	
Data Resisters			
Index Registers			
Indirect addressing using Index Registers			,IR0 to ,IR15
using index registers			-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
			DR0 to DR15, IR0 to DR0 to DR15, IR15
			,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15

# **Description**

The function performed by PRV(881) depends on the setting of operand C (the control data word).

# ■ Reading a PV (C = #0000)

Port and mode		Operation	Setting range	
Absolute pulse output	Linear Mode	Reads the pulse output PV and stores it in D and D+1.	8000 0000 to 7FFF FFFF hex (-2,147,483,648 to 2,147,483,647)	
	Circu- lar Mode		0000 0000 to FFFF FFFF hex (0 to 4,294,967,295)	
Relative pulse output				
High-speed counter input	Linear Mode	Reads the high-speed counter PV and stores it in D and D+1.	8000 0000 to 7FFF FFFF hex (-2,147,483,648 to 2,147,483,647)	
	Circu- lar Mode		0000 0000 to FFFF FFFF hex (0 to 4,294,967,295)	

#### ■ Reading High-speed Counter Rate-of-change or Frequency (C = #0001)

Reads the high-speed counter's rate-of-change (counter movements) or measured frequency value and stores it in D and D+1.

D: Rightmost 4 digits (hexadecimal or BCD)

D+1: Leftmost 4 digits (hexadecimal or BCD)

The possible range of the high-speed counter's rate-of-change (counter movements) or measured frequency value is 0000 0000 to FFFF FFFF hex.

Note When reading the high-speed counter rate-of-change (counter movements) with the sampling time set to the cycle time, use an instruction such as MOV(021) to read the value directly from A854 and A855 (counter 1) or A856 and A857 (counter 2). If PRV(881) is used to read the rate-of-change value, a value of 0 will be output.

#### ■ Reading the Analog Input Value (C = #0001, FQM1-MMA22 Only)

Reads the most recent analog input value and stores it in D.

The Motion Control Module converts the analog input data when PRV(881) is executed, so the most recent value is stored. The analog input method must be set to *Immediate refresh* in the System Setup in order to read the analog input value with PRV(881).

#### ■ Reading High-speed Counter Latch Value (C = #0002)

Reads the high-speed counter's PV and stores it in D and D+1 as an 8-digit hexadecimal value.

D: Rightmost 4 digits (hexadecimal)

D+1: Leftmost 4 digits (hexadecimal)

Range in linear mode: 8000 0000 to 7FFF FFFF hex. Range in circular mode: 0000 0000 to FFFF FFFF hex

#### **Execution Conditions**

Reading the High-speed counter PV, High-speed Counter Latch Value, Pulse Output PV, Pulse Counter PV (Time measurement), Elapsed Time of the One-shot Pulse Output, or Analog Input Value

To read the desired value, execute PRV(881) with P set to #0001, #0002, #0003, or #0004, C set to #0000, and D set to the first word address where the value will be stored.

# Note

The high-speed counter PVs read with PRV(881) are the same as the values stored in A850 and A851 (port 1 PV) and A852 and A853 (port 2 PV), but those Auxiliary Area words are refreshed just once each cycle whereas the value read with PRV(881) always provides the most recent data.

2. The pulse output PVs and pulse output counter PV (time measurement PVs) read with PRV(881) are the same as the values stored in A870 and A871 (port 1 PV) and A872 and A873 (port 2 PV), but those Auxiliary Area words are refreshed just once each cycle whereas the value read with PRV(881) always provides the most recent data.

# **Flags**

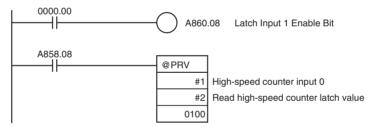
Name	Label	Operation
Error Flag	ER	ON if the combination of P and C is not allowed. (For example, ON if P = #0003 and C = #0001.)
		ON if P is set to a value other than #0001, #0002, #0003, or #0004.
		ON if C is set to a value other than #0000 or #0001.
		ON if an instruction controlling pulse I/O or a high-speed counter is being executed in the main program, an interrupt occurs, and PRV(881) is executed in the interrupt task.
		OFF in all other cases.

#### **Examples**

# **■** Example 1

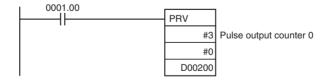
When CIO 0000.00 goes from OFF to ON in the following programming example, the latch input is enabled and the high-speed counter PV is latched if the latch input is ON.

When the Count Latched Flag goes from OFF to ON, PRV(881) reads the latched high-speed counter 0 PV and stores it in words CIO 0101 and CIO 0100.



#### **■** Example 2

When CIO 0001.00 goes from OFF to ON in the following programming example, PRV(881) reads the most recent pulse output counter PV and stores it as a hexadecimal value in D00200 and D00201.



# 3-20-3 REGISTER COMPARISON TABLE: CTBL(882)

### **Purpose**

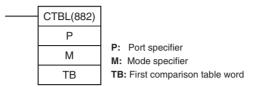
Use CTBL(882) to register a comparison table and compare the table values with a high-speed counter PV or pulse output counter PV. Either target value or range comparisons are possible. An interrupt task is executed when a specified condition is met.

When performing range comparisons, a bit pattern is output internally when the PV is within a specified range.

It is also possible to register a comparison table without starting the comparison. Once the table is registered, the comparison operation can be started/stopped with INI(880).

When performing high-speed analog sampling, CTBL(882) starts the sampling operation.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	CTBL(882)
	<b>Executed Once for Upward Differentiation</b>	@CTBL(882)
	<b>Executed Once for Downward Differentiation</b>	Not supported

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

#### P: Port Specifier

P specifies the port for which pulses are to be counted as shown in the following table.

Р	Port
#1	High-speed counter 1
#2	High-speed counter 2
#3	Pulse output 1 or Sampling counter
#4	Pulse output 2

#### M: Mode Specifier

The function of CTBL(882) is determined by the mode specifier, M, as shown in the following table.

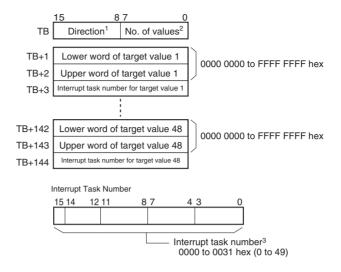
M	CTBL(882) function
#0	For a counter or pulse output, this mode registers a target value comparison table and starts comparison.
	For a sampling counter, this mode registers a target value comparison table, clears the sampling counter to 0, and starts sampling.
#1	For a counter or pulse output, this mode starts range comparison.
	For a sampling counter, this mode starts sampling without clearing the sampling counter to 0.
#2	Registers a target value comparison table.

# **TB: First Comparison Table Word**

TB is the first word of the comparison table. The structure of the comparison table depends on the type of comparison being performed.

• Target Value Comparison

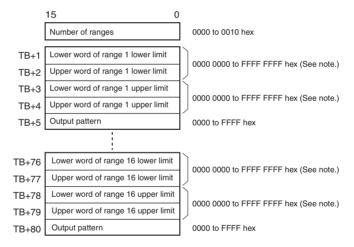
For target value comparison, the length of the comparison table is determined by the number of target values specified in TB. The table can be between 4 and 145 words long, as shown below.



- Note 1. Set 00 for incrementing or F0 for decrementing.
  2. Setting range: 01 to 30 hex (1 to 48 target values)
  3. Set the interrupt task number to FFFF hex to disable comparison.

#### Range Comparison

For range comparison, the length of the comparison table is determined by the number of ranges specified in TB. The table can be between 6 and 81 words long, as shown below.



### **Operand Specifications**

Area	Р	М	ТВ
CIO Area			CIO 0000 to CIO 6140
Work Area			W000 to W252
Auxiliary Bit Area			A448 to A956
Timer Area			T0000 to T0252
Counter Area			C0000 to C0252
DM Area			D00000 to D32764
Indirect DM addresses in binary			@ D00000 to @ D32767
Indirect DM addresses in BCD			*D00000 to *D32767
Constants	See operand description.	See operand description.	
Data Resisters			

Area	Р	M	ТВ
Index Registers			
Indirect addressing using Index Registers			,IR0 to ,IR15
doing index regions			-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
			DR0 to DR15, IR0 to DR0 to DR15, IR15
			,IR0+(++) to ,IR15+(++)
			,-()IR0 to , -()IR15

## **Description**

CTBL(882) registers a comparison table and starts comparison (with a high-speed counter PV or pulse output counter PV) for the port specified in P and the method specified in M. Once a comparison table is registered, it is valid until a different table is registered or until the Motion Control Module is switched to PROGRAM mode.

Each time CTBL(882) is executed, comparison is started under the specified conditions. When using CTBL(882) to start comparison, it is normally sufficient to use the differentiated variation (@CTBL(882)) of the instruction or an execution condition that is turned ON only for one cycle.

**Note** If the comparison table specifies an interrupt task number that is not in the program, a program error (fatal error) will occur when that interrupt is called.

#### ■ Registering a Target Value Comparison Table (M = #0002)

If M is set to #0002, CTBL(882) registers a comparison table to compare the high-speed counter PV or pulse output counter PV, but does not start comparison. In this case, start comparison separately with INI(880).

# ■ Registering a Target Value Comparison Table and Starting Comparison (M = #0000)

If M is set to #0000, CTBL(882) registers a comparison table to compare the high-speed counter PV or pulse output counter PV, and starts the comparison.

### **■** Stopping Comparison

Use INI(880) to stop comparison operations started with either CTBL(882) or INI(880).

#### **■ Target Value Comparison Operation**

Target value comparison compares the PV with a list of preset target values. Up to 48 target values can be registered in the table and the target values are compared in the order in which they appear in the table. When the PV matches a target value, CTBL(882) performs the following operations and then moves to the next target value in the table.

#### Execution of the Interrupt Task (FQM1-MMP22 and FQM1-MMA22)

The first comparison target value is determined by the direction setting (in the leftmost byte of TB) and the high-speed counter's PV, as follows.

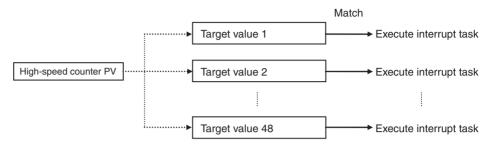
• Direction = 00 hex: Incrementing

Compares target values with the PV from the beginning of the table. The first target value in the table that is greater than the PV is used as the first comparison target value.

• Direction = F0 hex: Decrementing

Compares target values with the PV from the beginning of the table. The first target value in the table that is less than the PV is used as the first comparison target value.

If the direction setting is inappropriate (incrementing specified but all target values are less than the PV or decrementing specified but all target values are greater than the PV), the first target value registered in the table will be used as the first comparison target value.



# <u>Target Value Comparison Table Structure</u> (FQM1-MMP22 and FQM1-MMA22)

Word	Leftmost byte (bits 08 to 15)	Rightmost byte (bits 08 to 15)	Function
ТВ	Direction (See note 1.)	Number of target values (See note 2.)	Table definition
TB+1	Target value (rightmost 4 digits, hexadecimal)		One target value entry
TB+2	Target value (leftmost 4 digits, hexadecimal)		(Set the number of
TB+3	Interrupt task number (0000 to 0031, hexadecimal)		entries specified in TB.)

#### Note

- 1. Set the direction to 00 hex when incrementing or F0 hex when decrementing.
- 2. Set the number of target value entries between 01 and 30 hex (1 to 48).

Set interrupt task numbers between 0000 and 0031 hex. The same interrupt task number can be used for multiple target value entries.

When interrupt processing is not required, set the interrupt task number to FFFF hex to disable interrupt processing for that target value entry.

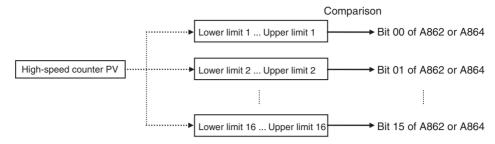
The comparison operation can be stopped with INI(880). Once a comparison table is registered, it is valid until a different table is registered or until the Motion Control Module stops operating.

# ■ Range Comparison Operation (M = #0001)

Range comparison compares the PV with target ranges defined by a lower limit and an upper limit. Up to 16 ranges (lower and upper limit pairs) can be set in the table.

The comparison operation is performed each time CTBL(882) is executed, and all of the entries in the comparison table are evaluated starting from the beginning of the table. The comparison results are output as flags (bits 0 to 15 correspond to ranges 1 to 16) with the corresponding bit ON when the comparison result is true. The flags are output to the Auxiliary Area word allocated to the port (words A862 to A865 for the high-speed counters and A880 to A883 for the pulse outputs).

At the same time, the specified output bit pattern is stored in the allocated word (A863 or A865 for the high-speed counters and A881 or A883 for the pulse outputs). When several comparison conditions are met at the same time, the output patterns are all ORed and the OR result is stored as the result.



High-speed Counter 1: Range comparison result = A862

Output pattern destination = A863

High-speed Counter 2: Range comparison result = A864

Output pattern destination = A865

Pulse Output 1: Range comparison result = A880

Output pattern destination = A881

Pulse Output 2: Range comparison result = A882

Output pattern destination = A883

# Range Comparison Table Structure

Word	Content	Function
ТВ	Number of ranges in table (0001 to 0010 hex)	Table definition
TB+1	Lower limit 1 (rightmost 4 digits, hexadecimal)	One range entry
TB+2	Lower limit 1 (leftmost 4 digits, hexadecimal)	(Set the number of range
TB+3	Upper limit 1 (rightmost 4 digits, hexadecimal)	entries specified in TB.)
TB+4	Upper limit 1 (leftmost 4 digits, hexadecimal)	
TB+5	Output pattern	

- Overlapping ranges can be specified.
- If the lower and upper limit values are reversed in linear mode, the comparison operation will not function properly, but an error will not occur. In linear mode, always set the upper limit ≥ lower limit.

# ■ High-speed Analog Sampling (M = #0000, FQM1-MMA22 Only)

This function stores the analog input data in the specified DM words of an FQM1-MMA22 Motion Control Module.

The high-speed analog sampling function stores the analog input value in the specified DM Area location (starting at TB+2) each time that the sampling counter PV matches the target value specified in TB and TB+1. Sampling stops automatically when the desired number of analog input samples (specified in TB+3) have been stored.

In order to use the high-speed analog sampling function, the input method must be set to *Immediate refresh* in the System Setup's **Analog Input/Output** Tab.

#### **Table Structure**

The following table shows the function of the table words

Word	Content
ТВ	Target value (rightmost 4 digits, hexadecimal)
TB+1	Target value (leftmost 4 digits, hexadecimal)
TB+2	First DM word for storage of analog input sample
	(Set a DM Area offset address between 0000 and 7FFF hex.)
TB+3	Number of samples
	(Specifies the number of samples to store. Set between 0001 and 8000 hex.)

Name	Label	Operation
Error Flag	ER	ON if P is set to a value other than #0001, #0002, #0003, or #0004.
		ON if M is set to a value other than #0000, #0001, or #0002.
		ON if one of the following errors is detected in a target value comparison table.
		ON if TB is not 01 to 30 hex.
		<ul> <li>In circular mode, ON if the content of TB+1 and TB+2 (target value) exceeds the maximum circular counter value.</li> </ul>
		ON if TB+3 (interrupt task number) contains a value other than #0000 to #0031 or #FFFF.
		ON if all of the interrupt task numbers in the table are set to #FFFF (disabled).
		ON if TB is not #0001 to #0010 hex in a range comparison table.
		ON if an instruction controlling a high-speed counter is being executed in the main program, an interrupt occurs, and CTBL(882) is executed in the interrupt task.
		OFF in all other cases.

#### **Precautions**

Do not change the maximum circular counter value when performing a comparison in circular mode.

When using target value comparisons, set target values that allow an interval greater than the "interrupt overhead time + interrupt task processing time" after the interrupt is generated.

Do not perform target value comparisons on the pulse output counter when using one of the following operation modes for pulse outputs. The pulse output will not operate properly if target value comparisons are performed.

- Independent mode (positioning)
- Electronic Cam mode
- · One-shot pulse output mode

Counting will start when the count start bit goes ON or the pulse output begins, but interrupt tasks will not be called until the comparison operation is started.

Use INI(880) to stop the target value comparison.

Once a target value comparison table is registered, it is valid until a different table is registered or until the Motion Control Module stops operating. The cycle time can be reduced by executing the up-differentiated variation of CTBL(882) only when necessary.

# Execution Conditions for each Function

- 1. Registering the Target Value Comparison Table and Starting Comparison To register the target value comparison table and start the comparison, execute CTBL(882) with P set to #0001, M set to #0000, and TB set to the address of the first word of the comparison table. Since the comparison operation will continue after CTBL(882) is executed one time, use either the up-differentiated variation of the instruction (@CTBL(882)) or an execution condition that is ON for just one cycle.
- 2. Starting Range Comparison

To perform range comparison, execute CTBL(882) with P set to #0001, M set to #0001, and TB set to the address of the first word of the comparison table. When CTBL(882) is executed with these conditions, the PV is com-

pared just once to the ranges specified in the table. The comparison operation does not continue.

3. Registering the Target Value Comparison Table Only

To just register the target value comparison table, execute CTBL(882) with P set to #0001, M set to #0002, and TB set to the address of the first word of the comparison table.

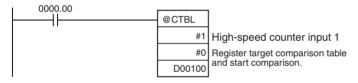
4. Starting High-speed Analog Sampling

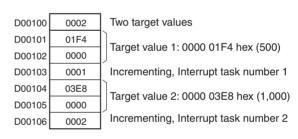
To start high-speed analog sampling, execute CTBL(882) with P set to #0003, M set to #0000 or #0001, and TB set to the address of the first word of the comparison settings table. Once CTBL(882) is executed, the comparison operation will continue until the FQM1-MMA22 Motion Control Module has stored the number of samples specified in TB+3. Since CT-BL(882) needs to be executed just one time, use either the up-differentiated variation of the instruction (@CTBL(882)) or an execution condition that is ON for just one cycle.

If M is set to #0000, the sampling counter will be cleared to 0 when sampling starts. If M is set to #0001, the sampling counter will not be cleared to 0.

#### **Example**

When CIO 0000.00 goes from OFF to ON in the following programming example, CTBL(882) registers a target value comparison table and starts comparison for high-speed counter 1. The PV of the high-speed counter is counted incrementally and when it reaches 500, it equals target value 1 and interrupt task 1 is executed. When the PV is incremented to 1,000, it equals target value 2 and interrupt task 2 is executed.





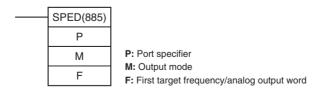
# 3-20-4 SPEED OUTPUT: SPED(885)

#### **Purpose**

SPED(885) is used to set the output pulse frequency for a specific port and start pulse output without acceleration or deceleration. Either independent mode positioning or continuous mode speed control is possible. For independent mode positioning, the number of pulses is set using PULS(886).

SPED(885) can also be executed during pulse output to change the target frequency of the current pulse outputs, creating stepped speed changes. This instruction is supported by the FQM1-MMP22 and FQM1-MMA22 only.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	SPED(885)
	Executed Once for Upward Differentiation	@SPED(885)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

# P: Port Specifier

The port specifier specifies the port where the pulses will be output.

Р	Port
#1	FQM1-MMP22: Pulse output 1
	FQM1-MMA22: Analog output 1
#2	FQM1-MMP22: Pulse output 2
	FQM1-MMA22: Analog output 2

# M: Output Mode

The value of M determines the output mode.

Output	Value of M	Mode
Pulse output	#0000	Continuous, CW
	#0001	Continuous, CCW
	#0002	Independent, CW
	#0003	Independent, CCW
Analog output	#0000 (fixed)	

#### F: First Frequency Word or First Analog Output Word

• Pulse Outputs (F = First Frequency Word)

The allowed frequency setting range is slightly different when F is specified as a constant or word address.

Setting method	Setting
Constant	Specify the frequency in 1-Hz units.
	Range: #0000 0000 to #000F 4240 (0 to 1 MHz)
Word address	Specify the frequency in 1-Hz units.
	Range: #0000 0000 or #0000 0001 to #000F 4240 (1 to 1 MHz)
	F: Rightmost 4 digits F+1: Leftmost 4 digits

The target frequency can be set between 1 Hz and 1 MHz, but the frequency that can actually be output depends on the clock frequency. Refer to 7-6-4 Pulse Output Specifications in the FQM1 Series Flexible Motion Controller Operation Manual (Cat. No. O012) to verify the allowed output range. An error will occur and the instruction will not be executed if the specified frequency exceeds the allowed output range. If the specified frequency is below the allowed output range, the lower limit frequency will be output.

The output frequencies are obtained by dividing the Motion Control Module's clock pulse with an integer dividing ratio, meaning the actual output frequency can be different from the set frequency. (Refer to *Precautions when Using Pulse Outputs* in the *FQM1 Series Flexible Motion Controller Operation Manual* (Cat. No. O012) for details.)

The output frequency will not be changed unless a minimum of one pulse is output. For example, if 1 Hz is output when 20 MHz (1 Hz to 1 MHz) is being used, execution will not be enabled for 1 s while the 1-pulse output is being completed. The instruction can be executed, but a 1-pulse output wait time will be required until the frequency is actually changed. For instructions with automatic acceleration/deceleration, such as PLS2(887) or ACC(888), the frequency will be changed automatically according to the acceleration/deceleration rate, but for either the start frequency or the acceleration/deceleration rate, a 1-pulse output wait time will be required. When using low frequencies, therefore, allow for delays in speed changes.

- Analog Outputs (F = First Analog Output Word)
   Sets the value that will be output from the analog output port. Specify the value in 4-digit hexadecimal.
  - -10 to +10 V Range:
     EC78 to 1388 hex (-5,000 to 5,000 decimal) (resolution: 10,000) corresponding to 0% to 100% voltage (-10 to 10 V)

     The possible setting range is actually EA84 to 157C (-5,500 to 5,500 decimal) corresponding to -5% to 105% voltage (-11 to 11 V)
  - 0 to 10 V, 0 to 5 V, and 1 to 5 V Ranges:
     0000 to 0FA0 hex (0000 to 4,000 decimal) (resolution: 4,000) corresponding to 0% to 100% of the FS range. (Actually, the setting range is FF38 to 1068 (–200 to 4,200 decimal) corresponding to –5% to 105% voltage (–0.5 to 10.5 V, –0.25 to 5.25 V, or 0.8 to 5.2 V).)

**Note** An error will occur and the ER Flag will be turned ON if the settings are outside of the ranges listed above.

# **Operand Specifications**

Area	Р	М	F
CIO Area			CIO 0000 to CIO 6143
Work Area			W000 to W255
Auxiliary Bit Area			A000 to A959
Timer Area			T0000 to T0255
Counter Area			C0000 to C0255
DM Area			D00000 to D32767
Indirect DM addresses in binary			@ D00000 to @ D32767
Indirect DM addresses in BCD			*D00000 to *D32767
Constants	See operand description.	See operand description.	See operand description.
Data Resisters			
Index Registers			
Indirect addressing using Index Registers			,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15

Execution Conditions for Pulse Output Functions (FQM1-MMP22) 1. Pulse Output in Independent Mode (Positioning) in the CW Direction: (Outputs just the Number of Pulses specified with PULS(886).)

- Execute SPED(885) with P set to #0001 or #0002, M set to #0002, and F set to the target frequency.
- Pulse Output in Independent Mode (Positioning) in the CCW Direction: (Outputs just the Number of Pulses specified with PULS(886).)
   Execute SPED(885) with P set to #0001 or #0002, M set to #0003, and F

set to the target frequency.

- Pulse Output in Continuous Mode (Speed Control) in the CW Direction Execute SPED(885) with P set to #0001 or #0002, M set to #0000, and F set to the target frequency.
- Pulse Output in Continuous Mode (Speed Control) in the CCW Direction Execute SPED(885) with P set to #0001 or #0002, M set to #0001, and F set to the target frequency.
- 5. Since SPED(885) starts the pulse output with the parameters specified in operands P, M, and F, it needs to be executed just one time. Use either the up-differentiated variation of the instruction (@ SPED(885)) or an execution condition that is ON for just one cycle.
- 6. Pulse outputs can be output independently and simultaneously from two output ports.
  - Set the pulse frequency in F in 1-Hz units between 0000 0000 and 000F 4240 hex (0 Hz to 1 MHz). The pulse frequency can be set to 0 to stop the pulse output.
  - The pulse output direction can be specified with operand M.
- 7. To generate pulse outputs with SPED(885), the pulse output operation mode must be set to *Relative pulse*, *Absolute pulse* (*Linear mode*), or *Absolute pulse* (*Circular mode*) in advance in the System Setup. Pulses will not be output and an error will occur if the pulse output operation mode is set to *Electronic cam control*, *1 shot*, or *Calculation* (*time measurement*).
- 8. Any of the following methods can be used to stop pulses being output by SPED(885).
  - a) Execute SPED(885) again with a target frequency of 0.
  - b) In independent mode (positioning), the pulse output will stop when the number of output pulses reaches the SV set with PULS(886).
  - c) Execute INI(880) with C set to #0003.
  - d) Switch the Motion Control Module to PROGRAM mode.
  - e) Execute ACC(888) with M set to #0008 or #0009 and the target frequency set to 0 Hz. Pulse output will decelerated to a stop. (If number of output pulses set for PULS(886) in independent mode is reached, an immediate stop will be performed.)

#### **Function Description**

Pulses can be output in independent mode or continuous mode.

- Independent Mode (Positioning)
   In independent mode, only a preset number of pulses are output. Set the number of output pulses in advance with PULS(886).
- Continuous Mode (Speed Control)
   In continuous mode, pulses are output continuously until stopped by executing SPED(885) again with a target frequency of 0, executing INI(880) with C = #0003, or switching the Motion Control Module to PROGRAM mode.

In independent mode (positioning), the number of output pulses must be specified in advance with PULS(886). (No pulses will be output if the number

of output pulses is not specified before executing SPED(885).) If the pulse output has been stopped, it is necessary to set the number of output pulses again with PULS(886).

**Note** When pulses are being output from pulse output 1 or 2 in independent mode (positioning), the number of pulses that have been output can be monitored in the following Auxiliary Area words:

Pulse output 1: A870 (leftmost 4 digits) and A871 (rightmost 4 digits) Pulse output 2: A872 (leftmost 4 digits) and A873 (rightmost 4 digits)

Pulses can be output from two ports simultaneously.

- When pulses are already being output by SPED(885), SPED(885) can be executed again to change the output frequency. Even though the frequency is changed, pulses are still output in independent mode (positioning), so the number of output pulses does not change.
  - The frequency cannot be changed if pulses are already being output and SPED(885) is executed again with a pulse output in the opposite direction. Similarly, the frequency cannot be changed if pulses are already being output in independent mode, and SPED(885) is executed again in continuous mode.
- It may not be possible to change the frequency with SPED(885) if pulses are being output by another instruction (such as a pulse output with PLS2(887).) If SPED(885) is executed to change the frequency when it cannot be changed, an error will occur.
  - For details on the conditions when the frequency can be changed with SPED(885), refer to 7-6-15 Pulse Output Starting Conditions in the FQM1 Series Flexible Motion Controller Operation Manual (Cat. No. 0012).
- When independent mode positioning is performed with SPED(885) but the CW/CCW direction is not correct for the present position and target position, pulses will still be output in the specified direction. When Absolute pulse (Linear mode) operation is being used in this case, the target position will never be reached within the 8000 0000 to 7FFF FFFF range. With the pulse output counter, outputs will continue without producing an overflow or underflow even when the counter exceeds the range above. The target value will be reached after exceeding the range.

• When pulse output is started, the direction of rotation (CW or CCW) will be reflected in the Rotation Direction Flags (A874.08 and A875.08).

Mode	Description	Frequency changes
Continuous (Speed con- trol)	Mode #0 or #1 (Continuous mode) The frequency is changed from the present frequency to the target frequency in one step and the pulse output continues at the target frequency. The output will continue until stopped with INI(880) or by executing SPED(885) with a target frequency of 0.	Pulse output continues until execution of INI (880) with C = #3, SPED(885) with a target frequency of 0, or ACC(888) with a target frequency of 0.  Target frequency (F and F+1)  Present frequency  Time  SPED(885) executed.
Independent (Positioning)	Mode #2 or #3 (Independent mode) The frequency is changed to the target frequency in one step and the pulse output continues until the number of pulses specified with PULS(886) have been output. (With independent mode, the number of pulses must be set in advance with PULS(886) and the output operates according to that setting.)	Frequency Specified number of pulses (Specified with PULS(886).)  Target frequency (F and F+1)  Time  SPED(885) Stops after specified number of pulses of pulses

# Execution Conditions for Analog Output Functions (FQM1-MMA22)

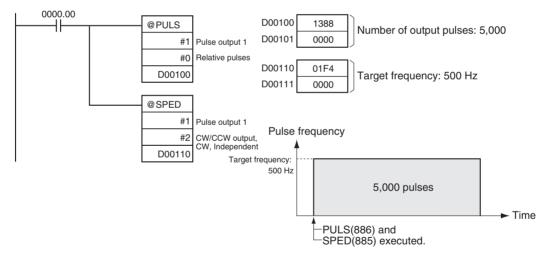
- Generating an Analog Output
   Execute SPED(885) with P set to #0001 or #0002, M set to #0000, and F set to the desired analog output value.
- 2. When SPED(885) is executed, the analog output is generated according to the values specified by P, M, and F.
- 3. Analog outputs can be output independently and simultaneously from two output ports.
- 4. Analog outputs are not distinguished as continuous or independent outputs. The analog output generated by SPED(885) will maintain its output value until one of the following events occurs:
  - a) SPED(885) or ACC(888) is executed with a different target value.
  - b) The *Output stop function* is set to a setting other than *Hold* and the Motion Control Module is switched to PROGRAM mode or the Analog Output Conversion Enable Bit (A814.00 or A815.00) is reset to 0.
- 5. The present analog output value will be changed if SPED(885) is executed again while an analog output value is being output or the analog output target value has been reached after execution of ACC(888).
- 6. The present analog output value will not be changed and an error will occur if SPED(885) is executed by interrupting an existing SPED(885) analog output or ACC(888) has been executed to generate an analog output but the target value has not been reached.
- In order to generate analog outputs with SPED(885) or ACC(888), the output method must be set to *Immediate refresh* in the System Setup's **Analog Input/Output** Tab. If the output method is set to *End refresh*, an error will occur and an analog output will not be generated by SPED(885) or ACC(888).

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if P is set to a value other than #0001 or #0002.
		For the FQM1-MMP22, ON if F is not set between #0 and #F4240.
		For the FQM1-MMA22, ON if F is not in range.
		<ul> <li>-10 to +10 V Range:</li> <li>ON if F is not between EA84 and 157C.</li> </ul>
		<ul> <li>0 to 10 V, 0 to 5 V, and 1 to 5 V Ranges:</li> <li>ON if F is not between FF38 and 1068.</li> </ul>
		For the FQM1-MMP22, ON if the specified frequency is not supported at the selected Motion Control Module clock frequency.
		For the FQM1-MMP22, ON if SPED(885) is executed when the present pulse output cannot be changed. (For example, the pulse output cannot be changed when pulses are being output by PLS2(887) and the target value has not been reached.)
		ON if an instruction controlling pulse or analog I/O is being executed in the main program, an interrupt occurs, and SPED(885) is executed in the interrupt task.
		OFF in all other cases.

# **Example**

When CIO 0000.00 goes from OFF to ON, PULS(886) sets the number of output pulses for pulse output 1 to a relative value of 5,000 pulses. SPED(885) is executed next to start pulse output using the CW/CCW method in the clockwise direction in independent mode at a target frequency of 500 Hz.



# 3-20-5 SET PULSES: PULS(886)

# **Purpose**

PULS(886) sets the number of output pulses for independent mode pulse outputs that are started later in the program. PULS(886) can also be used to set the number of output pulses and frequency for electronic cam control.

• Independent Mode

PULS(886) sets the number of output pulses to be output in an independent mode (positioning) operation. The specified number of output pulses will be output when SPED(885) or ACC(888) is executed in independent mode.

• Electronic Cam Control

PULS(886) sets the number of output pulses and frequency, and outputs pulses. The following functions have been added to CPU Units with unit version 3.2 or later.

- In ring mode, the pulse output can be set to pass through 0. For example, if the ring value is 359, the cam can be moved from 350 past 0 to 10 using a CW pulse output.
- The pulse output frequency can be calculated automatically in both ring mode and linear mode.

#### **Ladder Symbol**



P: Port specifier

T: Pulse type

N: First number of pulses word

#### **Variations**

Variations	Executed Each Cycle for ON Condition	PULS(886)
	Executed Once for Upward Differentiation	@PULS(886)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	lock program areas Step program areas		Interrupt tasks
OK	OK	OK	OK

# **Operands**

# P: Port Specifier

Р	Port
#1	Pulse output 1
#2	Pulse output 2

#### T: Pulse Type

T specifies the type of pulses that are output as follows:

Т	Pulse type	Notes
#0	Relative pulse output	See note 1.
#1	Absolute pulse output	See note 2.
#2	Pulse output with absolute position specified	See note 3.
#3	Pulse output with absolute position specified (A point past zero can be specified.)	See note 4.
#4	Pulse output with relative position specified (A point past zero can be specified and the pulse output frequency can be calculated automatically.)	See note 4.

#### Note

- 1. To specify a relative pulse output, the pulse output operation mode must be set to *Relative pulse* in the System Setup.
- 2. To specify an absolute pulse output, the pulse output operation mode must be set to *Absolute pulse (Linear mode)* or *Absolute pulse (Circular mode)* in the System Setup.
- 3. To perform electronic cam control, the pulse output operation mode must be set to *Electronic cam control* in the System Setup.
- 4. Settings #3 and #4 can be used only in CPU Units with unit version 3.2 or later. A point past the zero point can be specified only when using ring mode, so settings #2 and #3 are identical when using linear mode.

#### N: First Number of Pulses Word

For a relative pulse output, specify the number of output pulses. For an absolute pulse output, specify the target position.

The number of pulses actually output depends on the pulse type, as shown below.

- Relative pulses:
   Actual number of pulses = Number of output pulses SV
- Absolute pulses:
   Actual number of pulses = Number of output pulses SV PV

Words	Function	Setting range	Conditions
N+1, N	, i	0000 0000 to FFFF FFFF	Specifies the number of output pulses when relative pulse output is selected.
		8000 0000 to 7FFF FFFF	Specifies the target position when absolute (linear mode) pulse output is selected.
		0000 0000 to Maximum cir- cular counter value	Specifies the target position when absolute (circular mode) pulse output is selected.
		8000 0000 to 7FFF FFFF	Specifies the target position for a pulse output (linear mode) with absolute position specified.
		0000 0000 to 7FFF FFFF	Specifies the target position for a pulse output (ring mode) with absolute position specified, D = #2.
		8000 0000 to 7FFF FFFF (Set a ring value up to 3FFF FFFF.)	When specifying the target position for a pulse output in ring mode with an absolute position specified (D = $\#$ 3 or $\#$ 4), the allowed setting range is the ((ring value + 1) + target position) or (target position – (ring value + 1)).
N+3, N+2	Pulse output frequency (8-digit hexadecimal), only when T = #2 or #3	0000 0001 to 0	000F 4240 hex (1 Hz to 1 MHz)
N+2	Pulse output command cycle (4-digit hex), only when D = #4.	0001 to 01F4 l (Set word N+3	nex (0.1 to 50.0 ms) to 0000 hex.)

The output frequency can be set between 1 Hz and 1 MHz, but the frequency that can actually be output depends on the clock frequency. Refer to 7-6-4 Pulse Output Specifications in the FQM1 Series Flexible Motion Controller Operation Manual (Cat. No. O012) to verify the allowed output range. An error will occur and the instruction will not be executed if the specified frequency exceeds the allowed output range. If the specified frequency is below the allowed output range (except 0000 0000), the lower limit frequency will be output. If the output frequency is set to 0000 0000, the instruction will be treated as NOP(000) and the output status will be maintained.

The output frequency will not be changed unless a minimum of one pulse is output. For example, if 1 Hz is output when 20 MHz (1 Hz to 1 MHz) is being used, execution will not be enabled for 1 s while the 1-pulse output is being completed. The instruction can be executed, but a 1-pulse output wait time will be required until the frequency is actually changed. For instructions with automatic acceleration/deceleration, such as PLS2(887) or ACC(888), the frequency will be changed automatically according to the acceleration/

deceleration rate, but for either the start frequency or the acceleration/deceleration rate, a 1-pulse output wait time will be required. When using low frequencies, therefore, allow for delays in speed changes.

#### **Operand Specifications**

Area	Р	Т	N
CIO Area			CIO 0000 to CIO 6142
Work Area			W000 to W254
Auxiliary Bit Area			A448 to A958
Timer Area			T0000 to T0254
Counter Area			C0000 to C0254
DM Area			D00000 to D32766
Indirect DM addresses in binary			@ D00000 to @ D32767
Indirect DM addresses in BCD			*D00000 to *D32767
Constants	See operand description.	See operand description.	See operand description.
Data Resisters			
Index Registers			
Indirect addressing			,IR0 to ,IR15
using Index Registers			-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
			DR0 to DR15, IR0 to DR0 to DR15, IR15
			,IR0+(++) to ,IR15+(++)
			,-()IR0 to , -()IR15

#### **Description**

PULS(886) sets the pulse type and number of pulses specified in T and N for the port specified in P. Actual output of the pulses is started later in the program using SPED(885) or ACC(888) in independent mode.

An error will occur if PULS(886) is executed while pulses are being output, so the number of output pulses cannot be changed. Execute this instruction with either the up-differentiated variation of the instruction (@PULS(886)) or an execution condition that is ON for just one cycle.

Once the number of pulses is determined by executing PULS(886), the calculated number of pulses will not be changed even if INI(880) is executed to change the pulse output PV.

It is also possible to specify values to move outside of the number of output pulses PV range (-2,147,483,648 to +2,147,483,647).

When pulse output is started in Electronic Cam Mode, the direction of rotation (CW or CCW) will be reflected in the Rotation Direction Flags (A874.08 and A875.08).

#### **Execution Conditions**

Setting the Number of Output Pulses for Relative Pulse Output
 To set the number of output pulses for a relative pulse output, execute
 PULS(886) with P set to #1 or #2, T set to #0, and the number of output

pulses set in N and N+1.

- Setting the Target Position for Absolute Pulse Output
   To set the target position for an absolute pulse output, execute PULS(886) with P set to #1 or #2, T set to #1, and the target position set in N and N+1.
- 3. Setting the Target Position for Electronic Cam Control and Starting the Output

To set the target position for electronic cam control and start the pulse output, execute PULS(886) with P set to #1 or #2, D set to #2 to #4. Set the specified position in the number of pulses word and the pulse output frequency (when D is #2 or #3) or the pulse output command cycle (when D is #4). The pulse output command cycle is the time until the specified pulses will be cut off. Normally, this interval lasts until the next PULS(886) instruction is executed for pulse output with an absolute position specified.

4. When PULS(886) was executed to start electronic cam control and the target position has been reached, the pulse output will stop automatically. The pulse output direction and number of pulses are determined by the following formulae:

Value	Formula
Direction	PV < Target: CW direction, PV > Target: CCW direction PV = Target: Maintain status
Number of pulses	PV of pulse output – target pulse amount

The number of pulses actually output depends on the pulse type, as shown below.

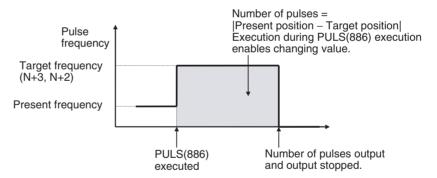
Relative pulses:

Actual number of pulses = Specified number of output pulses

Absolute pulses:

Actual number of pulses = |Present position - target position|

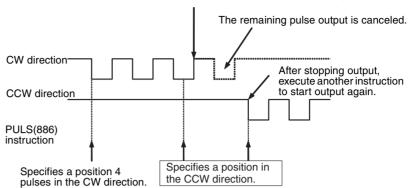
6. If PULS(886) was executed to start a pulse output in electronic cam control mode and the pulses are still being output, PULS(886) can be executed in electronic cam control mode again to change the target position and pulse output frequency.



Note a) When the pulse output direction is reversed by the absolute position specified in electronic cam control, the pulse output will be forcibly stopped after completing one output pulse. The pulse wave will not be interrupted abruptly, but the remaining pulses will not be output. After the output is stopped, pulses will not be output automatically in the opposite direction. The output will start when another pulse output instruction is executed.

If another instruction is executed in the opposite direction of the current movement before the axis is forcibly stopped, the instruction will not be executed. It may take some time to forcibly stop movement when the pulse output frequency is low.

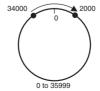
Output is forcibly stopped after outputting one pulse.



- b) If a previously executed PULS(886) instruction reaches its target position while another PULS(886) instruction is being executed, the pulse output will be stopped and the later instruction will not be executed. In this case, execute PULS(886) again. The EQ Flag will go OFF in this case.
- 7. If a PULS(886) instruction is executed during an independent mode (positioning) pulse output, the number of output pulses or target position will not be set again. (The number of output pulses and target position cannot be changed during an independent mode pulse output.) Execute this instruction with either the up-differentiated version of the instruction (@PULS(886)) or an execution condition that is ON for just one cycle.
- 8. The pulse output operation mode must be set to *Electronic cam control* in order to perform electronic cam control. If a different operation mode is selected, PULS(886) will not be executed and an error will occur.
- 9. Any of the following methods can be used to stop pulses being output in electronic cam control mode by PULS(886).
  - a) Execute INI(880) with C set to #0003 (immediate stop).
  - b) The pulse output will stop when the target position is reached (immediate stop).
  - c) Switch the Motion Control Module to PROGRAM mode.
- 10. Pulse outputs can be output independently and simultaneously from two output ports.
- 11. When the pulse output operation mode is set to Absolute pulse (Linear mode) and the specified target position is the same as the present position, PULS(886) will not be executed and the target position will not be set. The EQ Flag will go OFF in this case.
- 12. When D is set to #3 or #4 for absolute pulse output in ring mode, it is possible to send a command that moves through the 0 point.

To move through 0 in the CW direction, calculate the target position to be set in N+1 and N as shown below.

SV in N+1 and N = (ring value + 1) + target position For example, if the ring value range is 0 to 35,999 and you want to move from 34,000 to 2,000 through 0, use the following command.



SV in N+1 and N = (35,999 + 1) + 2,000 = 38,000 (9470 hex)

To move through 0 in the CCW direction, calculate the target position to be set in N+1 and N as shown below.

SV in N+1 and N = 0 - target position

For example, if the ring value range is 0 to 35,999 and you want to move from 2,000 to 34,000 through 0, use the following command.



SV in N+1 and N = 34,000 - 36,000 = -2,000 (FFFF F830 hex)

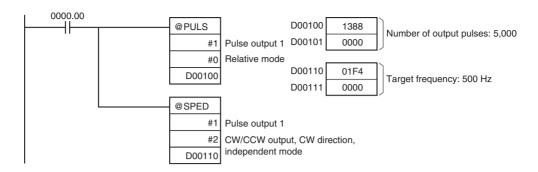
- **Note** Do not set an SV in N+1 and N that would move around the ring more than once. The correct position may not be calculated (including moving from the present position through 0 and back to the present position).
- 13. If D is set to #3 or #4 when using absolute pulse outputs in Ring Mode and a new target position is being specified after starting execution of a movement that passes through 0, use PRV(881) to read the present value of the pulse output to see whether 0 has been passed. If the new target position will cause movement to pass through 0 again, refer to item 12, above, to set the value in N+1 and N. If N+1 and N are not set correctly, the pulse output may be in the wrong direction. Or, in this case, set D to #3 (and not #4) so that the pulse output frequency is not automatically calculated. The calculated frequency may not always be correct.

#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if P is set to a value other than #1 or #2.	
		ON if D is set to a value other than #0 to #4.	
		ON if the pulse output operation mode is set to 1 shot or Calculation (time measurement) mode in the System Setup.	
		ON if an instruction controlling pulse output is being executed in the main program, an interrupt occurs, and PULS(886) is executed in the interrupt task.	
		OFF in all other cases.	
Equal Flag	=	Operation when T is set to #0 or #1:	
		ON when the target position is set with PULS(886).	
		OFF when the target position could not be set with PULS(886).	
		Operation when T is set to #2, #3, #4:	
		ON when the pulse output is started by PULS(886).	
		OFF when the pulse output could not be started by PULS(886).	

# Example

When CIO 0000.00 goes from OFF to ON in the following programming example, PULS(886) sets the number of output pulses for pulse output 1. A relative value of 5,000 pulses is set. SPED(885) is executed next to start pulse output using the CW/CCW method in the clockwise direction in independent mode at a target frequency of 500 Hz.

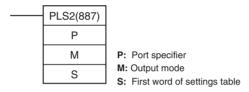


# 3-20-6 PULSE OUTPUT: PLS2(887)

# **Purpose**

PLS2(887) outputs pulses to the specified port based on the specified target position, target frequency, startup frequency, acceleration rate, and deceleration rate. The acceleration rate and deceleration rate can be set separately. Only independent mode positioning is supported.

# **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	PLS2(887)
	Executed Once for Upward Differentiation	@PLS2(887)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Operands**

#### P: Port Specifier

The port specifier indicates the port.

Р	Port
#1	Pulse output 1
#2	Pulse output 2

#### M: Output Mode

M	Mode
#0	CW direction
#1	CCW direction

# S: First Word of Settings Table

Word	Content
Т	Target position (8-digit hexadecimal)
T+1	Relative pulse output: 0000 0000 to FFFF FFFF Absolute pulse output (linear mode): 8000 0000 to 7FFF FFFF
T+2	Target frequency (8-digit hexadecimal)
T+3	0000 0001 to 000F 4240
T+4	Starting frequency (8-digit hexadecimal)
T+5	0000 0000 to 000F 4240

Word	Content
T+6	Acceleration rate (4-digit hexadecimal)
	0001 to 270F
T+7	Deceleration rate (4-digit hexadecimal)
	0001 to 270F

The acceleration rate and deceleration rate specify the amount that the frequency will be changed each 2 ms or 1 ms. Set the rates in 1-Hz units. The 0001 to 270F hex setting range corresponds to a 1 Hz to 9.999 kHz range.)

The target frequency specifies the frequency reached after acceleration. Set the frequency in 1-Hz units. (The 0000 0001 to 000F 4240 hex setting range corresponds to a 1 Hz to 1 MHz range.)

The starting frequency specifies the frequency at which the output starts. Set the frequency in 1-Hz units. (The 0000 0000 to 000F 4240 hex setting range corresponds to a 0 Hz to 1 MHz range.)

The target frequency can be set between 1 Hz and 1 MHz and the starting frequency can be set between 0 Hz and 1 MHz. But the frequency that can actually be output depends on the clock frequency. Refer to 7-6-4 Pulse Output Specifications in the FQM1 Series Flexible Motion Controller Operation Manual (Cat. No. O012) to verify the allowed output range. An error will occur and the instruction will not be executed if the specified frequency exceeds the allowed output range. If the specified frequency is below the allowed output range, the lower limit frequency will be output.

The output frequencies are obtained by dividing the Motion Control Module's clock pulse with an integer dividing ratio, meaning the actual output frequency can be different from the set frequency.

Also, the pulse frequencies actually output during acceleration/deceleration are frequencies that can actually be output with the integer dividing ratio. If the acceleration or deceleration rate is low, there may not be an change in the frequency in every 2 ms interval.

Refer to *Precautions when Using Pulse Outputs* in the *FQM1 Series Flexible Motion Controller Operation Manual* (Cat. No. 0012) for details.

The output frequency will not be changed unless a minimum of one pulse is output. For example, if 1 Hz is output when 20 MHz (1 Hz to 1 MHz) is being used, execution will not be enabled for 1 s while the 1-pulse output is being completed. The instruction can be executed, but a 1-pulse output wait time will be required until the frequency is actually changed. For instructions with automatic acceleration/deceleration, such as PLS2(887) or ACC(888), the frequency will be changed automatically according to the acceleration/deceleration rate, but for either the start frequency or the acceleration/deceleration rate, a 1-pulse output wait time will be required. When using low frequencies, therefore, allow for delays in speed changes.

# **Operand Specifications**

Area	Р	M	S
CIO Area			CIO 0000 to CIO 6136
Work Area			W000 to W248
Auxiliary Bit Area			A448 to A952
Timer Area			T0000 to T0248
Counter Area			C0000 to C0248
DM Area			D00000 to D32760
Indirect DM addresses in binary			@ D00000 to @ D32767

Area	Р	М	S
Indirect DM addresses in BCD			*D00000 to *D32767
Constants	See operand description.	See operand description.	DR0 to DR15
Data Resisters			
Index Registers			
Indirect addressing using Index Registers			,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15

#### **Description**

PLS2(887) operation proceeds as described below.

- 1. PLS2(887) starts a pulse output at the specified starting frequency and accelerates the output each 1 ms or 2 ms by the specified frequency step.
- 2. When the target frequency is reached, the frequency acceleration stops and the pulse output continues at a constant frequency.
- 3. When the distance to the target position (calculated number of pulses from the target position) reaches the deceleration point calculated from the deceleration rate and frequency, PLS2(887) decelerates the output each 1 ms or 2 ms by the specified frequency step. PLS2(887) stops the pulse output at the target position.

If the specified number of pulses is too low for the acceleration and deceleration stages, PLS2(887) will not perform trapezoidal acceleration/deceleration. The pulse output will start decelerating before the target frequency is reached or the pulse output may not even accelerate from the starting frequency. In this case, the PLS2(887) Target Frequency Not Reached Flag (A874.02 or A875.02) will turn ON.

The PLS2(887) Target Frequency Not Reached Flag is turned ON during acceleration when the deceleration point is reached and turned OFF when deceleration is completed.

#### Note

PLS2(887) calculates the number of pulses required for deceleration based on the specified target position, starting speed, and deceleration rate. This value is known as the number of deceleration pulses and deceleration starts when the number of remaining pulses reaches the number of deceleration pulses. This point is known as the deceleration point.

If the total number of output pulses is less than number of deceleration pulses, the total number of output pulses will be output resulting in triangular control.

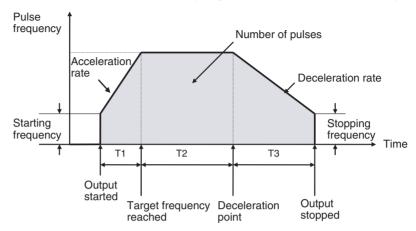
If the total number of output pulses is greater than number of deceleration pulses but less than the number required for acceleration and deceleration, the deceleration point will be reached during acceleration and deceleration will start at that point.

# Operation

When PLS2(887) is executed just once, the pulse output is controlled until it stops with the specified settings, so use either the up-differentiated variation of the instruction (@PLS2(887)) or an execution condition that is ON for just one cycle.

The number of pulses actually output depends on the pulse type, as shown below.

- Relative pulse output:
   Actual number of pulses = Target position
- Absolute pulse output (linear mode):
   Actual number of pulses = |Target position Present position|



 $T1 \approx 0.002 \times (Target frequency - Starting frequency) \div (Acceleration rate)$ 

 $T3 \approx 0.002 \times (Target frequency - Starting frequency) \div (Deceleration rate)$ 

T2 ≈ (Number of pulses -

((Target frequency + Starting frequency) × (T1+T3) ÷ 2)) ÷ Target frequency

These equations are approximations. The actual values of T1, T2, and T3 will vary depending on the pulse output operating conditions. (The number of output pulses is output accurately.)

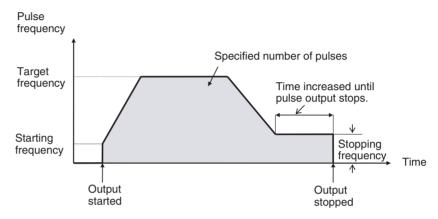
With version 3.3 or higher, if the starting frequency is set to 0 Hz when the pulse output clock is set to 20 MHz (full range), the starting frequency will be the acceleration rate and the stopping frequency will be the smaller of the acceleration rate or the deceleration rate.

Note

- 1. The stopping frequency is the same as the starting frequency. If the stopping frequency is below the allowed output range (determined by the selected clock frequency), the lower limit frequency will be output.
- 2. If the number of pulses is lower than the number required for acceleration and deceleration, trapezoidal acceleration/deceleration will not be possible and deceleration will begin before the target frequency is reached. When the starting frequency has been set to 0, pulses may be output at the lower limit output frequency for the selected clock frequency.
- 3. When using PLS2(887) for an absolute pulse output (linear mode), check the present position before specifying the CW or CCW direction. Pulses will not be output if the direction setting is incorrect for the relationship between the present position and target position. An error will occur if PLS2(887) is executed with settings that prevent pulse output.
- 4. PLS2(887) will not be executed and an error will occur if a pulse output is already being output from the specified port.
- 5. Any of the following methods can be used to stop pulses being output by PLS2(887).
  - a) Execute INI(880) with C set to #0003.
  - b) The pulse output will stop when the target position is reached.
  - c) Switch the Motion Control Module to PROGRAM mode.
  - d) Execute ACC(888) with M set to #0008 or #0009 and the target frequency set to 0 Hz. Pulse output will decelerated to a stop. (If number

- of output pulses set for PULS(886) in independent mode is reached, an immediate stop will be performed.)
- e) Execute ACC(888) with M set to #0008 or #0009 and the target frequency set to 0 Hz. Pulse output will decelerated to a stop. (If number of output pulses set for PULS(886) in independent mode is reached, an immediate stop will be performed.)

/!\ Caution With PLS2(887), the output may continue for some time at the stopping frequency, depending on factors such as the acceleration/deceleration rate and the target speed. (Even when this happens, the correct number of pulses will be output.)



If this problem occurs, correct the system by adjusting the acceleration rate, deceleration rate, target speed, or starting frequency. If the starting frequency is low, it is easy to adjust the system by increasing the starting frequency to 500 Hz or higher.

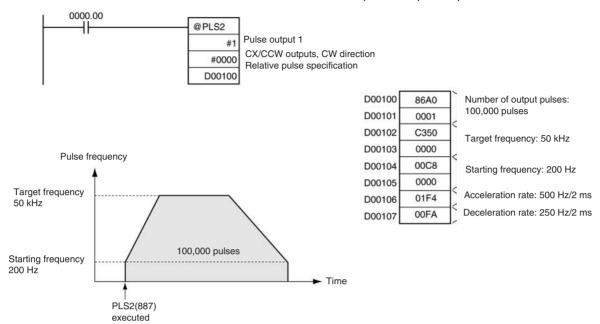
**Note** PLS2(887) cannot be used if the pulse output operation mode is set to *Abso*lute pulse (Circular mode) or 1 shot mode in the System Setup.

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if P is set to a value other than #1 or #2.
		ON if M is set to a value other than #0 or #1.
		ON if the pulse output operation mode is set to Absolute pulse (Circular mode) or One-Short pulse output, or Time measurement using pulse counter in the System Setup.
		ON if the target frequency, acceleration rate, or deceleration rate setting is incorrect. (For example, if the target frequency is less than the starting frequency.)
		ON if the CW/CCW direction setting is incorrect for the relationship between the present position and target position.
		ON if pulses are already being output from the specified output port.
		ON if an instruction controlling pulse output is being executed in the main program, an interrupt occurs, and PLS2(887) is executed in the interrupt task.
		OFF in all other cases.

#### **Example**

When CIO 0000.00 goes from OFF to ON, PLS2(887) starts a relative pulse output of 100,000 pulses from pulse output 1. The pulse output begins at a starting frequency of 200 Hz and accelerates to a target frequency of 50 kHz at an acceleration rate of 500 Hz/2 ms. When the output reaches the deceleration point, it decelerates back to the starting frequency of 200 Hz at a deceleration rate of 250 Hz/2 ms. The pulse output stops at 200 Hz.



# 3-20-7 ACCELERATION CONTROL: ACC(888)

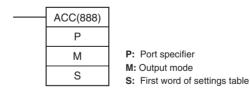
# **Purpose**

ACC(888) outputs pulses to the specified output port at the specified frequency using the specified acceleration and deceleration rate. (The acceleration rate is the same as the deceleration rate.)

ACC(888) can perform positioning (independent mode) or speed control (continuous mode). For positioning, ACC(888) is used in combination with PULS(886). ACC(888) can also be executed during pulse output to change the target frequency or acceleration/deceleration rate, enabling smooth (sloped) speed changes.

This instruction is supported by the FQM1-MMP22 and FQM1-MMA22 Motion Control Modules only.

#### **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	ACC(888)
	<b>Executed Once for Upward Differentiation</b>	@ACC(888)
	<b>Executed Once for Downward Differentiation</b>	Not supported

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

# **Operands**

# P: Port Specifier

The port specifier specifies the port where the pulses will be output.

Р	Port	
#1	FQM1-MMP22: Pulse output 1	
	FQM1-MMA22: Analog output 1	
#2	FQM1-MMP22: Pulse output 2	
	FQM1-MMA22: Analog output 2	

#### M: Output Mode

The value of M determines the pulse output mode in the FQM1-MMP22.

Module	Value of M	Mode
FQM1-MMP22	#0000	CW, acceleration, continuous mode
(Pulse output)	#0001	CCW, acceleration, continuous mode
	#0002	CW, deceleration, continuous mode
	#0003	CCW, deceleration, continuous mode
	#0004	CW, acceleration, independent mode
	#0005	CCW, acceleration, independent mode
	#0006	CW, deceleration, independent mode
	#0007	CCW, deceleration, independent mode
	#0008	Continuous mode speed change
	#0009	Independent mode speed change
FQM1-MMA22	#0000 (fixed)	

# S: First Word of Settings Table

• FQM1-MMP22 Settings

Word	Content
S	Specifies the acceleration and deceleration rates
	<ul> <li>2 ms cycle (speed-change cycle) Set a frequency change of 0001 to 270F hex (1 to 9,999 Hz, in 1-Hz units). The frequency is changed by this amount every 2 ms.</li> <li>1 ms cycle (speed-change cycle) Set a frequency change of 0001 to 270F hex (1 to 9,999 Hz, in 1-Hz units). The frequency is changed by this amount every 1 ms.</li> </ul>
S+1, S+2	Specifies the target frequency in 8-digit hexadecimal. (S+1 contains the rightmost 4 digits and S+2 contains the leftmost 4 digits.)
	Set a frequency of 0000 0000 to 000F 4240 hex (0 Hz to 1 MHz in 1-Hz units). This is the target frequency after acceleration.

The target frequency can be set between 0 Hz and 1 MHz, but the frequency that can actually be output depends on the clock frequency. Refer to 7-6-4 Pulse Output Specifications in the FQM1 Series Flexible Motion Controller Operation Manual (Cat. No. O012) to verify the allowed output range. An error will occur and the instruction will not be executed if the specified frequency exceeds the allowed output range. If the specified frequency is below the allowed output range, the lower limit frequency will be output.

The output frequencies are obtained by dividing the Motion Control Module's clock pulse with an integer dividing ratio, meaning the actual output frequency can be different from the set frequency.

Also, the pulse frequencies actually output during acceleration/deceleration are frequencies that can actually be output with the integer dividing ratio. If the acceleration or deceleration rate is low, there may not be an change in the frequency in every 2 ms interval.

Refer to *Precautions when Using Pulse Outputs* in the *FQM1 Series Flexible Motion Controller Operation Manual* (Cat. No. 0012) for details.

The output frequency will not be changed unless a minimum of one pulse is output. For example, if 1 Hz is output when 20 MHz (1 Hz to 1 MHz) is being used, execution will not be enabled for 1 s while the 1-pulse output is being completed. The instruction can be executed, but a 1-pulse output wait time will be required until the frequency is actually changed. For instructions with automatic acceleration/deceleration, such as PLS2(887) or ACC(888), the frequency will be changed automatically according to the acceleration/deceleration rate, but for either the start frequency or the acceleration/deceleration rate, a 1-pulse output wait time will be required. When using low frequencies, therefore, allow for delays in speed changes.

If the target frequency is set to 0 (Hz) and the mode specifier is set to #0008 or #0009, the instruction can be executed at any time in the same way as when stopping pulse outputs using INI(880).

## • FQM1-MMA22 Settings

Word	Content
S	Specifies the analog output's rate-of-change in 4-digit hexadecimal. The analog output value will be changed by this amount every 2 ms.
	-10 to 10 V 0000 to 2AF8 hex (0 to 11,000 decimal) = 0 to 110% (0 to +22 V)
	0 to 10 V, 0 to 5 V, or 1 to 5 V 0000 to 1130 hex (0 to 4,400 decimal) = 0 to 110% (0 to +11 V, 0 to +5.5 V, or 0 to +4.4 V)
S+1	Specifies the target analog output value in 4-digit hexadecimal.
	-10 to 10 V  EC78 to 1388 hex (-5,000 to 5,000 decimal) (resolution: 10,000) corresponding to 0% to 100% voltage (-10 to 10 V)  (Actually, the setting range is EA84 to 157C (-5,500 to 5,500 decimal) corresponding to -5% to 105% voltage (-11 to 11 V).)
	0 to 10 V, 0 to 5 V, or 1 to 5 V: 0000 to 0FA0 hex (0000 to 4,000 decimal) (resolution: 4,000) corresponding to 0% to 100% of the FS range. (Actually, the setting range is FF38 to 1068 (–200 to 4,200 decimal) corresponding to –5% to 105% voltage (–0.5 to 10.5 V, –0.25 to 5.25 V, or 0.8 to 5.2 V).)

**Note** An error will occur and the ER Flag will be turned ON if the settings exceed the ranges listed above.

# **Operand Specifications**

Area	Р	М	S
CIO Area			CIO 0000 to CIO 6141
Work Area			W000 to W253
Auxiliary Bit Area			A448 to A957
Timer Area			T0000 to T0253
Counter Area			C0000 to C0253
DM Area			D00000 to D32765
Indirect DM addresses in binary			@ D00000 to @ D32767
Indirect DM addresses in BCD			*D00000 to *D32767
Constants	See operand description.	See operand description.	
Data Resisters			

Area	Р	М	S
Index Registers			
Indirect addressing using Index Registers			,IR0 to ,IR15 -2048 to +2047 ,IR0 to -2048 to +2047 ,IR15 DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++) ,-()IR0 to , -()IR15

# **Description**

# Pulse Output (FQM1-MMP22)

Pulses can be output in independent mode (positioning) or continuous mode (speed control).

Mode	Description	Frequency changes
Speed control	Mode #0000 or #0001 (Acceleration + Continuous mode)  The frequency is increased from the present frequency to the target frequency at the specified acceleration/deceleration rate. The pulse output continues at the target frequency. The output will continue until stopped with INI(880) or by executing SPED(885) or ACC(888) with a target frequency of 0.	Pulse output will continue until stopped with INI(880) or by executing SPED(885) or ACC(888) with a target frequency of 0  Target frequency (T+1, T+2) Present frequency  ACC(888) executed
	Mode #0002 or #0003 (Deceleration + Continuous mode) The frequency is decreased from the present frequency to the target frequency at the specified acceleration/deceleration rate. The pulse output continues at the target frequency. The output will continue until stopped with INI(880) or by executing SPED(885) or ACC(888) with a target frequency of 0.	Pulse output will continue until stopped with INI(880) or by executing SPED(885) or ACC(888) with a target frequency of 0  Present frequency  Target frequency (T+1, T+2)  ACC(888) executed
	Mode #0008 (Speed changes in Continuous mode) Pulse output is continued while automatically determining the pulse output direction and the need for acceleration or deceleration. If this mode is used when pulses are not being output, the instruction will not be executed and the ER Flag will turn ON.	Pulse frequency Target frequency after change Target frequency and acceleration rate changed again during acceleration Present frequency  ACC(888) ACC(888) executed for mode #0008 (Speed change in continuous mode)

Mode	Description	Frequency changes
Position- ing	Mode #0004 or #0005 (Acceleration + Independent mode)  The frequency is increased to the target frequency at the specified acceleration/deceleration rate.  The pulse output continues at the target frequency until the number of pulses specified with PULS(886) have been output. The pulse output stops automatically at that point.  (With independent mode, the number of pulses must be set in advance with PULS(886) and the output operates according to that setting.)	Pulse frequency Target frequency (T+1, T+2)  Accel/Decel Number of pulses specified with PULS(886)  Time  ACC(888) Pulse output stops when the specified number of pulses have been output.
	Mode #0006 or #0007 (Deceleration + Independent mode)  The frequency is decreased from the present frequency to the target frequency at the specified acceleration/deceleration rate. The pulse output continues at the target frequency until the number of pulses specified with PULS(886) have been output. The pulse output stops automatically at that point.  (With independent mode, the number of pulses must be set in advance with PULS(886) and the output operates according to that setting.)	Pulse frequency  Present frequency  Target frequency (T+1, T+2)  SPED(885) or other instruction executed  Number of pulses specified with PULS(886)  Accel/Decel Rate (T)  Pulse output stops when the specified number of pulses have been output.
	Mode #0009 (Speed changes in Independent mode) Pulse output is continued while automatically determining the pulse output direction and the need for acceleration or deceleration. If this mode is used when pulses are not being output, the instruction will not be executed and the ER Flag will turn ON.	Pulse frequency Target frequency before change Target frequency after change Target frequency and acceleration rate changed again during acceleration  ACC(888)  ACC(888) executed for mode #0009 (Speed change in independent model)  Number of pulses specified with PULS(886)  Time  Pulse output stops when the specified number of pulses have been output.

## Independent Mode (Positioning) Operation

In independent mode, only a preset number of pulses are output. Set the number of output pulses in advance with PULS(886).

In independent mode (positioning), the number of output pulses must be specified in advance with PULS(886). (No pulses will be output if the number of output pulses is not specified before executing ACC(888).) If the pulse output has been stopped, it is necessary to set the number of output pulses again with PULS(886).

If the number of output pulses set with PULS(886) is less than the number of pulses required for acceleration (Pulses  $\approx$  Time to reach target frequency  $\times$  (Target frequency – Starting frequency)  $\div$  2), the pulse output will stop before the target frequency is reached.

Likewise, if the number of output pulses set with PULS(886) is less than the number of pulses required for deceleration (Pulses  $\approx$  Time to reach target frequency  $\times$  (Target frequency – Starting frequency)  $\div$  2), the pulse output will stop before the target frequency is reached.

If the target frequency is set to 0 and the number of output pulses set with PULS(886) is greater than the number of pulses required for deceleration (Pulses  $\approx$  Time to reach target frequency  $\times$  (Target frequency – Starting

frequency)  $\div$  2), the pulse output will stop before the specified number of pulses have been output.

If a high acceleration/deceleration rate and low number of output pulses are set, the effective operation will have almost no acceleration/deceleration and the system will operate at nearly a steady speed.

- Continuous Mode (Speed Control) Operation
   In continuous mode, pulses are output continuously until stopped by executing SPED(885) with a target frequency of 0, executing or ACC(888) with M set to #0008 or #0009 and a target frequency of 0, executing INI(880) with C = #0003, or switching the Motion Control Module to PROGRAM mode.
- Continuous Mode and Independent Mode Operation
   The Rotation Direction Flags (A874.08 and A875.08) will reflect the direction of rotation (CW or CCW) during pulse output.

## **Analog Output (FQM1-MMA22)**

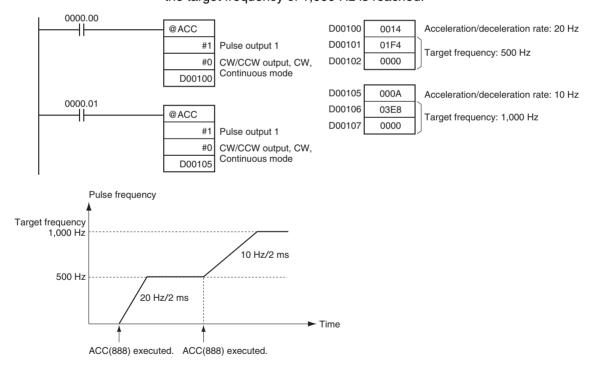
- To generate an analog output, execute ACC(888) with P set to #0001 or #0002, M set to #0000, and S set to the first of two words containing the analog output rate-of-change (slope) and target output value. ACC(888) needs to be executed just once, so use either the up-differentiated variation of the instruction (@ACC(888)) or an execution condition that is ON for just one cycle.
- 2. When ACC(888) is executed, the analog output is increased every 2 ms by the rate-of-change amount specified in S. When the target analog output value is reached, the value will stop increasing and remain at the target value.
- 3. Analog outputs can be output independently and simultaneously from two output ports.
- 4. Analog outputs are not distinguished as continuous or independent outputs. The analog output generated by ACC(888) will maintain its output value until one of the following events occurs:
  - a) SPED(885) or ACC(888) is executed with a different target value.
  - b) The *Output stop function* is set to a setting other than *Hold* and the Motion Control Module is switched to PROGRAM mode or the Analog Output Conversion Enable Bit (A814.00 or A815.00) is reset to 0.
- 5. If an analog output is being generated by SPED(885), that output value can be changed by executing ACC(888) with a different analog output value.
- 6. The present analog output value will not be changed and an error will occur if ACC(888) is executed while another ACC(888) is generating an accelerating or decelerating analog output (i.e., the earlier ACC(888) analog output has not reached its target value).

# **Flags**

Name	Label	Operation
Error Flag	ER	ON if P is set to a value other than #0001 or #0002.
		For the FQM1-MMP22, ON if M is not set between #0 and #7.
		For the FQM1-MMA22, ON if M is not set to #0.
		For the FQM1-MMP22, ON if the specified frequency is not supported at the selected Motion Control Module clock frequency.
		For the FQM1-MMP22, ON if ACC(888) is executed when the present pulse output cannot be changed. (For example, the pulse output cannot be changed when pulses are already being output by an PLS2(887) instruction but the target value has not been reached.)
		ON if an instruction controlling a pulse output or analog output is being executed in the main program, an interrupt occurs, and ACC(888) is executed in the interrupt task.
		OFF in all other cases.

## Example

When CIO 0000.00 goes from OFF to ON, ACC(888) starts pulse output from pulse output 1 in continuous mode in the clockwise direction using the CW/CCW method. Pulse output is accelerated at a rate of 20 Hz every 2 ms until the target frequency of 500 Hz is reached. When CIO 0000.01 goes from OFF to ON, ACC(888) changes to an acceleration rate of 10 Hz every 2 ms until the target frequency of 1,000 Hz is reached.



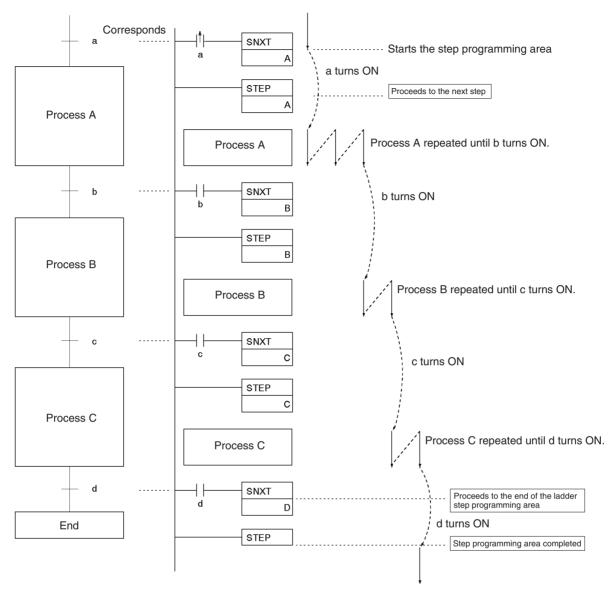
# 3-21 Step Instructions

This section describes Step Instructions, which are used to set up break points between sections in a large program so that the sections can be executed as units and reset upon completion.

Instruction	Mnemonic	Function code	Page
STEP DEFINE	STEP	008	563
STEP START	SNXT	009	563

In the FQM1, STEP(008)/SNXT(009) can be used together to create step programs.

Instruction	Operation	Diagram
SNXT(009): STEP START	Controls progression to the next step of the program.	Corresponds  Equivalent to this
STEP(008): STEP DEFINE	Indicates the start of a step. Repeats the same step program until the conditions for progression to the next step are established.	Corresponds  Equivalent to this



Note Work bits are used as the control bits for A, B, C and D.

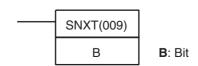
# 3-21-1 STEP DEFINE and STEP START: STEP(008)/SNXT(009)

**Purpose** 

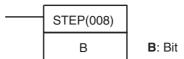
SNXT(009) is placed immediately before the STEP(008) instruction and controls step execution by turning the specified control bit ON. If there is another step immediately before SNXT(009), it also turns OFF the control bit of that process.

STEP(008) is placed immediately after the SNXT(009) instruction and before each process. It defines the start of each process and specifies the control bit for it. It is also placed at the end of the step programming area after the last SNXT(009) to indicate the end of the step programming area. When it appears at the end of the step programming area, STEP(008) does not take a control bit.

**Ladder Symbols** 



When defining the beginning of a step, a control bit is specified as follows:.



When defining the end of a step, a control bit is not specified as follows:



#### **Variations**

Variations		STEP(008)/ SNXT(009)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
Not allowed	OK	Not allowed	Not allowed

# **Operand Specifications**

Area	В
CIO Area	
Work Area	W000.00 to W255.15
Auxiliary Bit Area	
Timer Area	
Counter Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

# **Description**

## SNXT(009)

SNXT(009) is used in the following three ways:

- 1,2,3... 1. To start step programming execution.
  - 2. To proceed to the next step control bit.
  - 3. To end step programming execution.

The step programming area is from the first STEP(008) instruction (which always takes a control bit) to the last STEP(008) instruction (which never takes a control bit).

# **Starting Step Execution**

SNXT(009) is placed at the beginning of the step programming area to start step execution. It turns ON the control bit specified for B for the next STEP(008) and proceeds to step B (all instructions after STEP(008) B). A updifferentiated execution condition must be used for the SNXT(009) instruction that starts step programming area execution, or step execution will last for only one cycle. (If SNXT(009) is incorrectly placed at the beginning of the step programming area, it will operate in the same manner as SET (i.e., once it is turned ON, it will maintain its status until it is turned OFF by RESET.) If SNXT(009) is already ON when starting the next cycle, the step programming area will not be executed in the following cycles.)

### **Proceeding to the Next Step**

When SNXT(009) occurs in the middle of the step programming area, it is used to proceed to the next step. It turns OFF the previous control bit and turns ON the next control bit B, for the next step, thereby starting step B (all instructions after STEP(008) B).

# **Ending the Step Programming Area**

When SNXT(009) is placed at the very end of the step programming area, it ends step execution and turns OFF the previous control bit. The control bit specified for B is a dummy bit. This bit will however be turned ON, so be sure to select a bit that will not cause problems.

### STEP(008)

STEP(008) functions in following 2 ways, depending on its position and whether or not a control bit has been specified.

- **1,2,3...** 1. Starts a specific step.
  - 2. Ends the step programming area (i.e., step execution).

## Starting a Step

STEP(008) is placed at the beginning of each step with an operand, B, that serves as the control bit for the step.

The control bit B will be turned ON by SNXT(009) and the instruction in the step will be executed from the one immediately following STEP(008). A200.12 (Step Flag) will also turn ON when execution of a step begins.

After the first cycle, step execution will continue until the conditions for changing the step are established, i.e., until the SNXT(009) instruction turns ON the control bit in the next STEP(008).

When SNXT (009) turns ON the control bit for a step, the control bit B of the current instruction will be reset (turned OFF) and the step controlled by bit B will become interlocked.

Handling of outputs and instructions in a step will change according to the ON/OFF status of the control bit B. (The status of the control bit is controlled by SNXT(009)). When control bit B is turned OFF, the instructions in the step are reset and are interlocked. Refer to the following tables.

Control bit status	Handling
ON	Instructions in the step are executed normally.
ON→OFF	Bits and instructions in the step are interlocked as shown in the next table.
OFF	All instructions in the step are processed as NOPs.

## Interlock Status (IL)

Instruction output		Status
Bits specified for OUT, OUT NOT		All OFF
The following timer instruc-	PV	0000 hex (reset)
tions: TIM, TIMH(015), and TMHH(540)	Completion Flag	OFF (reset)
Bits or words specified for other instructions (see note)		Holds the previous status (but the instructions are not executed)

**Note** Indicates all other instructions, such as SET, REST, CNT, CNTR(012), SFT(010), and KEEP(011).

The STEP(008) instruction must be placed at the beginning of each step. STEP(008) is placed at the beginning of a step area to define the start of the step.

## **Ending the Step Programming Area**

STEP(008) is placed at the end of the step programming area without an operand to define the end of step programming When the control bit preceding a SNXT(009) instruction is turned OFF, step execute is stopped by SNXT(009).

Flags:STEP(008)

Name	Label	Operation
Error Flag	ER	ON when the specified bit B is not in the WR area.
		ON when STEP(008) is used in an interrupt program.
		OFF in all other cases.

Flags:SNXT(009)

Name	Label	Operation
Error Flag	ER	ON when the specified bit B is not in the WR area.
		ON when SNXT(009) is used in an interrupt program.
		OFF in all other cases.

**Precautions** 

The control bit, B, must be in the Work Area for STEP(008)/SNXT(009).

A control bit for STEP(008)/SNXT(009) cannot be use anywhere else in the ladder diagram. If the same bit is used twice, a duplication bit error will occur. If SBS(091) is used to call a subroutine from within a step, the subroutine outputs and instructions will not be interlocked when the control bit turns OFF.

Control bits within one section of step programming must be sequential and from the same word.

SNXT(009) will be executed only once, i.e., on the rising edge of the execution condition.

Input SNXT(009) at the end of the step programming area and make sure that the control bit is a dummy bit in the Work Area. If a control bit for a step is used in the last SNXT(009) in the step programming area, the corresponding step will be started when SNXT(009) is executed.

An error will occur and the Error Flag will turn ON if the operand B specified for SNXT(009) or STEP(008) is not in the Work Area or if the step program has been placed anywhere but in a cyclic task.

A200.12 (Step Flag) is turned ON for one cycle when STEP(008) is executed. This flag can be used to conduct initialization once the step execution has started.

# Placement Conditions for Step Programming Areas (STEP B to STEP)

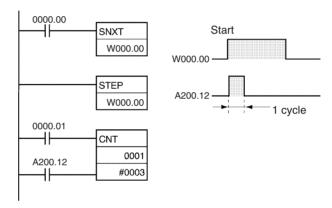
STEP(008) and SNXT(009) cannot be used inside of subroutines, interrupt tasks, or block programs.

Be sure that two steps are not executed during the same cycle.

# **Instructions that Cannot be Used Within Step Programs**

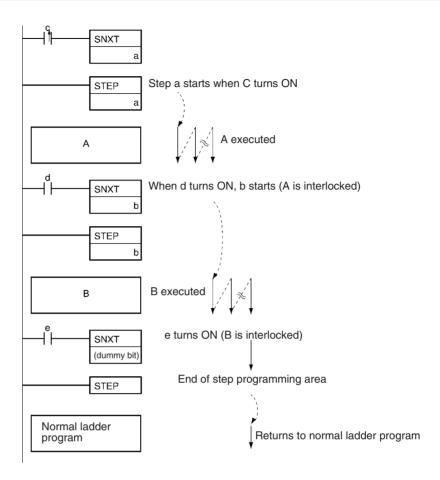
The instructions that cannot be used within step programs are listed in the following table.

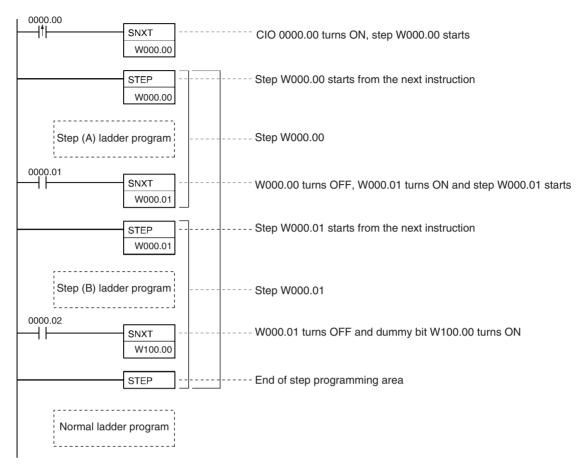
Function	Mnemonic	Name
Sequence Control Instruc-	END(001)	END
tions	IL(002)	INTERLOCK
	ILC(003)	INTERLOCK CLEAR
	JMP(004)	JUMP
	JME(005)	JUMP END
Subroutine Instructions	SBN(092)	SUBROUTINE ENTRY
	RET(093)	SUBROUTINE RETURN



### **Related Bits**

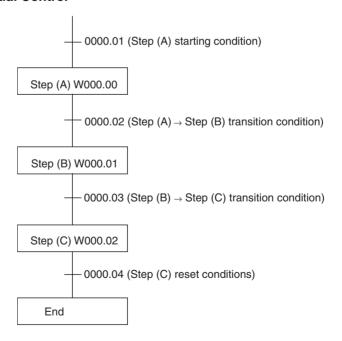
Name	Address	Details
Step Flag	A200.12	ON for one cycle when a step program is started using STEP(008). Can be used to reset timers and perform other processing when starting a new step.

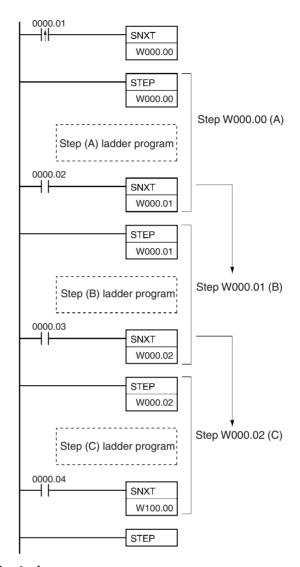




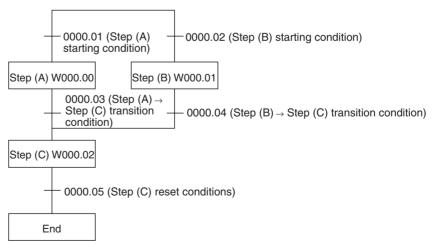
## **Examples**

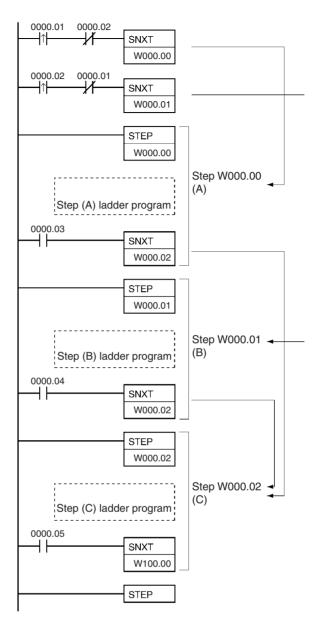
# **Sequential Control**





# **Branching Control**

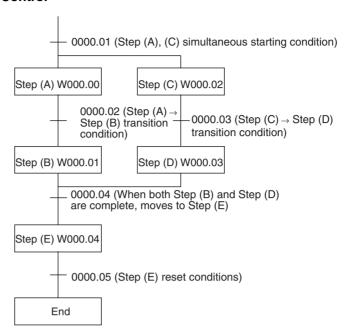


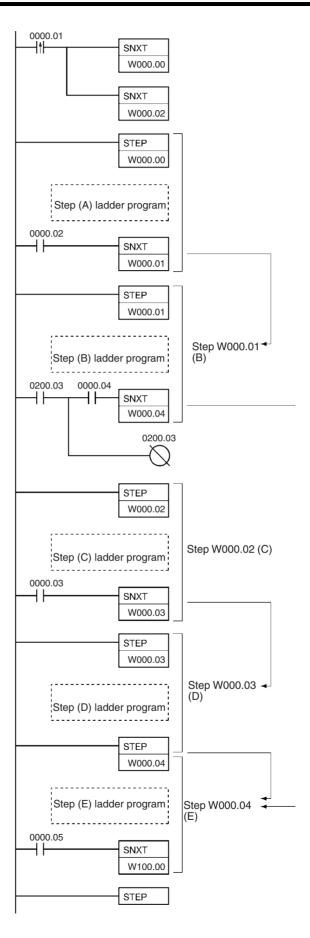


The above programming is used when steps A and B cannot be executed simultaneously. For simultaneous execution of A and B, delete the execution conditions illustrated below.

**Note** In the above example, where SNXT(009) is executed for W000.02, the branching moves onto the next steps even though the same control bit is used twice. This is not picked up as an error in the program check using the CX-Programmer. A duplicate bit error will only occur in a step ladder program only when a control bit in a step instructions is also used in the normal ladder diagram.

## **Parallel Control**



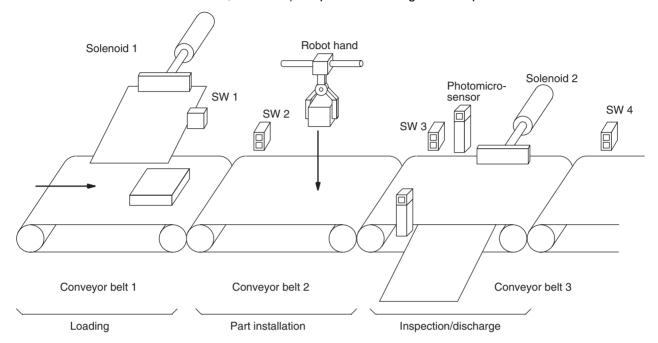


# **Application Examples**

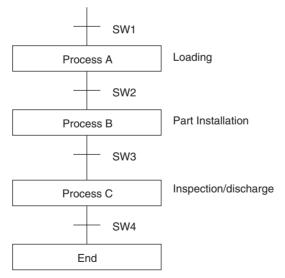
The following three examples demonstrate the three types of execution control possible with step programming. *Example 1* demonstrates sequential execution; *Example 2*, branching execution; and *Example 3*, parallel execution.

# Example 1: Sequential Execution

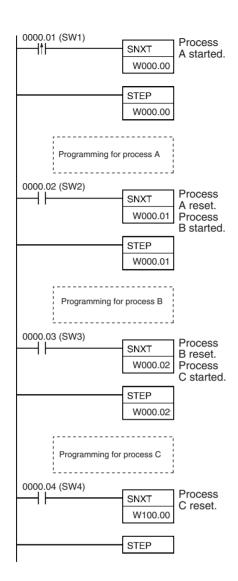
The following process requires that three processes, loading, part installation, and inspection/discharge, be executed in sequence with each process being reset before continuing on the next process. Various sensors (SW1, SW2, SW3, and SW4) are positioned to signal when processes are to start and end.

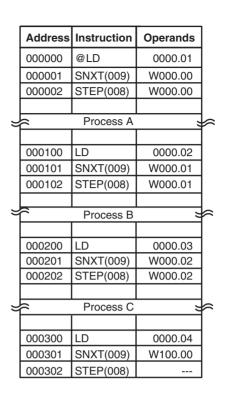


The following diagram demonstrates the flow of processing and the switches that are used for execution control.



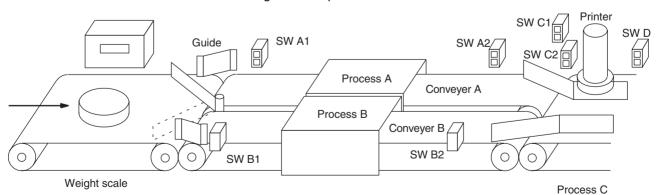
The program for this process, shown below, utilizes the most basic type of step programming: each step is completed by a unique SNXT(009) that starts the next step. Each step starts when the switch that indicates the previous step has been completed turns ON.



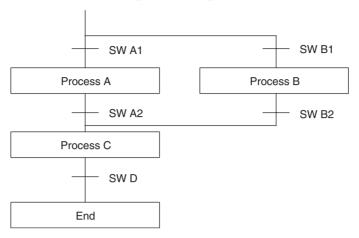


# Example 2: Branching Execution

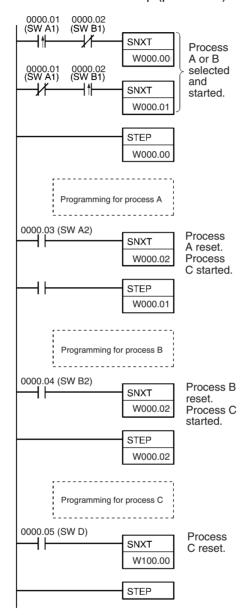
The following process requires that a product is processed in one of two ways, depending on its weight, before it is printed. The printing process is the same regardless of which of the first processes is used. Various sensors are positioned to signal when processes are to start and end.



The following diagram demonstrates the flow of processing and the switches that are used for execution control. Here, either process A or process B is used depending on the weight of the product.



The program for this process, shown below, starts with two SNXT(009) instructions that start processes A and B. Because of the way CIO 0000.01 (SW A1) and CIO 0000.02 (SW B1) are programmed, only one of these will be executed with an ON execution condition to start either process A or process B. Both of the steps for these processes end with a SNXT(009) that starts the step (process C).

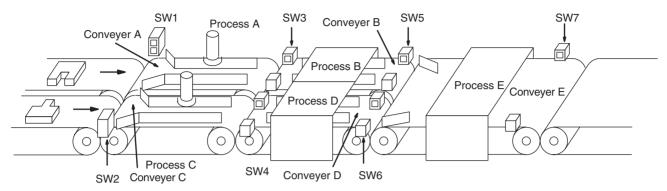


Address	Instruction	Operands
000000	@LD	0000.01
000001	AND NOT	0000.02
000002	SNXT(009)	W000.00
000003	LD NOT	0000.01
000004	@AND	0000.02
000005	SNXT(009)	W000.01
000006	STEP(008)	W000.00
斧	Process A	$\succeq$
000100	LD	0000.03
000101	SNXT(009)	W000.02
000102	STEP(008)	W000.01
		$\succeq$
	Process B	
		000001
000200	LD	0000.04
000201	SNXT(009)	W000.02
000202	STEP(008)	W000.02
<u> </u>		
	Process C	
000000	LD	0000.05
000300		0000.05
000301	SNXT(009)	W100.00
000302	STEP(008)	

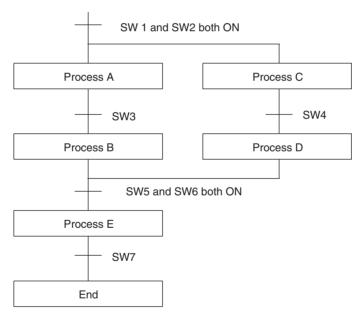
**Note** In the above programming, W000.02 is used in two SNXT(009) instructions. This will not produce a duplication error during the program check.

# Example 3: Parallel Execution

The following process requires that two parts of a product pass simultaneously through two processes each before they are joined together in a fifth process. Various sensors are positioned to signal when processes are to start and end.

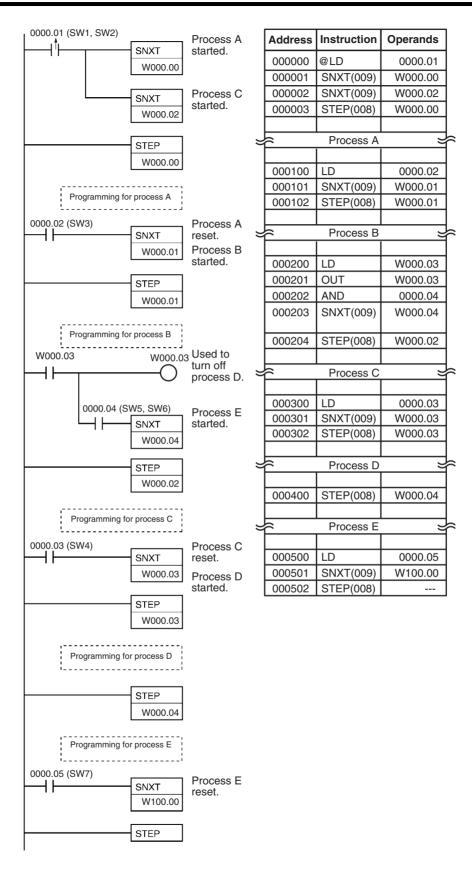


The following diagram demonstrates the flow of processing and the switches that are used for execution control. Here, process A and process C are started together. When process A finishes, process B starts; when process C finishes, process D starts. When both processes B and D have finished, process E starts.



The program for this operation, shown below, starts with two SNXT(009) instructions that start processes A and C. These instructions branch from the same instruction line and are always executed together, starting steps for both A and C. When the steps for both A and C have finished, the steps for process B and D begin immediately.

When both process B and process D have finished (i.e., when SW5 and SW6 turn ON), processes B and D are reset together by the SNXT(009) at the end of the programming for process B. Although there is no SNXT(009) at the end of process D, the control bit for it is turned OFF by executing SNXT(009) W000.04. This is because the OUT for bit W000.03 is in the step reset by SNXT(009) W000.04, i.e., W000.03 is turned OFF when SNXT(009) W000.04 is executed. Process B is thus reset directly and process D is reset indirectly before executing the step for process E.



# 3-22 I/O Refresh Instruction

This section describes the instruction used to refresh I/O.

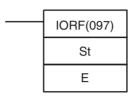
Instruction	Mnemonic	Function code	Page
I/O REFRESH	IORF	097	580

# 3-22-1 I/O REFRESH: IORF(097)

**Purpose** 

Refreshes the specified I/O words.

**Ladder Symbol** 



St: Starting word

E: End word

**Variations** 

Variations	Executed Each Cycle for ON Condition	IORF(097)
	Executed Once for Upward Differentiation	@IORF(097)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

**Operands** 

St: Starting Word

I/O Bit Area: CIO 2960 and CIO 2961

Basic I/O Unit I/O Bit Area: CIO 0000 to CIO 0019

E: End Word

I/O Bit Area: CIO 2960 and CIO 2961

Basic I/O Unit I/O Bit Area: CIO 0000 to CIO 0019

Note St and E must be in the same memory area.

# **Operand Specifications**

Area	St	E	
CIO Area	CIO 0000 to CIO 0019		
	CIO 2960 to CIO 2961		
Auxiliary Area			
Special Bit Area			
Timer Area			
Counter Area			
DM Area			
Indirect DM addresses in binary			
Indirect DM addresses in BCD			
Constants			
Index Registers			
Indirect addressing using	,IR0 to ,IR15		
Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to	o DR15, IR15	
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

# **Description**

IORF(097) refreshes the I/O words between St and E.

The following words can be refreshed: I/O Bit Area (CIO 2960 and CIO 2961) and Basic I/O Unit I/O Bit Area (CIO 0000 to CIO 0019).

Words allocated to Special I/O Units cannot be refreshed with IORF(097).

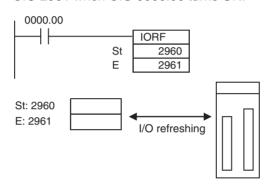
IORF(097) can be used in interrupt tasks to enable high-speed processing of the specified I/O words.

## **Flags**

Name	Label	Operation	
Error Flag	ER	ON if St is greater than E.	
		ON if St and E are in different memory areas.	
		OFF in all other cases.	

## **Examples**

The following example shows how to refresh the two words CIO 2960 and CIO 2961 when CIO 0000.00 turns ON.



# 3-23 Serial Communications Instructions

This section describes instructions used for serial communications.

Instruction	Mnemonic	Function code	Page
TRANSMIT	TXD	236	582
RECEIVE	RXD	235	587
CHANGE SERIAL PORT SETUP	STUP	237	592

# 3-23-1 Serial Communications

The TXD(236) and RXD(235) instructions send and receive data in no-protocol (custom) communications with an external device through a serial port on the Coordinator Module.

Instructions	Communications frames		Function
TXD(236) and RXD(235)	Any of the following can be No Start or End Code Data  Only Start Code  ST Data	Start and End Code ST Data ED  CR+LF End Code Data CR LF	Sends or receives data in one direction only. A send delay can be set.
	Only End Code Data ED	Start and CR+LF End Code ST Data CR LF	

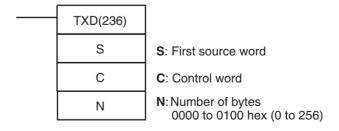
Instructions	Mode	Communications ports
TXD(236) and RXD(235)	No-protocol (custom)	Serial port in FQM1-CM002 FQM1-CM002 TXD(236)/ RXD(235) TXD(236)

# 3-23-2 TRANSMIT: TXD(236)

## **Purpose**

Outputs the specified number of bytes of data from the RS-232C port or RS-422A port on the Coordinator Module.

# **Ladder Symbol**



### **Variations**

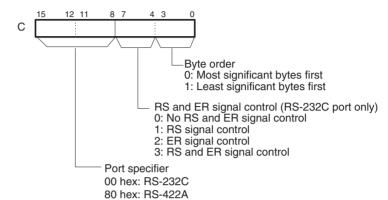
Variations	Executed Each Cycle for ON Condition	TXD(236)
	Executed Once for Upward Differentiation	@TXD(236)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

The contents of the control word, C, is as shown below.



## **Operand Specifications**

Area	S	С	N	
CIO Area	CIO 0000 to CIO 6143			
Work Area	W000 to W255			
Auxiliary Bit Area	A000 to A959	A000 to A959		
Timer Area	T0000 to T0255			
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767			
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants		Specified values only	#0000 to #0100 (binary)	
Data Resisters		DR0 to DR15		
Index Registers				
Indirect addressing	,IR0 to ,IR15			
using Index Registers	–2048 to +2047 ,IR0 to –2048 to +2047 ,IR15			
	DR0 to DR15, IR0 to DR0 to DR15, IR15			
	,IR0+(++) to ,IR15+(++)			
	,-()IR0 to , -(	-)IR15		

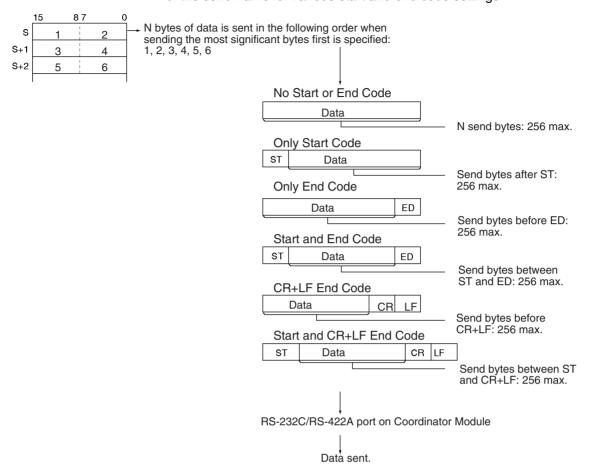
## **Description**

TXD(236) reads N bytes of data from words beginning with S and outputs the raw data in no-protocol mode from the RS-232C port or RS-422A port. (The output port is specified with bits 8 to 15 of C.)

The start and end codes specified for no-protocol mode are added to the data before the data is output. The start and end codes are specified in the System Setup.

Data can be sent only when the port's Send Ready Flag is ON. The Send Ready Flags are A392.05 and A318.09.

The following diagram shows the order in which data is sent and the contents of the send frame for various start and end code settings.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the no-protocol mode is not set in the System Setup.
		ON if the value of C is not within range.
		ON if the value for N is not between 0000 and 0100 hex.
		ON if a send is attempted when the Send Ready Flag (A392.05/A318.09) is OFF.
		OFF in all other cases.

## **Precautions**

TXD(236) can be used only for the Coordinator Modules's RS-232C port or RS-422A port. In addition, the port must be set to no-protocol mode in the System Setup.

The following send-message frame format can be set in the System Setup.

- Start code: None or 00 to FF hex.
- End code: None, CR+LF, or 00 to FF hex.

The data will be sent with any start and/or end codes specified in the System Setup. If start and end codes are specified, the codes will be added to the send data (N). Even in this case, the maximum number of bytes that can be specified for N is 256 bytes.

Data can be sent only when the port's Send Ready Flag (A392.05/A318.09) is  $\overline{\text{ON}}$ 

Data is sent in the order specified in C.

Nothing will be sent if 0 is specified for N.

If RS signal control is specified in C, bit 15 of S will be used as the RS signal.

If ER signal control is specified in C, bit 15 of S will be used as the ER signal.

If RS and ER signal control is specified in C, bit 15 of S will be used as the RS signal and bit 14 of S will be used as the ER signal.

If 1, 2, or 3 hex is specified for RS and ER signal control in C, TXD(236) will be executed regardless of the status of the Send Ready Flag (A392.05).

An error will occur and the Error Flag will turn ON in the following cases.

- If no-protocol mode is not set for the port in the System Setup
- If the value of C is not within range
- If the value for N is not between 0000 and 0100 hex
- If a send is attempted when the Send Ready Flag (A392.05/A318.09) is OFF.

**Note** The timing of sending data can be coordinated with the receiving device by setting a send delay.

## **Related Flags and Words**

The following System Setup settings and Auxiliary Area flag can be used as required when executing TXD(236).

#### System Setup Settings

Name	Description	Settings
No-protocol Mode Start Code	Specifies whether to use a start code in the frame format for no-protocol communications.	0: None (default) 1: Use start code (00 to FF hex)
No-protocol Mode End Code	Specifies whether to use an end code in the frame format for no-protocol communications.	0: None (default) 1: Use end code (00 to FF hex or CF+LF)
No-protocol Mode Send Delay	Specifies whether to delay sending data after execution of the instruction until sending the data from the port.	0 to 99,990 ms decimal (in 10-ms units) Default: 0 ms

### **Auxiliary Area**

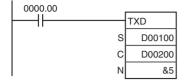
Send Ready Flags

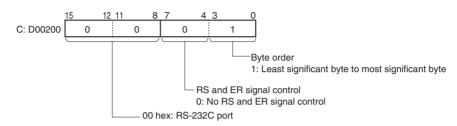
Name	Address	Contents
RS-232C Port Send Ready Flag		ON when data can be sent in
RS-422A Port Send Ready Flag	A318.09	the no-protocol mode.

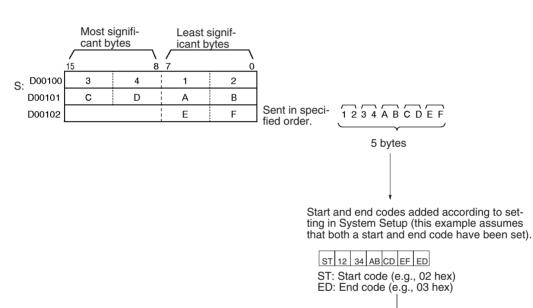
# **Example: Sending Data**

When CIO 0000.00 and the RS-232C port Send Ready Flag (A410.09) are ON in the following example, 5 bytes of data are sent from the RS-232C port on the Coordinator Module.

Sent

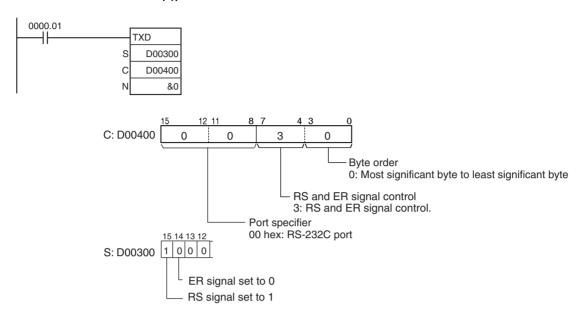






# **Example: Performing Signal Control**

When CIO 0000.01 and the RS-232C port Send Ready Flag (A410.09) are ON in the following example, the RS signal is set according to the status of D00300 bit 15 and the ER signal is set according to the status of D00300 bit 14.

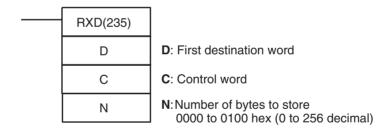


# 3-23-3 RECEIVE: RXD(235)

### **Purpose**

Reads the specified number of bytes of data from the RS-232C port or RS-422A port on the Coordinator Module.

## **Ladder Symbol**



#### **Variations**

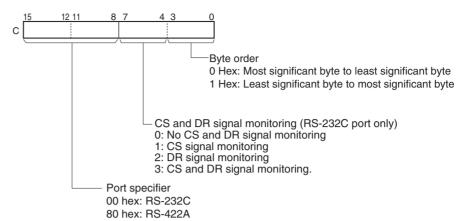
Variations	Executed Each Cycle for ON Condition	RXD(235)
	<b>Executed Once for Upward Differentiation</b>	@RXD(235)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

# **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

The contents of the control word, C, is as shown below.



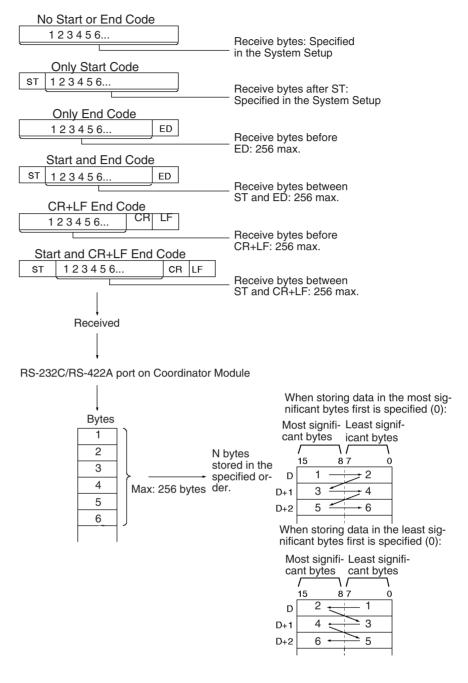
## **Operand Specifications**

Area	D	С	N
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255		
Auxiliary Bit Area	A448 to A959 A000 to A959		
Timer Area	T0000 to T0255		
Counter Area	C0000 to C0255		
DM Area	D00000 to D32767		
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants		Specified values only	#0000 to #0100 (binary)
Data Resisters		DR0 to DR15	
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

RXD(235) reads data that has been received in no-protocol mode at the RS-232C port or RS-422A port on the Coordinator Module (the port is specified with bits 8 to 15 of C) and stores N bytes of data in words beginning from D. If N bytes of data has not been received at the port, then only the data that has been received will be stored.

The following diagram shows the order in which data is received and the contents of the receive frame for various settings.



#### **Flags**

Name	Label	Operation
Error Flag	ER	ON if the no-protocol mode is not set in the System Setup.
		ON if the value of C is not within range.
		ON if the value for N is not between 0000 and 0100 hex.
		OFF in all other cases.

# **Precautions**

RXD(235) can be used only for the RS-232C port or RS-422A port on the Coordinator Module. In addition, the port must be set to no-protocol mode.

The following receive message frame format can be set in the System Setup.

- Start code: None or 00 to FF hex
- End code: None, CR+LF, or 00 to FF hex. If no end code is specified, the number of bytes to receive is set from 00 to FF hex (1 to 256 decimal; 00 specifies 256 bytes).

If the number of bytes is specified in the System Setup, the Reception Completed Flag (A392.06/A318.10) will turn ON when the specified number of bytes has been received. When the Reception Completed Flag turns ON, the number of bytes in the Reception Counter (A393/A319) will have the same value as the number of receive bytes specified in the System Setup. If more bytes are received than specified, the Reception Overflow Flag (A392.07/A318.11) will turn ON.

If an end code is specified in the System Setup, the Reception Completed Flag (A392.06/A318.10) will turn ON when the end code is received or when 256 bytes of data have been received. If more data is received after the Reception Completed Flag (A392.06/A318.10) turns ON, the Reception Overflow Flag (A392.07/A318.11) will turn ON.

When RXD(235) is executed, data is stored in memory starting at D. Once the data has been stored, the Reception Completed Flag (A392.06/A318.10) will turn ON (OFF if the Reception Overflow Flag (A392.07/A318.11) is ON) and the Reception Counter (A393/A319) will be cleared to 0.

If the RS-232C Port Restart Bit (A526.00) or the RS-422A Port Restart Bit (A526.07) is turned ON, the Reception Completed Flag (A392.06/A318.10) will be turned OFF (even if the Reception Overflow Flag is ON), and the Reception Counter (A393/A319) will be cleared to 0.

Data will be stored in memory in the order specified in C.

If 0 is specified for N, the Reception Completed Flag (A392.06/A318.10) and Reception Overflow Flag (A392.07/A318.11) will be turned OFF, the Reception Counter (A393/A319) will be cleared to 0, and nothing will be stored in memory.

If CS signal monitoring is specified in C, the status of the CS signal will be stored in bit 15 of D.

If DR signal monitoring is specified in C, the status of the DR signal will be stored in bit 15 of D.

If CS and DR signal monitoring is specified in C, the status of the CS signal will be stored in bit 15 of D and the status of the DR signal will be stored in bit 14 of D.

Receive data will not be stored if CS or DR signal monitoring is specified.

If 1, 2, or 3 hex is specified for CS and DR signal control in C, RXD(235) will be executed regardless of the status of the Reception Completed Flag (A392.06/A318.10).

An error will occur and the Error Flag will turn ON in the following cases.

- If no-protocol mode is not set for the port in the System Setup
- If the value of C is not within range
- If the value for N is not between 0000 and 0100 hex

**Note** Further data cannot be received if RXD(235) has not completed reading the current data. Always execute RXD(235) after receiving data and before data is received again.

# **Related Flags and Words**

The following System Setup settings and Auxiliary Area flag can be used as required when executing RXD(235).

# **System Setup Settings**

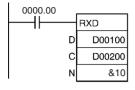
Name	Description	Settings	
No-protocol Mode Start Code	Specifies whether to use a start code in the frame format for no-protocol communications.	0: None (default) 1: Use start code (00 to FF hex)	
No-protocol Mode End Code	Specifies whether to use an end code in the frame format for no-protocol communications.	0: None (default) 1: Use end code (00 to FF hex or CF+LF)	
No-protocol Mode Number of bytes of Data	Specifies the number of bytes to receive when an end code is not used.	00 hex: 256 bytes 01 to FF hex: 1 to 255 bytes	

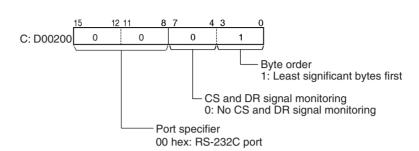
# **Auxiliary Area Flags**

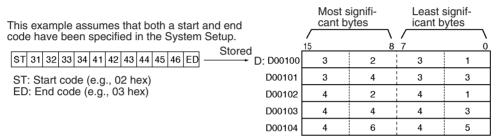
Name	Address	Contents
Reception Completed	A392.06	ON when no-protocol reception is completed.
Flag		Number of Receive Bytes Specified: The flag will turn ON when the specified number of bytes has been received.
		End Code Specified: The flag will turn ON when the end code is received or when 256 bytes have been received.
Reception Overflow Flag	A392.07	ON when more than the expected number of receive bytes has been received in no-protocol mode.
		Number of Receive Bytes Specified: The flag will turn ON when more data is received after reception was completed but before the received data is read from the buffer with RXD(235).
		End Code Specified: The flag will turn ON when more data is received after receiving an end code but before the received data is read from the buffer with RXD(235), or when 257 or more bytes of data are received without an end code.
Reception Counter	A393	Counts in hexadecimal the number of bytes received in no-protocol mode (0 to 256 decimal).
Reception Completed	A318.10	ON when no-protocol reception is completed.
Flag		Number of Receive Bytes Specified: The flag will turn ON when the specified number of bytes has been received.
		End Code Specified: The flag will turn ON when the end code is received or when 256 bytes have been received.
Reception Overflow Flag	A318.11	ON when more that the expected number of receive bytes has been received in no-protocol mode.
		Number of Receive Bytes Specified: The flag will turn ON when more data is received after reception was completed but before the received data was not read from the buffer with RXD(235).
		End Code Specified: The flag will turn ON when more data is received after receiving an end code but before the received data is read from the buffer with RXD(235), or when 257 or more bytes of data are received without an end code.
Reception Counter	A319	Counts in hexadecimal the number of bytes received in no-protocol mode (0 to 256 decimal).

## **Examples**

When CIO 0000.00 is ON in the following example, data is received from the RS-232C port and 10 bytes of data are stored starting in D00100.





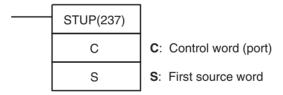


# 3-23-4 CHANGE SERIAL PORT SETUP: STUP(237)

### **Purpose**

Changes the communications parameters of a serial port on the FQM1-CM002 Coordinator Module. STUP(237) thus enables the protocol mode to be changed during FQM1 operation.

# **Ladder Symbol**



#### **Variations**

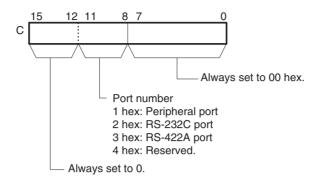
Variations	Executed Each Cycle for ON Condition	STUP(237)
	Executed Once for Upward Differentiation	@STUP(237)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

#### **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	Not allowed

## **Operands**

The contents of the control word, C, are as shown below.



## **Operand Specifications**

Area	С	S	
CIO Area	CIO 0000 to CIO 6143		
Work Area	W000 to W255	W000 to W246	
Auxiliary Bit Area	A000 to A959	A000 to A950	
Timer Area	T0000 to T0255	T0000 to T0246	
Counter Area	C0000 to C0255	C0000 to C0246	
DM Area	D00000 to D32767	D00000 to D32758	
Indirect DM addresses in binary	@ D00000 to @ D32767		
Indirect DM addresses in BCD	*D00000 to *D32767		
Constants	Specified values only	#0000	
Data Resisters	DR0 to DR15		
Index Registers			
Indirect addressing	,IR0 to ,IR15		
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15		
	DR0 to DR15, IR0 to DR0 to DR15, IR15		
	,IR0+(++) to ,IR15+(++)		
	,-()IR0 to , -()IR15		

## **Description**

STUP(237) writes 10 words of data from S to S+9 to the communications setup area of the specified port, as shown in the following table. When the constant #0000 is designated for S, the communications settings of the corresponding port will be set to the default settings.

Unit address	Module	Port No.	Serial port	Serial port communications setup area
00 hex	Coordinator Module	1 hex	Peripheral port	Communications parameters for the peripheral port in the System Setup
		2 hex	RS-232C port	Communications parameters for the RS-232C port in the System Setup
		3 hex	RS-422A port	Communications parameters for the RS-422A port in the System Setup

When STUP(237) is executed, the corresponding Port Settings Changing Flag (A619.01, A619.02, or A318.15) will turn ON. The flag will remain ON until changing the parameters has been completed.

Use STUP(237) to change communications parameter for a port during operation based on specified conditions. For example, STUP(237) can be used as follows:

The RS-422A port is set to Serial Gateway mode normally to send commands from a PT directly to a Servo Driver. When controlling the Servomotor by changing the parameters of the Servo Driver from the ladder program, the RS-422A port is switched to No-protocol mode.

The following communications parameters can be set:

Protocol mode, baud rate, data format, protocol macro transfer method, maximum length of protocol macro communications data, etc.

**Note** If the power to the FQM1 is cycled after the communications settings are changed with STUP(237), the original settings (i.e., the ones before STUP(237) was executed) will be used when the power turns ON.

## **Flags**

Name	Label	Operation
Error Flag	ER	ON if the values in C are not within range.
		ON if STUP(237) is executed for a port whose Communications Settings Changing Flag is already ON.
		ON if STUP(237) is executed in an interrupt task.
		OFF in all other cases.

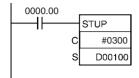
## **Related Flags and Words**

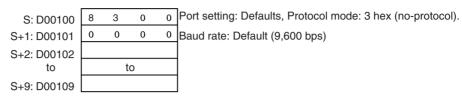
The following flags can be used as required when executing STUP(237). These flags are in the Auxiliary Area.

Name	Address	Contents
Peripheral Port Settings Changing Flag	A619.02	ON when the communications parameters are being changed for the peripheral port.
RS-232C Port Settings Changing Flag	A619.01	ON when the communications parameters are being changed for the RS-232C port.
RS-422A Port Settings Changing Flag	A318.15	ON when the communications parameters are being changed for the RS-422A port.

## **Examples**

When CIO 0000.00 turns ON in the following example, the communications parameters for the RS-422A port are changed to the settings contained in the 10 words from D00100 to D00109. In this example, the setting are changed from the Serial Gateway Mode to the No-protocol Mode.







RS-422A port parameter area

+360	8	3	0	0
+361	0	0	0	0
+362				
to		t	0	
+367				

## 3-24 Debugging Instructions

This section describes the instruction used to debug programs.

Instruction	Mnemonic	Function code	Page
TRACE MEMORY SAMPLING	TRSM	045	596

#### **Trace Memory Sampling: TRSM(045)** 3-24-1

**Purpose** 

When TRSM(045) is executed, the status of a preselected bit or word is sampled and stored in Trace Memory. TRSM(045) can be used anywhere in the program, any number of times.

**Ladder Symbol** 



**Variations** 

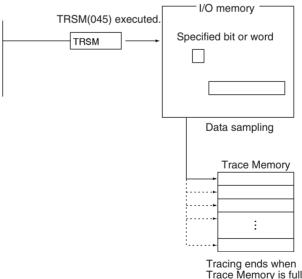
Variations	Executed Each Cycle	TRSM(045)
	Executed Once for Upward Differentiation	Not supported
	<b>Executed Once for Downward Differentiation</b>	Not supported

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Description**

Before TRSM(045) is executed, the bit or word to be traced must be specified with the CX-Programmer. Each time that TRSM(045) is executed, the current value of the specified bit or word is sampled and recorded in order in Trace Memory. The trace ends when the Trace Memory is full. The contents of Trace Memory can be monitored from the CX-Programmer when necessary.



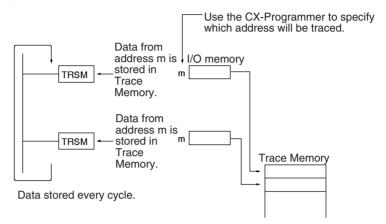
Trace Memory is full.

This instruction only indicates when the specified data will be sampled. All other settings and data trace operations are set with the CX-Programmer. The other two ways to control data sampling are sampling at the end of each cycle and sampling at a specified interval (independent of the cycle time).

TRSM(045) does not require an execution condition and is always executed as if it had an ON execution condition. Connect TRSM(045) directly to the left bus bar.

Use TRSM(045) to sample the value of the specified bit or word at the point in the program when the instruction's execution condition is ON. If the instruction's execution condition is ON every cycle, the specified bit or word's value will be stored in Trace Memory every cycle.

It is possible to incorporate two or more TRSM(045) instructions in a program. In this case, the value of the same specified bit or word will be stored in Trace Memory each time that one of the TRSM(045) instructions is executed.



**Note** Refer to the CX-Programmer Operation Manual (Cat. No. W437) for details on data tracing.

The data-tracing operations performed with the CX-Programmer are summarized in the following list.

- *1,2,3...* 1. Set the following parameters with the CX-Programmer.
  - a) Set the address of the bit or word to be traced.
  - Set the trigger condition. One of the three following conditions can control when data stored into Trace Memory is valid.
    - i) The Trace Start Bit goes from OFF to ON.
    - ii) A specified bit goes from OFF to ON.
    - iii) The value of a specified word matches the set value.
  - c) Set the sampling interval to "TRSM" for sampling at the execution of TRSM(045) in the program.
  - d) Set the delay.
  - When the Sampling Start Bit (A508.15) is turned from OFF to ON with the CX-Programmer, the specified data will begin being sampled each time that TRSM(045) is executed and the sampled data will be stored in Trace Memory. The Trace Busy Flag (A508.13) will be turned ON at the same time.
  - 3. When the trigger condition (Trace Start Bit ON, specified bit ON, or value of specified word matching set value) is met, the sampled data will be valid beginning with the next sample plus or minus the number of samples set with the delay setting. The Trace Trigger Monitor Flag (A508.11) will be turned ON at the same time.
  - 4. The trace will end when TRSM(045) has been executed enough times to fill the Trace Memory. When the trace ends, the Trace Completed Flag (A508.12) will be turned ON and the Trace Busy Flag (A508.13) will be turned OFF.
  - 5. Read the contents of Trace Memory with the CX-Programmer.

The following table shows relevant bits and flags in the Auxiliary Area. Only A508.14 and A508.15 are meant to be controlled by the user, and A508.15

must not be turned ON from the program, i.e., it must be turned ON only from the CX-Programmer.

Name	Address	Operation
Trace Trigger Monitor Flag	A508.11	This flag is turned ON when the trigger condition has been established with the Trace Start Bit. It is turned OFF when sampling is started for the next trace (by the Sampling Start Bit).
Trace Completed Flag	A508.12	This flag is turned ON when trace samples have filled the Trace Memory. It is turned OFF the next time that the Sampling Start Bit goes from OFF to ON.
Trace Busy Flag	A508.13	This flag is turned ON when the Sampling Start Bit goes from OFF to ON. It is turned OFF when the trace is completed.
Trace Start Bit	A508.14	The trace trigger conditions are established when this bit is turned from OFF to ON. The offset indicated by the delay value (positive or negative) determines which data samples are valid.
Sampling Start Bit	A508.15	When this bit is turned from OFF to ON from the CX-Programmer, data samples will start being stored in Trace Memory with one of the following three methods:
		Periodic sampling (10 to 2,550 ms intervals)     Sampling at TRSM(045) execution     Sampling at the end of each cycle
		This bit must be turned ON and OFF from the CX-Programmer.

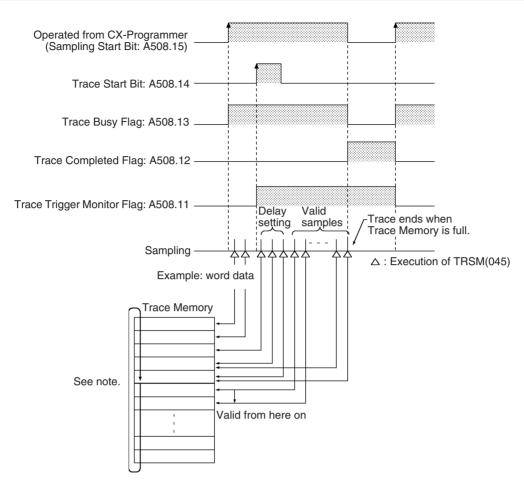
#### **Precautions**

TRSM(045) is processed as NOP(000) when data tracing is not being performed or when the sampling interval set in the parameters with the CX-Programmer is not set to sample on TRSM(045) instruction execution.

Do not turn the Sampling Start Bit (A508.15) ON or OFF from the program. This bit must be turned ON and OFF from the CX-Programmer.

## Example

The following example shows the overall data trace operation.



**Note** Trace Memory has a ring structure. Data is stored to the end of the Trace Memory area and then wraps to the beginning of the area, ending just before the first valid data sample.

## 3-25 Failure Diagnosis Instructions

This section describes instructions used to define and handle errors.

Instruction	Mnemonic	Function code	Page
FAILURE ALARM	FAL	006	600
SEVERE FAILURE ALARM	FALS	007	603

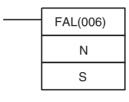
## 3-25-1 FAILURE ALARM: FAL(006)

**Purpose** 

Generates or clears user-defined non-fatal errors. Non-fatal errors do not stop FQM1 operation.

**Ladder Symbol** 

• Generating or Clearing User-defined Non-fatal Errors



N: FAL number

**S:** #0000 or

#0000 to #FFFF

**Variations** 

Variations	Executed Each Cycle for ON Condition	FAL(006)
	Executed Once for Upward Differentiation	@FAL(006)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

## Generating or Clearing User-defined Non-fatal Errors

The following table shows the function of the operands.

N	S	Function
0	#0001 to #01FF	Clears the non-fatal error with the corresponding FAL number.
	#FFFF	Clears all non-fatal errors.
	Other (See note.)	Clears the most serious non-fatal error.
1 to 511	Creating errors:	Generates a non-fatal error with the corre-
(These FAL num-	#0000	sponding FAL number.
bers are shared with FALS num- bers.)	Clearing errors: #0000 to #FFFF	

**Note** Other settings would be constants #0200 through #FFFE or a word address.

## **Operand Specifications**

Area	N	S
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A000 to A959
Timer Area		T0000 to T0255
Counter Area		C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ D32767

Area	N	S
Indirect DM addresses in BCD		*D00000 to *D32767
Constants	0 to 511	#0000 to #FFFF
		(binary)
Data Resisters		
Index Registers		
Indirect addressing		,IR0 to ,IR15
using Index Registers		-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
		DR0 to DR15, IR0 to DR0 to DR15, IR15
		,IR0+(++) to ,IR15+(++)
		,-()IR0 to , -()IR15

## **Description**

The operation of FAL(006) depends on the value of N. Set N to 0000 to clear an error and set N to 0001 to 01FF to generate an error.

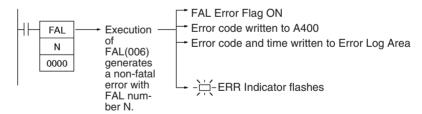
## **Generating Non-fatal User-defined Errors**

When FAL(006) is executed with N set to an FAL number (&1 to &511) that is not equal to the content of A400 (the system-generated FAL/FALS number), a non-fatal error will be generated with that FAL number and the following processing will be performed:

- 1. The FAL Error Flag (A402.15) will be turned ON. (FQM1 operation will continue.)
  - 2. The error code will be written to A400. Error codes 4101 to 42FF correspond to FAL numbers 0001 to 01FF (1 to 511).

**Note** If a fatal error or a more serious non-fatal error occurs at the same time as the FAL(006) instruction, the more serious error's error code will be written to A400.

- 3. The error code will be written to the Error Log Area (A100 through A199).
- 4. The ERR Indicator on the Modules will flash.



#### Clearing Non-fatal Errors without the CX-Programmer

When FAL(006) is executed with N set to 0, non-fatal errors can be cleared. The value of S will determine the processing, as shown in the following table.

S	Process
&1 to &511 (0001 to 01FF hex)	The FAL error of the specified number will be cleared.
FFFF hex	All non-fatal errors (including system errors) will be cleared.
0200 to FFFE hex or word specification	The most serious non-fatal error (even if it is a non-fatal system error) that has occurred will be cleared. When more than one FAL error has occurred, the FAL error with the smallest FAL number will be cleared.

## **Flags**

Name	Label	Operation
Error Flag		ON if N is not within the specified range of 0 to 511 decimal.  OFF in all other cases.

The following tables show relevant words and flags in the Auxiliary Area.

• Auxiliary Area Words/Flags for User-defined Errors

Name	Address	Operation
FAL Error Flag		ON when an error is generated with FAL(006).

• Auxiliary Area Words/Flags for both User-defined and System Errors

Name	Address	Operation
Error Log Area	A100 to A199	The Error Log Area contains the error codes for the most recent 20 errors, including errors generated by FAL(006).
Error code	A400	When an error occurs, its error code is stored in A400. The error codes for FAL numbers 0001 to 01FF are 4101 to 42FF, respectively.
		If two or more errors occur simultaneously, the error code of the most serious error will be stored in A400.

#### **Precautions**

# N must be between 0 and 511. An error will occur and the Error Flag will be turned ON if N is outside of the specified range.

## **Examples**

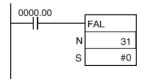
## Creating a User-defined Error

When CIO 0000.00 turns ON in the following example, a non-fatal error will be generated with FAL number 31 and the following processing will be performed:

- The FAL Error Flag (A402.15) will be turned ON. (FQM1 operation will continue.)
  - 2. The error code 411F will be written to A400. Error codes 4101 to 42FF correspond to FAL numbers 0001 to 01FF (1 to 511).

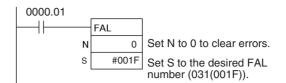
**Note** If a fatal error or a more serious non-fatal error occurs at the same time as or before the FAL(006) instruction, the more serious error's error code will be written to A400.

- 3. The error code will be written to the Error Log Area (A100 through A199).
- 4. The ERR Indicator on the Modules will flash.



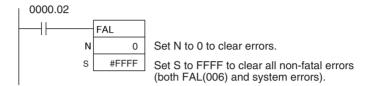
#### Clearing a Particular Non-fatal Error

When CIO 0000.01 is ON in the following example, FAL(006) will clear the non-fatal error with FAL number 31, and turn OFF the FAL Error Flag (A402.15).



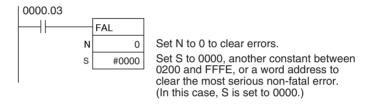
## **Clearing All Non-fatal Errors**

When CIO 0000.02 is ON in the following example, FAL(006) will clear all of the non-fatal errors, and turn OFF the FAL Error Flag (A402.15).



## **Clearing the Most Serious Non-fatal Error**

When CIO 0000.03 is ON in the following example, FAL(006) will clear the most serious non-fatal error that has occurred and reset the error code in A400. If the cleared error was originally generated by FAL(006), the FAL Error Flag (A402.15) will be turned OFF.

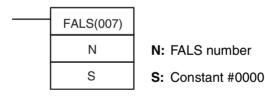


## 3-25-2 SEVERE FAILURE ALARM: FALS(007)

## **Purpose**

Generates user-defined fatal errors. Fatal errors stop FQM1 operation.

#### **Ladder Symbol**



## **Variations**

Variations	Executed Each Cycle for ON Condition	FALS(007)
	<b>Executed Once for Upward Differentiation</b>	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

The following table shows the function of the operands.

Operand	Function
N	1 to 511 (These FALS numbers are shared with FAL numbers.)
S	Specify #0000.

## **Operand Specifications**

Area	N	S
CIO Area		CIO 0000 to CIO 6143
Work Area		W000 to W255
Auxiliary Bit Area		A000 to A959
Timer Area		T0000 to T0255
Counter Area		C0000 to C0255
DM Area		D00000 to D32767
Indirect DM addresses in binary		@ D00000 to @ D32767
Indirect DM addresses in BCD		*D00000 to *D32767
Constants	1 to 511	#0000 to #FFFF
		(binary)
Index Registers		
Data Resisters		
Index Registers		
Indirect addressing		,IR0 to ,IR15
using Index Registers		-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
		DR0 to DR15, IR0 to DR0 to DR15, IR15
		,IR0+(++) to ,IR15+(++)
		,-()IR0 to , -()IR15

## **Description**

FALS(007) generates user-defined error.

- 1,2,3... 1. The FALS Error Flag (A401.06) will be turned ON. (FQM1 operation will stop.)
  - 2. The error code will be written to A400. Error codes C101 to C2FF correspond to FALS numbers 0001 to 01FF (1 to 511).

**Note** If an error more serious than the FALS(007) instruction (one with a higher error code) has occurred, A400 will contain the more serious error's error code.

- 3. The error code will be written to the Error Log Area (A100 through A199).
- 4. The ERR Indicators on the FQM1 Modules will be lit.

**Note** Input #1 to #511 for the FALS number on the CX-Programmer.

## Clearing FALS(007) User-defined Fatal Errors

To clear errors generated by FALS(007), first eliminate the cause of the error, and then either clear the error from the CX-Programmer or turn the FQM1 OFF and then ON again.

## **Flags**

Name	Label	Operation
Error Flag	ER	ON if N is not within the specified range 1 to 511.
		OFF in all other cases.

The following tables show relevant words and flags in the Auxiliary Area.

Auxiliary Area Words/Flags for User-defined Errors Only

Name	Address	Operation
FALS Error Flag	A401.06	ON when an error is generated with FALS(007).

• Auxiliary Area Words/Flags for both User-defined and System Errors

Name	Address	Operation
Error Log Area	A100 to A199	The Error Log Area contains the error codes for the most recent 20 errors, including errors generated by FALS(007).
Error code	A400	When an error occurs, its error code is stored in A400. The error codes for FALS numbers 0001 to 01FF (1 to 511 decimal) are C101 to C2FF, respectively.
		If two or more errors occur simultaneously, the error code of the most serious error will be stored in A400.

#### **Precautions**

N must be between 0001 and 01FF. An error will occur and the Error Flag will be turned ON if N is outside of the specified range.

## **Examples**

## Generating a User-defined Error

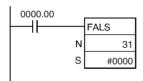
When CIO 0000.00 is ON in the following example, FALS(007) will generate a fatal error with FALS number 31 and execute the following processes.

1,2,3...

- 1. The FALS Error Flag (A401.06) will be turned ON.
- 2. The corresponding error code (C11F) will be written to A400.

**Note** A400 will contain the error code of the most serious of all of the errors that have occurred, including non-fatal and fatal system errors, as well as errors generated by FAL(006) and FAL(007).

- 3. The error code will be written to the Error Log Area (A100 through A199).
- 4. The ERR Indicators on the Modules will be lit.



Other Instructions Section 3-26

## 3-26 Other Instructions

This section describes instructions for manipulating the Carry Flag, selecting the EM bank, and extending the maximum cycle time.

Instruction	Mnemonic	Function code	Page
SET CARRY	STC	040	606
CLEAR CARRY	CLC	041	606

## 3-26-1 SET CARRY: STC(040)

Sets the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	STC(040)
	Executed Once for Upward Differentiation	@STC(040)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

#### **Description**

When the execution condition is ON, STC(040) turns ON the Carry Flag (CY). Although STC(040) turns the Carry Flag ON, the flag will be turned ON/OFF by the execution of subsequent instructions that affect the Carry Flag.

#### **Flags**

Name	Label	Operation
Error Flag	ER	Unchanged
Equals Flag	=	Unchanged
Carry Flag	CY	ON
Negative Flag	N	Unchanged

#### **Precautions**

ROL(027), ROLL(572), ROR(028), and RORL(573) make use of the Carry Flag in their rotation shift operations. When using any of these instructions, use STC(040) and CLC(041) to set and clear the Carry Flag.

## 3-26-2 CLEAR CARRY: CLC(041)

**Purpose** Turns OFF the Carry Flag (CY).

**Ladder Symbol** 



**Variations** 

Variations	Executed Each Cycle for ON Condition	CLC(041)
	<b>Executed Once for Upward Differentiation</b>	@CLC(041)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	ОК	OK

Other Instructions Section 3-26

## **Description**

When the execution condition is ON, CLC(041) turns OFF the Carry Flag (CY). Although CLC(041) turns the Carry Flag OFF, the flag will be turned ON/ OFF by the execution of subsequent instructions which affect the Carry Flag.

#### **Flags**

Name	Label	Operation
Error Flag	ER	Unchanged
Equals Flag	=	Unchanged
Carry Flag	CY	OFF
Negative Flag	N	Unchanged

#### **Precautions**

+C(402), +CL(403), +BC(406), and +BCL(407) make use of the Carry Flag in their addition operations. Use CLC(041) just before any of these instructions to prevent any influence from other preceding instructions.

-C(412), -CL(413), -BC(416), and -BCL(417) make use of the Carry Flag in their subtraction operations. Use CLC(041) just before any of these instructions to prevent any influence from other preceding instructions.

ROL(027), ROLL(572), ROR(028), and RORL(573) make use of the Carry Flag in their rotation shift operations. When using any of these instructions, use STC(040) and CLC(041) to set and clear the Carry Flag.

**Note** The +(400), +L(401), +B(404), +BL(405), -(410), -L(411), -B(414), and -BL(415) instructions do not include the Carry Flag in their addition and subtraction operations. In general, use these instructions when performing addition or subtraction.

## 3-27 Block Programming Instructions

This section describes block programs and the block programming instructions.

Instruction	Mnemonic	Function code	Page
BLOCK PROGRAM BEGIN	BPRG	096	611
BLOCK PROGRAM END	BEND	801	611
IF (NOT)	IF (NOT)	802	613
ELSE	ELSE	803	613
IF END	IEND	804	613

## 3-27-1 Introduction

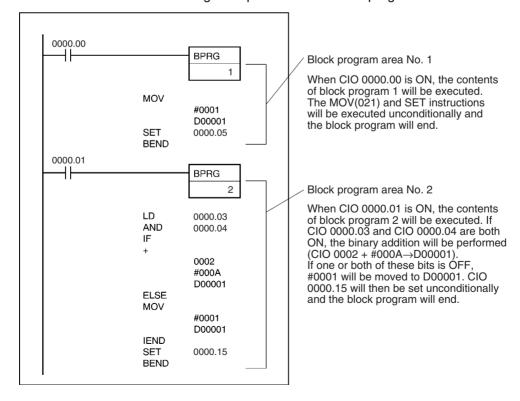
## **Block Programs**

Up to 128 block programs can be created within the overall user program (all tasks). The execution of each block program is controlled by a single execution condition. All instructions between BPRG(096) and BEND(801) are executed unconditionally when the execution condition for BPRG(096) is turned ON. The execution of all the block programming instructions except for BPRG(096) is not affected by the execution condition. This allows programming that is to be executed under a single execution condition to be grouped together in one block program.

Each block is started by one execution condition in the ladder diagram and all instructions within the block are written in mnemonic form. The block program is thus a combination of ladder and mnemonic instructions.

Block programs enable programming operations that can be difficult to program with ladder diagrams, such as conditional branches and step progressions.

The following example shows two block programs.



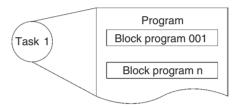
## **Tasks and Block Programs**

Block programs can be located within tasks. While tasks are used to divide large programming units, block programs can be used within tasks to further divide programming into smaller units controlled with a single ladder diagram execution condition.

Just like tasks, block programs that are not executed (i.e., which have an OFF input condition) do not require execution time and can thus be used to reduce the cycle time (somewhat the same as jumps). Also like tasks, other blocks can be paused or restarted from within a block program.

There are, however, differences between tasks and block programs. One difference is that input conditions are not used within block programs unless intentionally programmed with IF(802) instructions. Also, there are some instructions that cannot be used within block programs, such as those that detect upward and downward differentiation.

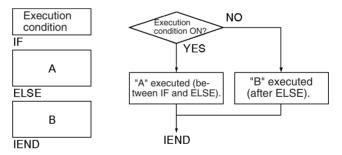
Block programs can be used either within cyclic tasks or interrupt tasks. Each block program number from 0 to 127 can be used only once and cannot be used again, even in a different task.



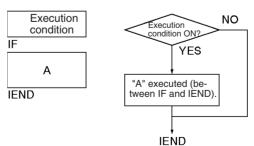
## **Using Block Programming Instructions**

Basically speaking, IF(802), ELSE(803), and IEND(810) are used for execution conditions (along with bits) inside block programs.

If "A" or "B" is to be executed, then IF A ELSE B IEND are used as shown below.



If "A" or nothing is to be executed, IF A IEND are used as shown below.



## <u>Instructions Taking Execution Conditions within Block Programs</u>

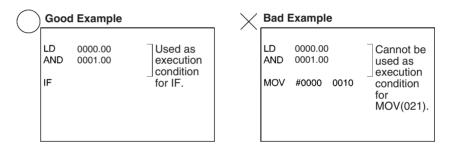
The following instruction can take execution conditions within a block program.

Instruction type	Instruction name	Mnemonic
Block programming instructions	IF (NOT)	IF (NOT)

## **Instructions with Application Restrictions within Block Programs**

The instructions listed in the following table can be used only to create execution conditions for IF(802) and cannot be used by themselves. The execution of these instructions may be unpredictable if used by themselves or in combination with any other instructions.

Mnemonic	Name
LD/LD NOT	LOAD/LOAD NOT
AND/AND NOT	AND/AND NOT
OR/OR NOT	OR/OR NOT
>, <, =, >=, <=, <> (S) (L)	Symbol Comparison Instruction (not right-hand instructions)



## **Instructions Not Applicable in Block Programs**

The instructions listed in the following table cannot be used within block programs.

Instruction group	Mnemonic	Name	Alternative
Sequence	OUT	OUTPUT	Use SET and RSET.
Output Instructions	OUT NOT	OUTPUT NOT	
Instructions	DIFU(013)	DIFFERENTIATE UP	None
	DIFD(014)	DIFFERENTIATE DOWN	None
	KEEP(011)	KEEP	None
Sequence Control	IL(002) and ILC(003)	INTERLOCK and INTER- LOCK CLEAR	Divide the block program into smaller blocks.
Instructions	END(001)	END	Use BEND(801).
Timer and	TIM	TIMER	None
Counter Instructions	TIMH(015)	HIGH-SPEED TIMER	
Instructions	TMHH(540)	ONE-MS TIMER	
	CNT	COUNTER	
	CNTR(012)	REVERSIBLE COUNTER	
Subroutine Instructions	SBN(092) and RET(093)	SUBROUTINE ENTRY and SUBROUTINE RETURN	None
Shift Instructions	SFT(010)	SHIFT REGISTER	Use other Shift Instructions.

Instruction group	Mnemonic	Name	Alternative
Downward	Mnemonics with @	Upward Differentiated Instructions	None
Differenti- ated Instruc- tions	Mnemonics with %	Downward Differentiated Instructions	None

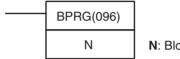
**Note** JMP(004) and JME(005) can be used. JMP(004) does not take any execution condition and jumps to JME(005) unconditionally.

## 3-27-2 BLOCK PROGRAM BEGIN/END: BPRG(096)/BEND(801)

**Purpose** Define a block programming area. For every BPRG(096), there must be a cor-

responding BEND(801).

Ladder Symbols BLOCK PROGRAM BEGIN



N: Block program number

## **BLOCK PROGRAM END**

BEND(801)

Variations BPRG(096)

Variations	Executed Each Cycle for ON Condition BPRG(096)	
	Executed Once for Upward Differentiation	Not supported.
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **BEND(801)**

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
(See note.)	OK	OK	OK

**Note** BPRG(096) is allowed only once at the beginning of each block program.

Operands N: Block Program Number

The block program number must be between 0 and 127 decimal.

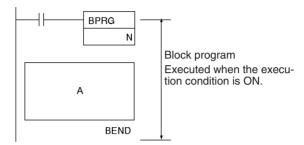
Operand Specifications (BPRG(096))

Area	N
CIO Area	
Work Area	
Auxiliary Bit Area	
Timer Area	
Counter Area	
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	0 to 127 (decimal)

Area	N
Index Registers	
Indirect addressing using Index Registers	

#### **Description**

BPRG(096) executes the block program with the block number designated in N, i.e., the one immediately after it and ending with BEND(801). All instructions between BPRG(096) and BEND(801) are executed with ON execution conditions (i.e., unconditionally).



When the execution condition for BPRG(096) is OFF, the block program will not be executed and no execution time will be required for the instructions in the block program.

## **Flags**

## **BPRG(096)**

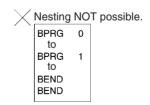
Name	Label	Operation
Error Flag	ER	ON if BPRG(096) is already being executed.
		ON if N is not between 0 and 127 (BCD).
		ON if the same block program number is used more than
		once.
		OFF in all other cases.

## **BEND(801)**

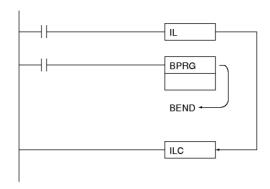
Name	Label	Operation
Error Flag	ER	ON if a block program is not being executed.
		OFF in all other cases.

#### **Precautions**

Each block program number can be used only once within the entire user program. Block programs cannot be nested.



If the block program is in an interlocked program section and the execution condition for IL(002) is OFF, the block program will not be executed.

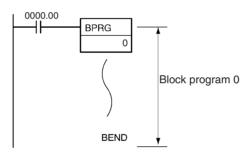


BPRG(096) and the corresponding BEND(801) must be in the same task.

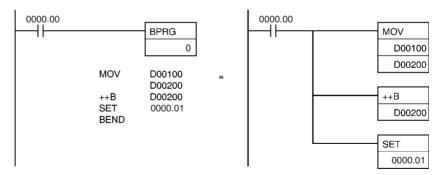
An error will occur and the Error Flag will turn ON if BPRG(096) is in the middle of a block program, BEND(801) is not in a block program, N is not between #0000 and #007F (binary), there is no block program, or if the same block program number is used more than once.

## **Examples**

When CIO 0000.00 turns ON in the following example, block program 0 will be executed. When CIO 0000.00 is OFF, the block program will not be executed.



The two program sections shown below both execute MOV(021), ++B(594), and SET for the same execution condition (i.e., when CIO 0000.00 turns ON).



## 3-27-3 Branching: IF (NOT)(802), ELSE(803), and IEND(804)

## **Purpose**

Branches the block program either based on an execution condition or on the status of an operand bit.

## **Ladder Symbol**

IF(802) B **B**: Bit operand IF(802)
IF(802) NOT B
ELSE(803)
IEND(804)

#### **Variations**

Variations	Always Executed in Block Program
variations	Always Executed III Block Flogram

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

**Note** IF(802), ELSE(803), and IEND(804) can be used in block programming regions within subroutines and interrupt tasks.

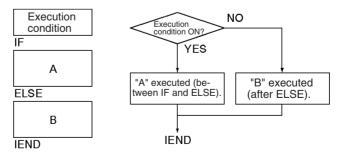
## **Operand Specifications**

Area	В
CIO Area	CIO 0000.00 to CIO 6143.15
Work Area	W000.00 to W255.15
Auxiliary Bit Area	A00000 to A959.15
Timer Area	T0000 to T0255
Counter Area	C0000 to C0255
Task Flags	TK0000
Condition Flags	ER, CY, >, =, <, N, OF, UF, >=, <>, <=, ON, OFF, AER
Clock Pulses	0.02 s, 0.1 s, 0.2 s, 1 s, 1 min
DM Area	
Indirect DM addresses in binary	
Indirect DM addresses in BCD	
Constants	
Data Resisters	
Index Registers	
Indirect addressing	,IR0 to ,IR15
using Index Registers	-2048 to +2047 ,IR0 to -2048 to +2047 ,IR15
	DR0 to DR15, IR0 to DR0 to DR15, IR15
	,IR0+(++) to ,IR15+(++)
	,-()IR0 to , -()IR15

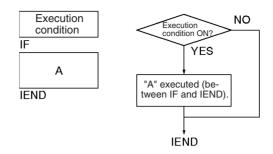
## **Description**

## Operation without an Operand for IF(802)

If an operand bit is not specified, an execution condition must be created before IF(802) starting with LD. If the execution condition is ON, the instructions between IF(802) and ELSE(803) will be executed and if the execution condition is OFF, the instructions between ELSE(803) and IEND(804) will be executed.

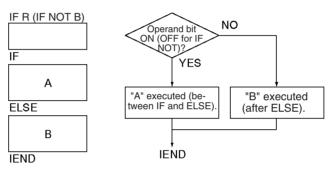


If the ELSE(803) instruction is omitted and the execution condition is ON, the instructions between IF(802) and IEND(804) will be executed and if the execution condition is OFF, only the instructions after IEND(804) will be executed.

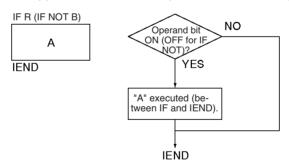


## Operation with an Operand for IF(802) or IF NOT(802)

An operand bit, B, can be specified for IF(802) or IF NOT(802). If the operand bit is ON, the instructions between IF(802) and ELSE(803) will be executed. If the operand bit is OFF, the instructions between ELSE(803) and IEND(804) will be executed. For IF NOT(802), the instructions between IF(802) and ELSE(803) will be executed if the operand bit is OFF, and the instructions between ELSE(803) and IEND(804) will be executed if the operand bit is ON.



If the ELSE(803) instruction is omitted and the operand bit is ON, the instructions between IF(802) and IEND(804) will be executed and if the operand bit is OFF, only the instructions after IEND(804) will be executed. The same will happen for the opposite status of the operand bit if IF NOT(802) is used.



#### **Flags**

Name	Label	Operation	
Error Flag	ER	ON if the branch instructions are not in a block program.	
		ON if more than 253 branches are nested.	
		OFF in all other cases.	

#### **Precautions**

Instructions in block programs are generally executed unconditionally. Branching, however, can be used to create conditional execution based on execution conditions or operand bits.

Use IF A ELSE B IEND to branch between A and B.

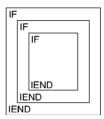
Use IF A IEND to branch between A and doing nothing.

Branches can be nested to up to 253 levels.

A error will occur and the Error Flag will turn ON if the branch instructions are not in a block program or if more than 253 branches are nested.

## **Nesting Branches**

Up to 253 branches can be nested within the top level branch.

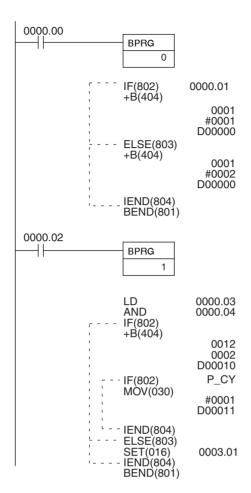


## **Examples**

The following example shows two different block programs controlled by CIO 0000.00 and CIO 0000.02.

The first block executes one of two additions depending on the status of CIO 0000.01. This block is executed when CIO 0000.00 is ON. If CIO 0000.01 is ON, 0001 is added to the contents of CIO 0001. If CIO 0000.01 is OFF, 0002 is added to the contents of CIO 0001. In either case, the result is placed in D00000.

The second block is executed when CIO 0000.02 is ON and shows nesting two levels. If CIO 0000.03 and CIO 0000.04 are both ON, the contents of CIO 0012 and CIO 0002 are added and the result is placed in D00010 and then 0001 is moved into D00011 based on the status of CY. If either CIO 0000.03 or CIO 0000.04 is OFF, then the entire addition operation is skipped and CIO 0003.01 is turned ON.



Address	Instruction	Operands
000000	LD	0000.00
000001	BPRG(096)	0
000002	IF(802)	0000.01
000003	+B(404)	
		0001
		#0001
		D00000
000004	ELSE(803)	
000005	+B(404)	
		0001
		#0002
		D00000
000006	IEND(804)	
000007	BEND(801)	
800000	LD	0000.02
000009	BPRG(096)	1
000010	LD	0000.03
000011	AND	0000.04
000012	IF(802)	
000013	+B(404)	
		0012
		0002
		D00010
000014	IF(802)	CY
000015	MOV(030)	
		#0001
		D00011
000016	IEND(804)	
000017	ELSE(803)	
000018	SET(016)	0003.01
000019	IEND(804)	
000020	BEND(801)	

## 3-28 Function Block Instructions

This section describes the instructions used with function blocks.

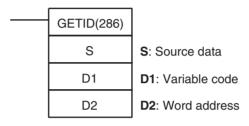
Instruction	Mnemonic	Function code	Page
GET VARIABLE ID	GETID	286	618

## 3-28-1 GET VARIABLE ID: GETID(286)

## **Purpose**

Outputs the FINS command variable type (data area) code and word address for the specified variable or address. This instruction is generally used to get the assigned address of a variable in a function block.

## **Ladder Symbol**



#### **Variations**

Variations	Executed Each Cycle for ON Condition	GETID(286)
	<b>Executed Once for Upward Differentiation</b>	@GETID(286)
	<b>Executed Once for Downward Differentiation</b>	Not supported.

## **Applicable Program Areas**

Block program areas	Step program areas	Subroutines	Interrupt tasks
OK	OK	OK	OK

## **Operands**

#### S: Source data

Specifies the variable or address for which the variable type and word address will be retrieved.

#### D1: Variable code

Contains the FINS variable type code (data area code) of the source data.

## D2: Word address

Contains the word address of the source data in 4-digit hexadecimal.

## **Operand Specifications**

Area	S	D1	D2	
CIO Area	CIO 0000 to CIO 6	143	<del>!</del>	
Work Area	W000 to W255			
Auxiliary Bit Area		A000 to A959		
Timer Area		T0000 to T0255		
Counter Area	C0000 to C0255			
DM Area	D00000 to D32767			
Indirect DM addresses in binary	@ D00000 to @ D32767			
Indirect DM addresses in BCD	*D00000 to *D32767			
Constants				
Data Registers	DR0 to DR15			

Area	S	D1	D2		
Index Registers					
Indirect addressing	,IR0 to ,IR15				
using Index Registers	-2048 to +2047 ,IR	048 to +2047 ,IR0 to -2048 to +2047 ,IR15			
DR0 to DR15, IR0 to DR0 to DR15, IR15 ,IR0+(++) to ,IR15+(++)					

## **Description**

GETID(286) retrieves the data area address of the specified source variable or address, outputs the data area code to D1 in 4-digit hexadecimal, and outputs the word address number to D2 in 4-digit hexadecimal.

The following table shows the variable type (data area) codes and corresponding address ranges for the PLC's data areas.

Data area		Data Data area code size (Output to D1.)		Address (Output to D2.)	
CIO Area	CIO	Word	00B0 hex	0000 to 17FF hex (0000 to 6,143 decimal)	
Work Area	W		00B1 hex	0000 to 00FF hex (000 to 255 decimal)	
DM Area	D		0082 hex	0000 to 7FFF hex (0000 to 32,767 decimal)	

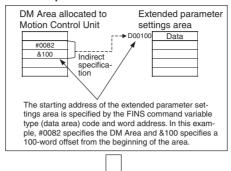
Variables in function blocks are automatically allocated addresses by the CX-Programmer unless the AT specification is used. For example, if it is necessary to indirectly specify the extended parameter settings of a Special Unit such as a Motion Control Unit and a variable is used at the beginning of the extended parameter settings area, that variable's address must be set. In this case, GETID(286) can be used to retrieve the variable's data area address.

## **Flags**

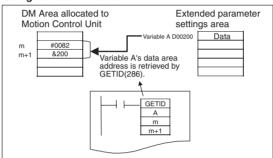
Name	Label	Operation
Error Flag	ER	ON if S is not within the allowed range.

## **Example**

#### **Normal Operation**



## **Using Function Blocks**



# **SECTION 4 Instruction Execution Times and Number of Steps**

This section provides instruction execution times and the number of steps for each FQM1 instruction.

4-1	FQM1 l	Instruction Execution Times and Number of Steps	622
	4-1-1	Sequence Input Instructions	622
	4-1-2	Sequence Output Instructions	623
	4-1-3	Sequence Control Instructions	623
	4-1-4	Timer and Counter Instructions	624
	4-1-5	Comparison Instructions	624
	4-1-6	Data Movement Instructions.	625
	4-1-7	Data Shift Instructions	626
	4-1-8	Increment/Decrement Instructions	627
	4-1-9	Symbol Math Instructions	628
	4-1-10	Conversion Instructions	629
	4-1-11	Logic Instructions	629
	4-1-12	Special Math Instructions	630
	4-1-13	Floating-point Math Instructions	630
	4-1-14	Double-precision Floating-point Instructions	631
	4-1-15	Table Data Processing Instructions	632
	4-1-16	Data Control Instructions	633
	4-1-17	Subroutine Instructions	633
	4-1-18	Interrupt Control Instructions	633
	4-1-19	High-speed Counter and Pulse Output Instructions (Only for Motion Control Modules)	634
	4-1-20	Step Instructions	635
	4-1-21	I/O Refresh Instructions	635
	4-1-22	Serial Communications Instructions	636
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## 4-1 FQM1 Instruction Execution Times and Number of Steps

The following table lists the execution times for all instructions that are available for the FQM1.

The total execution time of instructions within one whole user program is the process time for program execution when calculating the cycle time. (See note.)

**Note** User programs are allocated tasks that can be executed within cyclic tasks and interrupt tasks that satisfy interrupt conditions.

Execution times for most instructions differ depending on the conditions when the instruction is executed. The top line for each instruction in the following table shows the minimum time required to process the instruction and the necessary execution conditions, and the bottom line shows the maximum time and execution conditions required to process the instruction.

The execution time can also vary when the execution condition is OFF.

The following table also lists the length of each instruction in the *Length* (*steps*) column. The number of steps required in the user program area for each of the instructions varies from 1 to 7 steps, depending upon the instruction and the operands used with it. The number of steps in a program is not the same as the number of instructions.

Note

1. Program capacity for the FQM1 is measured in steps. Basically speaking, 1 step is equivalent to 1 word.

Most instructions are supported in differentiated form (indicated with  $\uparrow$ ,  $\downarrow$ , @, and %). Specifying differentiation will increase the execution times by the following amounts.

Symbol	μ <b>s</b>
↑ or ↓	+0.5
@ or %	+0.5

2. Use the following time as a guideline when instructions are not executed. Approx. 0.2 to 0.5  $\mu s$ 

## 4-1-1 Sequence Input Instructions

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
LOAD	LD		1	0.10	Yes	
LOAD NOT	LD NOT		1	0.10	Yes	
AND	AND		1	0.10	Yes	
AND NOT	AND NOT		1	0.10	Yes	
OR	OR		1	0.10	Yes	
OR NOT	OR NOT		1	0.10	Yes	
AND LOAD	AND LD		1	0.05	Yes	
OR LOAD	OR LD		1	0.05	Yes	
NOT	NOT	520	1	0.05	Yes	
CONDITION ON	UP	521	3	0.50	Yes	
CONDITION OFF	DOWN	522	4	0.50	Yes	
LOAD BIT TEST	LD TST	350	4	0.35	Yes	
LOAD BIT TEST	LD TSTN	351	4	0.35	Yes	

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
AND BIT TEST	AND TST	350	4	0.35	Yes	
AND BIT TEST	AND TSTN	351	4	0.35	Yes	
OR BIT TEST	OR TST	350	4	0.35	Yes	
OR BIT TEST	OR TSTN	351	4	0.35	Yes	

## 4-1-2 Sequence Output Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
OUTPUT	OUT		1	0.35	Yes	
OUTPUT NOT	OUT NOT		1	0.35	Yes	
KEEP	KEEP	011	1	0.40	Yes	
DIFFERENTIATE UP	DIFU	013	2	0.50	Yes	
DIFFERENTIATE DOWN	DIFD	014	2	0.50	Yes	
SET	SET		1	0.30	Yes	
RESET	RSET		1	0.30	Yes	
MULTIPLE BIT SET	SETA	530	4	11.8		Setting 1 bit
				64.1		Setting 1,000 bits
MULTIPLE BIT	RSTA	531	4	11.8		Resetting 1 bit
RESET				64.0		Resetting 1,000 bits
SINGLE BIT RESET	RSTB	533	2	0.50	Yes	
SINGLE BIT OUT- PUT	OUTB	534	2	0.50	Yes	

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

## 4-1-3 Sequence Control Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
END	END	001	1	7.0	Yes	
NO OPERATION	NOP	000	1	0.05	Yes	
INTERLOCK	IL	002	1	0.15	Yes	
INTERLOCK CLEAR	ILC	003	1	0.15	Yes	
JUMP	JMP	004	2	0.95	Yes	
JUMP END	JME	005	2			
CONDITIONAL JUMP	CJP	510	2	0.95	Yes	When jump condition is met

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
CONDITIONAL JUMP	CJPN	511	2	0.95	Yes	When jump condition is met
MULTIPLE JUMP	JMP0	515	1	0.15	Yes	
MULTIPLE JUMP END	JME0	516	1	0.15	Yes	
FOR-NEXT LOOPS	FOR	512	2	1.00	Yes	Specification with a constant
FOR-NEXT LOOPS	NEXT	513	1	0.45	Yes	When repeating a loop
				0.55	Yes	When ending loop repetition
BREAK LOOP	BREAK	514	1	0.15	Yes	

## 4-1-4 Timer and Counter Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
TIMER	TIM		3	1.30	Yes	
COUNTER	CNT		3	1.30	Yes	
HIGH-SPEED TIMER	TIMH	015	3	1.80	Yes	
ONE-MS TIMER	TMHH	540	3	1.75	Yes	
REVERSIBLE COUNTER	CNTR	012	3	24.8		

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

## 4-1-5 Comparison Instructions

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
Input Comparison	LD, AND, OR +=	300	4	0.35	Yes	
Instructions (unsigned)	LD, AND, OR + <>	305				
(unsigned)	LD, AND, OR + <	310				
	LD, AND, OR +<=	315				
	LD, AND, OR +>	320				
	LD, AND, OR +>=	325				
Input Comparison	LD, AND, OR +=+L	301	4	0.35	Yes	
Instructions (double, unsigned)	LD, AND, OR +<>+L	306				
	LD, AND, OR +<+L	311				
	LD, AND, OR +<=+L	316				
	LD, AND, OR +>+L	321				
	LD, AND, OR +>=+L	326				

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
Input Comparison	LD, AND, OR +=+S	302	4	0.35	Yes	
Instructions (signed)	LD, AND, OR +<>+S	307				
	LD, AND, OR +<+S	312				
	LD, AND, OR +<=+S	317				
	LD, AND, OR +>+S	322				
	LD, AND, OR +>=+S	327				
Input Comparison Instructions (double,	LD, AND, OR +=+SL	303	4	0.35	Yes	
signed)	LD, AND, OR +<>+SL	308				
	LD, AND, OR +<+SL	313				
	LD, AND, OR +<=+SL	318				
	LD, AND, OR +>+SL	323				
	LD, AND, OR +>=+SL	328				
COMPARE	CMP	020	3	0.10	Yes	
DOUBLE COMPARE	CMPL	060	3	0.50	Yes	
SIGNED BINARY COMPARE	CPS	114	3	0.30	Yes	
DOUBLE SIGNED BINARY COMPARE	CPSL	115	3	0.50	Yes	
TABLE COMPARE	TCMP	085	4	30.3		
MULTIPLE COM- PARE	MCMP	019	4	47.5		
UNSIGNED BLOCK COMPARE	ВСМР	068	4	50.3		
EXPANDED BLOCK COMPARE	BCMP2	502	4	15.3		Number of data words: 1
				689.1		Number of data words: 255
AREA RANGE COMPARE	ZCP	088	3	11.6		
DOUBLE AREA RANGE COMPARE	ZCPL	116	3	11.4		

## 4-1-6 Data Movement Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
MOVE	MOV	021	3	0.30	Yes	
DOUBLE MOVE	MOVL	498	3	0.60	Yes	
MOVE NOT	MVN	022	3	0.35	Yes	

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
DOUBLE MOVE NOT	MVNL	499	3	0.60	Yes	
MOVE BIT	MOVB	082	4	0.50	Yes	
MOVE DIGIT	MOVD	083	4	0.50	Yes	
BLOCK TRANSFER	XFER	070	4	0.8	Yes	Transferring 1 word
				650.2	Yes	Transferring 1,000 words
BLOCK SET	BSET	071	4	0.55	Yes	Setting 1 word
				400.2	Yes	Setting 1,000 words
DATA EXCHANGE	XCHG	073	3	0.80	Yes	
SINGLE WORD DISTRIBUTE	DIST	080	4	10.5		
DATA COLLECT	COLL	081	4	10.5		
MOVE TO REGIS- TER	MOVR	560	3	0.60	Yes	
MOVE TIMER/ COUNTER PV TO REGISTER	MOVRW	561	3	0.60		

## 4-1-7 Data Shift Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
SHIFT REGISTER	SFT	010	3	12.4		Shifting 1 word
				368.1		Shifting 1,000 words
REVERSIBLE	SFTR	084	4	14.0		Shifting 1 word
SHIFT REGISTER				1.44 ms		Shifting 1,000 words
ASYNCHRONOUS	ASFT	017	4	13.9		Shifting 1 word
SHIFT REGISTER				3.915 ms		Shifting 1,000 words
WORD SHIFT	WSFT	016	4	9.7		Shifting 1 word
				728.1		Shifting 1,000 words
ARITHMETIC SHIFT LEFT	ASL	025	2	0.45	Yes	
DOUBLE SHIFT LEFT	ASLL	570	2	0.80	Yes	
ARITHMETIC SHIFT RIGHT	ASR	026	2	0.45	Yes	
DOUBLE SHIFT RIGHT	ASRL	571	2	0.80	Yes	
ROTATE LEFT	ROL	027	2	0.45	Yes	
DOUBLE ROTATE LEFT	ROLL	572	2	0.80	Yes	
ROTATE LEFT WITHOUT CARRY	RLNC	574	2	0.45	Yes	
DOUBLE ROTATE LEFT WITHOUT CARRY	RLNL	576	2	0.80	Yes	
ROTATE RIGHT	ROR	028	2	0.45	Yes	

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
DOUBLE ROTATE RIGHT	RORL	573	2	0.80	Yes	
ROTATE RIGHT WITHOUT CARRY	RRNC	575	2	0.45	Yes	
DOUBLE ROTATE RIGHT WITHOUT CARRY	RRNL	577	2	0.80	Yes	
ONE DIGIT SHIFT	SLD	074	3	10.1		Shifting 1 word
LEFT				1.208 ms		Shifting 1,000 words
ONE DIGIT SHIFT	SRD	075	3	11.7		Shifting 1 word
RIGHT				1.775 ms		Shifting 1,000 words
SHIFT N-BITS LEFT	NASL	580	3	0.45	Yes	
DOUBLE SHIFT N-BITS LEFT	NSLL	582	3	0.80	Yes	
SHIFT N-BITS RIGHT	NASR	581	3	0.45	Yes	
DOUBLE SHIFT N-BITS RIGHT	NSRL	583	3	0.80	Yes	

## 4-1-8 Increment/Decrement Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
INCREMENT BINARY	++	590	2	0.45	Yes	
DOUBLE INCRE- MENT BINARY	++L	591	2	0.80	Yes	
DECREMENT BINARY		592	2	0.45	Yes	
DOUBLE DECRE- MENT BINARY	L	593	2	0.80	Yes	
INCREMENT BCD	++B	594	2	12.1		
DOUBLE INCRE- MENT BCD	++BL	595	2	9.37		
DECREMENT BCD	B	596	2	11.5		
DOUBLE DECRE- MENT BCD	– –BL	597	2	9.3		

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

# 4-1-9 Symbol Math Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
SIGNED BINARY ADD WITHOUT CARRY	+	400	4	0.30	Yes	
DOUBLE SIGNED BINARY ADD WITH- OUT CARRY	+L	401	4	0.60	Yes	
SIGNED BINARY ADD WITH CARRY	+C	402	4	0.40	Yes	
DOUBLE SIGNED BINARY ADD WITH CARRY	+CL	403	4	0.60	Yes	
BCD ADD WITH- OUT CARRY	+B	404	4	16.3		
DOUBLE BCD ADD WITHOUT CARRY	+BL	405	4	22.9		
BCD ADD WITH CARRY	+BC	406	4	17.2		
DOUBLE BCD ADD WITH CARRY	+BCL	407	4	24.1		
SIGNED BINARY SUBTRACT WITH- OUT CARRY	_	410	4	0.3	Yes	
DOUBLE SIGNED BINARY SUB- TRACT WITHOUT CARRY	-L	411	4	0.60	Yes	
SIGNED BINARY SUBTRACT WITH CARRY	-C	412	4	0.40	Yes	
DOUBLE SIGNED BINARY SUB- TRACT WITH CARRY	-CL	413	4	0.60	Yes	
BCD SUBTRACT WITHOUT CARRY	<b>–</b> В	414	4	16.3		
DOUBLE BCD SUB- TRACT WITHOUT CARRY	–BL	415	4	23.1		
BCD SUBTRACT WITH CARRY	–BC	416	4	18.1		
DOUBLE BCD SUB- TRACT WITH CARRY	-BCL	417	4	24.2		
SIGNED BINARY MULTIPLY	*	420	4	0.65	Yes	
DOUBLE SIGNED BINARY MULTIPLY	*L	421	4	12.8		
UNSIGNED BINARY MULTIPLY	*U	422	4	0.75	Yes	
DOUBLE UNSIGNED BINARY MULTIPLY	*UL	423	4	12.4		
BCD MULTIPLY	*B	424	4	16.9		

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
DOUBLE BCD MUL- TIPLY	*BL	425	4	34.7		
SIGNED BINARY DIVIDE	/	430	4	0.70	Yes	
DOUBLE SIGNED BINARY DIVIDE	/L	431	4	11.9		
UNSIGNED BINARY DIVIDE	/U	432	4	0.8	Yes	
DOUBLE UNSIGNED BINARY DIVIDE	/UL	433	4	11.9		
BCD DIVIDE	/B	434	4	18.3		
DOUBLE BCD DIVIDE	/BL	435	4	26.7		

#### 4-1-10 Conversion Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
BCD-TO-BINARY	BIN	023	3	0.40	Yes	
DOUBLE BCD-TO- DOUBLE BINARY	BINL	058	3	7.4		
BINARY-TO-BCD	BCD	024	3	8.0		
DOUBLE BINARY- TO-DOUBLE BCD	BCDL	059	3	8.0		
2'S COMPLEMENT	NEG	160	3	0.35	Yes	
DOUBLE 2'S COM- PLEMENT	NEGL	161	3	0.60	Yes	
ASCII CONVERT	ASC	086	4	11.8		Converting 1 digit into ASCII
				18.1		Converting 4 digits into ASCII
ASCII TO HEX	HEX	162	4	12.2		Converting 1 digit

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

# 4-1-11 Logic Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
LOGICAL AND	ANDW	034	4	0.30	Yes	
DOUBLE LOGICAL AND	ANDL	610	4	0.60	Yes	
LOGICAL OR	ORW	035	4	0.45	Yes	
DOUBLE LOGICAL OR	ORWL	611	4	0.60	Yes	
EXCLUSIVE OR	XORW	036	4	0.45	Yes	

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
DOUBLE EXCLU- SIVE OR	XORL	612	4	0.60	Yes	
EXCLUSIVE NOR	XNRW	037	4	0.45	Yes	
DOUBLE EXCLU- SIVE NOR	XNRL	613	4	0.60	Yes	
COMPLEMENT	СОМ	029	2	0.45	Yes	
DOUBLE COMPLE- MENT	COML	614	2	0.80	Yes	

## 4-1-12 Special Math Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
ARITHMETIC PRO- CESS	APR	069	4	24.3		Linear approximation specification, normal
				12.1		Linear approximation table transfer, 1 word
				126.1		Linear approximation table transfer, 128 words
				241.3		Linear approximation table transfer, 256 words
				21.5		Linear approximation buffer specification, 256 words, beginning
				186.9		Linear approximation buffer specification, 256 words, end
				104.5		Linear approximation buffer specification, 128 words, end
BIT COUNTER	BCNT	067	4	0.65	Yes	Counting 1 word
VIRTUAL AXIS	AXIS	981	4	47.9		Relative mode
				48.1		Absolute mode
				8.3		Stopping processing

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

# 4-1-13 Floating-point Math Instructions

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
FLOATING TO 32- BIT	FIXL	451	3	7.4		
32-BIT TO FLOAT- ING	FLTL	453	3	7.0		
FLOATING-POINT ADD	+F	454	4	11.4		

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
FLOATING-POINT SUBTRACT	_F	455	4	11.0		
FLOATING-POINT DIVIDE	/F	457	4	11.1		
FLOATING-POINT MULTIPLY	*F	456	4	11.0		
DEGREES TO RADIANS	RAD	458	3	9.7		
RADIANS TO DEGREES	DEG	459	3	9.4		
SINE	SIN	460	3	15.8		
COSINE	cos	461	3	15.5		
TANGENT	TAN	462	3	17.5		
ARC SINE	ASIN	463	3	42.7		
ARC COSINE	ACOS	464	3	42.5		
ARC TANGENT	ATAN	465	3	21.3		
SQUARE ROOT	SQRT	466	3	25.5		
EXPONENT	EXP	467	3	18.1		
LOGARITHM	LOG	468	3	16.1		
EXPONENTIAL POWER	PWR	840	4	31.5		
Floating Symbol	LD, AND, OR +=F	329	3	8.9		
Comparison	LD, AND, OR +<>F	330				
	LD, AND, OR + <f< td=""><td>331</td><td></td><td></td><td></td><td></td></f<>	331				
	LD, AND, OR +<=F	332				
	LD, AND, OR +>F	333				
	LD, AND, OR +>=F	334				

# 4-1-14 Double-precision Floating-point Instructions

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
DOUBLE FLOAT- ING TO 16-BIT BINARY	FIXD	841	3	15.0		
DOUBLE FLOAT- ING TO 32-BIT BINARY	FIXLD	842	3	15.2		
16-BIT BINARY TO DOUBLE FLOATING	DBL	843	3	10.2		
32-BIT BINARY TO DOUBLE FLOATING	DBLL	844	3	10.2		
DOUBLE FLOAT- ING-POINT ADD	+D	845	4	19.1		
DOUBLE FLOAT- ING-POINT SUB- TRACT	-D	846	4	19.3		

Instruction	Mnemonic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
DOUBLE FLOAT- ING-POINT MULTI- PLY	*D	847	4	24.1		
DOUBLE FLOAT- ING-POINT DIVIDE	/D	848	4	34.7		
DOUBLE DEGREES TO RADIANS	RADD	849	3	38.1		
DOUBLE RADIANS TO DEGREES	DEGD	850	3	38.6		
DOUBLE SINE	SIND	851	3	56.8		
DOUBLE COSINE	COSD	852	3	53.5		
DOUBLE TANGENT	TAND	853	3	125.4		
DOUBLE ARC SINE	ASIND	854	3	27.0		
DOUBLE ARC COSINE	ACOSD	855	3	29.6		
DOUBLE ARC TAN- GENT	ATAND	856	3	19.5		
DOUBLE SQUARE ROOT	SQRTD	857	3	62.3		
DOUBLE EXPO- NENT	EXPD	858	3	158.1		
DOUBLE LOGA- RITHM	LOGD	859	3	22.4		
DOUBLE EXPO- NENTIAL POWER	PWRD	860	4	285.0		
DOUBLE SYMBOL	LD, AND, OR +=D	335	3	13.1		
COMPARISON	LD, AND, OR +<>D	336				
	LD, AND, OR + <d< td=""><td>337</td><td></td><td></td><td></td><td></td></d<>	337				
	LD, AND, OR +<=D	338				
	LD, AND, OR +>D	339				
	LD, AND, OR +>=D	340				

## 4-1-15 Table Data Processing Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
FIND MAXIMUM	MAX	182	4	13.0		Searching for 1 word
				1.41 ms		Searching for 1,000 words
FIND MINIMUM	MIN	183	4	12.8		Searching for 1 word
				1.412 ms		Searching for 1,000 words

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

#### 4-1-16 Data Control Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
SCALING	SCL	194	4	22.7		
SCALING 2	SCL2	486	4	21.8		
SCALING 3	SCL3	487	4	26.1		
AVERAGE	AVG	195	4	27.9		Average of an operation
				27.9		Average of 64 operations

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

#### 4-1-17 Subroutine Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
SUBROUTINE CALL	SBS	091	2	25.5	Yes	
SUBROUTINE ENTRY	SBN	092	2			
SUBROUTINE RETURN	RET	093	1	21.9	Yes	
MACRO	MCRO	099	4	47.4		
JUMP TO SUBROU- TINE	JSB	982	4	34.9		

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

# **4-1-18 Interrupt Control Instructions**

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
SET INTERRUPT MASK	MSKS	690	3	7.6		
READ INTERRUPT MASK	MSKR	692	3	5.2		
CLEAR INTERRUPT	CLI	691	3	7.2		
DISABLE INTER- RUPTS	DI	693	1	5.3		
ENABLE INTER- RUPTS	El	694	1	5.6		
INTERVAL TIMER	STIM	980	4	9.5		One-shot timer
				11.0		One-shot pulse output
				9.5		Scheduled interrupt
				10.8		Reading timer PV
				7.4		Stopping timer
				17.8		Starting pulse counting
				14.7		Stopping pulse counting

# 4-1-19 High-speed Counter and Pulse Output Instructions (Only for Motion Control Modules)

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
MODE CONTROL	INI	880	4	16.7		Starting high-speed counter comparison
				12.7		Stopping high-speed counter comparison
				13.3		Changing pulse output PV
				10.9		Changing high-speed counter circular value
				16.7		Starting pulse output comparison
				12.6		Stopping pulse output comparison
				14.9		Changing pulse output PV
				13.1		Changing pulse output circular value
				12.5		Stopping pulse output
				10.1		Stopping sampling counter comparison
				14.5		Changing sampling counter PV
				13.9		Changing sampling counter circular value
HIGH-SPEED	PRV	881	4	13.5		Reading pulse output PV
COUNTER PV READ				15.1		Reading high-speed counter PV
				50.8		Reading analog input PV
				14.3		Reading high-speed counter travel distance
				12.1		Reading high-speed counter latched value
COMPARISON TABLE LOAD	CTBL	882	4	36.5		Registering target value table and starting comparison for 1 target value
				259.6		Registering target value table and starting comparison for 48 target values
				22.1		Executing range comparison for 1 range
				113.7		Executing range comparison for 16 ranges
				22.1		Only registering target value table for 1 target value
				240.1		Only registering target value table for 48 target values
				20.9		Registering a sampling counter target value table and starting comparison
				42.8		Analog output

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
SPEED OUTPUT	SPED	885	4	23.7		Continuous mode
				32.7		Independent mode
				42.9		Analog output
SET PULSES	PULS	886	4	15.9		Setting pulse output in relative mode
				16.1		Setting pulse output in absolute mode
				31.5		Absolute output mode (electronic cam)
				35.7		Absolute output mode (electronic cam, 0 point can be passed)
				40.4		Absolute output mode (electronic cam, 0 point can be passed and the output frequency can be calculated automatically)
PULSE OUTPUT	PLS2	887	4	53.5		
ACCELERATION	ACC	888	4	42.5		Continuous mode
CONTROL				44.1		Independent mode
				18.7		Analog output

# 4-1-20 Step Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
STEP DEFINE	STEP	800	2	24.3		Step control bit ON
				13.0		Step control bit OFF
STEP START	SNXT	009	2	9.1		

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

## 4-1-21 I/O Refresh Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions			
I/O REFRESH	IORF	097	3	7.7		Refreshing 1 input word			
				7.6		Refreshing 1 output word			
				20.1		Refreshing 1 input word on Basic I/O Unit			
				20.1	Refreshing 1 output word on Basic I/O Units				
				57.6		Refreshing 10 input words on Basic I/O Unit			
				59.9		Refreshing 10 output words on Basic I/O Units			

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

#### 4-1-22 Serial Communications Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
TRANSMIT	TXD	236	4	24.1		Sending 1 byte
				342.6		Sending 256 bytes
RECEIVE	RXD	235	4	36.2		Storing 1 byte
				348.9		Storing 256 bytes
CHANGE SERIAL PORT SETUP	STUP	237	3	441.1		

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

## 4-1-23 Debugging Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
TRACE MEMORY	TRSM	045	1	34.6		Sampling 1 bit and 0 words
SAMPLING				148.3		Sampling 31 bits and 6 words

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

## 4-1-24 Failure Diagnosis Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa-tion	Conditions
FAILURE ALARM	FAL	006	3	157.1		Recording errors
				56.0		Deleting errors (in order of priority)
				457.0		Deleting errors (all errors)
				53.6		Deleting errors (individually)
SEVERE FAILURE ALARM	FALS	007	3			

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

#### 4-1-25 Other Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Hardware implementa- tion	Conditions
SET CARRY	STC	040	1	0.15	Yes	
CLEAR CARRY	CLC	041	1	0.15	Yes	

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

## 4-1-26 Block Programming Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)		Conditions
BLOCK PROGRAM BEGIN	BPRG	096	2	20.3		
BLOCK PROGRAM END	BEND	801	1	17.2		
Branching	IF (execution condition)	802	1	6.8	Yes	IF true
				12.2		IF false
Branching	IF (relay number)	802	2	11.0	Yes	IF true
				16.5		IF false
Branching (NOT)	IF NOT	802	2	11.5	Yes	IF true
	(relay number)			16.8		IF false
Branching	ELSE	803	1	11.4	Yes	IF true
				13.4	1	IF false
Branching	IEND	804	1	13.5	Yes	IF true
-				7.0		IF false

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

## 4-1-27 Special Function Block Instructions

Instruction	Mne- monic	Code	Length (steps) (See note.)	ON execution time (μs)	Conditions
GET VARIABLE ID	GETID	286	4	21.3	 

**Note** When a double-length operand is used, add 1 to the value shown in the length column in the above table.

#### **Execution Times for Function Block Instances**

The influence on the cycle time resulting from executing function block instances in FQM1-CM002/MMP22/MMA22 CPU Units is as follows:

Cycle time influence of function block instance execution = Starting time A + I/O parameter transfer time B + Function block execution time C

#### A, B, and C are as follows:

		Description	Model
			FQM1-CM002 FQM1-MMP22 FQM1-MMA22
Α	Starting time	Time required to start execution excluding the I/O parameter transfer time	15.0 μs
В	I/O parameter transfer time	Time for 1 BOOL I/O variable (1 bit)	1.0 μs
		Time for 1 INT, UINT, or WORD I/O variable (1 word)	0.8 μs
		Time for 1 DINT, UDINT, or DWORD I/O variable (2 words)	1.1 μs
		Time for 1 LINT, ULINT, or LWORD I/O variable (4 words)	2.2 μs
С	Function block execution time	Total of the execution times for the instructions inside the in other ladder diagram programming)	stance (same as for

#### Example

The execution time for a function block instance with three INT input variables (one word each) and two INT output variables (one word each) would be as follows assuming that the total instruction execution time for the instructions in the function block is 10  $\mu$ s.

$$6.8 \, \mu s + (3 + 2) \times 0.3 \, \mu s + 10 \, \mu s = 18.3 \, \mu s$$

**Note** If there is more than one instance of the same function block in a program, the overall execution time would be increased by the above amount for each instance.

#### **Number of Program Steps for Function Block Instances**

The number of program steps required when function block instances are used in a user program is as follows:

Number of steps =
Number of instances × (Steps to call the function block m +
Steps to transfer I/O parameters n × Number of parameters) +
Instruction steps in function block definition p (See note.)

**Note** If there is more than one instance of the same function block in a program, the the number of instruction steps for the function block definition is required only for the first instance. The "Instruction steps in function block definition p" in the above formula is not multiplied by the number of instances.

Description			Time for FQM1 CPU Unit
m	Number of steps required to call the function block		57 steps
n	Number of steps required to transfer I/O parameters	Time for 1 BOOL I/O variable (1 bit)	6 steps
		Time for 1 INT, UINT, or WORD I/O variable (1 word)	6 steps
		Time for 1 DINT, UDINT, or DWORD I/O variable (2 words)	6 steps
		Time for 1 LINT, ULINT, or LWORD I/O variable (4 words)	12 steps
р	Number of instruction steps	umber of instruction steps Add 27 steps to the total of the instruction steps inside the function block definition (same as for other ladder diagram programming)	

#### **Example**

The number of instructions required for one instance of a function block with five INT input variables (one word each) and five INT output variables (one word each) would be as follows assuming that the function block definition contained 100 programming steps.

 $57 + (5 + 5) \times 6$  steps + 100 steps + 27 steps = 244 steps

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# **Revision History**

A manual revision code appears as a suffix to the catalog number on the front cover of the manual.



The following table outlines the changes made to the manual during each revision. Page numbers refer to the previous version.

Revision code	Date	Revised content
01	December 2005	Original production
02	November 2006	Information added and changed for the addition of functionality supported by unit version 3.2 of the Coordinator Module and Motion Control Modules.
03	April 2008	Page vii: Updated description for mounting CJ-series Units
		Page vii: Added version upgrade table for version 3.2 to version 3.3.
		Page 538: Added paragraph at bottom of page.
		Page 545: Added a paragraph above operand specifications table.
		Page 549: Changed T settings for Equal Flag in the table.
		Page 551: Added paragraph above operand specifications table.
		Page 553: Added information on version 3.3 or later above notes.
		Page 556: Added a paragraph at bottom of page.