

Simple, Compact Inverters JX-series

# Replace Guide From 3G3JX to 3G3MX2

3G3MX2- A 🗆 🗆 🗆 🗆 3G3JX-A 🗆 🗆 🗆



I924-E1-01

NOTE

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### Introduction

This guide provides the reference information for replacement and does not contain safety information and other details that are required for actual use. Thoroughly read and understand the manuals for both the old and new inverters to ensure that the system is used safely. Review the entire contents of these manuals, including all safety precautions, precautions for safe use, and precautions for correct use.

#### **Intended Audience**

This guide is intended for the following personnel.

- · Personnel in charge of introducing control equipment
- · Personnel in charge of designing control systems
- · Personnel in charge of installing and maintaining control equipment
- · Personnel in charge of managing control systems and facilities

The personnel must also have the following knowledge.

· Knowledge of electrical systems (an electrical engineer or the equivalent)

#### Applicable Products

This guide covers the following products.

- · 3G3JX series Inverter
- · 3G3MX2 series Type V1 Inverter

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#### Change in Specifications.

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

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### Precautions

- When building a system, check the specifications for all devices and equipment that will make up the system and make sure that the OMRON products are used well within their rated specifications and performances. Safety measures, such as safety circuits, must be implemented in order to minimize the risks in the event of a malfunction.
- Thoroughly read and understand the manuals for all devices and equipment that will make up the system to ensure that the system is used safely. Review the entire contents of these manuals, including all safety precautions, precautions for safe use, and precautions for correct use.
- · Confirm all regulations, standards, and restrictions that the system must adhere to.

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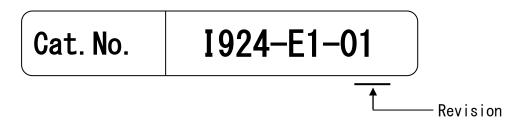
### Related Manuals

Manual name	Cat. No.	Model	Description
3G3JX Series	I558	3G3JX-0000	Describes how to install and wire the inverter, set parameters
Compact Simplified			needed to operate the inverter, and remedies to be taken and
Inverter			inspection methods to be used in case that problems occur.
User' s Manual			
3G3MX2 Series Type V1	I585	3G3MX2-000-V1	Describes how to install and wire the inverter, set parameters
Multi-function			needed to operate the inverter, and remedies to be taken and
Compact Inverter			inspection methods to be used in case that problems occur.
User's Manual			

Please see the manuals below for related	product information	llea thaca man	uals for reference
Flease see the manuals below for related	product information.	. Use these man	uals for reference.

### **Revision History**

A manual revision code appears as a suffix to the catalog number on the front and back covers of the manual.



Revision code	Date	Revised content
01	July 2019	Original production

## Index

## 1. Target model

- (1) Replaced (old) model
- 3G3JX series Compact Simplified Inverter

3G3JX-0000

(2) New model

3G3MX2 Series Type V1 Multi-function Compact Inverter 3G3MX2-DDDDV1

### 2. Precautions for replacement

- (1) There are some differences between 3G3JX and 3G3MX2-V1. Before replacement, refer to not only this guide but also related product user's manuals.
- (2) 3G3JX has a 3-phase 400-V class 3.7 kW capacitor model. Please replace with a 3-phase 400-V class 4.0 kW capacitor model.
- (3) 3G3JX has single/3-phase 200-V class models. Please replace with single-phase 200-V class models or 3-phase 200-V class models.
- (4) There are some differences between 3G3JX and 3G3MX2-V1 in mounting dimensions and arrangement and function of terminal block. Refer to related product user's manuals.
- (5) For differences between 3G3JX and 3G3MX2-V1 in default parameter values and parameter functions, refer to this guide. For details of functions, refer to related product user's manuals at the time of setting.
- (6) There is no volume control on 3G3MX2-V1. To input commands with the volume control, please use the optional operator 3G3AX-OP01.
- (7) To connect the CX-Drive and 3G3MX2-V1, please use a commercially available USB cable. The 3G3JX dedicated cable 3G3AX-PCAN2 cannot be used with 3G3MX2-V1.
- (8) 3G3JX has a built-in radio noise filter. To use 3G3MX2-V1 under the same installation conditions, please attach an optional radio noise filter.
- (9) Please note that the program of the host controller needs to be changed when replacing 3G3JX using Modbus communication. The digital operator for 3G3JX cannot be used for 3G3MX2-V1.

#### **External Dimensions and Mounting dimensions** 3.

The following tables show external dimensions and mounting dimensions of 3G3JX and 3G3MX2-V1. You can install multiple 3G3MX2-V1s side by side like 3G3JXs. Note that the external dimensions of 3G3MX2-V1 are smaller than or equal to 3G3JX but the depths (D) of all 3G3MX2-V1 models and the heights (H) of over 5.5 kW models of 3G3MX2-V1 are larger than 3G3JX.

	■ 3-phase 200-V class*1												
	3G3JX Series								3G3	MX2-V1	Series	3	
Model	Dimensions (mm)			Mounting dimensions (mm)		Model	Dimensions (mm)			Mounting dimensions (mm)			
3G3JX-	w	Н	D	W1	H1	Screw hole	3G3MX2-	w	н	D	W1	H1	Screw hole
A2002	80	155	97.4	67	143	Ф5	A2002-V1	68	128	109	56	118	Φ4.5
A2004	80	155	111.4	67	143	Φ5	A2004-V1	68	128	122.5	0	0	Φ4.5
A2007	80	155	134.4	67	143	Φ5	A2007-V1	68	128	145.5	0	0	Φ4.5
A2015	110	189	159.4	98	176	Φ5	A2015-V1	108	128	170.5	0	0	Φ4.5
A2022	110	189	159.4	98	176	Φ5	A2022-V1	108	128	170.5	0	0	Φ4.5
A2037	110	189	159.4	98	176	Φ5	A2037-V1	140	128	170.5	0	0	Φ4.5
A2055	180	250	169.4	164	235	Φ6	A2055-V1	140	260	155	0	0	Φ6
A2075	180	250	169.4	164	235	Φ6	A2075-V1	140	260	155	0	0	Φ6

#### 3.1. External Dimensions

	3G3JX Series							3G3MX2-V1 Series					
Model 3G3JX	Dimensions (mm)		Mounting dimensions (mm)			Model	Dimensions (mm)			Mounting dimensions (mm)			
-	w	Н	D	W1	H1	Screw hole	3G3MX2-	w	Н	D	W1	H1	Screw hole
A4004	110	189	132.4	98	176	Φ5	A4004-V1	108	128	143.5	96	118	Φ4.5
A4007	110	189	159.4	98	176	Φ5	A4007-V1	108	128	170.5	96	118	Φ4.5
A4015	110	189	159.4	98	176	Φ5	A4015-V1	108	128	170.5	96	118	Φ4.5
A4022	110	189	159.4	98	176	Φ5	A4022-V1	108	128	170.5	96	118	Φ4.5
A4037	110	189	159.4	98	176	Φ5	A4040-V1	140	128	170.5	128	118	Φ4.5
A4055	180	250	169.4	164	235	Φ6	A4055-V1	140	260	155	122	248	Φ6
A4075	180	250	169.4	164	235	Φ6	A4075-V1	140	260	155	122	248	Ф6.

#### ■ 3-phase 400-V class

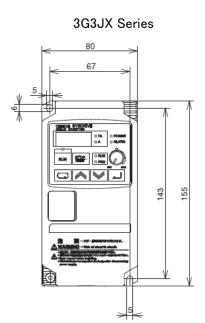
#### ■ Single-phase 200-V class\*2

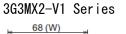
	3G3JX Series						3G3MX2-V1 Series							
Model 3G3JX	Dimensions (mm)			Мо		dimensions nm)	Model 3G3MX2-				Mounting dimensions (mm)			
-	W	Н	D	W1	H1	Screw hole	JGJMAZ-	W	Н	D	W1	H1	Screw hole	
AE002	80	155	97.4	67	143	Φ5	AB002-V1	68	128	109	56	118	Φ4.5	
AE004	80	155	111.4	67	143	Φ5	AB004-V1	68	128	122.5	56	118	Φ4.5	
AE007	110	189	132.4	98	176	Φ5	AB007-V1	108	128	170.5	96	118	Φ4.5	

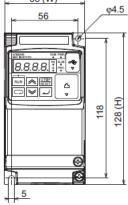
AE015	110	189	159.4	98	176	Φ5	AB015-V1	108	128	170.5	96	118	Φ4.5
AE022	110	189	159.4	98	176	Φ5	AB022-V1	108	128	170.5	96	118	Φ4.5

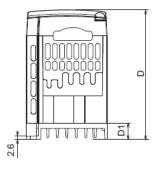
- \*1. When using 3G3JX-AE□ with 3-phase 200 V input, select from 3G3MX2-V1 3-phase 200 V input specifications.
- \*2. When using 3G3JX-AE□ with single-phase 200 V input, select from 3G3MX2-V1 single-phase 200 V input specifications.

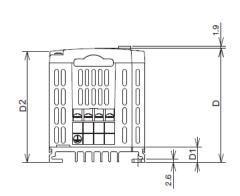
#### 3.2. External Dimensions





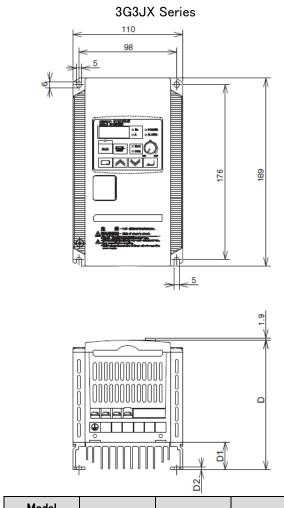


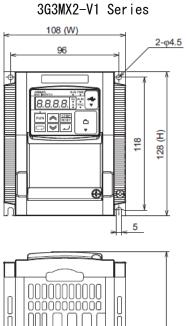




Model 3G3JX-	D [mm]	D1 [mm]	D2 [mm]		
A2002	95.5	13	93		
AE002	95.5	13			
A2004	109.5	27	107		
AE004	109.5	21	107		
A2007	132	50	130		

Model 3G3MX2-	D [mm]	D1 [mm]		
A2002-V1	109	13.5		
AB002-V1	109	13.5		
A2004-V1	122.5	27		
AB004-V1	122.5	27		
A2007-V1	145.5	50		



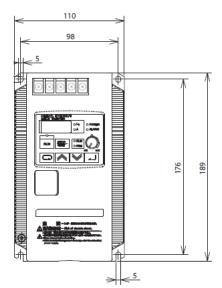


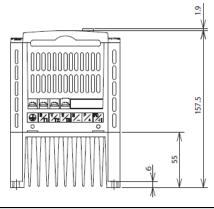
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		,	l

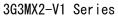
Model 3G3JX-	D [mm]	D1 [mm]	D2 [mm]			
A4004	130.5	28	0.6			
AE007	130.5	20	2.6			
A2015						
A2022						
A4007						
A4015	157.5	55	6			
A4022						
AE015						
AE022						

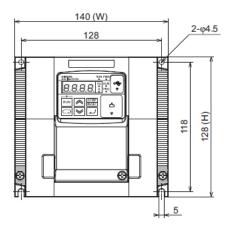
Model	D [mm]	D1 [mm]	
3G3MX2-	נווווון ט	Ci fuuni	
A4004-V1	143.5	28	
A2015-V1		55	
A2022-V1			
A4007-V1			
A4015-V1	170.5		
A4022-V1	170.5		
AB007-V1			
AB015-V1			
AB022-V1			

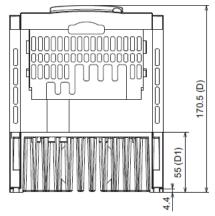
#### 3G3JX Series





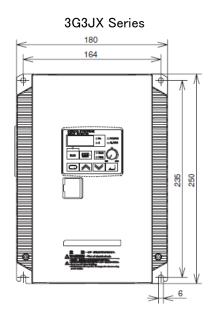


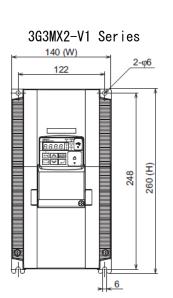


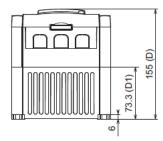


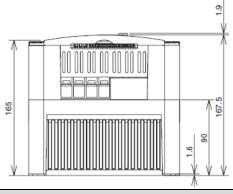
Model
3G3JX-
A2037
A4037

Model
3G3MX2-
A2037-V1
A4040-V1









Model	
3G3JX-	
A2055	
A2075	
A4055	
A4075	

Model
3G3MX2-
A2055-V1
A2075-V1
A4055-V1
A4075-V1

### 4. Arrangement and Function of Terminal Block

There are some difference of Arrangement and Function of Terminal Block between 3G3JX and 3G3MX2-V1. Before setting, to refer this section. Refer to related product user's manual.

3G3JX			3G3MX2-V1	Remarks
Terminal	Terminal name	Terminal name Terminal Terminal name		remarks
P24	Internal 24 VDC	P24	Internal 24 VDC	
PSC	Input terminal power	PSC	Input terminal power	For sink logic input:
	supply		supply	Short-circuited to P24
				For source logic input:
				Short-circuited to SC. To
				activate contact input via an
				external power supply,
				remove the short-circuit bar.
S1	Multi-function input	S1	Multi-function input	The terminals S3 and S4 are
S2		S2		shared with the safety input.
S3		S3		When the safety function
S4		S4		selector switch is ON, S3
				and S4 are automatically set
				to safety input (GS1, GS2).
S5	Multi-function input	S5 (TH)	Multi-function input	When the Multi-function
			(External thermistor	Input S5 Selection (C005) is
			input used in	set to 19 (TH: PTC
			common)	thermistor thermal
				protection), the inverter will
				trip if the external thermistor
				detects a temperature error.
				(The inverter trips when the
				resistance of the thermistor
				is approximately 3 k $\Omega$ or
				higher.)
SC	Input signal common	SC	Input signal common	
AM	Analog frequency	AM	Multi-function	This terminal can output the
	monitor/Analog		analog output	specified signal as a 0 to
	output current		(Voltage)	10-VDC voltage signal.
	monitor			
FS	Frequency reference	FS	Frequency reference	
	power supply		power supply	
FV	Voltage frequency	FV	Voltage frequency	Frequency reference input
	reference signal		reference signal	(Analog voltage input)

#### 4.1. Control Circuit Terminal Block

FI	Current frequency	FI	Current frequency	Frequency reference input
	reference signal		reference signal	(Analog current input)
FC	Frequency reference	SC	Input signal common	In 3G3MX2-V1, common
	common			terminal for the internal
				power supply, digital input,
				and analog I/O terminals.
P1	Multi-function	P1	Multi-function	This terminal is automatically
	output terminal		output terminal	set to P1 (EDM: Safety
			(Safety monitor	monitor signal) when the
			terminal used in	EDM function selector
			common)	switch is turned ON.
PC	Output signal	PC	Output signal	
	common		common	
MA	Relay output	MA	Relay output	
MB	signal	MB	terminal	
МС		MC	Relay output	
			common	
SP	Sent and received	RS+	Modbus terminal(+)	In 3G3JX, it is located in the
	data: Positive side			RJ45 connector for digital
				operator connection.
SN	Sent and received	RS-	Modbus terminal(-)	
	data: Negative side			

### 5. Functional difference

### 5.1. Dual duty rating

3G3MX2-V1 supports the dual duty rating: heavy load (CT) and light load (VT) that allows the inverter to drive a motor whose capacity is one size large. Heavy load (CT) is used in this guide.

Heavy load (CT)	This mode is for general loads that temporarily exceed the rated
	torque during acceleration and deceleration.
Light load (VT)	This mode is for a fan, pump, or other device that operates at the rated
	motor torque or lower. With a load tolerance of 120% (of rated
	torque)/min, the inverter can drive a motor that is one size larger.

#### 5.2. Modbus communication

Some Modbus addresses differ between 3G3JX and 3G3MX2-V1.

In order to operate correctly, refer to the 3G3MX2-V1 User's Manual for the addresses and parameter settings and change not only parameter settings but also PLC/PC programs.

### 6. Parameter List

### 6.1. The difference of parameter arrangement, parameter name and default value

There are some difference of Parameter name, settings, number, date range and arrangement between 3G3JX and 3G3MX2-V1. Before setting, to refer this section. Refer to related product user's manuals.

		3G3JX		3G3MX2-V1	
Name	Parameter No.	Default setting	Parameter No.	Default setting	Remark
Frequency reference	A001	00: Digital Operator (FREQ	A001	02: Digital Operator	
selection	A001	adjuster)	A001		The initial value differs because there is no
FV/FI selection	A005	02: Switches between FV/FREQ adjuster via terminal AT	A005	00: Switch between FV (Voltage) and FI (Current)	adjuster on 3G3MX-V1.
Jogging stop selection	A039	00: Free-run stop	A039	04: Deceleration stop on jogging stop/Enabled during operation	Set A039 to 03 to be the same setting as 3G3JX.
Torque boost selection	A041	00: Manual torque boost only	A041	01: Automatic torque boost	In addition to manual torque boost, 3G3MX-V1 has automatic torque boost enabled by default.
Manual torque boost voltage	A042	5	A042	1	For applications with excessive starting torque, such as fans or pumps, turn off automatic torque
Manual torque boost frequency	A043	2.5	A043	5	boost.
Acceleration time 2	A092	15	A092	10	Set A092 to 15 to be the same setting as 3G3JX.
Deceleration time 2	A093	15	A093	10	Set A093 to 15 to be the same setting as 3G3JX.
Acceleration pattern selection	A097	00: Line	A097	01: S-shape curve	Set A097 to 00 to be the same setting as 3G3JX.
Deceleration pattern selection	A098	00: Line	A098	01: S-shape curve	Set A098 to 00 to be the same setting as 3G3JX.
FI start ratio	A103	0	A103	20	Set A103 to 0 to be the same setting as 3G3JX.
FI start selection	A105	01: 0 Hz start	A105	00: FI Start Frequency (A101)	Set A105 to 01 to be the same setting as 3G3JX.
Operation frequency input A setting	A141	01: Digital Operator (FREQ adjuster)	A141	02: Input FV (Voltage)	Set A141 to 01 to be the same setting as 3G3JX.
Operation frequency input B setting	A142	2: FV 入力	A142	03: Input FI (Current)	Set A142 to 02 to be the same setting as 3G3JX.
2nd frequency reference selection	A201	00: Digital Operator (FREQ adjuster)	A201	02: Digital Operator	Set A201 to 00 to be the same setting as 3G3JX.
2nd torque boost selection	A241	00: Manual torque boost only	A241	01: Automatic torque boost	In addition to manual torque boost, 3G3MX-V1
2nd manual torque boost voltage	A242	0	A242	1	has automatic torque boost enabled by default. For applications with excessive starting torque,
2nd manual torque boost	A243	0	A243	5	such as fans or pumps, turn off automatic torque boost.
frequency 2nd acceleration time 2	A292	15	A292	10	Set A292 to 15 to be the same setting as 3G3JX.
2nd deceleration time 2	A293	15	A293	10	Set A293 to 15 to be the same setting as 3G3JX.
Electronic thermal		00: Reduced torque		01: Constant torque	
characteristics selection	B013	characteristics 1	B013	characteristics	Set B013 to 00 to be the same setting as 3G3JX.
Starting voltage of non- stop function at momentary power interruption	B051	0	B051	220	Set B051 to 0.0 to be the same setting as 3G3JX.
Stop deceleration level of non-stop function at momentary power interruption	B052	o	B052	360	Set B052 to 0.0 to be the same setting as 3G3JX.
Overvoltage protection integral time during deceleration	B056	0.2	B134	1	Set B134 to 0.2 to be the same setting as 3G3JX.
Carrier frequency	B083	3	B083	10	Set B083 to 3.0 to be the same setting as 3G3JX.
Initialization selection	B084	00: Clears the trip monitor	B084	00: Initialization disabled	Set B084 to 01 to be the same setting as 3G3JX.
Overvoltage LAD stop function level setting	B131	380	B096	360	Set B096 to 380 to be the same setting as 3G3JX.
2nd electronic thermal characteristics selection	B213	00: Reduced torque characteristics 1	B213	01: Constant torque characteristics	Set B213 to 00 to be the same setting as 3G3JX.
Overvoltage protection function selection during deceleration	B133	00: Disabled	B130	01: Enabled (DC voltage kept constant)	Set B130 to 00 to be the same setting as 3G3JX.
Automatic carrier reduction	B150	00: Disabled	B089	01: Enabled (dependent on current)	Set B089 to 0 to be the same setting as 3G3JX.
AM selection	C028	00: Output frequency	C028	07: LAD frequency	Set C028 to 00 to be the same setting as 3G3JX.
Overload warning level	C041	1.4	C041	1.84	Set C041 to rated current to be the same setting as 3G3JX.
Communication speed selection (Baud rate selection)	C071	4: 4800bps	C071	5: 9600bps	Set C071 to 04 to be the same setting as 3G3JX.
Reset selection	C102	00: Trip reset at power-on	C102	02: Enabled only during trip (Reset at power-on)	Set C102 to 00 to be the same setting as 3G3JX.
Logic operation function B input	C142	01: FA1 (constant speed arrival signal)	C143	00: RUN (Signal during RUN)	Set C143 to 02 to be the same setting as 3G3JX.
Output frequency setting/monitor	F001	0	F001	6	Set F001 to 0 to be the same setting as 3G3JX.

### 6.2. The difference of multi-function Input Settings

There are some difference of multi-function Input Settings between 3G3JX and 3G3MX2-V1. Before setting, to refer the following list. Refer to related product user's manuals.

		3G3JX	3G3MX2-V1		
Data No.	Code	Function name	Code	Function name	
0	FW	forward	FW	Forward	
1	RV	reverse	RV	Reverse	
2	CF1	multi-step speed setting binary 1	CF1	Multi-step speed setting binary 1	
3	CF2	Multi-step speed setting binary 2	CF2	Multi-step speed setting binary 2	
4	CF3	multi-step speed setting binary 3	CF3	Multi-step speed setting binary 3	
5	CF4	multi-step speed setting binary 4	CF4	Multi-step speed setting binary 4	
6	JG	jogging	JG	Jogging	
7	DB	external DC injection braking	DB	External DC injection braking	
8	SET	2nd control	SET	2nd control	
9	2CH	2-step acceleration/deceleration	2CH	2-step acceleration/deceleration	
11	FRS	free-run stop	FRS	Free-run stop	
12	EXT	external trip	EXT	External trip	
13	USP	USP function	UPS	Power recovery restart prevention function	
14	_	-	CS	Commercial switching	
15	SFT	soft lock	SFT	Soft lock	
16	AT	analog input switching	AT	Analog input switching	
18	RS	reset	RS	Reset	
19	PTC	thermistor input	ТН	PTC thermistor thermal protection	
20	STA	3-wire start	STA	3-wire start	
21	STP	3-wire stop	STP	3-wire stop	
22	F/R	3-wire forward/reverse	F/R	3-wire forward/reverse	
23	PID	PID enabled/disabled	PID	PID disabled	
24	PIDC	PID integral reset	PIDC	PID integral reset	
27	UP	UP/DWN function accelerated	UP	Remote operation accelerated	
28	DWN	UP/DWN function decelerated	DWN	Remote operation decelerated	
29	UDC	UP/DWN function data clear	UDC	Remote operation data clear	
31	OPE	forced operator	OPE	Forced operator function	
50	ADD	frequency addition	ADD	Set frequency A145 addition	

51	F-TM	forced terminal block	F-TM	Forced terminal block
52	RDY	ready function	ATR	Torque command input permission
53	SP-SET	special 2nd function	KHC	Integrated power clear
64	EMR	emergency shutoff	-	-
255	No function	_	no	No allocation

### 6.3. The difference of multi-function Output Settings

There are some difference of multi-function Output Settings between 3G3JX and 3G3MX2-V1. Before setting, to refer the following table. Refer to related product user's manuals.

		3G3JX	3G3MX2-V1		
Data No.	Code	Function name	Code	Function name	
0	RUN	signal during RUN	RUN	Signal during RUN	
1	FA1	constant speed arrival signal	FA1	Constant speed arrival signal	
2	FA2	over set frequency arrival signal	FA2	Set frequency exceeded signal	
3	OL	overload warning	OL	Overload warning	
4	OD	excessive PID deviation	OD	Excessive PID deviation	
5	AL	alarm output	AL	Alarm signal	
6	Dc	disconnection detection	FA3	Set-frequency only signal	
7	FBV	PID FB status output	ΟΤQ	Overtorque/Undertorque signal	
8	NDc	network error	-	-	
9	LOG	logic operation output	UV	Signal during undervoltage	
10	ODc	Do not use.	TRQ	Torque limit	
43	LOC	light load detection signal	LOC	Low current signal	

### 7. Modbus Communication Data Correspondence List

There are some difference of Modbus Communication Coil Number and Register Number between 3G3JX and 3G3MX2-V1. Adjust the program of the host controller after referring to the table below and check the operation. In addition, be sure to refer to the user's manuals for each inverter.

### 7.1. Coil Number

			3G3JX	3	3G3MX		
Item	R/W	Description			Modbus coil		
			Coil No.	Coil No.	spec. No.		
		1: Run					
RUN command		0: Stop (Enabled when A002	0001h	0001h	0000h		
		= 03)					
		1: Reverse					
Rotation direction command		0: Forward (Enabled when	0002h	0002h	0001h		
		A002 = 03)					
External Trip (EXT)	R/W	1: Trip	0003h	0003h	0002h		
Trip reset (RS)		1: Reset	0004h	0004h	0003h		
Multi-function Input 1			0007h	0007h	0006h		
Multi-function Input 2		1 : ON	0008h	0008h	0007h		
Multi-function Input 3	_	0 : OFF	0009h	0009h	0008h		
Multi-function Input 4	_		000Ah	000Ah	0009h		
Multi-function Input 5			000Bh	000Bh	000Ah		
		1: Run					
Operation status		0: Stop (Interlocked with	000Eh	000Fh	000Eh		
	4	d003)					
		1: Reverse					
RUN direction		0: Forward (Interlocked with	000Fh	0010h	000Fh		
	4	d003)					
Inverter ready		1: Ready	0010h	0011h	0010h		
	-	0: Not ready 1: ON					
AL (Alarm signal)			0014h	0018h	0017h		
OD (Excessive PID deviation)	-	0: OFF	0015h	0017h	0016h		
OL (Overload warning)	-		0013h 0016h	0017h 0016h	0015h		
FA2 (Set frequency exceeded	R		001011	001011	001311		
signal)		1 : ON	0017h	0015h	0014h		
FA1 (Constant speed arrival	-	0 : OFF					
signal)			0018h	0014h	0013h		
RUN (During RUN)			0019h	0013h	0012h		
	1	1: Writing		_			
During data write		0: Normal	001Ah	0049h	0048h		
CRC error	1		001Bh	004Ah	0049h		
Overrun error	1		001Ch	004Bh	004Ah		
Framing error	1	1: Error	001Dh	004Ch	004Bh		
Parity error	1	0: No error	001Eh	004Dh	004Ch		
Checksum error	1		001Fh	004Eh	004Dh		

### 7.2. Register Number

# 2. Register Number In 3G3MX2-V1, (Register address) = (Register number) -1 .

Function			3G3JX	3G3MX2-V1				
Function name	Register No.	Parameter No.	Monitor or setting data	Data resolution	Register No.	Parameter No.	Monitor or setting data	Data resolution
Frequency reference (Enable when A001 = 03)	0002h	-	$0 \sim 4000$	0.1[Hz]	0001h 0002h	F001(HIGH) F001(LOW)	0 to Maximum frequency	0.01[Hz]
Inverter status	0003h	-	00: Default 02: Stop 03: Run 04: Free-run stop (FRS) 05: Jogging 06: DC injection braking 07: Retry 08: Trip 09: Undervoltage	-	0002h	-	0: Initial status 2: Stop 3: Run 4: Free-run stop 5: Jogging 6: DC injection braking 8: Trip 9: During UV	-
PID feedback (Enable when A076 = 02)	0005h	-	$0\sim 1000$	0.1[%]	0006h	-	0~10000	0.01[%]
Output frequency monitor	1002h	d001	0 ~ 4000	0.1[Hz]			0 $\sim$ 40000 (In the high-frequency	0.01[Hz]
Output current monitor	1002h	d001	0 ~ 2000	0.1[%]	1002h 1003h	d001(LOW) d002	mode : ~58000) 0~65530	0.01[A]
Rotation direction monitor	1004h	d002	00: Stop 01: Forward 02: Reverse	-	1004h	d003	0: Stop 1: Forward 2: Reverse	-
PID feedback value monitor	1005h	d004(MSB)	0 ∼ 999900	0.01[%]	1005h	d004(HIGH)	0~100000	0.1
(A075 PID scale)	1006h	d004(LSB)	0	0.01[70]	1006h	d004(LOW)	0 100000	0.1
Multi-function input monitor	1007h	d005	0 to 63 Multi-function input status, Bit 0 = [1] to Bit 4 = [5]	-	1007h	d005	$2^0$ : Terminal S1 $\sim 2^6$ : Terminal S7/EB	ビット
Multi-function output monitor	1008h	d006	0 to 7 Multi-function output status, Bit 0 = [P1] Bit 1 = Not used. Bit 2 = [MA]	-	1008h	d006	$2^0$ : Terminal P1 ~2 <sup>1</sup> : Terminal P2 $2^6$ : Relay output terminal MA	ビット
Output frequency monitor		d007(MSB)	0 ~ 3996000	0.01			$0{\sim}3999600$ (In the high-frequency	0.01
(after conversion)	100Ah 100Ch	d007(LSB) d013	0~20000	0.01[%]	100Ah 1011h	d007(LOW) d013	mode : ~5799420) 0~6000	0.1[V]
Output voltage monitor		d013 d016(MSB)			1011h	d015 d016(HIGH)		
Total RUN time	100Fh	d016(LSB) d017(MSB)	0 ~ 999999	1[h]	1016h 1017h	d016(LOW) d017(HIGH)	0~999000	1[h]
Power ON time monitor	1011h	d017(LSB)	0 ~ 999999	1[h]	1018h	d017(LOW)	0~999000	1[h]
Fin temperature monitor	116Ah		0~2000	0.1[℃]	1019h	d018	-200~+1500	0.1 [°C] 1 [□]
Fault frequency monitor DC voltage monitor	0011h 116Ch	d080 d102	0 ~ 65535 0 ~ 9999	- 0.1[V]	0011h 1026h	d080 d102	0~65535 0~10000	0.1[V]
Electronic thermal monitor	116Dh	d102	0 ~ 1000	0.1[%]	1028h	d104	0~1000	0.1[%]
	0012h	d081	Trip monitor 1: Factor code	-	0012h 0013h	h h h d081	Fault Monitor 1 Fault Fault Monitor 1 Inverter	-
	0014h		Trip monitor 1: Frequency	0.1[Hz]	0014h 0015h		0~40000(LOW) 0~58000(HIGH)	0.01[Hz]
Fault monitor 1	0016h 0017h 0018h 0019h		Trip monitor 1: Current	0.1[A]	0016h		Output Current	0.01[A]
			Trip monitor 1: Voltage	1[V]	0017h	0001	DC Voltage	0.1[V]
-			ł	Trip monitor 1: Run time (MSB) Trip monitor 1: Run time (LSB)	1[h]	1[h] 0018h 0019h	-	Total RUN Time (HIGH) Total RUN Time (LOW)
	001911 001Ah		Trip monitor 1: ON time (MSB)		001911 001Ah	+	Total Power ON Time (HIGH)	
	001Bh		Trip monitor 1: ON time (LSB)	1[h]	001Bh	+	Total Power ON Time (LOW)	1[h]
	001Ch		Trip monitor 2: Factor code	-	001Ch 001Dh	-	Fault Monitor 1 Fault Fault Monitor 1 Inverter Status	-
	001Eh		Trip monitor 2: Frequency	0.1[Hz]	001Eh 001Fh		0~40000(LOW) 0~58000(HIGH)	0.01[Hz]
Fault monitor 2	0020h	d082	Trip monitor 2: Current	0.1[A]	0020h	d082	Output Current	0.01[A]
_	0021h		Trip monitor 2: Voltage	1[V]	0021h	+	DC Voltage	0.1[V]
-	0022h 0023h		Trip monitor 2: Run time (MSB) Trip monitor 2: Run time (LSB)	1[h]	0022h 0023h	+	Total RUN Time (HIGH) Total RUN Time (LOW)	1[h]
-	0023h		Trip monitor 2: ON time (MSB)	451.3	0023h	1	Total Power ON Time (HIGH)	451.2
	0025h		Trip monitor 2: ON time (LSB)	1[h]	0025h	1	Total Power ON Time (LOW)	1[h]
	0026h		Trip monitor 3: Factor code	-	0026h		Fault Monitor 1 Fault	- 1
	002011	ļ			0027h	ł	Fault Monitor 1 Inverter	
	0028h		Trip monitor 3: Frequency	0.1[Hz]	0028h 0029h	ł	0~40000(LOW) 0~58000(HIGH)	0.01[Hz]
	002Ah	ł	Trip monitor 3: Current	0.1[A]	0029h 002Ah	ł	Output Current	0.01[A]
Fault monitor 3	002Ah	d083	Trip monitor 3: Voltage	1[V]	002Ah	d083	DC Voltage	0.1[V]
l t	002Ch	I	Trip monitor 3: Run time (MSB)		002Ch	1	Total RUN Time (HIGH)	
	002Dh	l	Trip monitor 3: Run time (LSB)	1[h]	002Dh	4	Total RUN Time (LOW)	1[h]
	002Eh		Trip monitor 3: ON time (MSB)	1[h]	002Eh	4	Total Power ON Time (HIGH)	1[h]
	002Fh	E002(MCD)	Trip monitor 3: ON time (LSB)	r	002Fh	E002/UTCU	Total Power ON Time (LOW)	
Acceleration time 1		F002(MSB) F002(LSB)			1103h 1104h	F002(HIGH) F002(LOW)		1
			1 to 300000		2104h	F202(LOW)		
2nd acceleration time 1			The second decimal place is ignored	0.045.3	2103h	F202(LOW)	0. 30000	0.015.3
Deceleration time 1	1016h	F003(MSB)	when the value is over 10000 (100.0	0.01[s]	1105h	F003(HIGH)	0~360000	0.01[s]
	1017h	F003(LSB)	seconds).		1106h	F003(LOW)		
2nd deceleration time 1	1503h	F203(MSB)			2105h	F203(HIGH)		
	1504h	F203(LSB)			2106h	F203(LOW)		1
Operator rotation direction	1018h	F004	0: Forward		1107h	F004	00: Forward	

			00: Digital Operator (volume)				00: Volume 01: Control circuit terminal block	
			01: Terminal 02: Digital Operator (F001)				(Analog input)	
Frequency reference	10105	4001	03: ModBus communication		12016	4001	02: Digital Operator	
selection	1019h	A001	10: Frequency operation result	-	1201h	A001	03: Modbus communication 04: Option	-
							06: Pulse train frequency	
							07: DriveProgramming 10: Operation function output	
			01: Terminal				01: Control circuit terminal block	
RUN command selection	101Ah	A002	02: Digital Operator 03: ModBus communication		1202h	A002	(DriveProgramming) 02: Digital Operator	
KON COMMAND SELECTION	IUIAII	A002	03. Modeus communication	-	120211	A002	03: Modbus communication	-
	1010				1000		04: Option	
Base frequency 2nd base frequency	101Bh 150Ch	A003 A203	30. to maximum frequency A004 30. to maximum frequency A204	1[Hz]	1203h 2203h	A003 A203	300 to 1st Maximum Frequency 300 to 2nd Maximum Frequency	0.1[Hz]
Maximum frequency	101Ch	A004			1204h	A004	1st Base Frequency to 4000 (In the	
			$30 \sim 400$	1[Hz]			high-frequency mode : $\sim$ 5800) 1st Base Frequency to 4000 (In the	0.1[Hz]
2nd maximum frequency	150Dh	A204			2204h	A204	high-frequency mode : $\sim$ 5800)	
			02: Switches between FV/VR via terminal AT				00: Switch between FV and FI 02: Switch between FV and volume	
FV/FI selection	101Dh	A005	03: Switches between FI/VR via		1205h	A005	03: Switch between FI and volume	_
	101011	A005	terminal AT	-	120311	AUUS		-
			04: Terminal FV 05: Terminal FI					
FV start frequency	1020h	A011				A011(HIGH)	0~40000	
	10001		$0 \sim 4000$	0.1[Hz]	120Ch 120Dh	A011(LOW) A012(HIGH)	(In the high-frequency mode : $\sim$	0.01[Hz]
FV end frequency	1022h	A012			120Eh	A012(LOW)	58000)	
FV start ratio FV end ratio	1023h 1024h	A013 A014	$0 \sim 100$	1[%]	120Fh 1210h	A013 A014	0~100	1[%]
FV start selection	1025h	A015	00: Start frequency A011	-	1211h	A015	00: FV Start Frequency (A011)	-
			01: 0 Hz				01: 0 Hz 1 to 30/31 (500-ms filter with ±0.1-	
FV, FI sampling	1026h	A016	1 ~ 17	-	1212h	A016	Hz hysteresis)	1
Multi-step speed reference 0	1029h	A020			1216h	A020(HIGH)	0 Starting Frequency to 1st Maximum	
					1217h	A020(LOW)	Frequency	
2nd multi-step speed	150Fh	A220			2216h	A220(HIGH)	0 Starting Frequency to 2nd Maximum	
reference 0	130111	7220			2217h	A220(LOW)	Frequency	
Multi-step speed reference 1	102Bh	A021			1218h 1219h	A021(HIGH) A021(LOW)		
Multi atom anond reference 2	102Dh	4022	+		12191 121Ah	A021(LOW) A022(HIGH)		
Multi-step speed reference 2	102Dh	A022	-		121Bh	A022(LOW)		
Multi-step speed reference 3	102Fh	A023			121Ch 121Dh	A023(HIGH) A023(LOW)		
Multi-step speed reference 4	1031h	A024			121Eh	A024(HIGH)	-	
	10001		-		121Fh 1220h	A024(LOW) A025(HIGH)		
Multi-step speed reference 5	1033h	A025	_		1221h	A025(LOW)		
Multi-step speed reference 6	1035h	A026			1222h 1223h	A026(HIGH) A026(LOW)		
Multi-step speed reference 7	1037h	A027	0.0/Starting frequency to 4000	0.1[Hz]	1224h	A027(HIGH)		0.01[Hz]
	10001		+		1225h 1226h	A027(LOW) A028(HIGH)	0	
Multi-step speed reference 8	1039h	A028	+		1227h	A028(LOW)	Starting frequency to Maximum frequency	
Multi-step speed reference 9	103Bh	A029				A029(HIGH) A029(LOW)		
Multi-step speed reference	103Dh	A030	1		122Ah	A030(HIGH)		
10 Multi-step speed reference			-		122Bh 122Ch	A030(LOW) A031(HIGH)		
11	103Fh	A031			122Dh	A031(LOW)		
Multi-step speed reference	1041h	A032				A032(HIGH)		
12 Multi-step speed reference			+		122Fh	A032(LOW) A033(HIGH)		
13								
	1043h	A033			1230H	A033(LOW)		
Multi-step speed reference	1043h 1045h	A033 A034	-		1231h 1232h	A033(LOW) A034(HIGH)		
14	1045h	A034			1231h 1232h 1233h	A033(LOW) A034(HIGH) A034(LOW)		
					1231h 1232h	A033(LOW) A034(HIGH)		
14 Multi-step speed reference	1045h	A034	0~999	0.01[Hz]	1231h 1232h 1233h 1234h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH)	Starting Frequency to 999 (In the	0.01[Hz]
14 Multi-step speed reference 15	1045h 1047h	A034 A035	00: Free-run stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW)	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/	0.01[Hz]
14 Multi-step speed reference 15	1045h 1047h	A034 A035	00: Free-run stop 01: Deceleration stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW)	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation	0.01[Hz]
14 Multi-step speed reference 15	1045h 1047h	A034 A035	00: Free-run stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW)	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation	0.01[Hz]
14 Multi-step speed reference 15	1045h 1047h	A034 A035	00: Free-run stop 01: Deceleration stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW)	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging	0.01[Hz]
14 Multi-step speed reference 15	1045h 1047h	A034 A035	00: Free-run stop 01: Deceleration stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW)	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation	0.01[Hz]
14 Multi-step speed reference 15 Jogging frequency	1045h 1047h 1048h	A034 A035 A038	00: Free-run stop 01: Deceleration stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h 1238h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW) A038	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation	0.01[Hz]
14 Multi-step speed reference 15 Jogging frequency	1045h 1047h 1048h	A034 A035 A038	00: Free-run stop 01: Deceleration stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h 1238h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW) A038	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging	0.01[Hz]
14 Multi-step speed reference 15 Jogging frequency	1045h 1047h 1048h	A034 A035 A038	00: Free-run stop 01: Deceleration stop	0.01[Hz]	1231h 1232h 1233h 1234h 1235h 1238h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW) A038	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging stop/ Enabled during operation 05: DC injection braking on jogging	0.01[Hz]
14 Multi-step speed reference 15 Jogging frequency Jogging stop selection	1045h 1047h 1048h 1049h	A034 A035 A038	00: Free-run stop 01: Deceleration stop 02: DC injection braking stop	0.01[Hz]	1231h 1232h 1233h 1233h 1233h 1238h 1238h	A033(LOW) A034(HIGH) A034(HIGH) A035(HIGH) A035(LOW) A038	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging stop/ Enabled during operation 05: DC injection braking on jogging	0.01[Hz]
14 Multi-step speed reference 15 Jogging frequency	1045h 1047h 1048h	A034 A035 A038	00: Free-run stop 01: Deceleration stop	0.01[Hz] -	1231h 1232h 1233h 1234h 1235h 1238h	A033(LOW) A034(HIGH) A034(LOW) A035(HIGH) A035(LOW) A038	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging stop/ Enabled during operation 05: DC injection braking on jogging	0.01[Hz]
14 Multi-step speed reference 15 Jogging frequency Jogging stop selection Torque boost selection 2nd torque boost selection Manual torque boost voltage	1045h 1047h 1048h 1049h 1049h 104Ah 1510h 1048h	A034 A035 A038 A039 A039 A041 A241 A042	00: Free-run stop 01: Deceleration stop 02: DC injection braking stop 00: Manual torque boost only	0.01[Hz] - - 0.1[%]	1231h 1232h 1233h 1234h 1235h 1238h 1238h 1239h 1239h 1238h 1238h 1232h	A033(LOW) A034(HIGH) A034(HIGH) A035(HIGH) A035(LOW) A038 A038 A039 A039 A039	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 05: Manual torque boost	-
14 Multi-step speed reference 15 Jogging frequency Jogging stop selection	1045h 1047h 1048h 1049h 1049h	A034 A035 A038 A039 A039	00: Free-run stop 01: Deceleration stop 02: DC injection braking stop 00: Manual torque boost only 01: Simple torque boost 0 ~ 200	0.1[%]	1231h 1232h 1233h 1233h 1235h 1238h 1239h 1239h	A033(LOW) A034(HIGH) A034(HIGH) A035(HIGH) A035(LOW) A038 A038 A039 A039 A039	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 00: Manual torque boost 01: Automatic torque boost 0~200	- - 0.1[%]
14 Multi-step speed reference 15 Jogging frequency Jogging stop selection Torque boost selection 2nd torque boost selection Manual torque boost 2nd manual torque boost	1045h 1047h 1048h 1049h 1049h 1049h 1510h 104Bh 1511h 1042h 1512h	A034 A035 A038 A039 A039 A041 A241 A042 A242 A043 A243	00: Free-run stop 01: Deceleration stop 02: DC injection braking stop 00: Manual torque boost only 01: Simple torque boost 0 ~ 200 0 ~ 500	-	1231h 1232h 1233h 1234h 1235h 1238h 1238h 1239h 1239h 1239h 1230h 2230h	A033(LOW) A034(HIGH) A034(HIGH) A035(HIGH) A035(LOW) A038 A038 A039 A039 A039 A039 A041 A241 A042 A242 A043 A243	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 00: Manual torque boost 01: Automatic torque boost 0~200	-
14 Multi-step speed reference 15 Jogging frequency Jogging stop selection Torque boost selection 2nd torque boost selection Manual torque boost voltage 2nd manual torque boost	1045h 1047h 1048h 1049h 1049h 104Ah 1510h 104Ah 1511h 104Ch	A034 A035 A038 A039 A039 A041 A241 A042 A242 A043	00: Free-run stop 01: Deceleration stop 02: DC injection braking stop 00: Manual torque boost only 01: Simple torque boost 0 ~ 200	0.1[%]	1231h 1232h 1233h 1233h 1235h 1238h 1238h 1239h 1239h 1238h 2238h 123Ch 223Ch 123Dh	A033(LOW) A034(HIGH) A034(HIGH) A035(LOW) A035(LOW) A038 A038 A039 A039 A039 A039 A041 A241 A042 A242 A043	Starting Frequency to 999 (In the high-frequency mode : 10000) 00: Free-running on jogging stop/ Disabled during operation 01: Deceleration stop on jogging stop/ Disabled during operation 02: DC injection braking on jogging stop/Disabled during operation 03: Free-running on jogging stop/ Enabled during operation 04: Deceleration stop on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 05: DC injection braking on jogging stop/ Enabled during operation 00: Manual torque boost 01: Automatic torque boost 0~200	- - 0.1[%]

Output voltage gain 2nd output voltage gain	104Eh 1514h	A045 A245	20 ~ 100	1[%]	123Fh 223Fh	A045 A245	20~100	1[%]
			00: Disabled				00: Disabled	
DC injection braking selection	1051h	A051	01: Enabled during stop 02: Output frequency <a052 db<="" td=""><td>-</td><td>1245h</td><td>A051</td><td>01: Enabled 02: Enabled (Operates only at set frequency)</td><td>-</td></a052>	-	1245h	A051	01: Enabled 02: Enabled (Operates only at set frequency)	-
DC injection braking frequency	1052h	A052	$0 \sim 600$	0.1[Hz]	1246h	A052	0~6000	0.01[Hz]
DC injection braking delay time	1053h	A053	0~50	0.1[s]	1247h	A053	0~50	0.1[s]
DC injection braking power	1054h	A054	$0 \sim 100$	1[%]	1248h	A054	0~100 (70)	1[%]
DC injection braking time	1055h	A055	0 ~ 600	0.1[s]	1249h	A055	0~600 00: Edge operation	0.1[s]
DC injection braking method selection	1056h	A056	00: Edge operation 01: Level operation	-	124Ah	A056	01: Level operation	-
			0.0/Frequency lower limit		124Fh	A061(HIGH)	0	
Frequency upper limit	105Ah	A061	: A062 x 10 to Maximum frequency : A004 x 10		1250h	A061(LOW)	1st Frequency Lower Limit to 1st Maximum Frequency	
			0.0/2nd frequency lower limit		224Fh	A261(HIGH)	0	ł
2nd frequency upper limit	1517h	A261	: A262 x 10 to 2nd max. frequency : A204 x 10	0.4[1]-1	2250h	A261(LOW)	2nd Frequency Lower Limit to 2nd Maximum Frequency	0.04[1]-1
	1055		0.0/Starting frequency	0.1[Hz]	1251h	A062(HIGH)	0	0.01[Hz]
Frequency lower limit	105Bh	A062	: $b082 \times 10$ to Frequency upper limit: A061 × 10		1252h	A062(LOW)	Starting Frequency to 1st Maximum Frequency	
			0.0/Starting frequency		2251h	A262(HIGH)	0	†
2nd frequency lower limit	1518h	A262	: b082 x 10 to 2nd frequency upper limit: A261x10		2252h	A262(LOW)	Starting Frequency to 2nd Frequency Upper Limit	
Jump frequency 1	105Dh	A063			1253h	A063(HIGH)		
					1254h 1256h	A063(LOW)	0 $\sim$ 40000 (In the high-frequency	
Jump frequency 2	1060h	A065	$0 \sim 4000$	0.1[Hz]	1257h	A065(LOW)	mode : $\sim$ 58000)	0.01[Hz]
Jump frequency 3	1063h	A067			1259h			
Jump frequency width 1	105Eh	A064			125Ah 1255h	A067(LOW) A064		
Jump frequency width 2	1061h	A066	$0\sim 100$	0.1[Hz]	1258h	A066	$0 \sim 1000$ (In the high-frequency mode : $\sim 10000$ )	0.01[Hz]
Jump frequency width 3	1064h	A068			125Bh	A068	*	
	10.00		00: Disabled		1055		00: Disabled 01: Enabled	
PID selection	1068h	A071	01: Enabled	-	125Fh	A071	02: Enabled (Reverse output	-
PID P gain	1069h	A072	2 ~ 50	0.1	1260h	A072	enabled) 0~2500	0.01
PID P gain PID I gain	1069h	A072 A073	$2 \sim 50$ $0 \sim 1500$	0.1 0.1[s]	1260h	A072 A073	0~2500 0~36000	0.01 0.1[s]
PID D gain	106Bh	A074	$0 \sim 1000$	0.1[s]	1262h	A074	0~10000	0.01[s]
PID scale	106Ch	A075	$1 \sim 9999$	0.01	1263h	A075	1~9999	0.01
			00: Feedback (FI)				00: Current (FI)	
PID feedback selection	106Dh	A076	01: Feedback (FV) 02: External communication	-	1264h	A076	01: Voltage (FV) 02: Modbus communication	_
	100011	//0/0	10: Operation function output		120 111	//0/0	03: Pulse train frequency	
							10: Operation function output	
			00: OFF (Deviation = Target value - Feedback value)				00: Disabled (Deviation = Target value – Feedback value)	
Reverse PID function	106Eh	A077	01: ON (Deviation = Feedback value	-	1265h	A077	01: Enabled (Deviation = Feedback	-
	1005	1070	- Target value)	0.4504.3	10.00	1070	value Target value)	0.45043
PID output limit function	106Fh	A078	0 ~ 1000 00: Always ON	0.1[%]	1266h	A078	0~1000 00: Always ON	0.1[%]
AVR selection	1070h	A081	01: Always OFF	-	1269h	A081	01: Always OFF	-
			02: OFF during deceleration 200-V class				02: OFF during deceleration 200-V class:	
			0: 200/ 1: 215/ 2: 220/ 3: 230/ 4:				00 (200)/ 01 (215)/ 02 (220)/ 03	
AVR voltage selection	1071h	A082	240	-	126Ah	A082	(230)/ 04 (240)	_
Avit voltage selection	10/10	71002	400-V class		120/11	71002	400-V class:	
			0: 380/ 1: 400/ 2: 415/ 3: 440/ 4: 460/ 5: 480				05 (380)/ 06 (400)/ 07 (415)/ 08 (440)/ 09 (460)/ 10 (480)	
RUN mode selection	1072h	A085	00: Normal operation	-	126Dh	A085	00: Normal operation	-
Energy-saving response/	1072h	A085	01: Energy-saving operation $0 \sim 1000$	0.1[%]	126Eh	A085	01: Energy-saving operation 0~1000	0.1[%]
	1073h	A092(MSB	0.1000	0.1[70]	120Lh	A092(HIGH)	0.01000	0.1[%]
Acceleration time 2	1075h	A092(LSB)			1275h	A092(LOW)		
2nd acceleration time 2	1519h 151Ah		1 to 300000 The second decimal place is ignored		226Fh 2270h	A292(HIGH) A292(LOW)		
Deceleration time 2	1076h		when the value is over 10000 (100.0	0.01 [s]	1276h	A093(HIGH)	0~360000	0.01[s]
Deceleration time 2	1077h	A093(LSB)	seconds).		1277h	A093(LOW)		
2nd deceleration time 2	151Bh 151Ch	A293(MSB A293(LSB)			2271h 2272h	A293(HIGH) A293(LOW)		
2-step acceleration/							00: Switch via 2CH terminal ( multi-	
deceleration selection	1078h	A094	00: Switched via terminal 2CH	-	1278h	A094	function input: 09)	-
2nd 2-step acceleration/			01: Switched by setting		2273h	A294	01: Switch by setting( A095/ A295/ A096/ A296)	
	151Dh	A294					······································	
deceleration selection 2-step acceleration		A294 A095			1279h	A095(HIGH)		
deceleration selection 2-step acceleration frequency	107Ah	A095			127Ah	A095(LOW)		
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency			0 ~ 4000	0.1[H7]	127Ah 2274h 2275h	A095(LOW) A295(HIGH) A295(LOW)	0~40000 (In the high-frequency	0.01[Hz]
deceleration selection 2-step acceleration frequency 2-step acceleration frequency 2-step deceleration	107Ah	A095	0~4000	0.1[Hz]	127Ah 2274h 2275h 127Bh	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH)	0 $\sim$ 40000 (In the high-frequency mode : $\sim$ 58000)	0.01[Hz]
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration	107Ah 151Fh 107Ch	A095 A295	0 ~ 4000	0.1[Hz]	127Ah 2274h 2275h 127Bh 127Ch 2276h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW) A296(HIGH)		0.01[Hz]
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration frequency	107Ah 151Fh	A095 A295 A096	0 ~ 4000	0.1[Hz]	127Ah 2274h 2275h 127Bh 127Ch 2276h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW)	mode : ~58000)	0.01[Hz]
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration	107Ah 151Fh 107Ch	A095 A295 A096		0.1[Hz]	127Ah 2274h 2275h 127Bh 127Ch 2276h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW) A296(HIGH)	mode : ~58000) 00: Line 01: S-shape curve	0.01[Hz]
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration frequency Acceleration pattern selection	107Ah 151Fh 107Ch 1521h 107Dh	A095 A295 A096 A296 A097	0 ~ 4000 	0.1[Hz]	127Ah 2274h 2275h 127Bh 127Ch 2276h 2277h 127Dh	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW) A296(HIGH) A296(LOW) A097	mode : ~58000) 00: Line 01: S-shape curve 02: U-shape curve	0.01[Hz]
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration frequency Acceleration pattern	107Ah 151Fh 107Ch 1521h	A095 A295 A096 A296	00: Line	0.1[Hz] -	127Ah 2274h 2275h 127Bh 127Ch 2276h 2277h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW) A296(HIGH) A296(LOW)	mode : ~58000) 00: Line 01: S-shape curve	0.01[Hz]
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration frequency Acceleration pattern selection Deceleration pattern selection	107Ah 151Fh 107Ch 1521h 107Dh 107Eh	A095           A295           A096           A296           A097           A098	00: Line	0.1[Hz] -	127Ah 2274h 2275h 127Bh 127Ch 2276h 2277h 127Dh 127Dh 127Eh 1281h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(HIGH) A296(LOW) A296(LOW) A097 A098 A101(HIGH)	mode : ~58000) 00: Line 01: S-shape curve 02: U-shape curve 03: Inverted U-shape curve 04: EL-S-shape curve	0.01[Hz] -
deceleration selection 2-step acceleration frequency 2d 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration frequency Acceleration pattern selection FI start frequency	107Ah 151Fh 107Ch 1521h 107Dh 107Eh 1080h	A095 A295 A096 A296 A097 A098 A101	00: Line	0.1[Hz] - 0.1[Hz]	127Ah 2274h 2275h 127Bh 127Ch 2276h 2277h 127Dh 127Dh 127Eh 1281h 1282h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW) A296(HIGH) A296(LOW) A097 A097 A098 A101(HIGH) A101(LOW)	mode : ~58000) 00: Line 01: S-shape curve 02: U-shape curve 03: Inverted U-shape curve 04: EL-S-shape curve 0~40000 (In the high-frequency	0.01[Hz] - 0.01[Hz]
deceleration selection 2-step acceleration frequency 2nd 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration frequency Acceleration pattern selection Deceleration pattern selection	107Ah 151Fh 107Ch 1521h 107Dh 107Eh	A095           A295           A096           A296           A097           A098	00: Line 01: S-shape curve	-	127Ah 2274h 2275h 127Bh 127Ch 2276h 2277h 127Dh 127Dh 127Eh 1281h 1282h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW) A296(HIGH) A296(LOW) A097 A097 A098 A101(HIGH) A101(LOW)	mode : ~58000) 00: Line 01: S-shape curve 02: U-shape curve 03: Inverted U-shape curve 04: EL-S-shape curve	-
deceleration selection 2-step acceleration frequency 2-step acceleration frequency 2-step deceleration frequency 2nd 2-step deceleration frequency Acceleration pattern selection FI start frequency	107Ah 151Fh 107Ch 1521h 107Dh 107Eh 1080h	A095 A295 A096 A296 A097 A098 A101	00: Line 01: S-shape curve	-	127Ah 2274h 2275h 127Bh 127Ch 2276h 2277h 127Dh 127Dh 127Eh 1281h 1282h 1283h	A095(LOW) A295(HIGH) A295(LOW) A096(HIGH) A096(LOW) A296(LOW) A296(LOW) A097 A097 A098 A101(HIGH) A101(LOW) A102(HIGH)	mode : ~58000) 00: Line 01: S-shape curve 02: U-shape curve 03: Inverted U-shape curve 04: EL-S-shape curve 0~40000 (In the high-frequency	-

T should not be	1005		00: Start frequency A101		400-		00: FI Start Frequency (A101)	
FI start selection	1085h	A105	01: 0 Hz	-	1287h	A105	01: 0 Hz 00: Digital Operator (A020/A220)	-
Operation frequency input A setting	108Eh	A141	00: Digital Operator (F001) 01: Digital Operator (volume) 02: Input FV		12AFh	A141	01: Volume 02: Voltage (FV) input	
Operation frequency input B setting	108Fh	A142	-03: Input FI 04: RS485 communications	-	12B0h	A142	03: Current (FI) input 04: Modbus communication 05: Option 07: Pulse train frequency	-
Operator selection	1090h	A143	00: Addition $(A + B)$ 01: Subtraction $(A - B)$ 02: Multiplication $(A \times B)$	-	12B1h	A143	07: Pulse train frequency 00: Addition (A141 + A142) 01: Subtraction (A141 - A142) 02: Multiplication (A141 × A142)	-
Frequency addition amount	1091h	A145	0 ~ 4000	0.1[Hz]	12B3h 12B4h		0~40000 (In the high-frequency mode : ~58000)	0.01[Hz]
Frequency addition direction	1093h	A146	00: Adds the A145 value to the output	-	12B5h	A146	00: Frequency reference + A145 01: Frequency reference - A145	-
VR start frequency	1095h	A151	0 ~ 4000	0.1[Hz]			0~40000 (In the high-frequency	0.01[Hz]
VR end frequency	1097h	A152	$0 \sim 4000$	0.1[Hz]	12C7h 12C8h	A162(HIGH)	mode : ~58000) 0~40000 (In the high-frequency	0.01[Hz]
VR start ratio	1098h	A153	0 ~ 100	1[%]	12C9h 12CAh	A163	mode : $\sim$ 58000) 0 to VR End Ratio	1[%]
VR end ratio VR start selection	1099h 109Ah	A154 A155	0 ~ 100 0, 1	- 1[%]	12CBh 12CCh	A164 A165	VR Start Ratio to 100 00: VR Start Frequency (A161)	1[%]
	109A11	A155	0, 1 00: Alarm	-	12001	AIOS	01: 0 Hz 00: Trip	-
Retry selection	10A5h	b001	01: 0 Hz start 02: Frequency matching restart 03: Trip after frequency matching deceleration stop	-	1301h	b001	01: 0-Hz restart 02: Frequency matching restart 03: Trip after frequency matching deceleration stop 04: Frequency pull-in restart	-
Allowable momentary power Retry wait time	10A6h 10A7h	b002 b003	3 ~ 250 3 ~ 1000	0.1[s] 0.1[s]	1302h 1303h	b002 b003	3~250 3~1000	0.1[s] 0.1[s]
Momentary power interruption/undervoltage trip during stop selection	10A8h	b004	00: Disabled 01: Enabled	-	1304h	b004	00: Disabled 01: Enabled 02: Disabled during stop and deceleration stop by turning off the	-
Momentary power	10.00	1.005	00: 16 times		1005	1.005	RUN command 00: 16 times	
interruption retry time	10A9h	b005	01: No limit	-	1305h	b005	01: No limit 00: Frequency at interruption	-
Starting frequency at frequency pull-in restart	1170h	b011	00: Frequency at interruption 01: Max. frequency 02: Set frequency	-	131Fh	b030	01: Maximum frequency 02: Set frequency (Frequency reference)	-
Electronic thermal level 2nd electronic thermal level	10ADh 1527h	b012 b212	2000 to 10000 Set the rated current to 10000	0.01[%]	130Dh 230Ch	b012 b212	200~1000	0.1[%]
Electronic thermal characteristics selection	10AEh	b013	00: Reduced torque characteristics 1		130Eh	b013	00: Reduced torque characteristics	
2nd electronic thermal characteristics selection	1528h	b213	01: Constant torque characteristics 02: Reduced torque characteristics 2	-	230Dh	b213	01: Constant torque characteristics 02: Free setting	-
Overload limit selection	10B5h	b021	00: Disabled	-	1316h	b021	00: Disabled	-
2nd overload limit selection Overload limit level	1529h 10B6h	b221 b022	01: Enabled in acceleration/constant 00: Disabled	0.01[%]	2316h 1317h	b221 b022	01: Enabled during $200 \sim 2000$	0.1[%]
2nd overload limit level Overload limit parameter	152Ah 10B7h	b222 b023	01: Enabled in acceleration/constant $1 \sim 300$		2317h 1318h	b222 b023		
2nd overload limit parameter	152Bh	b223	$1 \sim 300$ $1 \sim 30000$	0.1[s]	2318h	b223	1~30000	0.1[s]
Deceleration rate constant Frequency pull-in restart	1171h 1172h	b029 b030	$1 \sim 30000$ 200 ~ 20000	0.1[s] 0.01[%]	131Eh 131Dh	b029 b028	1~30000 200~2000	0.1[s] 0.1[%]
Soft lock selection	10BCh	b031	<ul> <li>00: Data other than b031 cannot be changed when terminal SFT is ON.</li> <li>01: Data other than b031 and the specified frequency parameter cannot be changed when terminal SFT is ON.</li> <li>02: Data other than b031 cannot be changed.</li> <li>03: Data other than b031 and the specified frequency parameter cannot be changed.</li> <li>10: Data other than parameters changeable during operation cannot be changed.</li> </ul>	-	1320h	b031	00: Data other than b031 cannot be changed when terminal SFT is ON. 01: Data other than b031 and the set frequency cannot be changed when terminal SFT is ON. 02: Data other than b031 cannot be changed. 03: Data other than b031 and set frequency cannot be changed. 10: Data can be changed during RUN.	-
Selection of non-stop function at momentary power interruption	10C9h	b050	00: Disabled 01: Enabled (Stop) 02: Enabled (Restart)	-	1334h	b050	00: Disabled 01: Enabled (Deceleration stop) 02: Enabled (Constant voltage, without recovery) 03: Enabled (Constant voltage, with recovery)	-
Starting voltage of non-stop function at momentary power interruption	10CAh	b051	$0 \sim 10000$	0.1[V]	1335h	b051	0~10000	0.1[V]
Stop deceleration level of non-stop function at momentary power interruption	10CBh	b052	0 ~ 10000	0.1[V]	1336h	b052	0~10000	0.1[V]
Deceleration time of nonstop	10CCh	b053	1 ~ 30000	0.1[s]	1337h 1338h	b053(HIGH) b053(LOW)	1~360000	0.01[s]
function at momentary	1000				-	/		
Tunction at momentary Deceleration starting width of non-stop function at momentary power interruption	10CEh	b054	0~100	0.1[Hz]	1339h	b054	0~1000 (In the high-frequency mode : 10000)	0.01[Hz]
Deceleration starting width of non-stop function at momentary power		b054 b055	$0 \sim 100$ $2 \sim 50$	0.1[Hz] 0.1	1339h 1388h	b054 b133		0.01[Hz] 0.01

Starting frequency	10D1h	b082	$5 \sim 99$	0.1[Hz]	1355h	b082	$1 \sim 999$ (In the high-frequency mode : $\sim 10000$ )	0.01[Hz]
Carrier frequency	10D2h	b083	$20 \sim 120$	0.1[kHz]	1356h	b083	20~150 (100)	0.1[kHz]
Initialization selection	10D3h	b084	00: Clears the trip monitor 01: Initializes data 02: Clears the trip monitor and initializes data	-	1357h	b084	00: Initialization disabled 01: Clearing fault monitor 02: Initialize data 03: Clear fault monitor + Initialize data 04: Clear fault monitor + Initialize data + Clear DriveProgramming	-
Initialization parameter selection	10D4h	b085	00: Fixed Do not change.	-	1358h	b085	Do not change the default 00.	-
Frequency conversion	10D5h	b086	1 ~ 999	0.1	1359h	b086	1~9999	0.01
STOP key selection	10D6h	b087	00: Enabled 01: Disabled	-	135Ah	b087	00: Enabled 01: Disabled 02: Only RESET enabled	-
Free-run stop selection	10D7h	b088	00: 0 Hz start 01: Frequency pull-in restart	-	135Bh	b088	00: 0-Hz restart 01: Frequency matching restart 02: Frequency pull-in restart	-
Stop selection	10DAh	b091	00: Deceleration→Stop 01: Free-run stop	-	135Eh	b091	00: Deceleration stop 01: Free-run stop	-
Cooling fan control	10DBh	b092	00: Always ON 01: ON during RUN 02: Depends on the fin temperature	-	135Fh	b092	00: Always enabled 01: Enabled only during operation (including 5 minutes after power on/stop) 02: Dependent on cooling fin temperature	-
Overvoltage protection function selection during deceleration	1176h	b133	00: Disabled 01: Enabled	-	1385h	b130	00: Disabled 01: DC voltage kept constant 02: Acceleration enabled	-
Overvoltage protection level setting during deceleration	1177h	b134	200-V class: 330. to 395. 400-V class: 660. to 790.	1[V]	1386h	b131	200-V class: 330 to 395 400-V class: 660 to 790	1[V]
Overcurrent suppression function	10F7h	b140	00: Disabled 01: Enabled	-	131Ch	b027	00: Disabled 01: Enabled 02: Enabled (at reduced voltage startup)	-
Automatic carrier reduction	10F8h	b150	00: Disabled 01: Enabled	-	135Ch	b089	00: Disabled 01: Enabled (dependent on current) 02: Enabled (dependent on cooling fin temperature)	-

Multi-function input 5	110Fh	C015	ļ		140Fh	C015	
Multi-function input 4	110Eh	C014			140Eh	C014	
Multi-function input 3	110Dh	C013	01 : NC	-	140Dh	C013	-01: NC (NC contact)
Multi-function input 2	110Ch	C012	00 : NO		140Ch	C012	- 00: NO (NO contact)
Multi-function input 1	110Bh	C011	l		140Bh	C011	
							58: MI3 (General-purpose input 3)
							57: MI2 (General-purpose input 2)
selection	133011	C205					53: KHC (Integrated power clear) 56: MI1 (General-purpose input 1)
2nd multi-function input 5	1536h	C205					permission)
							52: ATR (Torque reference input
							51: F-TM (Forced terminal block)
			1				addition)
							50: ADD (Set frequency A145
selection							47: PCLR (Current position clear)
Multi-function input 5	1107h	C005			1405h	C005	46: LAC (LAD cancel)
							44: BOK (Brake confirmation)
							42: TRQ2 (Torque limit switching 2)
			1				41: TRQ1 (Torque limit switching 1)
							40: TL (Torque limit enabled)
							39: OLR (Overload limit switching)
selection	100011	C204					7)
2nd multi-function input 4	1535h	C204					38: SF7 (Multi-step speed setting bit
							6)
							37: SF6 (Multi-step speed setting bit
			1		+		5)
							36: SF5 (Multi-step speed setting bit
							4)
selection	110011	004			1-10-111	004	35: SF4 (Multi-step speed setting bit
Multi-function input 4	1106h	C004			1404h	C004	3)
							34: SF3 (Multi-step speed setting bit
							2)
			1				33: SF2 (Multi-step speed setting bit
							1)
							32: SF1 (Multi-step speed setting bit
selection	133411	C203					31: OPE (Forced operator function)
2nd multi-function input 3	1534h	C203					clear)
							29: UDC (Remote operation data
							decelerated)
			1	-			- 28: DWN (Remote operation -
							accelerated)
			255: NO				27: UP (Remote operation
selection			terminal 3 if enabled)				
	1105h	C003			1403h	C003	24: PIDC (PID integral reset)
Multi-function input 3			64: EMR(automatically allocated to				23: PID (PID disabled)
			53: SP-SET				22: F/R (3-wire forward/reverse)
			52: RDY				21: STP (3-wire stop)
			51: F-TM		<b>└──</b>		20: STA (3-wire start)
			50: ADD				<c005 only=""></c005>
			31: OPE				protection)
selection	100011	C202	29: UDC				19: TH (PTC thermistor thermal
2nd multi-function input 2	1533h	C202	28: DWN				18: RS (reset)
			27: UP				16: AT (Analog input switching)
			24: PIDC				15: SFT (Soft lock)
			23: PID		+		14: CS (Commercial switch)
			22: F/R				prevention function)
			2+1: STP				13: USP (Power recovery restart
selection	1.10	0002	20: STA		1.5211	2302	12: EXT (External trip)
Multi-function input 2	1104h	C002	19: PTC terminal 5 only		1402h	C002	11: FRS (Free-run stop)
			18: RS				acceleration/deceleration)
			16: AT				09: 2CH (2-step
			15: SFT				
							08: SET (2nd control)
			12: EXT 13: USP				braking)
selection	155211	C201	11: FRS				07: DB (External DC injection
2nd multi-function input 1	1532h	C201	09: 2CH				06: JG (Jogging)
							binary 4)
			08: SET				05: CF4 (Multi-step speed setting
			07: DB				binary 3)
			06: JG				04: CF3 (Multi-step speed setting
			05: CF4				binary 2)
selection	1100	0001	04:CF3		1.010	0001	03: CF2 (Multi-step speed setting
Multi-function input 1	1103h	C001	03: CF2		1401h	C001	binary 1)
			02: CF1				02: CF1 (Multi-step speed setting
			01: RV				01: RV (Reverse)

$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	ulti-function output rminal P1 selection	1114h	C021	00: RUN 01: FA1 02: FA2 03: OL 04: OD 05: AL 06: DC 07: FBV 08: NDC 09: LOG 10: ODc(Do not use.) 43: LOC		1415h	C021	00: RUN (During RUN) 01: FA1 (Constant speed arrival signal) 02: FA2 (Set frequency exceeded signal) 03: OL (Overload warning) 04: OD (Excessive PID deviation) 05: AL (Alarm signal) 06: FA3 (Set-frequency only signal) 07: OTQ (Overtorque/Undertorque signal) 09: UV (Signal during undervoltage) 10: TRQ (Torque limit) 11: RNT (RUN time over) 12: ONT (Power ON time over) 13: THM (Electronic thermal warning) 19: BRK (Brake release) 20: BER (Brake error) 21: ZS (O-Hz detection signal) 22: DSE (Excessive speed deviation) 23: POK (Position ready) 24: FA4 (Set frequency only signal 2) 25: FA5 (Set-frequency only signal 2) 26: OL2 (Overload warning 2) 27: FVDC (Analog FV disconnection	
AM selection111BhC02800: F (Output frequency) 01: A (Output current)-141ChC02800: Output frequency 01: Output torque 04: Output torque 05: Input power 06: Electronic thermal load rate 07: LAD frequency 10: Cooling fin temperature 11: Output torque (signed) 13: DriveProgramming (YA(1)) 16: Option (No applicable Option)Multi-function output111DhC031 00: NO 01: NC00: NO 01: NC-141FhC031 12: Or Votput torque (signed) 13: DriveProgramming (YA(1)) 16: Option (No applicable Option)Multi-function output Relay output (MA, MB)1122hC036 01: NC00: Enabled during acceleration/ deceleration/ constant speed 01: Enabled only during constant speed-141FhC031 00: NO (NO contact) 01: NC (NC contact)-Light load signal output mode1178hC038 0 to 200000.01[%]1427hC039 2429h0-20000.1[%] 0: During acceleration/ deceleration and constant speed 01: Only during constant speed 01: 122h 0<~2000		1119h	C026		-	141Ah	C026	<ul> <li>28: FIDC (Analog FI disconnection detection)</li> <li>31: FBV (PID feedback comparison)</li> <li>32: NDc (Communications disconnection detection)</li> <li>33: LOG1 (Logic operation output 1)</li> <li>34: LOG2 (Logic operation output 2)</li> <li>35: LOG3 (Logic operation output 3)</li> <li>39: WAC (Capacitor life warning)</li> <li>40: WAF (Cooling fan life warning)</li> <li>40: WAF (Cooling fan life warning)</li> <li>41: FR (Starting contact signal)</li> <li>42: OHF (Cooling fin overheat warning)</li> <li>43: LOC (Low current signal)</li> <li>44: MO1 (General-purpose output 1)</li> <li>45: MO2 (General-purpose output 3)</li> <li>50: IRDY (Operation ready)</li> <li>51: FWR (Forward run)</li> <li>52: RVR (Reverse run)</li> <li>53: MJA (Fatal fault signal)</li> <li>54: WCFV (Window comparator FV)</li> <li>55: WCFI (Window comparator FI)</li> <li>58: REFF (Frequency reference source)</li> <li>59: REF (RUN command source)</li> <li>60: SETM (Motor 2 selection)</li> <li>62: EDM (Safety device monitor signal)</li> </ul>	
Relay output (MA, MB)       1122h       C036       01 : NC       1       1424h       C036       01 : NC (NC contact)       -         Light load signal output mode       1178h       C038       00: Enabled during acceleration/ deceleration/ deceleration/ deceleration/ deceleration/ deceleration/ deceleration/ deceleration and constant speed       00: During acceleration/ deceleration/ deceleration/ deceleration/ deceleration and constant speed       00: During acceleration/ deceleration/ deceleration/ deceleration/ deceleration and constant speed       -       1426h       C038       00: During acceleration/ deceleration/ deceleration/ deceleration/ deceleration and constant speed       -       -       1426h       C038       00: During acceleration/ deceleration/ deceleration/ deceleration/ deceleration and constant speed       -       -       1426h       C038       00: During acceleration/ deceleration/ deceleration/ deceleration/ deceleration and constant speed       -       -       1426h       C038       00: During acceleration/ deceleration/ deceleration/ deceleration and constant speed       -       -       -       1426h       C038       00: During constant speed       -       -       -       -       0       -       0       -       0       -       0       -       0       -       0       -       0       -       0       -       0       -       0       -       0       -       0				01: A (Output current)	-			00: Output frequency 01: Output current 02: Output torque 04: Output voltage 05: Input power 06: Electronic thermal load rate 07: LAD frequency 10: Cooling fin temperature 11: Output torque (signed) 13: DriveProgramming (YA(1)) 16: Option (No applicable Option)	-
Relay output (MA, MB)       1122h       C036       01: NC       1424h       C036       01: NC (NC contact)         Light load signal output mode       1178h       C038       00: Enabled during acceleration/ deceleration/ deceleration/ deceleration and constant speed       00: During acceleration/ deceleration and constant speed       00: Ouring acceleration/ deceleration and constant speed       01: Only during constant speed       01: Only d				+	-			00: NO (NO contact)	_
Overload warning level         1124h         C041         0 to 20000         0.01[%]         1429h         C041         0~2000         0.1[%]           2nd overload warning level         153Ah         C241         Set to 10000 at rated current         0.01[%]         2429h         C241         0~2000         0.1[%]           Arrival frequency during acceleration         1126h         C042         0~2000         0.1[%]         1422h         C041         0~2000         0.1[%]	ght load signal output			00: Enabled during acceleration/ deceleration/ constant speed 01: Enabled only during constant			C038	00: During acceleration/ deceleration and constant speed	
Overload warning level         1124h         C041         0 to 20000         0.01[%]         1429h         C041         0~2000         0.1[%]           2nd overload warning level         153Ah         C241         Set to10000 at rated current         0.01[%]         2429h         C241         0~2000         0.1[%]           Arrival frequency during acceleration         1126h         C042         0~2000         0.1[%]         1422h         C041         0~2000         0.1[%]	ght load detection level	1179h	C039		0.01[%]	1427h	C039	0~2000	0.1[%]
2nd overload warning level         153Ah         C241         Set to10000 at rated current         0.01[%]         2429h         C241         0~2000         0.1[%]           Arrival frequency during acceleration         1126h         C042         0~4000         0.1[Hz]         142Ah         C042(LIGH)         0~40000 (In the high-frequency         0.01[Hz]						1429h			
acceleration $112$ $0 \sim 4000$ $0 \sim 11$ $142Bh C042(LOW) 0 \sim 40000$ (In the high-frequency 0.010 Hz)	nd overload warning level				U.UI[%]	2429h	C241		0.1[%]
Arrival requercy during 1129b C043	cceleration rrival frequency during			0 ~ 4000	0.1[Hz]	142Bh 142Ch	C042(LOW) C043(HIGH	0 $\sim$ 40000 (In the high-frequency	0.01[Hz]
deceleration 142Dh CU43(LOW)				0	0.45273			0. 1000	0.1[%]

								1
Communication speed							03(2400bps)/ 04(4800bps)/	
selection	1138h	C071			144Bh	C071	05(9600bps)/ 06(19.2kbps)/	
(Baud rate selection)							07(38.4kbps)/ 08(57.6kbps)/	
	11206	C072	-		144Ch	C072	09(76.8kbps)/ 10(115.2kbps)	
Communication station No.	1139h	C072	-		144Ch	C072	1~247	-
Communication parity selection	113Bh	C074			144Eh	C074	00: No/ 01: Even/ 02: Odd	_
Communication stop bit selection	113Ch	C075	Do not change through ModBus communication. For setting, refer to		144Fh	C075	1: 1 bit 2: 2 bits	
			"ModBus Setting" (4-78).				00: Trip	İ
Communication orman							01: Trip after deceleration stop	
Communication error	113Dh	C076			1450h	C076	02: Ignore	
selection							03: Free-run stop	
							04: Deceleration stop	
Communication error	44255	C0 77			4.4541	C077	0: Timeout disabled	0.04[-]
timeout	113Eh	C077			1451h	C077	1 to 9999	0.01[s]
Communication wait time	113Fh	C078			1452h	C078	0~1000	1[ms]
FV adjustment	1141h	C081	$0 \sim 2000$	0.450/3	1455h	C081	-0~2000	0.450(1
FI adjustment	1142h	C082	$-0 \sim 2000$	0.1[%]	1456h	C082	-0~2000	0.1[%]
UP/DWN selection	1149h	C101	00 : OFF 01 : ON	-	1469h	C101	00: Not store frequency data 01: Store frequency data	-
			00: Trip reset at power-on				00: Trip reset at power-on	
			01: Trip reset when the power is				01: Trip reset at power-off	-
Reset selection	114Ah	114Ah C102	OFF	-	146Ah	C102	02: Enabled only during trip (Reset	
	11 // 01		02: Enabled only during trip (Reset	et			at power-on)	
			when the power is ON.)				03: Trip reset only	
Logic operation function A			00 : RUN/01 : FA1/02 : FA2/03 :					
input	1150h	C141	OL/04 : OD/05 : AL/06 : Dc/07 :		1492h	C142	Same as C021 (Except 33 (LOG1) to	
Logic operation function B			FBV/08:NDc/10:ODc(使用しない で	-			35 (LOG3), 63 (OPO), and 255 (no))	-
input	1151h	C142	ください) /43 : LOC		1493h	C143		
							00:AND	
Logic operator selection	1152h	C143	00 : AND/01 : OR/02 : XOR	-	1494h	C144	01:OR	-
							02:XOR	
Output terminal P1 ON delay	1153h	C144	_		1486h	C130		
Output terminal P1 OFF	1154h	C145	$0 \sim 1000$	0.1[s]	1487h	C131	0~1000	0.1[s]
Relay output ON delay	1157h	C148	1	[.]	1490h	C140		[-]
Relay output OFF delay	1158h	C149			1491h	C141		
Motor capacity selection	1165h	H003	00 : 0.2/ 02 : 0.4/ 04 : 0.75/ 06 : 1.5/ 07 : 2.2/ 09 : 3.7/ 11 : 5.5/ 12 :		1503h	H003	00:0.1/ 01:0.2/ 02:0.4/ 03:0.55/ 04:0.75/ 05:1.1/ 06:1.5/ 07:2.2/	
2nd motor capacity selection	1541h	H203	7.5	-	2503h	H203	08:3.0/ 09:3.7/ 10:4.0/ 11:5.5/ 12:7.5/ 13:11.0/ 14:15.0/ 15:18.5	-
Motor pole number selection	1166h	H004	2/4/6/0	1[155]]	1504h	H004	00:2P/ 01:4P/ 02:6P/ 03:8P	
2nd motor pole number	1542h	H204	2/4/6/8	1[極]	2504h	H204	04~23:10~48Pは設定しないでください	-
Stabilization parameter	1168h	H006	0 255	450/3	1507h	H006		450/3
2nd stabilization parameter	1544h	H206	$-0. \sim 255.$	1[%]	2507h	H206	-0~255	1[%]
Enter command	0900h	-	Indefinite value	-	0900h	-	1	-

Please note that 3G3MX2-V1 does not provide the following functions:

	3G3JX				
Function name	Register No.	Parameter No.			
Overload limit source selection	10BBh	b028			
2nd overload limit source selection	152Ch	b228			
AM adjustment	10CFh	b080			
Monitor display selection	10D8h	b089			
Overvoltage LAD stop function	10F5h	b130			
Overvoltage LAD stop function level setting	10F6h	b131			
Ready function selection	10F9h	b151			
PID FB upper limit	112Eh	C052			
PID FB lower limit	112Fh	C053			
Operator/ModBus selection	1137h	C070			
AM offset adjustment	1145h	C086			

#### Note: Do not use this document to operate the Unit.

#### **OMRON** Corporation **Industrial Automation Company** Authorized Distributor: Tokyo, JAPAN Contact: www.ia.omron.com Regional Headquarters OMRON EUROPE B.V. Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands OMRON ELECTRONICS LLC 2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A Tel: (1) 847-843-7900/Fax: (1) 847-843-7787 Tel: (31)2356-81-300/Fax: (31)2356-81-388 © OMRON Corporation 2019 All Rights Reserved. OMRON (CHINA) CO., LTD. Room 2211, Bank of China Tower, OMRON ASIA PACIFIC PTE. LTD. In the interest of product improvement, No. 438A Alexandra Road # 05-05/08 (Lobby 2), 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200 specifications are subject to change without notice. Alexandra Technopark, Singapore 119967 Tel: (65) 6835-3011/Fax: (65) 6835-2711

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