E6J-C

CSM_E6J-C_DS_E_4_1

Ultracompact Rotary Encoder with External Diameter of 20 mm

- Incremental model
- External diameter of 20 mm.
- Resolution of up to 1,000 ppr.
- Both Solid-shaft Models and Hollow-shaft Models are available.





Be sure to read Safety Precautions on page 4

Ordering Information

Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Resolution (pulses/rotation)	Shaft	Model
5 VDC	NPN open-collector output	100, 200, 360, 600	Shaft model	E6J-CWZ1C (resolution) 1M Example: E6J-CWZ1C 100P/R 1M
		1000		
	Voltage output	100, 200, 360, 600	Shaft model	E6J-CWZ1E (resolution) 1M Example: E6J-CWZ1E 100P/R 1M
		1000	Shall model	
	Voltage output	360, 600	Hollow shaft	E6J-CWZ1EA2 (resolution) 1M Example: E6J-CWZ1EA2 360P/R 1M
		1000		

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks
Coupling	E69-C02B	Included in the shaft model.

Refer to Accessories for details.

Ratings and Specifications

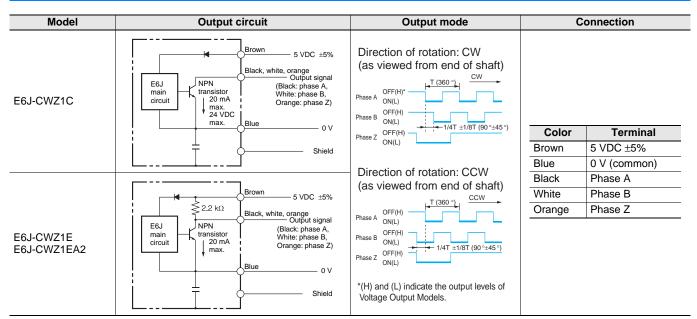
Item	Model	E6J-CWZ1C	E6J-CWZ1E	E6J-CWZ1EA2		
Shaft		Shaft Shaft dia. 2 mm, Length 10 mm		Hollow shaft Hollow shaft dia. 2 mm, Depth 10 mm		
Rated voltage		5 VDC ±5%				
Current consumption*1		40 mA max.				
Resolution (pulses/rotation)		100, 200, 360, 600, 1000		360, 600, 1000		
Output phases		Phases A, B, and Z				
Output configuration		NPN open-collector output Voltage output (NPN)				
Output capacity		Applied voltage: 24 VDC max. Load current: 20 mA max. Residual voltage: 0.5 V max. (at load current of 20 mA)	Output resistance: $2.2 \text{ k}\Omega$ Load current: 20 mA max. Residual voltage: 0.5 V max. (at load current of 20 mA)			
Rise and fall times of output		2 μs max. (Cable length: 1 m, Load current: 20 mA)				
Maximum response frequency*2		100 kHz (50 kHz when using phase Z reset)				
Phase difference between outputs		90°±45° between A and B				
Direction of rotation		Phase A precedes in CW (as viewed from end of shaft).				
Starting torque		1 mN·m max.				
Moment of inertia	100P/R	$0.034 \times 10^{-7} \text{ kg·m}^2$				
Moment of mertia	200P/R min.	$0.045 \times 10^{-7} \text{ kg} \cdot \text{m}^2$		$0.351 \times 10^{-7} \text{ kg-m}^2$		
Shaft loading	Radial	1.9 N				
Ondit loading	Thrust	1.9 N				
Maximum permissible speed		6,000 r/min				
Protective circuits		Power supply reverse polarity protection				
Ambient temperature range		Operating: -10 to 70°C (with no icing and condensation), Storage: -20 to 80°C (with no icing and condensation)				
Ambient humidity range		Operating/Storage: 35% to 85% (with no condensation)				
Insulation resistance		Excluded because of capacitor ground.				
Dielectric strength		Excluded because of capacitor ground.				
Vibration resistance		Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y and Z directions				
Shock resistance		Destruction: 500 m/s² 3 times each in X, Y and Z directions				
Degree of protection		IEC 60529 IP40				
Connection method		Pre-wired Models (Standard cable length: 1 m)				
	Case	Aluminum				
Material	Encoder	Aluminum				
	Shaft	SUS404 SUS304				
Weight (packed state)		Approx. 40 g				
Accessories		Instruction manual, Coupling, L-shaped wrench (M0.9) Instruction manual, L-shaped wrench (M0.9)		Instruction manual, L-shaped wrench (M0.9)		

Maximum response frequency × 60 Maximum electrical response speed (rpm) = -Resolution

This means that the E6J-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

^{*1.} An inrush current of approximately 3 A will flow for approximately 10 μs when the power is turned ON.
*2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

I/O Circuit Diagrams



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case. 2. The capacitor $(0.1\mu F, 100 \text{ V})$ is connected between 0 V and FG (frame ground) of a circuit. 3. Normally, connect shield to 0 V or to an external ground.

Safety Precautions

Refer to Warranty and Limitations of Liability.



This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Safe Use

Installation Environment

- Do not use in an environment where combustible or explosive gas is present.
- Do not keep or use in an environment where the E6J-C is exposed to water, oil, chemicals, steam or dust. The E6J-C is damaged or burned out due to an internal circuit disconnection or short.
- To ensure safe operation and maintenance of the product, install it away from high-voltage devices and power devices.

Power Supply and Wiring

- Never apply the voltage and AC power that exceed the <u>rated</u> voltage (5 VDC ±5%). This may damage or burn out the product.
- Do not make the wiring while it is supplying power. This may damage the product or cause an electric shock.
- Do not short the load. This may damage or burn out the product.

Others

- Do not attempt to disassemble, repair, or modify the product.
- When disposing of the product, treat it as industrial waste.

Precautions for Correct Use

Do not use the product in atmospheres or environments that exceed product ratings.

Mounting

- The Rotary Encoder is composed of high-precision parts. Dropping the Rotary Encoder may damage some of its functions. Care should be taken when handling.
- When securing this product with screws, do not exceed 0.15 N·m for tightening torque.

- If wiring after securing the Encoder, do not pull on the cable with a force exceeding 12 N. Also, do not apply shock to the Encoder or shaft (hollow shaft).
- When a mounting error (eccentricity, declination) is wide, excessive load is applied (as 1.9 N both for shaft loading radial and thrust), and the E6J-C is damaged and the life of that will be extremely shorten.

Mounting of Hollow Shaft

- \bullet The diameter of the mating shaft must be $2^{-0.004}_{-0.012}$ mm, and the insert length must be 4 to 9.5 mm.
- Prepare leaf spring of flanges not to apply the load that exceeds a shaft permissible load.
- Use the Allen set screw provided with the hollow shaft to secure the shaft. Use a tightening torque of 0.15 N·m and apply screw lock glue to the screw to prevent it from becoming loose.

Wiring

- If a surge occurs in the power supply used, connect a surge absorber between power supplies and suppress the surge. To avoid a noise or other errors, shorten the wiring for the encoder as much as possible.
- When the length of the rotary encoder cable is extended, check the cable type and response frequency. There is a tendency that the residual voltage increases or a waved distortion occurs, due to changes in the cable resistance and the capacity between cables.
- Do not lay the cables in parallel with high-voltage lines or power lines. Doing so may result in damage or malfunction due to induction interference.

Connection

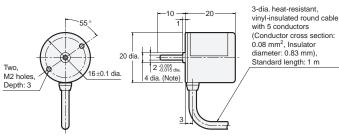
Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder E6J-CWZ1□



Note: The protrusion is a part of the shaft.

E6J-CWZ1EA2 35 ° Two, M2 holes, 19±0.1 We holes, 19±0.1 Two, M2 holes, 20 dia. Two, M2 holes, 20 dia.

Accessories (Order Separately)

Coupling E69-C02B

Refer to Accessories for details.

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